Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
CGM Ignition Switch Run/ Start Position Circuit Low	B2B0D	This DTC monitors for a CGM Ignition Switch Run/Start Position Circuit Low error as determined by the CGM	The CGM Diagnostic Status Message signal in GMLAN frame $3CF indicates that the CGM Ignition Switch Run/Start Position Circuit Low DTC has set in the CGM.		General Enable Criteria: Message $3CF Central Gateway Module	 is being received is present on the bus	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
CGM Ignition Switch Run/ Start Position Circuit High	B2B0E	This DTC monitors for a CGM Ignition Switch Run/Start Position Circuit High error as determined by the CGM	The CGM Diagnostic Status Message signal in GMLAN frame $3CF indicates that the CGM Ignition Switch Run/Start Position Circuit High DTC has set in the CGM.		General Enable Criteria: Message $3CF Central Gateway Module	 is being received is present on the bus	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
CGM Control Module Memory Failure	B2B12	This DTC monitors for a CGM Control Module Memory Failure error as determined by the CGM	The CGM Diagnostic Status Message signal in GMLAN frame $3CF indicates that the CGM Control Module Memory Failure DTC has set in the CGM.		General Enable Criteria: Message $3CF Central Gateway Module	 is being received is present on the bus	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
CGM Control Module Internal Performance Failure	B2B13	This DTC monitors for a CGM Control Module Internal Performance Failure error as determined by the CGM	The CGM Diagnostic Status Message signal in GMLAN frame $3CF indicates that the CGM Control Module Internal Performance Failure DTC has set in the CGM.		General Enable Criteria: Message $3CF Central Gateway Module	 is being received is present on the bus	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Crankshaft Position (CKP)-Camshaft Position (CMP) Correlation Bank 1 Sensor A	P0016	Detects cam to crank misalignment by monitoring if cam sensor pulse for bank 1 sensor A occurs during the incorrect crank position	4 cam sensor pulses less than or greater than nominal position in one cam revolution.	-10.0 Crank Degrees 10.0 Crank Degrees	Crankshaft and camshaft position signals are synchronized Engine is Spinning No Active DTCs: Time since last execution of diagnostic	 CrankSensor_FA P0340, P0341 < 1.0 seconds	2 failures out of 3 tests. A failed test is 4 failures out of 5 samples. One sample per cam rotation	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Outside Air Temperature (OAT) Sensor Circuit Performance (OAT wired to ECM)	P0071	Detects an Outside Air Temperature (OAT) sensor that is stuck in range. There are two components to the test: an engine off component, and an engine running component. If the engine has been off for a long enough period of time, and the coolant temperature and Intake Air Temperature (IAT) values are similar, then the air temperature values in the engine compartment of the vehicle are considered to have equalized. In this case, the engine off component of the diagnostic can be enabled. If the IAT and the OAT values are similar, then the OAT Performance Diagnostic passes. If the IAT and OAT values are not similar, the diagnostic will continue to monitor the IAT and the OAT as the vehicle starts to move. For applications that have ability to move without engaging the internal combustion	**Engine Off:** If IAT >= OAT: IAT - OAT If IAT < OAT: OAT - IAT If either of the following conditions are met, this diagnostic will pass: If IAT >= OAT: IAT - OAT If IAT < OAT: OAT - IAT	 > 15.0 deg C > 15.0 deg C <= 15.0 deg C <= 15.0 deg C	Time between current ignition cycle and the last time the engine was running Engine is not running Vehicle Speed Coolant Temperature - IAT IAT - Coolant Temperature OAT-to-IAT engine off equilibrium counter The "OAT-to-IAT engine off equilibrium counter" is a counter that is incremented or decremented based on vehicle speed when the engine is off. When this counter is high enough, the vehicle has reached an equilibrium where IAT and OAT can be compared. The value that is added or subtracted to the counter every 100 msec is contained in table **P0071: OAT Performance Drive Equilibrium Engine Off** No Active DTCs:	 >= 28,800.0 seconds >= 12.4 MPH < 15.0 deg C < 15.0 deg C >= 300.0 counts

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		engine, the engine off test will continue. If the vehicle has been moving quickly enough for a long enough period of time, the IAT and OAT values should have reached an equilibrium. This period of time is defined by the "OAT-to-IAT engine off equilibrium counter". The "OAT-to-IAT engine off equilibrium counter" is a counter that is incremented or decremented based on vehicle speed when the engine is off. When this counter is high enough, the vehicle has reached an equilibrium where IAT and OAT can be compared. While the "OAT-to-IAT engine off equilibrium counter" is counting, IAT and OAT are monitored for similarity. If they are similar, the OAT Performance Diagnostic passes. If the counter reaches an equilibrium and the IAT and OAT values are not similar, the OAT Performance Diagnostic will fail.	**Engine Running:** If IAT >= OAT: IAT - OAT If IAT < OAT: OAT - IAT If either of the following conditions are met, this diagnostic will pass: If IAT >= OAT: IAT - OAT If IAT < OAT: OAT - IAT	 > 15.0 deg C > 15.0 deg C <= 15.0 deg C <= 15.0 deg C	Time between current ignition cycle and the last time the engine was running Engine is running Vehicle Speed Engine air flow OAT-to-IAT engine running equilibrium counter The "OAT-to-IAT engine running equilibrium counter" is a counter that is incremented or decremented based on vehicle speed and engine air flow when the engine is running. When this counter is high enough, the vehicle has reached an equilibrium where IAT and OAT can be compared. The value that is added or subtracted to the counter every 100 msec is contained in table **P0071: OAT Performance Drive Equilibrium Engine Running** No Active DTCs:	 >= 28,800.0 seconds >= 12.4 MPH >= 10.0 grams/second >= 300.0 counts

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		If the engine off component of the diagnostic was enabled, but did not make a pass or fail decision, the engine running component will begin executing when the internal combustion engine starts to run. If the vehicle has been moving quickly enough for a long enough period of time, the IAT and OAT values should have reached an equilibrium. This period of time is defined by the "OAT-to-IAT engine running equilibrium counter". The "OAT-to-IAT engine running equilibrium counter" is a counter that is incremented or decremented based on vehicle speed when the engine is running. When this counter is high enough, the vehicle has reached an equilibrium where IAT and OAT can be compared. While the "OAT-to-IAT engine running equilibrium counter" is counting, IAT and OAT are monitored for						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		similarity. If they are similar, the OAT Performance Diagnostic passes. If the counter reaches an equilibrium and the IAT and OAT values are not similar, the OAT Performance Diagnostic will fail.						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Outside Air Temperature (OAT) Sensor Circuit Low	P0072	Detects a continuous short to ground in the Outside Air Temperature (OAT) signal circuit by monitoring the OAT sensor output resistance and failing the diagnostic when the OAT resistance is too low. The OAT sensor is a thermistor in which the resistance across the sensor can be equated to a temperature. A lower resistance is equivalent to a higher temperature.	Raw OAT Input	<= 46 Ohms (~150 deg C)	Continuous		40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Outside Air Temperature (OAT) Sensor Circuit High	P0073	Detects a continuous open circuit in the Outside Air Temperature (OAT) signal circuit by monitoring the OAT sensor output resistance and failing the diagnostic when the OAT resistance is too high. The OAT sensor is a thermistor in which the resistance across the sensor can be equated to a temperature. A higher resistance is equivalent to a lower temperature.	Raw OAT Input	>= 427,757 Ohms (~-60 deg C)	Continuous		40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Outside Air Temperature (OAT) Sensor Intermittent In-Range	P0074	Detects a noisy or erratic signal in the Outside Air Temperature (OAT) circuit by monitoring the OAT sensor and failing the diagnostic when the OAT signal has a noisier output than is expected. When the value of the OAT signal in °C is determined, a delta is calculated between the current reading and the previous reading. The absolute value of these deltas is summed over a number of OAT readings. The result of this summation is called a “string length”. Since the OAT signal is anticipated to be relatively smooth, a string length of a particular magnitude indicates a noisy or erratic OAT signal. The diagnostic will fail if the string length is too high.	String Length Where: "String Length" = sum of "Diff" calculated over And where: "Diff" = ABS(current OAT reading - OAT reading from 100 milliseconds previous)	> 100 deg C 10 consecutive OAT readings		Continuous	4 failures out of 5 samples Each sample takes 1.0 seconds	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Rail Pressure (FRP) Too Low	P0087	Determine if rail pressure is below an absolute value.	Rail pressure	< 0 to 13 MPa (see table **P0087 Minimum rail pressure**)	Run crank voltage Engine running, cranking excluded, for a time No IFT running (refer to FUL_IFT_St) No engine shut down request LowFuelConditionDiagnostic Fuel pressure estimated at high pressure pump inlet is valid Fuel pressure estimated at high pressure pump inlet No DTC active:	≥ 11.0 V >= 30.00 s = FALSE >= -110.00 kPa FuelPumpRlyCktFA P0091 P2294 P2296	125 failures out of 250 samples 6.25 ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Pressure Regulator 1 Performance	P0089	Determine when rail pressure is above maximum threshold when pressure is governed by Fuel Metering Unit valve.	Rail pressure	> 67 to 217 MPa (see table **P0089 Maximum rail pressure with MU**)	Run crank voltage Rail pressure is governed by Fuel Metering Unit (refer to *RailPresCntrl*)	≥ 11.0 V	160 failures out of 229 samples OR 160 continuous failures out of 229 samples 6.25 ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Pressure Regulator Solenoid 1 Control Circuit	P0090	Controller specific output driver circuit diagnoses the Fuel Metering Unit valve low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit: impedance between signal and controller ground	≥ 200 kΩ	Powertrain relay voltage Rail pressure is governed by Fuel Metering Unit (refer to *RailPresCntrl*) No active DTC since key is on: Powertrain relay voltage Run crank voltage Engine not cranking Metering Unit valve calibrated as present	≥ 11.0 V FHP_MU_DrvrCloseTFTKO FHP_MU_DrvrOpenTFTKO	45 failures out of 90 samples 6.25 ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Pressure Regulator Solenoid 1 Control Circuit Low Voltage	P0091	Controller specific output driver circuit diagnoses the Fuel Metering Unit valve low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground: impedance between signal and controller ground	≤ 0.5 Ω	Powertrain relay voltage Rail pressure is governed by Fuel Metering Unit (refer to *RailPresCntrl*) No active DTC since key is on:	≥ 11.0 V FHP_MU_DrvrCloseTFTKO FHP_MU_DrvrOpenTFTKO	45 failures out of 90 samples 6.25 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Pressure Regulator Solenoid 1 Control Circuit High Voltage	P0092	Controller specific output driver circuit diagnoses the Fuel Metering Unit valve low sided driver for a short to power failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power: impedance between signal and controller power	≤ 0.5 Ω	Powertrain relay voltage Rail pressure is governed by Fuel Metering Unit (refer to *RailPresCntrl*) No active DTC since key is on:	≥ 11.0 V FHP_MU_DrvrCloseTFTKO FHP_MU_DrvrOpenTFTKO	45 failures out of 90 samples 6.25 ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor 2 Circuit Performance (applications with IAT, IAT2 and IAT3)	P0096	Detects an Intake Air Temperature 2 (IAT2) sensor value that is stuck in range by comparing the IAT2 sensor value against the IAT and IAT3 sensor values and failing the diagnostic if the IAT2 value is more different than the IAT and IAT3 values than is expected. If the engine has been off for a long enough period of time, the air temperature values in the engine compartment of the vehicle are considered to have equalized, and the diagnostic can be enabled. The diagnostic will fail if the IAT and IAT3 values are similar, and the IAT2 value is not similar to the IAT and IAT3 values. The diagnostic will also fail if none of the three sensor values are similar to each other, and the IAT2 value is furthest from the sensor value that is in the middle of the three sensor values. This diagnostic is executed once per	**Good Correlation Between IAT and IAT3** ABS(Power Up IAT - Power Up IAT2) AND ABS(Power Up IAT - Power Up IAT3) AND ABS(Power Up IAT2 - Power Up IAT3)	 > 25 deg C <= 25 deg C > 25 deg C	Time between current ignition cycle and the last time the engine was running Powertrain Relay Voltage for a time No Active DTCs:	 > 28,800 seconds >= 11.0 Volts >= 0.9 seconds PowertrainRelayFault ECT_Sensor_Ckt_FA IAT_SensorCircuitFA MnfdTempSensorCktFA HumTempSnsrCktFA EngineModeNotRunTimer Error	Executes once at the beginning of each ignition cycle if enable conditions are met	Type B, 2 Trips
			Not Good Correlation, IAT in Middle Power Up IAT is between Power Up IAT2 and Power Up IAT3 AND ABS(Power Up IAT2 - Power Up IAT3) AND ABS(Power Up IAT - Power Up IAT2) > ABS(Power Up IAT - Power Up IAT3)	 > 25 deg C	Time between current ignition cycle and the last time the engine was running Powertrain Relay Voltage for a time No Active DTCs:	 > 28,800 seconds >= 11.0 Volts >= 0.9 seconds PowertrainRelayFault ECT_Sensor_Ckt_FA IAT_SensorCircuitFA MnfdTempSensorCktFA HumTempSnsrCktFA EngineModeNotRunTimer Error	Executes once at the beginning of each ignition cycle if enable conditions are met	
			Not Good Correlation, IAT3 in Middle Power Up IAT3 is between Power Up IAT and Power Up IAT2		Time between current ignition cycle and the last time the engine was running Powertrain Relay Voltage for a time	 > 28,800 seconds >= 11.0 Volts >= 0.9 seconds	Executes once at the beginning of each ignition cycle if enable conditions are met	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		ignition cycle if the enable conditions are met.	AND ABS(Power Up IAT - Power Up IAT2) AND ABS(Power Up IAT3 - Power Up IAT2) > ABS(Power Up IAT3 - Power Up IAT)	> 25 deg C	No Active DTCs:	PowertrainRelayFault ECT_Sensor_Ckt_FA IAT_SensorCircuitFA MnfdTempSensorCktFA HumTempSnsrCktFA EngineModeNotRunTimer Error		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor Circuit 2 Low	P0097	Detects a continuous short to ground in the Intake Air Temperature 2 (IAT2) signal circuit or an IAT2 sensor that is outputting a frequency signal that is too low. The diagnostic monitors the IAT2 sensor output frequency and fails the diagnostic when the IAT2 frequency is too low. The IAT2 sensor is a thermistor in which the resistance across the sensor can be equated to a temperature. The temperature value is converted by the sensor to a frequency value in Hertz. A digital square wave signal is transmitted by the sensor to the ECM. The ECM calculates the frequency of the square wave signal and converts that frequency to a temperature value. A lower frequency is equivalent to a lower temperature. This diagnostic is enabled if the Powertrain Relay voltage is high enough.	Raw IAT 2 Input	< 13 Hertz (~-60 deg C)	Powertrain Relay Voltage for a time No Active DTCs:	>= 11.0 Volts >= 0.9 seconds PowertrainRelayFault	40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor Circuit 2 High	P0098	Detects an Intake Air Temperature 2 (IAT2) sensor that is outputting a frequency signal that is too high. The diagnostic monitors the IAT2 sensor output frequency and fails the diagnostic when the IAT2 frequency is too high. The IAT2 sensor is a thermistor in which the resistance across the sensor can be equated to a temperature. The temperature value is converted by the sensor to a frequency value in Hertz. A digital square wave signal is transmitted by the sensor to the ECM. The ECM calculates the frequency of the square wave signal and converts that frequency to a temperature value. A higher frequency is equivalent to a higher temperature. This diagnostic is enabled if the Powertrain Relay voltage is high enough.	Raw IAT 2 Input	> 390 Hertz (~150 deg C)	Powertrain Relay Voltage for a time No Active DTCs:	>= 11.0 Volts >= 0.9 seconds PowertrainRelayFault	40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor 2 Intermittent In-Range	P0099	Detects a noisy or erratic signal in the Intake Air Temperature 2 (IAT2) circuit by monitoring the IAT2 sensor and failing the diagnostic when the IAT2 signal has a noisier output than is expected. When the value of the IAT2 signal in °C is determined, a delta is calculated between the current reading and the previous reading. The absolute value of these deltas is summed over a number of IAT2 readings. The result of this summation is called a “string length”. Since the IAT2 signal is anticipated to be relatively smooth, a string length of a particular magnitude indicates a noisy or erratic IAT2 signal. The diagnostic will fail if the string length is too high. This diagnostic is enabled if the Powertrain Relay voltage is high enough.	String Length Where: "String Length" = sum of "Diff" calculated over And where: "Diff" = ABS(current IAT 2 reading - IAT 2 reading from 100 milliseconds previous)	> 80.00 deg C 10 consecutive IAT 2 readings	Powertrain Relay Voltage for a time No Active DTCs:	>= 11.0 Volts >= 0.9 seconds PowertrainRelayFault	4 failures out of 5 samples Each sample takes 1.0 seconds	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Multiple Pressure Sensor Correlation Performance (3 intake air pressure sensor configuration)	P00C7	This monitor is used to identify if BARO, MAP and TCIAP pressure values are irrational when compared to each other. The plausibility monitor compares the BARO, MAP and TCIAP pressures in two different conditions: - at idle (part of the test enabled when the engine is running) - between key off and when the engine starts running (part of the test enabled when the engine is not running). If the three sensors are not in agreement the monitor is not able to pinpoint the sensor(s) that is/are not working correctly and therefore indicates that there is a fault that impacts the three sensors.	Difference (absolute value) in measured pressure between BARO sensor and TCIAP sensor AND Difference (absolute value) in measured pressure between BARO sensor and MAP sensor AND Difference (absolute value) in measured pressure between TCIAP sensor and MAP sensor	> **P0106, P2227, P227B, P00C7: Maximum pressure difference** [kPa] > **P0106, P2227, P227B, P00C7: Maximum pressure difference** [kPa] > **P0106, P2227, P227B, P00C7: Maximum pressure difference** [kPa]	Correlation diagnostic enabled by calibration Engine is running Run Crankrelay supply voltage in range Engine speed Requested fuel Throttle measured position Engine Coolant Temperature No faults are present	== 0.00 > 11.00 [V] < 1.00 [rpm] < 1.00 [mm^3] > 100.00 [%] > 200.00 [°C] CrankSensor_FA ==FALSE FUL_GenericInjSysFA ==FALSE TPS_PstnSnsrFA ==FALSE MAP_SensorCircuitFA ==FALSE AAP2_SnsrCktFA ==FALSE AAP_AAP5_SnsrCktFA ==FALSE AAP_AAP2_SnsrStabFA ==FALSE AAP_AAP5_SnsrStabFA ==FALSE ECT_Sensor_FA	500.00 fail counters over 400.00 sample counters sampling time is 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						==FALSE MAF_MAF_SnsrFA ==FALSE		
			Difference (absolute value) in measured pressure between MAP sensor and BARO sensor AND Difference (absolute value) in measured pressure between TCIAP sensor and MAP sensor AND Difference (absolute value) in measured pressure between TCIAP sensor and BARO sensor OR Difference (absolute value) in measured pressure between MAP sensor and BARO sensor AND Difference (absolute value) in measured pressure between TCIAP sensor and MAP sensor AND Difference (absolute value) in measured pressure between TCIAP sensor and BARO sensor OR Difference (absolute value) in measured pressure between MAP sensor and BARO sensor	> 10.0 [kPa] <= 10.0 [kPa] <= 10.0 [kPa] <= 10.0 [kPa] > 10.0 [kPa] <= 10.0 [kPa] <= 10.0 [kPa]	Time between current ignition cycle and the last time the engine was running Engine is not rotating Manifold Pressure Manifold Pressure Baro Pressure Baro Pressure TCIAP Pressure TCIAP Pressure No Active DTCs: No Pending DTCs:	> 10.0 [s] >= 50.0 [kPa] <= 115.0 [kPa] >= 50.0 [kPa] <= 115.0 [kPa] >= 50.0 [kPa] <= 115.0 [kPa] EngineModeNotRunTimer Error MAP_SensorFA AAP_SnsrFA AAP2_SnsrFA MAP_SensorCircuitFP AAP_SnsrCktFP AAP2_SnsrCktFP	4 fail counters over 5 sample counters sampling time is 12.5 ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			AND Difference (absolute value) in measured pressure between TCIAP sensor and MAP sensor AND Difference (absolute value) in measured pressure between TCIAP sensor and BARO sensor OR Difference (absolute value) in measured pressure between MAP sensor and BARO sensor AND Difference (absolute value) in measured pressure between TCIAP sensor and MAP sensor AND Difference (absolute value) in measured pressure between TCIAP sensor and BARO sensor	<= 10.0 [kPa] > 10.0 [kPa] > 10.0 [kPa] > 10.0 [kPa] > 10.0 [kPa]				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor 3 Circuit Performance	P00E9	Detects an Intake Air Temperature 3 (IAT3) sensor value that is stuck in range by comparing the IAT3 sensor value against the IAT and IAT2 sensor values and failing the diagnostic if the IAT3 value is more different than the IAT and IAT2 values than is expected. If the engine has been off for a long enough period of time, the air temperature values in the engine compartment of the vehicle are considered to have equalized, and the diagnostic can be enabled. The diagnostic will fail if the IAT and IAT2 values are similar, and the IAT3 value is not similar to the IAT and IAT2 values. The diagnostic will also fail if none of the three sensor values are similar to each other, and the IAT3 value is furthest from the sensor value that is in the middle of the three sensor values. This diagnostic is executed once per	**Good Correlation Between IAT and IAT2** ABS(Power Up IAT - Power Up IAT2) AND ABS(Power Up IAT - Power Up IAT3) AND ABS(Power Up IAT2 - Power Up IAT3)	<= 25 deg C > 25 deg C > 25 deg C	Time between current ignition cycle and the last time the engine was running Powertrain Relay Voltage for a time No Active DTCs:	> 28,800 seconds >= 11.0 Volts >= 0.9 seconds PowertrainRelayFault ECT_Sensor_Ckt_FA IAT_SensorCircuitFA MnfdTempSensorCktFA HumTempSnsrCktFA EngineModeNotRunTimerError	Executes once at the beginning of each ignition cycle if enable conditions are met	Type A, 1 Trips
			Not Good Correlation, IAT in Middle Power Up IAT is between Power Up IAT2 and Power Up IAT3 AND ABS(Power Up IAT2 - Power Up IAT3) AND ABS(Power Up IAT - Power Up IAT3) > ABS(Power Up IAT - Power Up IAT2)	> 25 deg C	Time between current ignition cycle and the last time the engine was running Powertrain Relay Voltage for a time No Active DTCs:	> 28,800 seconds >= 11.0 Volts >= 0.9 seconds PowertrainRelayFault ECT_Sensor_Ckt_FA IAT_SensorCircuitFA MnfdTempSensorCktFA HumTempSnsrCktFA EngineModeNotRunTimerError	Executes once at the beginning of each ignition cycle if enable conditions are met	
			Not Good Correlation, IAT2 in Middle Power Up IAT2 is between Power Up IAT and Power Up IAT3		Time between current ignition cycle and the last time the engine was running Powertrain Relay Voltage for a time	> 28,800 seconds >= 11.0 Volts >= 0.9 seconds	Executes once at the beginning of each ignition cycle if enable conditions are met	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		ignition cycle if the enable conditions are met.	AND ABS(Power Up IAT - Power Up IAT3) AND ABS(Power Up IAT2 - Power Up IAT3) > ABS(Power Up IAT2 - Power Up IAT)	> 25 deg C	No Active DTCs:	PowertrainRelayFault ECT_Sensor_Ckt_FA IAT_SensorCircuitFA MnfdTempSensorCktFA HumTempSnsrCktFA EngineModeNotRunTimer Error		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor Circuit 3 Low	P00EA	Detects a continuous short to ground in the Intake Air Temperature 3 (IAT3) signal circuit by monitoring the IAT3 sensor output resistance and failing the diagnostic when the IAT3 resistance is too low. The IAT3 sensor is a thermistor in which the resistance across the sensor can be equated to a temperature. A lower resistance is equivalent to a higher temperature.	Raw IAT 3 Input	< 56.42 Ohms (~150 deg C)	Engine Run Time	> 0.00 seconds	40 failures out of 50 samples 1 sample every 100 msec	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor Circuit 3 High	P00EB	Detects a continuous open circuit in the Intake Air Temperature 3 (IAT3) signal circuit by monitoring the IAT3 sensor output resistance and failing the diagnostic when the IAT3 resistance is too high. The IAT3 sensor is a thermistor in which the resistance across the sensor can be equated to a temperature. A higher resistance is equivalent to a lower temperature.	Raw IAT 3 Input	> 151,542 Ohms (~-60 deg C)	Engine Run Time	> 0.00 seconds	40 failures out of 50 samples 1 sample every 100 msec	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor 3 Intermittent In-Range	P00EC	Detects a noisy or erratic signal in the Intake Air Temperature 3 (IAT3) circuit by monitoring the IAT3 sensor and failing the diagnostic when the IAT3 signal has a noisier output than is expected. When the value of the IAT3 signal in °C is determined, a delta is calculated between the current reading and the previous reading. The absolute value of these deltas is summed over a number of IAT3 readings. The result of this summation is called a “string length”. Since the IAT3 signal is anticipated to be relatively smooth, a string length of a particular magnitude indicates a noisy or erratic IAT3 signal. The diagnostic will fail if the string length is too high.	String Length Where: "String Length" = sum of "Diff" calculated over And where: "Diff" = ABS(current IAT 3 reading - IAT 3 reading from 100 milliseconds previous)	> 80.00 deg C 10 consecutive IAT 3 readings	Continuous		4 failures out of 5 samples Each sample takes 1.0 seconds	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Humidity Sensor Circuit Low	P00F4	Detects a continuous short to ground in the humidity signal circuit or a humidity sensor that is outputting a duty cycle that is too low. The diagnostic monitors the humidity sensor duty cycle output and fails the diagnostic when the humidity duty cycle is too low. The humidity sensor converts the capacitance across the sensor to a relative humidity. The relative humidity value is converted by the sensor to a duty cycle value in %. A digital square wave signal is transmitted by the sensor to the ECM. The ECM calculates the duty cycle of the square wave signal and converts that duty cycle to a relative humidity value in % through a transfer function. This diagnostic is enabled if the Powertrain Relay voltage is high enough.	Humidity Duty Cycle	<= 5.0 %	Powertrain Relay Voltage for a time No Active DTCs:	>= 11.0 Volts >= 0.9 seconds PowertrainRelayFault	40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Humidity Sensor Circuit High	P00F5	Detects a humidity sensor that is outputting a duty cycle signal that is too high. The diagnostic monitors the humidity sensor duty cycle output and fails the diagnostic when the humidity duty cycle is too high. The humidity sensor converts the capacitance across the sensor to a relative humidity. The relative humidity value is converted by the sensor to a duty cycle value in %. A digital square wave signal is transmitted by the sensor to the ECM. The ECM calculates the duty cycle of the square wave signal and converts that duty cycle to a relative humidity value in % through a transfer function. This diagnostic is enabled if the Powertrain Relay voltage is high enough.	Humidity Duty Cycle	>= 95.0 %	Powertrain Relay Voltage for a time No Active DTCs:	>= 11.0 Volts >= 0.9 seconds PowertrainRelayFault	40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Humidity Sensor Circuit Intermittent	P00F6	Detects a noisy or erratic signal in the humidity circuit by monitoring the humidity sensor and failing the diagnostic when the humidity signal has a noisier output than is expected. When the value of relative humidity in % is determined, a delta is calculated between the current reading and the previous reading. The absolute value of these deltas is summed over a number of humidity readings. The result of this summation is called a “string length”. Since the humidity signal is anticipated to be relatively smooth, a string length of a particular magnitude indicates a noisy or erratic humidity signal. The diagnostic will fail if the string length is too high. This diagnostic is enabled if the Powertrain Relay voltage is high enough.	String Length Where: "String Length" = sum of "Diff" calculated over And where: "Diff" = ABS(current Humidity reading - Humidity reading from 100 milliseconds previous)	> 80 % 10 consecutive Humidity readings	Powertrain Relay Voltage for a time No Active DTCs:	>= 11.0 Volts >= 0.9 seconds PowertrainRelayFault	4 failures out of 5 samples Each sample takes 1.0 seconds	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Manifold Absolute Pressure (MAP) Sensor Performance (3 intake air pressure sensor configuration)	P0106	This monitor is used to identify MAP sensor internal faults (measurement with an offset or a drift). The plausibility monitor compares the BARO, MAP and TCIAP pressures in two different conditions: - at idle (part of the test enabled when the engine is running) - between key off and when the engine starts running (part of the test enabled when the engine is not running). If MAP sensor is not in agreement with the other two the monitor is able to pinpoint MAP as the faulty sensor.	Difference (absolute value) in measured pressure between MAP sensor and TCIAP sensor AND Difference (absolute value) in measured pressure between MAP sensor and BARO sensor AND Difference (absolute value) in measured pressure between BARO sensor and TCIAP sensor	> **P0106, P2227, P227B, P00C7: Maximum pressure difference** [kPa] > **P0106, P2227, P227B, P00C7: Maximum pressure difference** [kPa] <= **P0106, P2227, P227B, P00C7: Maximum pressure difference** [kPa]	Correlation diagnostic enabled by calibration Engine is running Run Crankrelay supply voltage in range Engine speed Requested fuel Throttle measured position Engine Coolant Temperature No faults are present	== 0.00 > 11.00 [V] < 1.00 [rpm] < 1.00 [mm^3] > 100.00 [%] > 200.00 [°C] CrankSensor_FA ==FALSE FUL_GenericInjSysFA ==FALSE TPS_PstnSnsrFA ==FALSE MAP_SensorCircuitFA ==FALSE AAP2_SnsrCktFA ==FALSE AAP_AAP5_SnsrCktFA ==FALSE AAP_AAP2_SnsrStabFA ==FALSE AAP_AAP5_SnsrStabFA ==FALSE ECT_Sensor_FA	500.00 fail counters over 400.00 sample counters sampling time is 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						==FALSE MAF_MAF_SnsrFA ==FALSE		
			MAP sensor OR MAP sensor OR Difference (absolute value) in measured pressure between MAP sensor and TCIAP sensor AND Difference (absolute value) in measured pressure between MAP sensor and BARO sensor AND Difference (absolute value) in measured pressure between BARO sensor and TCIAP sensor	< 50.0 [kPa] > 115.0 [kPa] > 10.0 [kPa] > 10.0 [kPa] <= 10.0 [kPa]	Time between current ignition cycle and the last time the engine was running Engine is not rotating No Active DTCs: No Pending DTCs:	> 10.0 [s] EngineModeNotRunTimer Error MAP_SensorCircuitFA AAP_SnsrCktFA MAP_SensorCircuitFP AAP_SnsrCktFP	4 fail counters over 5 sample counters sampling time is 12.5 ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Manifold Absolute Pressure Sensor Circuit Low (with pull-up)	P0107	Detects a continuous short to ground in the Manifold Absolute Pressure (MAP) signal circuit by monitoring the MAP sensor output voltage and failing the diagnostic when the MAP voltage is too low. The MAP sensor is a pressure transducer which outputs a voltage proportional to the absolute pressure.	MAP Voltage	< 3.0 % of 5 Volt Range (This is equal to 10.1 kPa)	Continuous		320 failures out of 400 samples 1 sample every 12.5 msec	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Manifold Absolute Pressure Sensor Circuit High (with pull-up)	P0108	Detects a continuous short to power or open circuit in the Manifold Absolute Pressure (MAP) signal circuit by monitoring the MAP sensor output voltage and failing the diagnostic when the MAP voltage is too high. The MAP sensor is a pressure transducer which outputs a voltage proportional to the absolute pressure.	MAP Voltage	> 97.0 % of 5 Volt Range (This is equal to 313.2 kPa)	Continuous		320 failures out of 400 samples 1 sample every 12.5 msec	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor Circuit Performance (applications with IAT, IAT2 and IAT3)	P0111	Detects an Intake Air Temperature (IAT) sensor value that is stuck in range by comparing the IAT sensor value against the IAT2 and IAT3 sensor values and failing the diagnostic if the IAT value is more different than the IAT2 and IAT3 values than is expected. If the engine has been off for a long enough period of time, the air temperature values in the engine compartment of the vehicle are considered to have equalized, and the diagnostic can be enabled. The diagnostic will fail if the IAT2 and IAT3 values are similar, and the IAT value is not similar to the IAT2 and IAT3 values. The diagnostic will also fail if none of the three sensor values are similar to each other, and the IAT value is furthest from the sensor value that is in the middle of the three sensor values. This diagnostic is executed once per	**Good Correlation Between IAT2 and IAT3** ABS(Power Up IAT - Power Up IAT2) AND ABS(Power Up IAT - Power Up IAT3) AND ABS(Power Up IAT2 - Power Up IAT3)	 > 25 deg C > 25 deg C <= 25 deg C	Time between current ignition cycle and the last time the engine was running Powertrain Relay Voltage for a time No Active DTCs:	 > 28,800 seconds >= 11.0 Volts >= 0.9 seconds PowertrainRelayFault ECT_Sensor_Ckt_FA IAT_SensorCircuitFA MnfdTempSensorCktFA HumTempSnsrCktFA EngineModeNotRunTimer Error	Executes once at the beginning of each ignition cycle if enable conditions are met	Type B, 2 Trips
			Not Good Correlation, IAT2 in Middle Power Up IAT2 is between Power Up IAT and Power Up IAT3 AND ABS(Power Up IAT - Power Up IAT3) AND ABS(Power Up IAT2 - Power Up IAT) > ABS(Power Up IAT2 - Power Up IAT3)	 > 25 deg C	Time between current ignition cycle and the last time the engine was running Powertrain Relay Voltage for a time No Active DTCs:	 > 28,800 seconds >= 11.0 Volts >= 0.9 seconds PowertrainRelayFault ECT_Sensor_Ckt_FA IAT_SensorCircuitFA MnfdTempSensorCktFA HumTempSnsrCktFA EngineModeNotRunTimer Error	Executes once at the beginning of each ignition cycle if enable conditions are met	
			Not Good Correlation, IAT3 in Middle Power Up IAT3 is between Power Up IAT and Power Up IAT2		Time between current ignition cycle and the last time the engine was running Powertrain Relay Voltage for a time	 > 28,800 seconds >= 11.0 Volts >= 0.9 seconds	Executes once at the beginning of each ignition cycle if enable conditions are met	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		ignition cycle if the enable conditions are met.	AND ABS(Power Up IAT - Power Up IAT2) AND ABS(Power Up IAT3 - Power Up IAT) > ABS(Power Up IAT3 - Power Up IAT2)	> 25 deg C	No Active DTCs:	PowertrainRelayFault ECT_Sensor_Ckt_FA IAT_SensorCircuitFA MnfdTempSensorCktFA HumTempSnsrCktFA EngineModeNotRunTimer Error		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor Circuit Low	P0112	Detects a continuous short to ground in the Intake Air Temperature (IAT) signal circuit by monitoring the IAT sensor output resistance and failing the diagnostic when the IAT resistance is too low. The IAT sensor is a thermistor in which the resistance across the sensor can be equated to a temperature. A lower resistance is equivalent to a higher temperature.	Raw IAT Input	< 58.00 Ohms (~150 deg C)	Engine Run Time	> 0.00 seconds	40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor Circuit High	P0113	Detects a continuous open circuit in the Intake Air Temperature (IAT) signal circuit by monitoring the IAT sensor output resistance and failing the diagnostic when the IAT resistance is too high. The IAT sensor is a thermistor in which the resistance across the sensor can be equated to a temperature. A higher resistance is equivalent to a lower temperature.	Raw IAT Input	> 142,438 Ohms (~-60 deg C)	Engine Run Time	> 0.00 seconds	40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor Intermittent In-Range	P0114	Detects a noisy or erratic signal in the Intake Air Temperature (IAT) circuit by monitoring the IAT sensor and failing the diagnostic when the IAT signal has a noisier output than is expected. When the value of the IAT signal in °C is determined, a delta is calculated between the current reading and the previous reading. The absolute value of these deltas is summed over a number of IAT readings. The result of this summation is called a “string length”. Since the IAT signal is anticipated to be relatively smooth, a string length of a particular magnitude indicates a noisy or erratic IAT signal. The diagnostic will fail if the string length is too high.	String Length Where: "String Length" = sum of "Diff" calculated over And where: "Diff" = ABS(current IAT reading - IAT reading from 100 milliseconds previous)	> 80.00 deg C 10 consecutive IAT readings	Continuous		4 failures out of 5 samples Each sample takes 1.0 seconds	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Coolant Temp Sensor Circuit Low	P0117	Circuit Continuity This DTC detects a short to ground in the ECT (Engine Coolant temperature) signal circuit or the ECT sensor. This is accomplished by monitoring the resistance of the circuit. If the resistance goes out of the expected range the DTC is set.	ECT Resistance (@ 150ºC)	< 52 Ohms			5 failures out of 6 samples 1 sec/ sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Coolant Temp Sensor Circuit High	P0118	Circuit Continuity This DTC detects a short to high or open in the ECT (Engine Coolant temperature) signal circuit or the ECT sensor. This is accomplished by monitoring the resistance of the circuit. If the resistance goes out of the expected range the DTC is set.	ECT Resistance (@ -60ºC)	> 139,500 Ohms	Engine run time OR IAT min	> 10.0 seconds ≥ -9.0 °C	5 failures out of 6 samples 1 sec/ sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Coolant Temperature (ECT) Sensor Circuit Intermittent	P0119	Circuit Erratic This DTC detects large step changes in the ECT (Engine Coolant temperature) signal circuit or the ECT sensor. Allowable high and low limits are calculated for the next sample based on the previous sample and sensor time constant. If the sensor responds faster than should be possible the DTC is set.	ECT temperature step change: 1) postive step change is greater than calculated high limit OR 2) negitive step change is lower than calculated low limit. The calculated high and low limits for the next reading use the following calibrations: 1) Sensor time constant 2) Sensor low limit 3) Sensor high limit *****Generic Example***** If the last ECT reading was 90 Deg C, the Time constant was calibrated at 10 seconds, the low limit was calibrated to -80 Deg C and the high limit was calibrated to 200 Deg C the caluculated limits are 101 Deg C and 73 Deg C. The next reading (after the 90 Deg C reading) must be between 73 Deg C and 101 Deg C to be valid. **********	 7.4 seconds -60.0 Deg C 200.0 Deg C	No Active DTC's	ECT_Sensor_Ckt_FP	3 failures out of 4 samples 1 sec/ sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Coolant Temperature Below Stat Regulating Temperature	P0128	This DTC detects if the ECT (EngineCoolant temperature) does not achieve the required target temperature after an allowed energy accumulation by the engine. This can be caused by an ECT sensor biased low or a cooling system that is not warming up correctly because of a stuck open thermostat or other fault.	Energy is accumulated after the first conbustion event using Range #1 or #2 below: Thermostat type is divided into normal (non-heated) and electrically heated. For this application the "type" cal (KeTHMG_b_TMS_ElecThstEquipped) = 0 If the type cal is equal to one, the application has an electrically heated t-stat, if equal to zero the the application has an non heated t-stat. See appropiate section below. ********** Type cal above = 1 (Electrically heated t-stat) == == == == Range #1 (Primary) ECT reaches Commanded temperature minus 19 °C when Ambient min is ≤ 52 °C and > 10 °C. Note: Warm up target for range #1 will be at least 69 °C == == == == Range #2 (Alternate) ECT reaches Commanded temperature minus 50 °C when Ambient min is ≤ 10 °C and > -9 °C. Note: Warm up target for range #2 will be at least	See the two tables named: **P0128_Maximum Accumulated Energy for Start-up ECT conditions - Primary** and **P0128_Maximum Accumulated Energy for Start-up ECT conditions - Alternate** in the Supporting tables section. This diagnostic models the net energy into and out of the cooling	No Active DTC's Engine not run time (soaking time before current trip) Engine run time Fuel Condition Distance traveled ********** If Engine RPM is continuously greater than for this time period The diagnostic test for this key cycle will abort ********** ********** If T-Stat Heater commanded duty cycle for this time period	ECT_Sensor_Ckt_FA ECT_Sensor_Perf_FA VehicleSpeedSensor_FA OAT_PtEstFiltFA IAT_SensorCircuitFA MAF_SensorFA THMR_AWP_AuxPumpFA THMR_AHV_FA THMR_SWP_Control_FA THMR_SWP_NoFlow_FA THMR_SWP_FlowStuckOn_FA EngineTorqueEstInaccurate ≥ 1,800 seconds 20 ≤ Eng Run Tme ≤ 1,450 seconds Ethanol ≤ 87 % ≥ 0.50 miles ********** 9,999 rpm 5.0 seconds ********** ********** > 20.0 % duty cycle > 5.0 seconds	1 failure to set DTC 1 sec/ sample Once per ignition key cycle	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			55 °C ********** Type cal above = 0 (non - heated t-stat) == == == == Range #1 (Primary) ECT reaches 69 °C when Ambient min is ≤ 52 °C and > 10 °C. == == == == Range #2 (Alternate) ECT reaches 55 °C when Ambient min is ≤ 10 °C and > -9 °C. **********	system during the warm-up process. The five energy terms are: heat from combustion (with AFM correction), heat from after-run, heat loss to enviroment, heat loss to cabin and heat loss to DFCO.	The diagnostic test for this key cycle will abort ********** ECT at start run	 ********** -40 ≤ ECT ≤ 50 °C		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Temperature Sensor A Performance (FTS wired to ECM)	P0181	Determine when fuel temperature sensor is not plausible, due to offset or drift.	Averaged for absolute difference between fuel temperature and reference temperature is IF fuel fired heater has been used ELSE (see **P0181 Fuel Temperature Sensor Reference**)	>= 20.00 °C >= 20.00 °C	A time and is passed since engine movement is detected Engine soak time No error for Engine Not Running timer The use of the fuel fired heater strategy has been recoognized No DTC active: (Engine coolant temperature OR ECT_OBD_GlobalCoolTmpEnbl (refer to "*OBD Coolant Enable Criteria*" section)) At least one valid value received from serial communication	> 1 s ≤ 6.00 s > 28,800 s FTS_FTS_CktFA FTS_PlausRefSnsrFlt > -40 °C = TRUE	45 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Temperature Sensor A Circuit Low (FTS wired to ECM)	P0182	Determine when a short circuit to ground affects fuel temperature sensor.	Fuel temperature sensor output resistance	< 50 Ω	Run crank voltage Run crank voltage Engine not cranking At least one valid value received from serial communication	> 6.0 V ≥ 11.0 V	10 failures out of 20 samples 100 ms/samples	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Temperature Sensor A Circuit High (FTS wired to ECM)	P0183	Determine when a short circuit to ground affects fuel temperature sensor.	Fuel temperature sensor output resistance	> 121,865 Ω	Run crank voltage Run crank voltage Engine not cranking At least one valid value received from serial communication	> 6.0 V ≥ 11.0 V	10 failures out of 20 samples 100 ms/samples	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Temperature Sensor A Circuit Intermittent (FTS wired to ECM)	P0184	Determine when fuel temperature sensor changes quicker than expected, likely due to an intermittent fault.	Fuel temperature	> (1 - α) * 156 °C + (Last good sample * α) with α = e^[- (amount of consecutive bad samples * 0.01)]	Run crank voltage Run crank voltage At least one valid value received from serial communication No active DTC:	> 6.0 V ≥ 11.0 V FTS_FTS_CktFA	10 failures out of 15 samples 100 ms/samples	Type B, 2 Trips
			Fuel temperature	< (1 - α) * -56 °C + (Last good sample * α) with α = e^[- (amount of consecutive bad samples * 0.01)]	Run crank voltage Run crank voltage At least one valid value received from serial communication No active DTC:	> 6.0 V ≥ 11.0 V FTS_FTS_CktFA	10 failures out of 15 samples 100 ms/samples	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Rail Pressure (FRP) Sensor A Performance	P0191	Determine when fuel rail pressure sensor is not plausible, due to offset or drift.	Rail pressure sensor output (as percentage of supply voltage) OR Rail pressure sensor output (as percentage of supply voltage)	> 14.0 % < 6.5 %	Engine off time No error for Engine Not Running timer No engine movement detected since begin of driving cycle (Engine coolant temperature OR ECT_OBD_GlobalCoolTmpEnbl (refer to "*OBD Coolant Enable Criteria*" section)) Run crank voltage Run crank voltage No active DTC:	≥ 300 s ≥ -40 °C = TRUE > 6.0 V ≥ 11.0 V ECT_Sensor_FA FHP_RPS_CktFA	30 failures out of 60 samples 6.25 ms/sample	Type A, 1 Trips
			Absolute difference between rail pressure #1 (first trace) and rail pressure #2 (second trace)	> 21.0 MPa	**P0191 Rail Pressure Sensor Configuration** Starter motor is not engaged OR Starter motor has been engaged for a time OR Run crank voltage	= CeFHPG_e_RPS_DoubleTrack ≥ 15 s > 8.4 V	20 failures out of 30 samples 6.25 ms/sample	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No active DTC:	FHP_RPS_CktFA FHP_RPS2_CktFA P0194		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Rail Pressure (FRP) Sensor A Circuit Low Voltage	P0192	Determine when a short circuit to ground affects fuel rail pressure sensor.	Fuel rail pressure sensor output (as percentage of supply voltage)	< 4.0 %	Starter motor is not engaged OR Starter motor has been engaged for a time OR Run crank voltage	 ≥ 15 s > 8.4 V	38 failures out of 76 samples OR 22 continuous failures out of 76 samples 6.25 ms/samples	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Rail Pressure (FRP) Sensor A Circuit High Voltage	P0193	Determine when a short circuit to voltage affects fuel rail pressure sensor.	Fuel rail pressure sensor output (as percentage of supply voltage)	> 94.8 %	Starter motor is not engaged OR Starter motor has been engaged for a time OR Run crank voltage	 ≥ 15 s > 8.4 V	38 failures out of 76 samples OR 22 continuous failures out of 76 samples 6.25 ms/samples	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Coolant Temperature Dropped Below Diagnostic Monitoring Temperature	P01F0	This DTC detects an unexplained cooling system cool down below the OBD monitoring threshold during normal operating conditions. This check is run throughout the key cycle.	For this application the "type" cal (KeTHMG_b_TMS_ElecThstEquipped) = 0 If the type cal is equal to one, the application has an electrically heated t-stat, if equal to zero the the application has an non heated t-stat. See appropiate section below. ********** Type cal above = 0 (non - heated t-stat) == == == == Engine coolant temperature ********** Type cal above = 1 (Electrically heated t-stat) == == == == Engine coolant temperature	 ≤ 68.0 Deg C ≤ 70.5 Deg C	No Active DTC's Engine Runtime Distance traveled this key cycle Ambient air pressure Ambient air temperature ********** Engine coolant temperature At least once during the key cycle Type 0 (non-heated t-stat) Type 1 (Electrically heated T-stat) ********** Heat to coolant DFCO time Thermostat duty cycle RPM Active Fuel Management is not in	ECT_Sensor_Ckt_FA VehicleSpeedSensor_FA OAT_PtEstFiltFA THMR_AWP_AuxPumpFA THMR_AHV_FA THMR_SWP_Control_FA EngineTorqueEstInaccurate ECT_Sensor_Perf_FA THMR_SWP_NoFlow_FA THMR_SWP_FlowStuckOn_FA ≥ 30.0 seconds ≥ 1.2 km ≥ 55.0 kPa ≥ -9.0 Deg C ≥ 69 Deg C ≥ 71.5 to 86.5 Deg C **Cool Down Diagnostic** ≥ **Min Heat to Coolant** ≤ 2.0 seconds ≤ 100.0 % ≤ 8,192 Half Cylinder Mode	30 seconds out of a 60 seconds window Continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 1 Open Circuit	P0201	This DTC checks the Injector 1 circuit for electrical integrity during operation.	Low current through the low side driver during operation indicates open circuit	Open circuit: circuit attached to the Controller external connections has an impedance >= 200 K Ohm	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderA and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderA	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] == TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 2 Open Circuit	P0202	This DTC checks the Injector 2 circuit for electrical integrity during operation.	Low current through the low side driver during operation indicates open circuit	Open circuit: circuit attached to the Controller external connections has an impedance >= 200 K Ohm	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderB and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderB	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] ==TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 3 Open Circuit	P0203	This DTC checks the Injector 3 circuit for electrical integrity during operation.	Low current through the low side driver during operation indicates open circuit	Open circuit: circuit attached to the Controller external connections has an impedance >= 200 K Ohm	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderH and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderH	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] ==TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 4 Open Circuit	P0204	This DTC checks the Injector 4 circuit for electrical integrity during operation.	Low current through the low side driver during operation indicates open circuit	Open circuit: circuit attached to the Controller external connections has an impedance >= 200 K Ohm	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderE and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderE	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] == TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 1 Injection Timing	P020A	This DTC detects an Injector fault or ECU fault that causes pull In period of the current pulse out of range on injector 1 The pull in period is the time for the injection current to rise to the current level (20.00 [A]) at the beginning of the pulse	Measurement of the Pull In period of the current pulse of the injector 1 provided by HWIO	< 0.00 [us] OR > 130.00 [us]	Test enabled by calibration; and Battery voltage and Key ON and No active DTC's: and At least one injection pulse is requested by the application software; (FUL_FuelInjectedCyl_CiEPSR_CylinderA and No information of dropped pulse reported by HWIO	== 1 [Boolean] > 11.00 [V] - FUL_InjCktTFTKO FUL_CntrlrStTFTKO FUL_BoostVoltTFTKO == TRUE); -	10 failures out of 20 samples 1 sample every engine cycle Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 2 Injection Timing	P020B	This DTC detects an Injector fault or ECU fault that causes pull In period of the current pulse out of range on injector 2 The pull in period is the time for the injection current to rise to the current level (20.00 [A]) at the beginning of the pulse	Measurement of the Pull In period of the current pulse of the injector 2 provided by HWIO	< 0.00 [us] OR > 130.00 [us]	Test enabled by calibration; and Battery voltage and Key ON and No active DTC's: and At least one injection pulse is requested by the application software; (FUL_FuelInjectedCyl_CiEPSR_CylinderB and No information of dropped pulse reported by HWIO	== 1 [Boolean] > 11.00 [V] - FUL_InjCktTFTKO FUL_CntrlrStTFTKO FUL_BoostVoltTFTKO == TRUE); -	10 failures out of 20 samples 1 sample every engine cycle Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 3 Injection Timing	P020C	This DTC detects an Injector fault or ECU fault that causes pull In period of the current pulse out of range on injector 3 The pull in period is the time for the injection current to rise to the current level (20.00 [A]) at the beginning of the pulse	Measurement of the Pull In period of the current pulse of the injector 3 provided by HWIO	< 0.00 [us] OR > 130.00 [us]	Test enabled by calibration; and Battery voltage and Key ON and No active DTC's: and At least one injection pulse is requested by the application software; (FUL_FuelInjectedCyl_CiEPSR_CylinderH and No information of dropped pulse reported by HWIO	== 1 [Boolean] > 11.00 [V] - FUL_InjCktTFTKO FUL_CntrlrStTFTKO FUL_BoostVoltTFTKO == TRUE); -	10 failures out of 20 samples 1 sample every engine cycle Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 4 Injection Timing	P020D	This DTC detects an Injector fault or ECU fault that causes pull In period of the current pulse out of range on injector 4 The pull in period is the time for the injection current to rise to the current level (20.00 [A]) at the beginning of the pulse	Measurement of the Pull In period of the current pulse of the injector 4 provided by HWIO	< 0.00 [us] OR > 130.00 [us]	Test enabled by calibration; and Battery voltage and Key ON and No active DTC's: and At least one injection pulse is requested by the application software; (FUL_FuelInjectedCyl_CiEPSR_CylinderE and No information of dropped pulse reported by HWIO	== 1 [Boolean] > 11.00 [V] - FUL_InjCktTFTKO FUL_CntrlrStTFTKO FUL_BoostVoltTFTKO == TRUE); -	10 failures out of 20 samples 1 sample every engine cycle Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.

Injection Timing Control Circuit	P0216	This DTC detects an ECU internal fault, by comparing the cumulative injection pulse width provided by HWIO and the cumulative injection pulse width calculated by Application SW.
		A calibration is used to define the pulses that have to be taken into account to calculate the cumulative injection pulse width, both by HWIO and by application SW.
		Two different thresholds are defined for detecting the fault. The high threshold depends on the number of injection pulses active, i.e. the injection pulses driven and monitored.
			The cumulative injection pulse width (both HWIO and Application SW) is calculated by considering only the pulses to be monitored, defined in the calibration **P0216_ET_CumulEnbl**
			
			if (Cumulative injection pulse width read by HWIO > Cumulative injection pulse width calculated by Application SW)
			{
			|Cumulative injection pulse width read by HWIO - Cumulative injection pulse width calculated by Application SW|
			}
			else
			{
			|Cumulative injection pulse width read by HWIO - Cumulative injection pulse width calculated by Application SW|
			}
			
			OR
			information of dropped pulse reported by HWIO
			
			Cumulative injection pulse width calculated by
				>
				P0216_PulsWidthErrHi
				[us] depending on the number of injection pulses active
				
				> 80.00 [us]
					Test enabled by calibration;
					
					and
					Battery voltage
					
					and
					Key ON
					
					and
					No active DTC's:
					
					and
					At least one Injection Pulse is requested by the application software (FUL_FuelInjected
					
					and
						== 1.00 [Boolean]
						
						> 11.00 [V]
						
						-
						
						FUL_InjCktTFTKO
						FUL_CntrlrStTFTKO
						FUL_BoostVoltTFTKO
						FUL_PullInErrTFTKO
						
						== TRUE);
							25 failures out of 50 samples
							
							or
							
							80 consecutive failures
							
							1 sample every cylinder firing
							
							Continuous
								Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Application SW is equal to the sum of the programmed pulses width and the end of injection period measurement provided by HWIO.					

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Turbocharger/ Supercharger "A" Overboost Condition	P0234	This monitor detects failures in the charging air system such to not fulfill the request of boost pressure in the intake manifold. It works only in steady state closed loop pressure control zone. The DTC checks a permanent negative control deviation of the boost pressure indicating an overboost condition. This monitor is used to detect any malfunction in the boost pressure system causing the vehicle's emissions to exceed the limits. The aim of the overboost pressure monitor is to detect obstructions in the exhaust pipe. The boost pressure is usually controlled by the VGT vanes. The intake manifold pressure is also affected by the throttle valve and the HP EGR valve position changes. The aim of this procedure is to identify a limitation of the VGT vanes (equal to an obstruction) that leads to exceed the emission limits.	Boost pressure tracking error(difference between the desired boost pressure and the measured pressure at intake manifold by MAP sensor) lower than a threshold. If throttle control is active: The setpoint used for closed loop control is the conversion of the desired upstream throttle boost pressure (target) in desired intake boost pressure. The conversion of the setpoint is done calculating the pressure drop over the throttle valve that is strictly dependent on the valve position. If throttle control is NOT active: The setpoint used for closed loop control is the intake manifold pressure: in this situation the diagnostic monitors the boost pressure closed loop control tracking error.	If throttle control is active (Refer to "Other AICR DSL flags" Free Form): (**P0234: Negative boost deviation threshold (throttle control active)** [kPa] x **P0234, P2263: Overboost barometric correction**) If throttle control is NOT active (Refer to "Other AICR DSL flags" Free Form): (**P0234: Negative boost deviation threshold (throttle control not active)** [kPa] x **P0234, P2263: Overboost barometric correction**)	Calibration on diagnostic enabling Engine Running Cranking ignition in range PT Relay voltage in range Difficult launch NOT detected Boost Pressure Control Closed Loop active No active transition from a combustion mode to another one Outside Air Temperature in range Desired Boost Pressure steady state: BstDes-BstDes_Old	**P0234, P0299: Boost pressure control deviation enabling** ==TRUE ==TRUE Battery voltage > 11.00 [V] Powertrain relay voltage > 11.00 [V] Refer to "LDT_DifficultLaunchActive" Free Form Refer to "Boost Control in Closed Loop" Free Form ==TRUE > -20.00 [°C] AND < 55.00 [°C] > -18 [kPa/s] AND < 20 [kPa/s]	280 fail counters over 350 sample counters sampling time is 25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Engine speed in range	> 1,600.00 [rpm] AND < 2,550.00 [rpm]		
					Desired intake Boost pressure in range	> **P0234: Minimum boost pressure for overboost monitor enabling** [kPa] AND **P0234: Maximum boost pressure for overboost <monitor enabling** [kPa]		
					(Engine Coolant Temperature OR OBD Coolant Enable Criteria), AND Engine Coolant Temperature	> 60 [°C] ==TRUE < 117 [°C]		
					Ambient Air Pressure in range	> 70 [kPa] AND < 110 [kPa]		
					Throttle Valve position	>= 90.00 [%] if throttle control is active (Refer to "Other AICR DSL flags" Free Form) >= 75.00 [%] if throttle control is NOT active (Refer to "Other AICR DSL flags" Free Form)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No active DTCs All enabling conditions last for a time	AIC_BstSysDiagDenomDsbl ==FALSE > **P0234: Overboost monitor delay timer** [s]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 1 Control Circuit Low Voltage	P0261	This DTC detects a short circuit to ground of the low side driver circuit of Injector 1.	Voltage low across low side drive during off state indicates short-to-ground	Short to ground: impedence between LS pin and controller ground <= 0.5 [Ohm]	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderA and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderA	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] ==TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 1 Control Circuit High Voltage	P0262	This DTC detects a short circuit to power supply of the low side driver circuit of Injector 1.	Voltage high across low side driver during On state indicates short to power	Short to power: impedence between LS pin and controller power <= 0.5 [Ohm]	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderA and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderA	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] ==TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 2 Control Circuit Low Voltage	P0264	This DTC detects a short circuit to ground of the low side driver circuit of Injector 2.	Voltage low across low side drive during off state indicates short-to-ground	Short to ground: impedence between LS pin and controller ground <= 0.5 [Ohm]	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderB and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderB	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] ==TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 2 Control Circuit High Voltage	P0265	This DTC detects a short circuit to power supply of the low side driver circuit of Injector 2.	Voltage high across low side driver during On state indicates short to power	Short to power: impedence between LS pin and controller power <= 0.5 [Ohm]	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderB and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderB	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] ==TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 3 Control Circuit Low Voltage	P0267	This DTC detects a short circuit to ground of the low side driver circuit of Injector 3.	Voltage low across low side drive during off state indicates short-to-ground	Short to ground: impedence between LS pin and controller ground <= 0.5 [Ohm]	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderH and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderH	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] ==TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 3 Control Circuit High Voltage	P0268	This DTC detects a short circuit to power supply of the low side driver circuit of Injector 3.	Voltage high across low side driver during On state indicates short to power	Short to power: impedence between LS pin and controller power <= 0.5 [Ohm]	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderH and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderH	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] ==TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injection Timing Performance	P026B	This DTC detects an injection timing only fault by comparison of the requested Start Of Injection by Application SW and the scheduled SOI by HWIO SW.	Comparison of the requested Start Of Injection by Application SW and the scheduled SOI by HWIO SW for all cylinders.	< -7.00 OR > 7.00	Test enabled by calibration AND Engine Speed in range AND At least one injection pulse is commanded by Application SW on all cylinders in the previous engine cycle FUL_FuelInjectedCyl_CiEPSR_CylinderA FUL_FuelInjectedCyl_CiEPSR_CylinderB FUL_FuelInjectedCyl_CiEPSR_CylinderC FUL_FuelInjectedCyl_CiEPSR_CylinderD FUL_FuelInjectedCyl_CiEPSR_CylinderE FUL_FuelInjectedCyl_CiEPSR_CylinderF FUL_FuelInjectedCyl_CiEPSR_CylinderG FUL_FuelInjectedCyl_CiEPSR_CylinderH AND At least one injection pulse is commanded by HWIO OR at least one post injection is commanded by Application SW, on all cylinders in the previous engine cycle	== 1.00 > 400 [rpm] AND < 3,000.00 == TRUE; - -	280.00 failures out of 400.00 samples 1 sample every engine revolution	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					AND No information of dropped pulse reported by HWIO AND No electrical fault on injectors are present AND No Injection Controller Fault AND No faults on crankshaft sensor for the entire driving cycle.	FUL_FuelInjCkt_FA FUL_CntrlStFA CrankSensor_FA AND CrankSensor_TFTKO		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 4 Control Circuit Low Voltage	P0270	This DTC detects a short circuit to ground of the low side driver circuit of Injector 4.	Voltage low across low side drive during off state indicates short-to-ground	Short to ground: impedence between LS pin and controller ground <= 0.5 [Ohm]	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderE and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderE	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] ==TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 4 Control Circuit High Voltage	P0271	This DTC detects a short circuit to power supply of the low side driver circuit of Injector 4.	Voltage high across low side driver during On state indicates short to power	Short to power: impedence between LS pin and controller power <= 0.5 [Ohm]	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderE and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderE	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] ==TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Turbocharger/ Supercharger "A" Underboost Condition	P0299	This monitor detects failures in the charging air system such to not fulfill the request of boost pressure in the intake manifold. It works only in steady state closed loop pressure control zone. The DTC checks a permanent positive control deviation of the boost pressure indicating an underboost condition. This monitor is used to detect any malfunction in the boost pressure system causing the vehicle's emissions to exceed the limits. The aim of the underboost pressure monitor is to detect leakages in the pipe after the compressor or in the intake/exhaust manifold. The boost pressure is usually controlled by the VGT vanes. The intake manifold pressure is also affected by the throttle valve and the HP EGR valve position changes. The aim of this procedure is to identify a limitation of the VGT vanes (equal to a leakage) that leads to exceed the emission	Boost pressure tracking error(difference between the desired boost pressure and the measured pressure at intake manifold by MAP sensor) higher than a threshold. If throttle control is active: The setpoint used for closed loop control is the conversion of the desired upstream throttle boost pressure (target) in desired intake boost pressure. The conversion of the setpoint is done calculating the pressure drop over the throttle valve that is strictly dependent on the valve position. If throttle control is NOT active: The setpoint used for closed loop control is the intake manifold pressure: in this situation the diagnostic monitors the boost pressure closed loop control tracking error.	If throttle control is active (Refer to "Other AICR DSL flags" Free Form): > (**P0299: Positive boost deviation threshold (throttle control active)** [kPa] x **P0299, P2263: Underboost barometric correction**) If throttle control is NOT active (Refer to "Other AICR DSL flags" Free Form): > (**P0299: Positive boost deviation threshold (throttle control not active)** [kPa] x **P0299, P2263: Underboost barometric correction**)	Calibration on diagnostic enabling Engine Running Cranking ignition in range PT Relay voltage in range Difficult launch NOT detected Boost Pressure Control Closed Loop active No active transition from a combustion mode to another one Outside Air Temperature in range Desired Boost Pressure steady state: BstDes-BstDes_Old	**P0234, P0299: Boost pressure control deviation enabling** ==TRUE ==TRUE Battery voltage > 11.00 [V] Powertrain relay voltage > 11.00 [V] Refer to "LDT_DifficultLaunchActive" Free Form Refer to "Boost Control in Closed Loop" Free Form ==TRUE > -20.00 [°C] AND < 55.00 [°C] > -18 [kPa/s] AND < 20 [kPa/s]	280.00 fail counters over 350.00 sample counters sampling time is 25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		limits.			Engine speed in range	> 1,250.00 [rpm] AND < 2,000.00 [rpm]		
					Desired intake Boost pressure in range	> **P0299: Minimum boost pressure for underboost monitor enabling** [kPa] AND **P0299: Maximum boost pressure for underboost monitor enabling** [kPa]		
					(Engine Coolant Temperature OR OBD Coolant Enable Criteria), AND Engine Coolant Temperature	> 60 [°C] ==TRUE < 117 [°C]		
					Ambient Air Pressure in range	> 70 [kPa] AND < 110 [kPa]		
					Throttle Valve position	>= 90.00 [%] if throttle control is active (Refer to "Other AICR DSL flags" Free Form) >= 75.00 [%] if throttle control is NOT active (Refer to "Other AICR DSL flags" Free Form)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No active DTCs All enabling conditions last for a time	AIC_BstSysDiagDenomDsbl ==FALSE > **P0299: Underboost monitor delay timer** [s]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Random Misfire Detected Cylinder 1 Misfire Detected Cylinder 2 Misfire Detected Cylinder 3 Misfire Detected Cylinder 4 Misfire Detected	P0300 P0301 P0302 P0303 P0304	These DTC's will determine if a random or a cylinder specific misfire is occurring by monitoring various terms derived from crankshaft velocity. The rate of misfire over an interval is compared to both emissions and catalyst damaging thresholds. The pattern of crankshaft acceleration after the misfire is checked to differentiate between real misfire and other sources of crank shaft noise. Emissions Neutral Default Action: If consumed Emissions Neutral Default DTCs from other subsystems are set: Ignore Rough Road, Traction, Stability, and Antilock brake signals. If default action not activated, Misfire Monitor could complete less frequently or inaccurately. Default Action Latched for duration of Trip Default Action: If Misfire P030x sets on some hybrid applications, the isolation damper	Crankshaft Deceleration Value(s) vs. Engine Speed and Engine load The equation used to calculate deceleration value is tailored to specific vehicle operating conditions. The selection of the equation used is based on the 1st single cylinder continuous misfire threshold tables encountered that are not max of range. If all tables are max of range at a given speed/load, that speed load region is an ***Undetectable region*** see Algorithm Description Document for additional details. SINGLE CYLINDER CONTINUOUS MISFIRE((Medres_Decel Medres_Jerk OR (Medres_Decel Medres_Jerk OR (Lores_Decel Lores_Jerk OR (Lores_Decel Lores_Jerk OR RevBalanceTime)	 - see details of thresholds on Supporting Tables Tab > **RufSCD_Decel** AND > **RufSCD_Jerk)** > **SCD_Decel** AND > **SCD_Jerk)** > **RufCyl_Decel** AND > **RufCyl_Jerk)** > **CylModeDecel** AND > **CylModeJerk)** >**RevMode_Decel**	Engine Run Time Engine Coolant Temp Or If ECT at startup Then System Voltage + Throttle delta - Throttle delta Early Termination option: (used on plug ins that may not have enough engine run time at end of trip for normal interval to complete.)	> 2 crankshaft revolution "ECT" If OBD Max Coolant Achieved = FALSE -9 ºC < ECT Or if OBD Max Coolant Achieved = TRUE -9 ºC < ECT < 125 ºC < -9 ºC If OBD Max Coolant Achieved = FALSE 21 ºC < ECT If OBD Max Coolant Achieved = TRUE 21 ºC < ECT < 125 ºC 9.00 < volts < 32.00 < 100.00 % per 25 ms < 100.00 % per 25 ms Not Enabled	Emission Exceedence = any (5) failed 200 rev blocks out of (16) 200 rev block tests Failure reported for (4) Exceedence in 1st (16) 200 rev block tests, or (4) Exceedences thereafter. OR when Early Termination Reporting = Enabled and engine rev > 1,000 revs and < 3,200 revs at end of trip	Type B, 2 Trips (Mil Flashes with Catalyst damage level of Misfire)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		between engine and transmission can go into extreme resonance. Default action is to move rpm out of the resonance zone. If default action not activated, significant hardware damage could occur rendering vehicle inoperable.	********** **This Feature only used on Diesel engines** Combustion Modes that force selection of Idle Tables ********** Other patterns of misfire use adjustments to the single cylinder continuous misfire threshold tables: RANDOM MISFIRE Use random misfire thresholds If no misfire for (Medres_Decel AND Medres_Jerk) OR (Medres_Decel AND Medres_Jerk) OR (Lores_Decel AND Lores_Jerk)	********** **This Feature only used on Diesel engines** **CombustModeIdleTbl** in Supporting Tables ********** > 3 Engine Cycles > **RufSCD_Decel** * **Random_SCD_Decel** >**RufSCD_Jerk** * **Random_SCD_Jerk** > **SCD_Decel** * **Random_SCD_Decel** > **SCD_Jerk** * **Random_SCD_Jerk** > **RufCyl_Decel** * **RandomCylModDecel** > **RufCyl_Jerk** * **RandomCylModJerk**			any Catalyst Exceedence = (1) 200 rev block as data supports for catalyst damage. Catalyst Failure reported with (1 or 3) Exceedences in FTP, or (1) Exceedence outside FTP. Continuous	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			OR (Lores_Decel AND Lores_Jerk)	> **CylModeDecel** * **RandomCylModDecel** > **CylModeJerk** * **RandomCylModJerk**				
			OR RevBalanceTime	> **RevMode_Decel** * **RandomRevModDecl**				
			PAIRED CYLINDER MISFIRE If a cylinder & it's pair are above PAIR thresholds (Medres_Decel AND Medres_Jerk)	> **RufSCD_Decel** * **Pair_SCD_Decel** > **RufSCD_Jerk** * **Pair_SCD_Jerk**				
			OR (Medres_Decel AND Medres_Jerk)	> **SCD_Decel** * **Pair_SCD_Decel** > **SCD_Jerk** * **Pair_SCD_Jerk**				
			OR (Lores_Decel AND Lores_Jerk)	> **RufCyl_Decel** * **PairCylModeDecel** > **RufCyl_Jerk** * **PairCylModeJerk**				
			OR (Lores_Decel AND Lores_Jerk)	> **CylModeDecel** * **PairCylModeDecel** > **CylModeJerk** * **PairCylModeJerk**				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			OR (Revmode Active AND (within one engine cycle: 2nd largest Lores_Decel)	> **CylModeDecel * PairCylModeDecel**				
			AND Above TRUE for))	> 35 engine cycles out of 100 engine cycles				
			BANK MISFIRE Cylinders above Bank Thresholds	>= 3 cylinders				
			(Medres_Decel	> **RufSCD_Decel * Bank_SCD_Decel**				
			AND Medres_Jerk)	> **RufSCD_Jerk * Bank_SCD_Jerk**				
			OR (Medres_Decel	> **SCD_Decel * Bank_SCD_Decel**				
			AND Medres_Jerk)	> **SCD_Jerk * Bank_SCD_Jerk**				
			OR (Lores_Decel	> **RufCyl_Decel * BankCylModeDecel**				
			AND Lores_Jerk)	> **RufCyl_Jerk * BankCylModeJerk**				
			OR (Lores_Decel	> **CylModeDecel * BankCylModeDecel**				
			AND Lores_Jerk)	> **CylModeJerk * BankCylModeJerk**				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			CONSECUTIVE CYLINDER MISFIRE 1st cylinder uses single cyl continuous misfire thresholds; 2nd Cylinder uses: (Medres_Decel	> **RufSCD_Decel** * **ConsecSCD_Decel**				
			AND Medres_Jerk)	> **RufSCD_Jerk** * **ConsecSCD_Jerk**				
			OR (Medres_Decel	> **SCD_Decel** * **ConsecSCD_Decel**				
			AND Medres_Jerk)	> **SCD_Jerk** * **ConsecSCD_Jerk**				
			OR (Lores_Decel	> **RufCyl_Decel** * **ConsecCylModDecel**				
			AND Lores_Jerk)	> **RufCyl_Jerk** * **ConsecCylModeJerk**				
			OR (Lores_Decel	> **CylModeDecel** * **ConsecCylModDecel**				
			AND Lores_Jerk)	> **CylModeJerk** * **ConsecCylModeJerk**				
			CYLINDER DEACTIVATION MODE (Active Fuel Managment)					

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			AFM: SINGLE CYLINDER CONTINUOUS MISFIRE (CylAfterDeacCyl_Decel AND CylAfterDeacCyl_Jerk) OR (CylBeforeDeacCylDecel AND CylBeforeDeacCyl_Jerk) AFM: RANDOM MISFIRE Use random misfire thresholds If no misfire for (CylAfterDeacCyl_Decel AND CylAfterDeacCyl_Jerk) (CylBeforeDeacCylDecel AND CylBeforeDeacCyl_Jerk)	> **CylModeDecel * ClyAfterAFM_Decel** > **CylModeJerk * CylAfterAFM_Jerk** > **CylModeDecel * CylBeforeAFM_Decel** > **CylModeJerk * ClyBeforeAFM_Jerk** > 3 Engine Cycles > **CylModeDecel * ClyAfterAFM_Decel * RandomAFM_Decl** > **CylModeJerk * CylAfterAFM_Jerk * RandomAFM_Jerk** > **CylModeDecel * CylBeforeAFM_Decel * RandomAFM_Decl** > **CylModeJerk * ClyBeforeAFM_Jerk * RandomAFM_Jerk** - see details on Supporting Tables Tab				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Misfire Percent Emission Failure Threshold	≥ 4.50 % P0300				
			Misfire Percent Catalyst Damage	> **Catalyst_Damage_Misfire_Percentage** in Supporting Tables whenever secondary conditions are met.				
			When engine speed and load are less than the FTP cals (3) catalyst damage exceedences are allowed.	≤ 0 FTP rpm AND ≤ 0 FTP % load	(at low speed/loads, one cylinder may not cause cat damage) Engine Speed Engine Load Misfire counts	 > 8,192 rpm AND > 200 % load AND < 180 counts on one cylinder		
					Engine Speed	580 < rpm < ((Engine Over Speed Limit) - 400) OR 8,191) Engine speed limit is a function of inputs like Gear and temperature	4 cycle delay	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						see **EngineOverSpeedLimit** in supporting tables		
					No active DTCs:	TPS_FA EnginePowerLimited MAF_SensorTFTKO MAP_SensorTFTKO IAT_SensorTFTKO ECT_Sensor_Ckt_TFTKO 5VoltReferenceB_FA CrankSensor_TFTKO CrankSensor_FA CamLctnIntFA CamLctnExhFA CamSensorAnyLctnTFTKO AnyCamPhaser_FA AnyCamPhaser_TFTKO AmbPresDfltdStatus	4 cycle delay	
					P0315 & engine speed	> 1,000 rpm	4 cycle delay	
					Fuel Level Low	LowFuelConditionDiagnostic	500 cycle delay	
					Cam and Crank Sensors	in sync with each other	4 cycle delay	
					Misfire requests TCC unlock	Not honored because Transmission in hot mode or POPD intrusive diagnostic running	4 cycle delay	
					Fuel System Status	≠ Fuel Cut	4 cycle delay	
					Active FuelManagement	Transition in progress	0 cycle delay	
					Undetectable engine	***Undetectable region***	4 cycle delay	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					speed and engine load region	from Malfunction Criteria		
					Abusive Engine Over Speed	> 8,192 rpm	0 cycle delay	
					Below zero torque (except CARB approved 3000 rpm to redline triangle.)	< **ZeroTorqueEngLoad** or <**ZeroTorqueAFM** if AFM is active in Supporting Tables	4 cycle delay	
					Below zero torque: TPS Vehicle Speed	≤ 100.0 % (≤ 100.0 % in AFM) > 318 mph (> 318 mph AFM)	4 cycle delay	
					NEGATIVE TORQ AFM If deactivated cylinders appear to make power, torque is negative: DeactivatedCyl_Decel AND DeactivatedCyl_Jerk AND # of Deact Cyls Inverted	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Delay if PTO engaged	Not Enabled	4 cycle delay	
					********** **This Feature only used on Diesel engines**	**********	**********	
					Combustion Mode	= **InfrequentRegen** value in Supporting Tables	4 cycle delay	
					Driver cranks before Wait to Start lamp extinguishes	IF TRUE	**WaitToStart** cycle delay	
					Brake Torque **********	> 199.99 % Max Torque **********	4 cycle delay **********	
					DRIVELINE RING FILTER After a low level misfire, another misfire may not be detectable until driveline ringing ceases. If no ringing seen, stop filter early.			
					Filter Driveline ring:	> "**Ring Filter**" # of engine cycles after misfire in Supporting Tables		
					Stop filter early:	> "**Number of Normals**" # of engine cycles after misfire in Supporting Tables tab		
					ABNORMAL ENGINE SPEED OSCILLATION: (checks each "misfire" candidate in 100 engine			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Cycle test to see if it looks like some disturbance like rough road (abnormal).) Used Off Idle, and while not shifting, TPS Engine Speed Veh Speed Auto Transmission indivdual candidate deemed abnormal if number of consecutive decelerating cylinders after "misfire": (Number of decels can vary with misfire detection equation) Consecutive decels while in SCD Mode Cyl Mode Rev Mode At the end of 100 engine cycle test, the ratio of abnormal/candidate is checked to confirm if real misfire is present within the 100 engine cycles. abnormal candidates/ total candidates MISFIRE CRANKSHAFT	> 200 % > 1,000 rpm > 3 mph not shifting > **Abnormal SCD Mode** > **Abnormal Cyl Mode** > **Abnormal Rev Mode** in Supporting Tables > 0.50 ratio	discard 100 engine cycle test	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					PATTERN RECOGNITION checks each "misfire" candidate in 100 engine Cycle test to see if overall crankshaft pattern looks like real misfire (recognized), or some disturbance like rough road (unrecognized). At the end of 100 engine cycle test, the ratio of unrecog/recognized is checked to confirm if real misfire is present within the 100 engine cycles. Typically used for checking a single misfire per engine cycle but can support some other patterns on some packages Pattern Recog Enabled: Pattern Recog Enabled during Cylinder Deac Pattern Recog Enabled consecutive cyl pattrn Engine Speed Veh Speed The 1st check for "recognized" is the 1st fired cylinder after the misfire candidate should both accelerate and jerk an amount based acceleration and jerk of Single Cylinder Misfire	 Enabled Not Enabled Disabled 700 < rpm < 6,800 > 0.0 mph		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					thresholds in effect at that speed and load. (CylAfter_Accel AND CylAfter_Jerk) Addtionally, the crankhaft is checked again a small calibratible number of cylinders later to see if the distrubance is still large like rough road, or has calmed down like real misfire. The size of disturbance is compared to a multiplier times the ddt_jerk value used to detect misfire at that speed and load. If there is repetitive misfire on consecutive engine cycles, the expected snap is adjusted due to the higher expected disturbance. Num of Cylinders after misfire to start check of crankshaft snap "misfire" recognized if: Crankshaft snap after: isolated "misfire"	> Misfire_ decel ***** **1st_FireAftrMisfr_Acel** > Misfire_Jerk ***** **1st_FireAftrMisfr_Jerk** Or if AFM mode is active: > Misfire_ decel * **1stFireAftrMisAcelAFM** > Misfire_Jerk * **1stFireAfterMisJerkAFM** 2 Cylinders < Misfire_Jerk *****		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					repetative "misfire"	**SnapDecayAfterMisfire** < Misfire_Jerk * **SnapDecayAfterMisfire** * **RepetSnapDecayAdjst**		
					At the end of 100 engine cycle test, the ratio of unrecog/recognized is checked to confirm if real misfire is present.	in Supporting Tables		
					Ratio of Unrecog/Recog	> 0.60	discard 100 engine cycle test	
					**********	**********	**********	
					NON-CRANKSHAFT BASED ROUGH ROAD:	**********		
					Rough Road Source	Disabled		
					**********		**********	
					IF Rough Road Source = WheelSpeedInECM ABS/TCS Wheel speed noise VSES	CeRRDR_e_None **********		
						active > **WSSRoughRoadThres**	discard 100 engine cycle test	
					AND No Emission Neutral Default Action DTCs	active ABS Failed Vehicle Dynamics Control System Status Driven Wheel Rotation Status Non Driven Wheel Rotation Status		
					**********	**********	**********	
					IF Rough Road Source = "FromABS" ABS/TCS	**********	discard 100	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					RoughRoad VSES AND No Emission Neutral Default Action DTCs ********** IF Rough Road Source = "TOSS" TOSS dispersion AND No Active DTCs ********** Default Action Isolator Resonance Default Action Option ********** If Isolator Resonance Option Enabled AND Misfire P030x TFTKO	active detected active ABS Failed Vehicle Dynamics Control System Status ********** >**TOSSRoughRoadThres** in supporting tables Transmission Output Shaft Angular Velocity Validity TransmissionEngagedState_FA (Auto Trans only) ClutchPstnSnsr FA (Manual Trans only) ********** ********** Not Enabled ********** Set engine speed limits: 0 < Eng RPM < 9,000	engine cycle test ********** discard 100 engine cycle test 4 cycle delay ********** **********	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Crankshaft Position System Variation Not Learned	P0315	This DTC determines if the crankshaft sensor learn values that are stored in memory are valid. The angle between each tooth of the reluctor wheel is learned, and the sum of all angles together should sum to 360° (one revolution of the reluctor wheel). Default values, or corrupted values will not sum to 360°.	The Crankshaft target wheel should be 360 degrees around in circumferance. Loss or controller non-volitile memory or an error in memory will cause the values of individual teeth learn to be defaulted or incorrect. Set the DTC if the Differance between the sum of the reluctor wheel's teeth and 360 degrees is greater than:	> 0.001 degrees	OBD Manufacturer Enable Counter	MEC = 0	0.50 seconds Frequency Continuous100 msec	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Crankshaft Position (CKP) Sensor A Circuit	P0335	Determines if a fault exists with the crank position sensor signal	Time since last crankshaft position sensor pulse received	>= 4.0 seconds	Starter engaged AND (cam pulses being received OR (MAF_SensorFA AND Engine Air Flow	 = FALSE > 2.0 grams/second))	Continuous every 100 msec	Type A, 1 Trips
			No crankshaft pulses received	>= 0.3 seconds	Engine is Running Starter is not engaged		Continuous every 12.5 msec	
			No crankshaft pulses received		Engine is Running OR Starter is engaged No DTC Active:	 P0340 P0341	2 failures out of 10 samples One sample per engine revolution	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Crankshaft Position (CKP) Sensor A Performance	P0336	Determines if a performance fault exists with the crank position sensor signal	Time in which 10 or more crank re-synchronizations occur	< 10.0 seconds	Engine Air Flow Cam-based engine speed No DTC Active:	>= 2.0 grams/second > 450 RPM P0335	Continuous every 250 msec	Type A, 1 Trips
			No crankshaft synchronization gap found	>= 0.4 seconds	Engine is Running Starter is not engaged		Continuous every 12.5 msec	
			Time since starter engaged without detecting crankshaft synchronization gap	>= 1.5 seconds	Starter engaged AND (cam pulses being received OR (MAF_SensorFA AND Engine Air Flow	 = FALSE > 2.0 grams/second))	Continuous every 100 msec	
			Crank pulses received in one engine revolution OR Crank pulses received in one engine revolution	< 51 > 65	Engine is Running OR Starter is engaged No DTC Active:	 P0340 P0341	8 failures out of 10 samples One sample per engine revolution	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Camshaft Position (CMP) Sensor Circuit Bank 1 Sensor A	P0340	Determines if a fault exists with the cam position bank 1 sensor A signal	Time since last camshaft position sensor pulse received OR Time that starter has been engaged without a camshaft sensor pulse	>= 5.5 seconds >= 4.0 seconds	Starter engaged AND (crank pulses being received OR (MAF_SensorFA AND Engine Air Flow	 = FALSE > 2.0 grams/second))	Continuous every 100 msec	Type A, 1 Trips
			Fewer than 4 camshaft pulses received in a time	> 3.0 seconds	Engine is running Starter is not engaged		Continuous every 100 msec	
			No camshaft pulses received during first 12 MEDRES events (There are 12 MEDRES events per engine cycle		Crankshaft is synchronized Starter must be engaged to enable the diagnostic, but the diagnostic will not disable when the starter is disengaged No DTC Active:	 CrankSensor_FA	Continuous every MEDRES event	
			The number of camshaft pulses received during 100 engine cycles	= 0	Crankshaft is synchronized No DTC Active:	 CrankSensor_FA	8 failures out of 10 samples Continuous every engine cycle	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Camshaft Position (CMP) Sensor Performance Bank 1 Sensor A	P0341	Determines if a performance fault exists with the cam position bank 1 sensor A signal	The number of camshaft pulses received during first 12 MEDRES events is OR (There are 12 MEDRES events per engine cycle)	< 4 > 6	Crankshaft is synchronized Starter must be engaged to enable the diagnostic, but the diagnostic will not disable when the starter is disengaged No DTC Active:	CrankSensor_FA	Continuous every MEDRES event	Type A, 1 Trips
			The number of camshaft pulses received during 100 engine cycles OR	< 398 > 402	Crankshaft is synchronized No DTC Active:	CrankSensor_FA	8 failures out of 10 samples Continuous every engine cycle	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation (EGR) Flow insufficient	P0401	This monitor detects failures in the air system such to not fulfill the request of mass air flow through the intake circuit. This monitor is used to detect any malfunction in the air system that leads to lower EGR rate causing the vehicle's emissions to exceed the OBD limits. The aim of the EGR flow monitor is to detect HP EGR obstructions (insufficient EGR flow). The EGR flow depends on several variables like the HP EGR valve position, intake manifold pressure, exhaust pressure, EGR cooler outlet temperature. The aim of this procedure is to identify a limitation of the HP EGR (equal to an obstruction) that leads to exceed the OBD limits. In particular environmental conditions where the provided EGR flow amount is not enough to have a robust monitoring, the EGR flow intrusive test can be enabled. When the intrusive test is	Air mass tracking error: difference between the fresh air requested (set point) and the fresh air measured by MAF sensor.	< (SeaBaro Constant x **P0401: Insufficient EGR flow barometric table B (sea level)** [mg]) + (MidBaro Constant x **P0401: Insufficient EGR flow barometric table B (mid level)** [mg]) + (LoBaro Constant x **P0401: Insufficient EGR flow barometric table B (low level)** [mg]) + (SeaBaro Constant x	Calibration on diagnostic enabling HP EGR control is in closed loop on air flow OR LP EGR (if present) control is in closed loop on air flow OR Diagnostic enabled by calibration when HP/LP EGR control is in closed loop on HP/LP EGR flow Engine Running Cranking ignition in range PT Relay voltage in range Air Control is Active (air control in closed loop) Desired EGR rate Engine speed is steady state: |RPM-RPM_old| for a minimum number of samples	**P0401, P0402: EGR flow monitor enabling** ==TRUE Refer to "Other AICR DSL flags" Free Form 1.00 ==TRUE ==TRUE Battery voltage > 11.00 [V] Powertrain relay voltage > 11.00 [V] Refer to "Air Control Active" Free Form > 0 [%] <= 6 [rpm] > 50 [counts]	270.00 fail counters over 300.00 sample counters sampling time is 25 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		enabled, a dedicated flow setpoint value is provided to air control.		**P0401: Insufficient EGR flow barometric table A (sea level)** [mg] x **P0401: Insufficient EGR flow barometric correction (sea level)**) + (MidBaro Constant x **P0401: Insufficient EGR flow barometric table A (mid level)** [mg] x **P0401: Insufficient EGR flow barometric correction (mid level)**) + (LoBaro Constant x **P0401: Insufficient EGR flow barometric table A (low level)** [mg] x **P0401: Insufficient EGR flow barometric correction (low level)**)	Fuel request is steady state: |FUEL-FUEL_old| for a minimum number of samples An air control transition has ended OR Such condition is disabled by calibration No active transition from a combustion mode to another one Throttle measured position Outside Air Temperature Ambient Pressure Engine Coolant Temperature OR OBD Coolant Enable Criteria Desired EGR flow	<= 0.35 [mm^3] > 140 [counts] Refer to "Air Control Transition"Free Form OR 1.00 ==TRUE ==TRUE > 90.00 [%] > -20.00 [°C] > 72.00 [kPa] > 60.00 [°C] ==TRUE > **P0401: Minimum desired EGR flow** [mg]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Desired fuel quantity	> **P0401: Insufficient EGR flow Min fuel enabling condition** [mm^3] AND < **P0401: Insufficient EGR flow Max fuel enabling condition** [mm^3]		
					Outside air temperature in range	Condition must be TRUE. Refer to "P0401, P0402: Outside air temperature" Free Form		
					No faults on proper temperature sensor	AIC_EGR_FlowDiagAirTempFA ==FALSE		
					All enabling conditions last for a time	> 1.00 [s]		
			Air mass tracking error: difference between the fresh air requested (set point) and the fresh air measured by MAF sensor.	< (SeaBaro Constant x **P0401: Insufficient EGR flow barometric table B (sea level)** [mg]) + (	Calibration on diagnostic enabling	**P0401, P0402: EGR intrusive test enabling** ==TRUE	270.00 fail counters over 300.00 sample counters	
					Difficult launch NOT detected	Refer to "LDT_DifficultLaunchActive" Free Form	sampling time is 25 ms	
					HP EGR control is in closed loop on air flow OR LP EGR (if present)	Refer to "Other AICR DSL flags" Free Form		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
				MidBaro Constant x **P0401: Insufficient EGR flow barometric table B (mid level)** [mg]) + (LoBaro Constant x **P0401: Insufficient EGR flow barometric table B (low level)** [mg]) + (SeaBaro Constant x **P0401: Insufficient EGR flow barometric table A (sea level)** [mg] x **P0401: Insufficient EGR flow barometric correction (sea level)**) + (MidBaro Constant x	control is in closed loop on air flow OR Diagnostic enabled by calibration when HP/LP EGR control is in closed loop on HP/LP EGR flow Engine Running Cranking ignition in range PT Relay voltage in range Air Control is Active (air control in closed loop) Desired EGR rate Engine speed is steady state: |RPM-RPM_old| for a minimum number of samples Fuel request is steady state: |FUEL-FUEL_old| for a minimum number of samples An air control transition	1.00 ==TRUE ==TRUE Battery voltage > 11.00 [V] Powertrain relay voltage > 11.00 [V] Refer to "Air Control Active" Free Form > 0 [%] <= 6 [rpm] > 50 [counts] <= 0.35 [mm^3] > 140 [counts] Refer to "Air Control		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
				P0401: Insufficient EGR flow barometric table A (mid level) [mg] x **P0401: Insufficient EGR flow barometric correction (mid level)**) + (LoBaro Constant x **P0401: Insufficient EGR flow barometric table A (low level)** [mg] x **P0401: Insufficient EGR flow barometric correction (low level)**)	has ended OR Such condition is disabled by calibration No active transition from a combustion mode to another one Throttle measured position Outside Air Temperature Ambient Pressure Engine Coolant Temperature OR OBD Coolant Enable Criteria Outside air temperature in range No faults on proper temperature sensor No faults on crank sensor or on fuel injection system	Transition"Free Form OR 1.00 ==TRUE ==TRUE > 90.00 [%] > -20.00 [°C] > 72.00 [kPa] > 60.00 [°C] ==TRUE Condition must be FALSE. Refer to "P0401, P0402: Outside air temperature" Free Form AIC_EGR_FlowDiagAirTempFA ==FALSE CrankSensor_FA ==FALSE FUL_GenericInjSysFA		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						==FALSE		
					Time since last EGR flow insufficient monitoring (standard test or intrusive test) test completion	> 1.00 [s]		
					Desired fuel quantity	> **P0401: Insufficient EGR intrusive test Min fuel enabling condition** [mm^3] AND < **P0401: Insufficient EGR intrusive test Max fuel enabling condition** [mm^3]		
					All enabling conditions above last for a time	> 1.00 [s]		
					All enabling conditions (included the above timer) last for a time	> 1.00 [s]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Warm Up Catalyst Efficiency Below Threshold Bank 1	P0421	The Catalyst (CC DOC) monitor only runs during DPF regeneration and compares the CC DOC released oxidation heat and the post-injected fuel quantity both evaluated inside a determined portion of the DPF regeneration itself. This comparison (ratio) produces an Aging Index that shall be greater than the efficiency threshold, in case of fresh (efficient) Catalyst. If, instead, the so calculated Aging Index is below the efficiency threshold, the diagnosis reports fail because the Catalyst is too much damaged to play well its role (conversion inefficiency detected) and shall be replaced. It is needed that post-injection is enabled during CC DOC monitor in order to produce enough exothermic heat across the Catalyst to evaluate the component conversion efficiency in a reliable way. EWMA Filtering functionality (including	Catalyst Aging Index < Threshold If - Catalyst EWMA filter enabling calibration = TRUE AND - Catalyst conversion inefficiency previously detected (Catalyst Fault Active = TRUE) Then: Catalyst Aging Index < Repass Threshold	Aging Index < **CatCrtdEffThrsh** [Curve] If EWMA Enbl Cal = 0.00 [Boolean] AND Catalyst FA = CAT_CatSysEffLoB1_FA Then: Aging Index < **CatCrtdEffRepEWMA** [Curve]	- Catalyst monitor in DPF regeneration enabled by calibrations AND No active DTCs: - Catalyst up temperature sensor not in fault (Fault Flag = FALSE) AND - Catalyst down temperature sensor not in fault (Fault Flag = FALSE); Temperature Learning concluded: - Number of elapsed samples (task time = 100 [ms]) equal to calibration; **Catalyst monitor status is DISABLED if:** - DPF regeneration disabled OR - Injection system in fault (Fault Flag = TRUE) OR - Ambient temperature	RegenMonitorEnabled = 1.00 [Boolean] AND DPF_RegenMonitorSelected = NOT(0.00 [Boolean]) AND ReportingEnabled= 1.00 [Boolean] AND Cat Up Temp Snsr Flt = NOT (EGT_SnsrCatUpFlt) AND Cat Dwn Temp Snsr Flt = NOT (EGT_SnsrCatDwnFlt); Samples nr. = 10.00 [Counter]; **Catalyst monitor status is DISABLED if:** DPF_DPF_St = SootLoading [Enumerative] OR Injection System Flt = FUL_GenericInjSysFlt OR Amb Temp FA = CAT_OutsideTempFA	Task Time = 100 [ms] If - Catalyst EWMA filter enabling cailibration = FALSE (EWMA Enbl Cal = 0.00 [Boolean]) Then: 2 trips (with malfunction) to set DTC (Type B) If - Catalyst EWMA filter enabling cailibration = TRUE (EWMA Enbl Cal = 0.00 [Boolean]) AND - EWMA status = EWMA Standard Then: 1 trip (with malfunction) to set DTC (Type A) If - Catalyst EWMA filter enabling cailibration = TRUE (EWMA Enbl Cal = 0.00 [Boolean])	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		Fast Initial Response (FIR), Rapid Response (RR) and EWMA Standard) is supported by the Catalyst (CC DOC) monitor.			information in fault (Fault Active = TRUE) OR - Catalyst up exhaust flow estimation in fault (Fault Flag = TRUE) OR - Ambient conditions not always satisfied while engine running: Ambient pressure lower than calibration OR Ambient temperature lower than calibration OR - Catalyst monitor already performed successfully in current driving cycle (Catalyst monitor shall run only once per driving cycle) OR HC unloading enabled; **Catalyst monitor status can move from DISABLED to TRIGGERED if:** - DPF regeneration enabled AND - Injection system not in fault (Fault Flag = FALSE) AND - Ambient temperature information not in fault	OR Cat Up Exh Flow Flt = EXF_TotExhCatUpFlt OR - Ambient conditions not always satisfied while engine running: Amb Press < 70.00 [KPa] OR Amb Temp < 253.00 [K] OR Catalyst monitor already performed successfully in current driving cycle (Catalyst monitor shall run only once per driving cycle) [Boolean] OR HCI_DeHC_ExhInjDsbl = TRUE [Boolean]; **Catalyst monitor status can move from DISABLED to TRIGGERED if:** DPF_DPF_St ≠ SootLoading [Enumerative] AND Injection System Flt = NOT (FUL_GenericInjSysFlt) AND Amb Temp FA = NOT (CAT_OutsideTempFA)	AND - EWMA status = Fast Initial Response (FIR) Then: - 1 trip (with malfunction) to set DTC (Type A) and return to EWMA status = EWMA Standard - 0.00 [Counter] elapsed trips (with no mulfunction) to report pass and return to EWMA status = EWMA Standard If - Catalyst EWMA filter enabling cailibration = TRUE (EWMA Enbl Cal = 0.00 [Boolean]) AND - EWMA status = Rapid Response (RR) Then: - 1 trip (with malfunction) to set DTC (Type A) and return to EWMA status = EWMA Standard - 1 trip (with no mulfunction) to report pass - 0.00 [Counter]	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					(Fault Active = FALSE) AND - Catalyst up exhaust flow estimation not in fault (Fault Flag = FALSE) AND - Ambient conditions always satisfied while engine running: Ambient pressure higher than calibration AND Ambient temperature higher than calibration AND - Catalyst monitor not yet performed successfully in current driving cycle (Catalyst monitor shall run only once per driving cycle) AND - If DPF regeneration has been interrupted in previous driving cycle or in current driving cycle Then: Engine coolant temperature lower than calibration AND - Catalyst up exhaust temperature (by sensor) lower than calibration AND HC unloading disabled; **Catalyst monitor status can move from TRIGGERED to**	AND Cat Up Exh Flow Flt = NOT (EXF_TotExhCatUpFlt) AND Ambient conditions always satisfied while engine running: Amb Press > 70.00 [KPa] AND Amb Temp > 253.00 [K] AND Catalyst monitor not yet performed successfully in current driving cycle (Catalyst monitor shall run only once per driving cycle) [Boolean] AND If Interrupted DPF regeneration counter > 0 [Counter] Then: Eng Cool Temp < 255.99 [°C] AND Cat Up Temp Snsr < 1,500.00 [K]; AND HCI_DeHC_ExhInjDsbl = FALSE [Boolean]; **Catalyst monitor status can move from TRIGGERED to**	elapsed trips (with no mulfunction) to report pass and return to EWMA status = EWMA Standard	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					ENABLED (oxidation heat release integrator and post injected fuel integrator are both enabled) if: - DPF regeneration enabled AND - Injection system not in fault (Fault Flag = FALSE) AND - Ambient temperature information not in fault (Fault Active = FALSE) AND - Catalyst up exhaust flow estimation not in fault (Fault Flag = FALSE) AND - Ambient conditions always satisfied while engine running: Ambient pressure higher than calibration AND Ambient temperature higher than calibration AND - Catalyst monitor not yet performed successfully in current driving cycle (Catalyst monitor shall run only once per driving cycle) AND - Catalyst up exhaust temperature (by sensor) higher than calibration AND - Post injection enabled	**ENABLED (oxidation heat release integrator and post injected fuel integrator are both enabled) if:** DPF_DPF_St ≠ SootLoading [Enumerative] AND Injection System Flt = NOT (FUL_GenericInjSysFlt) AND Amb Temp FA = NOT (CAT_OutsideTempFA) AND Cat Up Exh Flow Flt = NOT (EXF_TotExhCatUpFlt) AND - Ambient conditions always satisfied while engine running: Amb Press > 70.00 [KPa] AND Amb Temp > 253.00 [K] AND Catalyst monitor not yet performed successfully in current driving cycle (Catalyst monitor shall run only once per driving cycle) [Boolean] AND Cat Up Temp Snsr > 0.00 [K] AND FUL_PostEnbl = TRUE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						[Boolean]		
					AND - Catalyst up exhaust flow estimation in range	AND 0.00 < Cat Up Exh Flow < 1,000.00 [g/s]		
					AND - Catalyst up exhaust temperature (by sensor) in range	AND 0.00 < Cat Up Temp Snsr [K] < 1,000.00		
					AND - Post injection fuel rate in range	AND 0.00 < Post Inj Fuel Qnty [g/s] < 1,000.00		
					AND - Consecutive time in which Post Injection Fuel rate is lower than a threshold is less than a calibration	AND Post Inj Fuel Qnty [g/s] < -1.00 for less than 0.00 [s]		
					AND HC unloading disabled;	AND HCI_DeHC_ExhInjDsbl = FALSE [Boolean];		
					Oxidation heat release integrator and post injected fuel integrator are both frozen if: - Engine not running	**Oxidation heat release integrator and post injected fuel integrator are both frozen if:** - Engine not running		
					OR - Catalyst up exhaust flow estimation out of range	OR Cat Up Exh Flow [g/s] < 0.00 OR Cat Up Exh Flow > 1,000.00 [g/s]		
					OR - Catalyst up exhaust temperature (by sensor) out of range	OR Cat Up Temp Snsr [K] < 0.00 OR Cat Up Temp Snsr [K] > 1,000.00		
					OR - Post injection fuel rate	OR Post Inj Fuel Qnty [g/s] <		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					out of range OR - Consecutive time in which Post Injection Fuel rate is lower than a threshold is more than a calibration **Catalyst monitor status can move from ENABLED (oxidation heat release integrator and post injected fuel integrator are both enabled) to DONE (integrators are stopped and the ratio between the total integrated oxidation heat and the total integrated injected fuel is performed with the consequent creation of the Catalyst Aging Index to be compared with the Fault Threshold --> Diagnostic test evaluation trigger) if:** - DPF regeneration enabled AND - Injection system not in fault (Fault Flag = FALSE) AND - Ambient temperature information not in fault	0.00 OR Post Inj Fuel Qnty [g/s] > 1,000.00 OR Post Inj Fuel Qnty [g/s] < -1.00 for more than 0.00 [s] **Catalyst monitor status can move from ENABLED (oxidation heat release integrator and post injected fuel integrator are both enabled) to DONE (integrators are stopped and the ratio between the total integrated oxidation heat and the total integrated injected fuel is performed with the consequent creation of the Catalyst Aging Index to be compared with the Fault Threshold --> Diagnostic test evaluation trigger) if:** DPF_DPF_St ≠ SootLoading [Enumerative] AND Injection System Flt = NOT (FUL_GenericInjSysFlt) AND Amb Temp FA = NOT (CAT_OutsideTempFA)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					(Fault Active = FALSE) AND - Catalyst up exhaust flow estimation not in fault (Fault Flag = FALSE) AND - Ambient conditions always satisfied while engine running: Ambient pressure higher than calibration AND Ambient temperature higher than calibration AND - Catalyst monitor not yet performed successfully in current driving cycle (Catalyst monitor shall run only once per driving cycle) AND - Integrated post injected fuel quantity higher than curve AND HC unloading disabled;	AND Cat Up Exh Flow Flt = NOT (EXF_TotExhCatUpFlt) AND - Ambient conditions always satisfied while engine running: Amb Press > 70.00 [KPa] AND Amb Temp > 253.00 [K] AND Catalyst monitor not yet performed successfully in current driving cycle (Catalyst monitor shall run only once per driving cycle) [Boolean] AND Intgr Post Inj Fuel Qnty > **CatCrtdMaxFuel** [g] AND HCI_DeHC_ExhInjDsbl = FALSE [Boolean];		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Main Catalyst Efficiency Below Threshold Bank 1	P0422	The Second Catalyst (UF DOC) monitor only runs during DPF regeneration and compares the UF DOC released oxidation heat and the exhaust-injected fuel quantity (by HCI) both evaluated inside a determined portion of the DPF regeneration itself. This comparison (ratio) produces an Aging Index that shall be greater than the efficiency threshold, in case of fresh (efficient) Second Catalyst. If, instead, the so calculated Aging Index is below the efficiency threshold, the diagnosis reports fail because the Second Catalyst is too much damaged to play well its role (conversion inefficiency detected) and shall be replaced. It is needed that exhaust-injection (by HCI) is enabled during UF DOC monitor in order to produce enough exothermic heat across the Second Catalyst to evaluate the component conversion efficiency in a reliable way.	Second Catalyst Aging Index < Threshold If - Second Catalyst EWMA filter enabling calibration = TRUE AND - Second Catalyst conversion inefficiency previously detected (Second Catalyst Fault Active = TRUE) Then: Second Catalyst Aging Index < Repass Threshold	Aging Index < **Cat2_CrtdEffThrsh** [Curve] If EWMA Enbl Cal = 0.00 [Boolean] AND Second Catalyst FA = CAT_Cat2_SysEffLoB1_FA Then: Aging Index < **Cat2CrtdEffRepEWMA** [Curve]	- Second Catalyst monitor enabling calibration = TRUE AND No active DTCs: - Second Catalyst up temperature estimation not in fault (Fault Flag = FALSE) AND - Second Catalyst down temperature sensor not in fault (Fault Flag = FALSE); Temperature Learning concluded: - Number of elapsed samples (task time = 100 [ms]) equal to calibration; **Second Catalyst monitor status is DISABLED if:** - DPF regeneration disabled OR - HCI system in fault (Fault Flag = TRUE) OR - Ambient temperature information in fault (Fault Active = TRUE) OR - Second Catalyst up exhaust flow estimation in fault (Fault Flag = TRUE)	Monitor Enbl Cal = 1.00 [Boolean] AND Cat2 Up Temp Estim Flt = NOT (EGT_TempCat2_UpFlt) AND Cat2 Dwn Temp Snsr Flt = NOT (EGT_SnsrCat2_DwnFlt); Samples nr. = 10.00 [Counter]; **Second Catalyst monitor status is DISABLED if:** DPF_DPF_St = SootLoading [Enumerative] OR HCI System Flt = HCI_GenericShtOffReq OR Amb Temp FA = CAT_OutsideTempFA OR Cat2 Up Exh Flow Flt = EXF_TotExhCat2_UpFlt	Task Time = 100 [ms] If - Second Catalyst EWMA filter enabling cailibration = FALSE (EWMA Enbl Cal = 0.00 [Boolean]) Then: 2 trips (with malfunction) to set DTC (Type B) If - Second Catalyst EWMA filter enabling cailibration = TRUE (EWMA Enbl Cal = 0.00 [Boolean]) AND - EWMA status = EWMA Standard Then: 1 trip (with malfunction) to set DTC (Type A) If - Second Catalyst EWMA filter enabling cailibration =	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		EWMA Filtering functionality (including Fast Initial Response (FIR), Rapid Response (RR) and EWMA Standard) is supported by the Second Catalyst (UF DOC) monitor.			OR - Ambient conditions not always satisfied while engine running: Ambient pressure lower than calibration OR Ambient temperature lower than calibration OR - Second Catalyst monitor already performed successfully in current driving cycle (Second Catalyst monitor shall run only once per driving cycle) OR HC unloading enabled; **Second Catalyst monitor status can move from DISABLED to TRIGGERED if:** - DPF regeneration enabled AND - HCI system not in fault (Fault Flag = FALSE) AND - Ambient temperature information not in fault (Fault Active = FALSE) AND - Second Catalyst up exhaust flow estimation not in fault (Fault Flag = FALSE) AND	OR - Ambient conditions not always satisfied while engine running: Amb Press < 70.00 [KPa] OR Amb Temp < 253.00 [K] OR Second Catalyst monitor already performed successfully in current driving cycle (Second Catalyst monitor shall run only once per driving cycle) [Boolean] OR HCI_DeHC_ExhInjDsbl = TRUE [Boolean]; **Second Catalyst monitor status can move from DISABLED to TRIGGERED if:** DPF_DPF_St ≠ SootLoading [Enumerative] AND HCI System Flt = NOT (HCI_GenericShtOffReq) AND Amb Temp FA = NOT (CAT_OutsideTempFA) AND Cat2 Up Exh Flow Flt = NOT (EXF_TotExhCat2_UpFlt) AND	TRUE (EWMA Enbl Cal = 0.00 [Boolean]) AND - EWMA status = Fast Initial Response (FIR) Then: - 1 trip (with malfunction) to set DTC (Type A) and return to EWMA status = EWMA Standard - 0.00 [Counter] elapsed trips (with no mulfunction) to report pass and return to EWMA status = EWMA Standard If - Second Catalyst EWMA filter enabling cailibration = TRUE (EWMA Enbl Cal = 0.00 [Boolean]) AND - EWMA status = Rapid Response (RR) Then: - 1 trip (with malfunction) to set DTC (Type A) and return to EWMA status =	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Ambient conditions always satisfied while engine running: Ambient pressure higher than calibration AND Ambient temperature higher than calibration AND - Second Catalyst monitor not yet performed successfully in current driving cycle (Second Catalyst monitor shall run only once per driving cycle) AND - If DPF regeneration has been interrupted in previous driving cycle or in current driving cycle Then: Engine coolant temperature lower than calibration AND - Second Catalyst up exhaust temperature (by estimation) lower than calibration; **Second Catalyst monitor status can move from TRIGGERED to ENABLED (oxidation heat release integrator and exhaust injected fuel (by HCl) integrator are both enabled) if:** - DPF regeneration	Ambient conditions always satisfied while engine running: Amb Press > 70.00 [KPa] AND Amb Temp > 253.00 [K] AND Second Catalyst monitor not yet performed successfully in current driving cycle (Second Catalyst monitor shall run only once per driving cycle) [Boolean] AND If Interrupted DPF regeneration counter > 0 [Counter] Then: Eng Cool Temp < 255.99 [°C] AND Cat2 Up Temp Estim < 1,500.00 [K]; **Second Catalyst monitor status can move from TRIGGERED to ENABLED (oxidation heat release integrator and exhaust injected fuel (by HCl) integrator are both enabled) if:** DPF_DPF_St ≠	EWMA Standard - 1 trip (with no mulfunction) to report pass - 0.00 [Counter] elapsed trips (with no mulfunction) to report pass and return to EWMA status = EWMA Standard	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					enabled AND - HCI system not in fault (Fault Flag = FALSE) AND - Ambient temperature information not in fault (Fault Active = FALSE) AND - Second Catalyst up exhaust flow estimation not in fault (Fault Flag = FALSE) AND Ambient conditions always satisfied while engine running: Ambient pressure higher than calibration AND Ambient temperature higher than calibration AND - Second Catalyst monitor not yet performed successfully in current driving cycle (Second Catalyst monitor shall run only once per driving cycle) AND - Second Catalyst up exhaust temperature (by estimation) higher than calibration AND - Exhaust injection (by HCI) enabled AND - Second Catalyst up exhaust flow estimation	SootLoading [Enumerative] AND HCI System Flt = NOT (HCI_GenericShtOffReq) AND Amb Temp FA = NOT (CAT_OutsideTempFA) AND Cat2 Up Exh Flow Flt = NOT (EXF_TotExhCat2_UpFlt) AND Ambient conditions always satisfied while engine running: Amb Press > 70.00 [KPa] AND Amb Temp > 253.00 [K] AND Second Catalyst monitor not yet performed successfully in current driving cycle (Second Catalyst monitor shall run only once per driving cycle) [Boolean] AND Cat2 Up Temp Estim > 0.00 [K] AND HCI_InjReleaseSt = TRUE [Boolean] AND Cat2 Up Exh Flow > 0.00 [g/s]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					higher than calibration AND - Exhaust injection fuel quantity (by HCl) higher than calibration; **Oxidation heat release integrator and exhaust injected fuel (by HCl) integrator are both frozen if:** - Engine not running OR - Second Catalyst up exhaust flow estimation lower than calibration OR - Exhaust injection fuel quantity (by HCl) lower than calibration; **Second Catalyst monitor status can move from ENABLED (oxidation heat release integrator and exhaust injected fuel (by HCl) integrator are both enabled) to DONE (integrators are stopped and the ratio between the total integrated oxidation heat and the total integrated injected fuel is performed with the consequent creation of the Second Catalyst Aging Index to be compared with the Fault Threshold --> Diagnostic test**	AND Exh Inj Fuel Qnty (by HCl) > 0.00 [g]; **Oxidation heat release integrator and exhaust injected fuel (by HCl) integrator are both frozen if:** - Engine not running OR Cat2 Up Exh Flow < 0.00 [g/s] OR Exh Inj Fuel Qnty (by HCl) < 0.00 [g]; **Second Catalyst monitor status can move from ENABLED (oxidation heat release integrator and exhaust injected fuel (by HCl) integrator are both enabled) to DONE (integrators are stopped and the ratio between the total integrated oxidation heat and the total integrated injected fuel is performed with the consequent creation of the Second Catalyst Aging Index to be compared with the Fault Threshold --> Diagnostic test**		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					evaluation trigger) if: - DPF regeneration enabled AND - HCI system not in fault (Fault Flag = FALSE) AND - Ambient temperature information not in fault (Fault Active = FALSE) AND - Second Catalyst up exhaust flow estimation not in fault (Fault Flag = FALSE) AND Ambient conditions always satisfied while engine running: Ambient pressure higher than calibration AND Ambient temperature higher than calibration AND - Second Catalyst monitor not yet performed successfully in current driving cycle (Second Catalyst monitor shall run only once per driving cycle) AND - Integrated exhaust injected fuel quantity (by HCI) higher than curve.	**evaluation trigger) if:** DPF_DPF_St ≠ SootLoading [Enumerative] AND HCI System Flt = NOT (HCI_GenericShtOffReq) AND Amb Temp FA = NOT (CAT_OutsideTempFA) AND Cat2 Up Exh Flow Flt = NOT (EXF_TotExhCat2_UpFlt) AND Ambient conditions always satisfied while engine running: Amb Press > 70.00 [KPa] AND Amb Temp > 253.00 [K] AND Second Catalyst monitor not yet performed successfully in current driving cycle (Second Catalyst monitor shall run only once per driving cycle) [Boolean] AND Intgr Exh Inj Fuel Qnty (by HCI) > **Cat2_CrtdMaxFuel** [g].		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Level Sensor 1 Performance (For use on vehicles with a single fuel tank)	P0461	This DTC will detect a primary fuel tank level sensor stuck in-range.	a) Sensed fuel volume change is b) while engine fuel consumption is	a) < 3 liters b) >= 38.22 liters	1. Diagnostic Enabled 2. Engine Operational State	1. == True 2. == Running	250 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Level Sensor 1 Circuit Low Voltage	P0462	This DTC will detect a primary fuel tank sensor stuck out-of-range low.	Fuel level Sender % of 5V range	< 10 % or 74.70 liters	a) Diagnostic enabled status b) Fuel Level Sensor Initialized status c) Fuel Level Sensor Data Available Status d) Communication faults status	a) == True b) == True c) == True d) <> True	100 failures out of 125 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Level Sensor 1 Circuit High Voltage	P0463	This DTC will detect a primary fuel tank level sensor stuck out-of-range high.	Fuel level Sender % of 5V range	> 60 % or 8.41 liters	a) Diagnostic enabled status b) Fuel Level Sensor Initialized status c) Fuel Level Sensor Data Available Status d) Communication faults status	a) == True b) == True c) == True d) <> True	100 failures out of 125 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cooling Fan 1 Relay Control Circuit Open (Output Driver Monitor) [Non- EREV]	P0480	Diagnoses the cooling fan 1 relay control low side driver circuit for circuit faults	Voltage low during driver off state (indicates open circuit)	Open Circuit: ≥ 200 K Ω impedance between signal and controller ground	Powertrain Relay Voltage	Voltage ≥ 11.00 volts	50.00 failures out of 63.00 samples 100 ms / sample	Type B, 2 Trips Note: In certain controllers P0691 may also set (Fan 1 Short to Ground).

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cooling Fan System Performance [Electro-Viscous Engine-Driven Fan Only]	P0483	Detects inability to control fan speed to desired RPM	Weighted filtered Cooling Fan Speed Differential [Measured - Commanded]	1. <= -500.00 RPM OR 2. >= 500.00 RPM	1. System Performance Test Triggered [FEAD_b_SysPerfTestTrig] 2. Commanded Cooling Fan Output Duty Cycle [FEAR_Pct_PWM_OutputDutyCycle] 3a. Intake Air Temp Sensor Fault Active [DTCs P0112, P0113, P1111, P1112] 3b. Engine Coolant Temp Sensor FA [DTCs P0116, P0117, P0118, P0119, P1114, P1115] 3c. Cooling Fan Speed Sensor Circuit FA [DTC P0526] 3d. Cooling Fan FOD_OutputDriver_FA 3e. Ignition Sw Position Run_Crank Circuit voltage 3f. Induction Air Temp 4. System Performance Test enabled 5. Fan Speed Total Weighting Filtered Factor Calculation [See Supporting Calculation and Tables] P0483 Calculation - Total	1. == TRUE 2. >= 5.00 % 3a. <> TRUE 3b. <> TRUE 3c. <> TRUE 3d. <> TRUE 3e. >= 11.00 volts 3f. >= -20.00 degC 4. == TRUE 5. > 0.60 [dimensionless]	Fail condtion present >= 600.00 ; 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Weighting Factor			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cooling Fan Speed High [Electro-Viscous Engine-Driven Fan Only]	P0495	Diagnoses the engine-driven cooling fan speed during OFF state against a rational speed accounting for inertia and ram-air flow effects	Measured Cooling Fan Speed	> Calculated Allowed Fan Drag Speed RPM	a) Diagnostic enabled b) Hydraulic Fan Clutch Pumped Out [FEAD_b_ClutchPumpedOut] c) Calculated Cooling Fan Speed [FEAD_n_FanDriveSpeed]	a) == TRUE b) == TRUE c) > 1,500.00 RPM	800.00 failures / 1,000.00 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Low Engine Speed Idle System	P0506	This DTC will determine if a low idle exists	Filtered Engine Speed Error	> 75.00 rpm	Baro	> 70 kPa	Diagnostic runs in every 12.5 ms loop	Type B, 2 Trips
			filter coefficient	0.00175	Coolant Temp	> KeSPDD_T_EnblECT_Min (60 °C) and < KfECTI_T_EngCoolHotHiThresh (120 °C) Must verify KfECTI_T_EngCoolHotLoThresh (118) is less than KfECTI_T_EngCoolHotHiThresh (120)	Diagnostic reports pass or fail in 10 seconds once all enable conditions are met	
					Engine run time	≥ 60 sec		
					Ignition voltage	32 ≥ volts ≥ 11		
					Time since gear change	≥ 3 sec		
					Time since a TCC mode change	> 3 sec		
					IAT	> -20 °C		
					Vehicle speed	≤ 1.24 mph		
					Commanded RPM delta	≤ 25 rpm		
					Idle time	> 5 sec		
					For manual transmissions: Clutch Pedal Position or Clutch Pedal Position	> 12.00 pct < 75.00 pct		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						PTO not active Transfer Case not in 4WD LowState Off-vehicle device control (service bay control) must not be active. following conditions not TRUE: (VeTESR_e_EngSpdReqIntvType = CeTESR_e_EngSpdMinLimit AND VeTESR_e_EngSpdReqRespType = CeTESR_e_NoSuggestion) Clutch is not depressed		
					No active DTCs	TC_BoostPresSnsrFA ECT_Sensor_FA EnginePowerLimited EGRValveCircuit_FA EGRValvePerformance_FA IAT_SensorCircuitFA EvapFlowDuringNonPurge_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA FuelInjectorCircuit_FA MAF_SensorFA EngineMisfireDetected_FA IgnitionOutputDriver_FA		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						TPS_FA TPS_Performance_FA VehicleSpeedSensor_FA FuelLevelDataFault LowFuelConditionDiagnostic Clutch Sensor FA AmbPresDfltdStatus P2771		
					All of the above met for Idle time	> 5 sec The diagnostic does not run during autostop as engine is shutdown during that time (occurs in a hybrid or 12v start stop vehicle)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
High Engine Speed Idle System	P0507	This DTC will determine if a high idle exists	Filtered Engine Speed Error	< -150.00 rpm	Baro	> 70 kPa	Diagnostic runs in every 12.5 ms loop	Type B, 2 Trips
			filter coefficient	0.00175	Coolant Temp	> KeSPDD_T_EnblECT_Min (60 °C) and < KfECTI_T_EngCoolHotHiThresh (120 °C) Must verify KfECTI_T_EngCoolHotLoThresh (118) is less than KfECTI_T_EngCoolHotHiThresh (120)	Diagnostic reports pass or fail in 10 seconds once all enable conditions are met	
					Engine run time	≥ 60 sec		
					Ignition voltage	32 ≥ volts ≥ 11		
					Time since gear change	≥ 3 sec		
					Time since a TCC mode change	> 3 sec		
					IAT	> -20 °C		
					Vehicle speed	≤ 1.24 mph		
					Commanded RPM delta	≤ 25 rpm		
					For manual transmissions: Clutch Pedal Position or Clutch Pedal Position	> 12.00 pct < 75.00 pct		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						PTO not active Transfer Case not in 4WD LowState Off-vehicle device control (service bay control) must not be active. following conditions not TRUE: (VeTESR_e_EngSpdReqIntvType = CeTESR_e_EngSpdMinLimit AND VeTESR_e_EngSpdReqRespType = CeTESR_e_NoSuggestion) Clutch is not depressed TC_BoostPresSnsrFA ECT_Sensor_FA EnginePowerLimited EGRValveCircuit_FA EGRValvePerformance_FA IAT_SensorCircuitFA EvapFlowDuringNonPurge_FA FuelTrimSystemB1_FA FuelTrimSystemB2_FA FuelInjectorCircuit_FA MAF_SensorFA EngineMisfireDetected_FA IgnitionOutputDriver_FA TPS_FA TPS_Performance_FA VehicleSpeedSensor_FA		
					No active DTCs			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					All of the above met for Idle time	FuelLevelDataFaultLow FuelConditionDiagnostic Clutch SensorFA AmbPresDfltdStatus P2771 > 5 sec The diagnostic does not run during autostop as engine is shutdown during that time (occurs in a hybrid or 12v start stop vehicle)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Oil Pressure (EOP) Sensor Circuit Low Voltage	P0522	Determines if the Engine Oil Pressure (EOP) Sensor circuit voltage is too low. This diagnostic compares the EOP circuit voltage to the reference voltage.	(Engine Oil Pressure Sensor Circuit Voltage) ÷ 5 Volts) *100	< 5.00 percent Deadband: < 5 percent or > 95 percent	Engine Speed Enable Engine Speed Disable Oil Pressure Sensor In Use Diagnostic Status	> 400 rpm < 350 rpm Yes Enabled	800 failures out of 1,000 samples Performed every 6.25 msec	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Oil Pressure (EOP) Sensor Circuit High Voltage	P0523	Determines if the Engine Oil Pressure (EOP) Sensor circuit voltage is too high. This diagnostic compares the EOP circuit voltage to the reference voltage.	(Engine Oil Pressure Sensor Circuit Voltage) ÷ 5 Volts) *100	> 95.00 percent Deadband: < 5 percent or > 95 percent	Oil Pressure Sensor In Use Diagnostic Status	Yes Enabled	800 failures out of 1,000 samples Performed every 6.25 msec	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cooling Fan Speed Sensor Circuit [Electro-Viscous Engine-Driven Fan Only]	P0526	Diagnoses the engine driven cooling fan speed sensor	Measured Cooling Fan Speed	< 4.00 RPM	a) Commanded Fan Output Duty Cycle [FEAR_Pct_PWM_Output DutyCycle] b) Diagnostic enabled c) Timer - Test Enable	a) >= 36.00 % b) == TRUE c) >= 2.00 seconds	900.00 failures / 1,200.00 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Air Conditioning High Side Pressure Sensor (HSPS) Circuit Low Voltage	P0532	Determines if the Air Conditioning High Side Pressure Sensor circuit voltage is too low	(AC High Side Pressure Sensor Circuit Voltage) ÷ 5 Volts) *100	< 2 percent	AC HSP Sensor Present Diagnostic Status	Yes Enabled	80 failures out of 100 samples Performed every 25 msec	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Air Conditioning High Side Pressure Sensor (HSPS) Circuit High Voltage	P0533	Determines if the Air Conditioning High Side Pressure Sensor circuit voltage is too high	(AC High Side Pressure Sensor Circuit Voltage) ÷ 5 Volts) *100	> 98 percent	AC HSP Sensor Present Diagnostic Status	Yes Enabled	80 failures out of 100 samples Performed every 25 msec	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.

Idle Control System - Fuel Quantity Lower Than Expected	P054E	This DTC detects if the fuel quantity of the torque forming pulses is lower than the expected fuel quantity request when the engine is idle. Depending on combustion mode and gear, different maps of fuel quantity thresholds can be used. Each map depends on engine speed and engine coolant temperature	Depending on Combustion Mode
			
			case **StrongExhGasWarmUp:**
			{
			transmission in Gear:
			Fuel quantity of the torque forming pulses
			
			transmission in Park/ Neutral:
			Fuel quantity of the torque forming pulses
			
			}
			
			case **SoftExhGasWarmUp:**
			{
			transmission in Gear:
			Fuel quantity of the torque forming pulses
				< 0.5* **P054E_IFM_MinFuelIdleV3_G** [mm^3] depending on engine speed and engine coolant temperature
				
				< 0.5* **P054E_IFM_MinFuelIdleV3_PN** [mm^3] depending on engine speed and engine coolant temperature
				
				< 0.5* **P054E_IFM_MinFuelIdleV2_G** [mm^3] depending on engine speed and engine coolant
					For enabling the monitor, all the following conditions must be satisfied continuously for more than
					
					Test enabled by calibration
					
					and current gear
					
					and depending on **Gear Selection Calibration =** CeFULR_e_InGearNeutralPark (
					CeFULR_e_InGear: transmission
					
					CeFULR_e_NeutralPark: transmission
					
					CeFULR_e_InGearNeutralPark: transmission)
					
					and engine speed
					
					and engine speed
						5.00 [s]
						
						1.00 [Boolean]
						
						unchanged
						
						in gear
						
						in park/neutral
						
						in gear and in park neutral
						
						> hysteresis(511.00 , 511.00 + 0.00)[rpm]
						
						<hysteresis(1,560.00 , 1,560.00 + 0.00)[rpm]
							200.00 failures out of 255.00 samples
							
							1 sample every cylinder firing event
								Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
				temperature	and			
			transmission in Park/ Neutral:		(			
			Fuel quantity of the torque forming pulses	< 0.5* **P054E_IFM_MinFuelIdleV2_PN** [mm^3] depending on engine speed and engine coolant temperature	OBD Coolant Enable Criteria	== TRUE		
					OR			
					engine coolant temperature	> hysteresis(-21.00 , -20.00) [°C]		
			}		)			
					and			
			case **HC unloading driving and park/neutral (HCS_DeHC_Drive || HCS_DeHC_Park):**		outside air temperature	> hysteresis(-21.00 , -20.00) [°C]		
			{		and			
			transmission in Gear:		vehicle speed	< 3.00 [kph]		
			Fuel quantity of the torque forming pulses	< 0.5* **P054E_IFM_MinFuelIdleHC_G** [mm^3] depending on engine speed and engine coolant temperature	and enabled in the combustion mode	**P054E_IFM_CombModesEnbl**		
					and Accelerator Pedal Position	<= 0.05 [%]		
			transmission in Park/ Neutral:		and Engine running	-		
			Fuel quantity of the torque forming pulses	< 0.5* **P054E_IFM_MinFuelIdleHC_PN** [mm^3] depending on engine speed and engine coolant temperature	and PTO_PTO_Active	== 0 [Boolean]		
					and Run Crank voltage	>= 11.00 [V]		
			}		and if the transmission is manual			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.

			default:
			{
			transmission in Gear:
			Fuel quantity of the torque forming pulses
			
			transmission in Park/ Neutral:
			Fuel quantity of the torque forming pulses
			
			}
				< 0.5* **P054E_IFM_MinFuelldleC1_G** [mm^3] depending on engine speed and engine coolant temperature
				
				< 0.5* **P054E_IFM_MinFuelldleC1_PN** [mm^3] depending on engine speed and engine coolant temperature
					(
					if the Gear is Neutral
					AND
					the clutch pedal position
					
					OR
					
					the clutch pedal position
					)
					
					NLT_Active
					
					and
					No active DTC's:
					
					Depending on the **OAT Source Calibration =** CeOATR_e_ECM_OAT_Sensor
					(
					CeOATR_e_NonOBD_NonECM_NonVICM:
					
					default:
					)
						> 0.00
						
						< 0.00
						
						==0 [Boolean]
						
						OAT_OAT_SnsrNonEmissFA
						
						OAT_PtEstFiltFA
						
						CrankSensor_TFTKO
						
						ECT_Sensor_FA
						
						Transmission Estimated Gear Validity
						
						VehicleSpeedSensor_FA
						
						AcceleratorPedalFailure
						
						ClutchPedalPosSensor_FA
						
						NLT_ActvErr
						
						(FUL_GenericInjSysFA
						AND
						FUL_GenericInjSysFlt
						)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.

Idle Control System - Fuel Quantity Higher Than Expected	P054F	This DTC detects if the fuel quantity of the torque forming pulse is higher than the expected fuel quantity request when the engine is idle. Depending on combustion mode and gear, different maps of fuel quantity thresholds can be used. Each map depends on engine speed and engine coolant temperature	Depending on Combustion Mode
			
			case **StrongExhGasWarmUp**:
			{
			transmission in Gear:
			Fuel quantity of the torque forming pulses
			
			transmission in Park/ Neutral:
			Fuel quantity of the torque forming pulses
			
			}
			
			case **SoftExhGasWarmUp:**
			{
			transmission in Gear:
			Fuel quantity of the torque forming pulses
				
				> 1.5* **P054F_IFM_MaxFuelIdleV3_G** [mm^3] depending on engine speed and engine coolant temperature
				
				> 1.5* **P054F_IFM_MaxFuelIdleV3_PN** [mm^3] depending on engine speed and engine coolant temperature
				
				> 1.5* **P054F_IFM_MaxFuelIdleV2_G** [mm^3] depending on engine speed and engine coolant temperature
					For enabling the monitor, all the following conditions must be satisfied continuously for more than
					
					Test enabled by calibration
					
					and
					current gear
					
					and
					depending on **Gear Selection Calibration =** CeFULR_e_InGearNeutralPark
					{
					CeFULR_e_InGear: transmission
					
					CeFULR_e_NeutralPark: transmission
					
					CeFULR_e_InGearNeutralPark: transmission
					}
					
					and
					engine speed
					
					and
					engine speed
					
					and
						5.00 [s]
						
						1.00 [Boolean]
						
						unchanged
						
						in gear
						
						in park/neutral
						
						in gear and in park neutral
						
						> hysteresis(511.00 , 511.00 + 0.00) [rpm]
						
						< hysteresis(1,560.00 , 1,560.00 + 0.00) [rpm]
							200.00 failures out of 255.00 samples
							
							1 sample every cylinder firing event
								Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			transmission in Park/ Neutral: Fuel quantity of the torque forming pulses	> 1.5* **P054F_IFM_MaxFuelIdleV2_PN** [mm^3] depending on engine speed and engine coolant temperature	{ OBD Coolant Enable Criteria	== TRUE		
					OR engine coolant temperature	> hysteresis(-21.00 , -20.00) [°C]		
			}		}			
			case **HC unloading driving and park/neutral (HCS_DeHC_Drive || HCS_DeHC_Park):** {		and outside air temperature	> hysteresis(-21.00 , -20.00) [°C]		
			transmission in Gear: Fuel quantity of the torque forming pulses	> 1.5* **P054F_IFM_MaxFuelIdleHC_G** [mm^3] depending on engine speed and engine coolant temperature	and vehicle speed	< 3.00 [kph]		
					and enabled in the combustion mode	**P054F_IFM_CombModesEnbl**		
					and Accelerator Pedal Position	<= 0.05 [%]		
					and Engine running	-		
			transmission in Park/ Neutral: Fuel quantity of the torque forming pulses	> 1.5* **P054F_IFM_MaxFuelIdleHC_PN** [mm^3] depending on engine speed and engine coolant temperature	and PTO_PTO_Active	== 0 [Boolean]		
					and Run Crank voltage	>= 11.00 [V]		
					and if the transmission is manual (			
			}		if the Gear is Neutral AND the clutch pedal position	> 0.00		
			default:					

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.

			{
			transmission in Gear:
			Fuel quantity of the torque forming pulses
			
			transmission in Park/ Neutral:
			Fuel quantity of the torque forming pulses
			
			}
				
				> 1.5* **P054F_IFM_MaxFuelIdleC1_G** [mm^3] depending on engine speed and engine coolant temperature
				
				> 1.5* **P054F_IFM_MaxFuelIdleC1_PN** [mm^3] depending on engine speed and engine coolant temperature
					OR
					
					the clutch pedal position
					)
					
					NLT_Active
					
					and
					No active DTC's:
					
					Depending on the **OAT Source Calibration =**
					CeOATR_e_ECM_OAT_Sensor
					{
					CeOATR_e_NonOBD_NonECM_NonVICM:
					
					default:
					}
						< 0.00
						
						==0 [Boolean]
						
						OAT_OAT_SnsrNonEmissFA
						
						OAT_PtEstFiltFA
						
						CrankSensor_TFTKO
						
						ECT_Sensor_FA
						
						Transmission Estimated Gear Validity
						
						VehicleSpeedSensor_FA
						
						AcceleratorPedalFailure
						
						ClutchPedalPosSensor_FA
						
						NLT_ActvErr
						
						(FUL_GenericInjSysFA
						AND
						FUL_GenericInjSysFlt
						)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
System Voltage Low	P0562	Detects a low 12V battery system. This diagnostic reports the DTC when battery voltage is low. Monitoring occurs when the engine speed is above a calibrated value.	System voltage low	Battery voltage <= 9.00	System voltage low diag enable = TRUE Run Crank voltage Engine speed >=	1.00 Voltage ≥ 6.00 volts 400.00	400 failures out of 500 samples 12.5 ms / sample	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
System Voltage High	P0563	Detects a high 12V battery system. This diagnostic reports the DTC when battery voltage is high.	System voltage high	Battery voltage >= 18.00	System voltage high diag enable = TRUE Run Crank voltage	1.00 Voltage ≥ 6.00 volts	400 failures out of 500 samples 12.5 ms / sample	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Mutil-Functon Switch Circuit	P0564	Detect when cruise control multi-function switch circuit (analog) voltage is in an invalid range	Cruise Control analog circuit voltage must be "between ranges" for greater than a calibratable period of time.	The cruise control analog voltage A/D count ratio is considerred to be "between ranges" when the ratio is measured in the following ranges: 0.28 -0.31, 0.415-0.445, 0.585 - 0.615 0.78 - 0.81, 1.005 - 1.035	CAN cruise switch diagnostic enable in ECM	1.00	fail continuously for greater than 0.500 seconds	Type C, No SVS , Emissions Neutral Diagnostics – special type C

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control On Switch Circuit	P0565	Detects a failure of the cruise on/off switch in a continously applied state	Cruise Control On switch remains applied for greater than a calibratable period of time.	fail continuously in the applied state for greater than 20.00 seconds	CAN cruise switch diagnostic enable in ECM	1.00	fail continuously for greater than 20.00 seconds	Type C, No SVS , Emissions Neutral Diagnostics – special type C

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Resume Circuit	P0567	Detects a failure of the cruise resume switch in a continously applied state	Cruise Control Resume switch remains applied for greater than a calibratable period of time.	fail continuously in the applied state for greater than 89.000 seconds	CAN cruise switch diagnostic enable in ECM	1.00	fail continuously for greater than 89.000 seconds	Type C, No SVS , Emissions Neutral Diagnostics – special type C

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Set Circuit	P0568	Detects a failure of the cruise set switch in a continously applied state	Cruise Control Set switch remains applied for greater than a calibratable period of time.	fail continuously in the applied state for greater than 89.000 seconds	CAN cruise switch diagnostic enable in ECM	1.00	fail continuously for greater than 89.000 seconds	Type C, No SVS , Emissions Neutral Diagnostics – special type C

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Cancel Switch Circuit	P056C	Detects a failure of the cruise cancel switch in a continously applied state	Cruise Control Cancel switch remains applied for greater than a calibratable period of time.	fail continously in the applied state for greater than 20.00 seconds	CAN cruise switch diagnostic enable in ECM	1.00	fail continuously for greater than 20.00 seconds	Type C, No SVS , Emissions Neutral Diagnostics – special type C

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Input Circuit	P0575	Determines if cruise switch state received from the BCM is valid.	If x of y rolling count / protection value faults occur, disable cruise for duration of fault	Message <> 2's complement of message Message rollling count<>previous message rolling count value plus one	Cruise Control Switch Serial Data Error Diagnostic Enable Serial communication to BCM Power Mode Engine Running	1.00 No loss of communication = RUN = TRUE	9 failures out of / 17 samples Performed on every received message 9 rolling count failures out of / 17 samples Performed on every received messagw	Type C, No SVS , Emissions Neutral Diagnostics – special type C

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Brake Pedal Position Sensor Circuit Range/ Performance	P057B	This diagnostic monitors the Brake Pedal Position Sensor for a stuck in range failure	.Brake pedal position sensor movement diagnostic cal is enabled 1.00	True	Brake Pedal Position Sensor Circuit Range / Performance Diagnostic Enable	1.00 ignition voltage > 10.00		MIL: Type A, 1 Trips
			Calculated EWMA value must be greater than calibratable theshold after calibratable number of tests have completed to report a "test passed" for P057B	EWMA value looked up in supporting table **P057B KtBRKI_K_FastTestPointWeight** P057B as a function of calculated brake pedal position delta EWMA value is > 0.80	calculated brake pedal position delta sample counter > 50.00 for fast test OR calculated brake pedal position delta sample counter > 1,000.00 for slow test	calculated brake pedal position delta > 4.24 OR (for slow test) shift lever has been in park once this key cycle vehicle speed >= 5.00 accelerator pedal position < 5.00	total number of EWMA tests > 20.00	
			Calculated EWMA Value must be less than calibratable threshold after calibratable number of tests have completed to report a "test failed" for P057B. This test runs once per key cycle	EWMA value looked up in supporting table **P057B KtBRKI_K_CmpltTestPointWeight** P057B as a function of calculated brake pedal position delta EWMA value is less thatn 0.40	no DTC's active (P057C, P057D)	shift lever has been in park once this key cycle vehicle speed >= 5.00 accelerator pedal position < 5.00	total number of EWMA tests > 2.00	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Brake Pedal Position Sensor Circuit Low	P057C	detects short to ground for brake pedal position sensor	If x of y samples are observed below failure threshold, default brake pedal position to zero percent.	5.00	Brake Pedal Position Sensore Low Voltage Diagnostic Enable	1.00	20 / 32.00 counts	MIL: Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Brake Pedal Position Sensor Circuit High	P057D	detects open circuit for brake pedal position sensor	If x of y samples are observed above failure threshold, default brake pedal position to zero percent and set DTC	95.00	Brake Pedal Position Sensore High Voltage Diagnostic Enable	1.00	20.00 / 32.00 counts	MIL: Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Brake Pedal Position Sensor Circuit Intermittent/ Erratic	P057E	detects noisy / erratic ouput for brake pedal position sensor	If x of y samples are observed above failure threshold, default brake pedal position to zero percent and set DTC	17.00	Brake Pedal Position Sensor Circuit Intermittent / Erratic Diagnostic Enable	1.00	5.00 / 20.00 counts	MIL: Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Multi-function Circuit Low Voltage	P0580	detects short to ground failure for cruise multi-function switch circuit	Cruise Control analog circuit voltage must be in an "Open Short To Ground" range for greater than a calibratable period of time.	The cruise control analog voltage A/D count ratio is considerred to be "open short to ground when the ratio is measured in the following rangs: 0 - 0.185	CAN cruise switch diagnostic enable in ECM	1.00	fail continuously for greater than 2.00 seconds	Type C, No SVS , Emissions Neutral Diagnostics – special type C

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Multi-function Circuit High Voltage	P0581	detects short to power failure for cruise multi-function switch circuit	Cruise Control analog circuit voltage must be in "Short To Power" range for greater than a calibratable period of time.	The cruise control analog voltage A/D count ratio is considered to be "short to power" when the ratio is measured in the following range: 1.005 - 1.035	CAN cruise switch diagnostic enable in ECM	1.00	fail continuously for greater than 2.00 seconds	Type C, No SVS ,Emissions Neutral Diagnostics – special type C

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Control Module Read Only Memory (ROM)	P0601	This DTC will be stored if the calibration check sum is incorrect or the flash memory detects an uncorrectable error via the Error Correcting Code.	The Primary Processor's calculated checksum does not match the stored checksum value. Covers all software and calibrations.	1 failure if the fault is detected during the first pass. 5.00 failures if the fault occurs after the first pass is complete.			Diagnostic runs continuously in the background.	Type A, 1 Trips
			The Primary Processor's Error Correcting Code hardware in the flash memory detects an error. Covers all software and calibrations.	254 failures detected via Error Correcting Code			Diagnostic runs continuously via the flash hardware.	
			The Primary Processor's calculated checksum does not match the stored checksum value for a selected subset of the calibrations.	2 consecutive failures detected or 5 total failures detected.			Diagnostic runs continuously. Will report a detected fault within 200 ms.	
			The Secondary Processor's calculated checksum does not match the stored checksum value. Covers all software and calibrations.	1 failure if the fault is detected during the first pass. 5 failures if the fault occurs after the first pass is complete.			Diagnostic runs continuously in the background.	
				In all cases, the failure count is cleared when controller shuts down				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
ECM Long Term Memory Reset	P0603	This DTC detects an invalid NVM which includes a Static NVM, Perserved NVM, ECC ROM in NVM Flash Region, and Perserved NVM during shut down.	Static NVM region error detected during initialization				Diagnostic runs at controller power up.	Type A, 1 Trips
			Perserved NVM region error detected during initialization				Diagnostic runs at controller power up.	
			ECC ROM fault detected in NVM Flash region ECC ROM Error Count >	 3			Diagnostic runs at controller power up.	
			Perserved NVM region error detected during shut down.				Diagnostic runs at controller power down.	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
ECM RAM Failure	P0604	Indicates that the ECM has detected a RAM fault. This includes Primary Processor System RAM Fault, Primary Processor Cache RAM Fault, Primary Processor TPU RAM Fault, Primary Processor Update Dual Store RAM Fault, Primary Processor Write Protected RAM Fault, and Secondary Processor RAM Fault. This diagnostic runs continuously.	Indicates that the primary processor is unable to correctly read data from or write data to system RAM. Detects data read does not match data written >=	254 counts			Will finish first memory scan within 30 seconds at all engine conditions - diagnostic runs continuously (background loop)	Type A, 1 Trips
			Indicates that the primary processor is unable to correctly read data from or write data to cached RAM. Detects data read does not match data written >=	254 counts			Will finish first memory scan within 30 seconds at all engine conditions - diagnostic runs continuously (background loop)	
			Indicates that the primary processor is unable to correctly read data from or write data to TPU RAM. Detects data read does not match data written >=	5 counts			Will finish first memory scan within 30 seconds at all engine conditions - diagnostic runs continuously (background loop)	
			Indicates that the primary processor detects a mismatch between the data and dual data is found during RAM updates. Detects a mismatch in data and dual data updates >	0.45891 s			When dual store updates occur.	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Indicates that the primary processor detects an illegal write attempt to protected RAM. Number of illegal writes are >	65,534 counts			Diagnostic runs continuously (background loop)	
			Indicates that the secondary processor is unable to correctly read data from or write data to system RAM. Detects data read does not match data written >=	5 counts			Will finish first memory scan within 30 seconds at all engine conditions - diagnostic runs continuously (background loop)	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Internal ECM Processor Integrity Fault	P0606	Indicates that the ECM has detected an internal processor integrity fault. These include diagnostics done on the SPI Communication as well as a host of diagnostics for both the primary and secondary processsors.	Loss or invalid message of SPI communication from the Secondary Processor at initialization detected by the Primary Processor or loss or invalid message of SPI communication from the Secondary Processor after a valid message was received by the Primary Processor	Loss or invalid message at initialization detected or loss or invalid message after a valid message was recieved	Run/Crank voltage Run/Crank voltage	>= 6.41 Volts or >= 11.00 Volts, else the failure will be reported for all conditions	In the primary processor, 159 / 399 counts intermittent or 39 counts continuous; 39 counts continuous @ initialization. 12.5 ms /count in the ECM main processor	Type A, 1 Trips
			Loss or invalid message of SPI communication from the Primary Processor at initialization detected by the Secondary Processor or loss or invalid message of SPI communication from the Primary Processor after a valid message was received by the Secondary Processor	Loss or invalid message at initialization detected or loss or invalid message after a valid message was recieved			In the secondary processor, 20 / 200 counts intermittent or 0.1875 s continuous; 0.4750 s continuous @ initialization. 12.5 ms /count in the ECM secondary processor	
			Checks for stack over or underflow in secondary processor by looking for corruption of known pattern at stack boundaries. Checks number of stack over/ under flow since last powerup reset >=	3		Test is Enabled: 1 (If 0, this test is disabled)	variable, depends on length of time to corrupt stack	
			MAIN processor is verified by responding to a seed sent from the secondary with a key response to secondary. Checks number of incorrect keys	2 incorrect seeds within 8 messages, 0.2000 seconds		ignition in Run or Crank	150 ms for one seed continually failing	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			received > or Secondary processor has not received a new within time limit					
			Time new seed not received exceeded			always running	0.450 seconds	
			MAIN processor receives seed in wrong order			always running	3 / 17 counts intermittent. 50 ms/count in the ECM main processor	
			2 fails in a row in the Secondary processor's ALU check			Test is Enabled: 1 (If 0, this test is disabled)	25 ms	
			2 fails in a row in the Secondary processor's configuration register masks versus known good data			Test is Enabled: 1 (If 0, this test is disabled)	12.5 to 25 ms	
			Secondary processor detects an error in the toggling of a hardware discrete line controlled by the MAIN processor: number of discrete changes > = or < = over time window(50ms)	7 17		Test is Enabled: 0 . (If 0, this test is disabled) time from initialization >= 0.4875 seconds	50 ms	
			Software background task first pass time to complete exceeds			Run/Crank voltage > 6.41	360.000 seconds	
			2 fails in a row in the MAIN processor's ALU check			Test is Enabled: 1 (If 0, this test is disabled)	25 ms	
			2 fails in a row in the MAIN processor's			Test is Enabled: 1	12.5 to 25 ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			configuration register masks versus known good data			(If 0, this test is disabled)		
			Checks number of stack over/under flow since last powerup reset >=	3		Test is Enabled: 1 (If 0, this test is disabled)	variable, depends on length of time to corrupt stack	
			Voltage deviation >	0.4950		Test is Enabled: 1 (If 0, this test is disabled)	5 / 10 counts or 0.150 seconds continuous; 50 ms/count in the ECM main processor	
			Checks for ECC (error correcting code) circuit test errors reported by the hardware for flash memory. Increments counter during controller initialization if ECC error occured since last controller initialization. Counter >=	3 (results in MIL), 5 (results in MIL and remedial action)		Test is Enabled: 1 (If 0, this test is disabled)	variable, depends on length of time to access flash with corrupted memory	
			Checks for ECC (error correcting code) circuit test errors reported by the hardware for RAM memory circuit. Increments counter during controller initialization if ECC error occured since last controller initialization. Counter >=	3 (results in MIL), 5 (results in MIL and remedial action)		Test is Enabled: 1 (If 0, this test is disabled)	variable, depends on length of time to write flash to RAMvariable, depends on length of time to write flash to RAM	
			MAIN processor DMA transfer from Flash to RAM has 1 failure			Test is Enabled: 0 (If 0, this test is disabled)	variable, depends on length of time to write flash to	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
							RAM	
			Safety critical software is not executed in proper order.	>= 1 incorrect sequence.		Test is Enabled: 1 (If 0, this test is disabled)	Fail Table, f(Loop Time). See supporting tables: **P0606_PSW Sequence Fail f (Loop Time)** / Sample Table, f (Loop Time)See supporting tables: **P0606_PSW Sequence Sample f(Loop Time)** counts 50 ms/count in the ECM main processor	
			MAIN processor determines a seed has not changed within a specified time period within the 50ms task.	Previous seed value equals current seed value.		Test is Enabled: 1 (If 0, this test is disabled)	Table, f(Loop Time). See supporting tables: **P0606_Last Seed Timeout f (Loop Time)**	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Starter Relay Control Circuit Open (Conventional)	P0615	Controller specific output driver circuit diagnoses the Starter relay (Conventional) high sided driver for an open circuit failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	 >= 200 KOhms impedance between signal and controller ground.	Starter control diag enable = TRUE Engine speed Run Crank voltage	1.00 0.00 RPM 11.00 volts	40 failures out of 50 samples 50 ms / sample	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Starter Relay Control Circuit Low Voltage (Conventional)	P0616	Controller specific output driver circuit diagnoses the Starter relay (Conventional) high sided driver for a short to ground failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	 <= 0.5 Ohms impedance between signal and controller ground	Starter control diag enable = TRUE Engine speed Run Crank voltage	1.00 0.00 RPM 6.41 volts	8 failures out of 10 samples 50 ms / sample	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Starter Relay Control Circuit High Voltage (Conventional)	P0617	Controller specific output driver circuit diagnoses the Starter Relay high sided driver for a short to power failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	<= 0.5 Ohms impedance between signal and controller power	Starter control diag enable = TRUE Engine speed Run Crank voltage	1.00 0.00 RPM 6.41 volts	40 failures out of 50 samples 50 ms / sample	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Internal Control Module Fuel Injector Control Performance	P062B	This DTC Diagnoses the internal fuel injector control module circuit for circuit faults. The following check are performed: - Chip initialization - Boost voltage - chip test - Code and Parameter - SPI error (SPI communication failed)	Driver Status OR (Driver Status for a number of samples)	== FAILED (chip test not passed OR Wrong download of microcode OR SPI error) == NOT INITIALIZED (chip not initialized OR Boost Voltage < 40.00) > 10 samples	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Boost Voltage has achieved (at least one time)	== 1 [Boolean] > 11.00 [V] - - 40.00 [V]	4 failures out of 8 samples 12.5 ms / sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Injector Driver Circuit Performance Bank 1	P062D	This DTC detects if there is: open circuit of the power supply line of the injector or Boost voltage fault or ECU internal fault The monitoring determines if the boost voltage is above a threshold or below another threshlod with hysteresis	Internal ECU Boost Voltage	> 60.00 [V] OR < hysteresis(40.00 , 41.00) [V]	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking	== 1 [Boolean] > 11.00 [V] - -	14 failures out of 20 samples 6.25 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Powertrain Internal Control Module EEPROM Error	P062F	This DTC detects a NVM long term performance. There are two types of diagnostics that run during controller power up. One for HWIO reports that writing to NVM (at shutdown) will not succeed, and the other HWIO reports the assembly calibration integrity check has failed.	HWIO reports that writing to NVM (at shutdown) will not succeed				Diagnostic runs at controller power up.	Type B, 2 Trips
			HWIO reports the assembly calibration integrity check has failed				Diagnostic runs at controller power up.	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
5 Volt Reference #1 Circuit	P0641	Detects a continuous or intermittent short on the 5 volt reference circuit #1 by monitoring the reference percent Vref1 and failing the diagnostic when the percent Vref1 is too low or too high or if the delta between the filtered percent Vref1 and non-filtered percent Vref1 is too large. This diagnostic only runs when battery voltage is high enough.	ECM percent Vref1 < or ECM percent Vref1 > or the difference between ECM filtered percent Vref1 and percent Vref1 >	4.875 % Vref1 5.125 % Vref1 0.0495 % Vref1	Diagnostic enabled AND [(Run/Crank voltage for Time period AND Starter engaged) OR (Run/Crank voltage AND Starter engaged)]	= 1 > 6.41 Volts = 0.02 Seconds = FALSE > 8.41 Volts = TRUE	19 / 39 counts; or 0.1875 sec continuous; 12.5 ms/count in main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Malfunction Indicator Lamp (MIL) Control Circuit (ODM) Open	P0650	Detects an inoperative malfunction indicator lamp control low side driver circuit. This diagnostic reports the DTC when an open circuit is detected.	Voltage low during driver off state (indicates open circuit)	Open circuit: ≥ 200 K Ω impedance between signal and controller ground	Run/Crank Voltage Remote Vehicle Start is not active	Voltage ≥ 11.00 volts	1 failures out of 1 samples 50 ms / sample	Type B, No MIL NO MIL Note: In certain controllers P263A may also set (MIL Control Short to Ground)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
5 Volt Reference #2 Circuit	P0651	Detects a continuous or intermittent short on the 5 volt reference circuit #2 by monitoring the reference percent Vref2 and failing the diagnostic when the percent Vref2 is too low or too high or if the delta between the filtered percent Vref2 and non-filtered percent Vref2 is too large. This diagnostic only runs when battery voltage is high enough.	ECM percent Vref2 < or ECM percent Vref2 > or the difference between ECM filtered percent Vref2 and percent Vref2 >	4.875 % Vref2 5.125 % Vref2 0.0495 % Vref2	Diagnostic enabled AND [(Run/Crank voltage for Time period AND Starter engaged) OR (Run/Crank voltage AND Starter engaged)]	= 1 > 6.41 Volts = 0.02 Seconds = FALSE > 8.41 Volts = TRUE	19 / 39 counts; or 0.1875 sec continuous; 12.5 ms/count in main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Shared High Side Drive #1 Control Circuit Low (STG) - (GEN III Controllers ONLY)	P0658	Controller specific output driver circuit diagnoses the shared high sided driver # 1 for a short to ground failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	- Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. - Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	≤ 0.5 Ω impedance between output and controller ground	Shared high side drive #1 low diag enable Powertrain relay voltage Run Crank voltage Powertrain relay state	= 1.0 >= 11.00 > 6.00 = ON	20 failures out of 25 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Shared High Side Drive #1 Control Circuit High (STP) - (GEN III Controllers ONLY)	P0659	Controller specific output driver circuit diagnoses the shared high sided driver # 1 for a short to power failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	- Voltage measurement outside of controller specific acceptable range during driver off state indicates short to power failure. - Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	≤ 0.5 Ω impedance between output and controller power	Shared high side drive #1 diag enable Powertrain relay voltage Run Crank voltage Powertrain relay state	= 1.0 >= 11.00 > 6.00 = ON	20 failures out of 25 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Powertrain Relay Control (ODM) Open	P0685	Detects an open circuit in the Powertrain Relay driver. This diagnostic reports the DTC when an open circuit failure is present. Monitoring occurs when the output is powered off. A decision is made by comparing a voltage measurement to a controller specific voltage threshold.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	Open Circuit: ≥ 200 K Ω ohms impedance between output and controller ground	Run/Crank Voltage	Voltage ≥ 11.00 volts	8 failures out of 10 samples 250 ms / sample	Type B, 2 Trips Note: In certain controllers P0686 may also set (Powertrain Relay Control Short to Ground).

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Powertrain Relay Control (ODM) Low	P0686	Detects a short to ground in the Powertrain Relay low side driver. This diagnostic reports the DTC when a short to ground failure is present. Monitoring occurs when the output is powered off. A decision is made by comparing a voltage measurement to a controller specific voltage threshold.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	Short to ground: ≤ 0.5 Ω impedance between output and controller ground	Run/Crank Voltage	Voltage ≥ 11.00 volts	8 failures out of 10 samples 250 ms / sample	Type B, 2 Trips Note: In certain controllers P0685 may also set (Powertrain Relay Control Open Circuit).

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Powertrain Relay Control (ODM) High	P0687	Detects a short to power in the Powertrain Relay low side driver. This diagnostic reports the DTC when a short to power failure is present. Monitoring occurs when the output is powered off. A decision is made by comparing a voltage measurement to a controller specific voltage threshold.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	Short to power: ≤ 0.5 Ω impedance between output and controller power	Run/Crank Voltage	Voltage ≥ 11.00 volts	8 failures out of 10 samples 250 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Control Module Power Relay Feedback Circuit Low Voltage	P0689	Detects low voltage in the control module relay feedback circuit. This diagnostic reports the DTC when low voltage is present. Monitoring occurs when run crank voltage is above a calibrated value.	Control module relay feedback circuit low voltage	Powertrain relay voltage <= 5.00	Powertrain relay short low diagnostic enable Run Crank voltage Powertrain relay state	= 1.00 > 9.00 = ON	5 failures out of 6 samples 1000 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Powertrain Relay Feedback Circuit High	P0690	Detects higher than expected voltage in the powertrain relay feedback circuit. This diagnostic reports the DTC when higher than expected voltage is present. For example, the powertrain relay could be stuck on. Monitoring occurs when the relay is commanded "off" for a calibrated duration.	Powertrain Relay Voltage	>= 4.00 volts will increment the fail counter	Powertrain relay commanded “OFF” No active DTCs:	>= 2.00 seconds PowertrainRelayStateOn_FA	50 failures out of 63 samples 100ms / Sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cooling Fan 1 Relay Control Circuit Low Voltage (Output Driver Monitor)	P0691	Diagnoses the cooling fan 1 relay control low side driver circuit for circuit faults	Voltage low during driver off state (indicates short-to-ground)	Short to ground: ≤ 0.5 Ω impedance between signal and controller ground	Powertrain Relay Voltage	Voltage ≥ 11.00 volts	50.00 failures out of 63.00 samples 100 ms / sample	Type B, 2 Trips Note: In certain controllers P0480 may also set (Fan 1 Open Circuit).

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cooling Fan 1 Relay Control Circuit High Voltage (ODM)	P0692	Diagnoses the cooling fan 1 relay control low side driver circuit for circuit faults	Voltage high during driver on state (indicates short to power)	Short to power: ≤ 0.5 Ω impedance between signal and controller power	Powertrain Relay Voltage	Voltage ≥ 11.00 volts	50.00 failures out of 63.00 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
5 Volt Reference #3 Circuit	P0697	Detects a continuous or intermittent short on the 5 volt reference circuit #3 by monitoring the reference percent Vref3 and failing the diagnostic when the percent Vref3 is too low or too high or if the delta between the filtered percent Vref3 and non-filtered percent Vref3 is too large. This diagnostic only runs when battery voltage is high enough.	ECM percent Vref3 < or ECM percent Vref3 > or the difference between ECM filtered percent Vref3 and percent Vref3 >	4.875 % Vref3 5.125 % Vref3 0.0495 % Vref3	Diagnostic enabled AND [(Run/Crank voltage for Time period AND Starter engaged) OR (Run/Crank voltage AND Starter engaged)]	= 1 > 6.41 Volts = 0.02 Seconds = FALSE > 8.41 Volts = TRUE	19 / 39 counts; or 0.1875 sec continuous; 12.5 ms/count in main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
5 Volt Reference #4 Circuit	P06A3	Detects a continuous or intermittent short on the 5 volt reference circuit #4 by monitoring the reference percent Vref4 and failing the diagnostic when the percent Vref4 is too low or too high or if the delta between the filtered percent Vref4 and non-filtered percent Vref4 is too large. This diagnostic only runs when battery voltage is high enough.	ECM percent Vref4 < or ECM percent Vref4 > or the difference between ECM filtered percent Vref4 and percent Vref4 >	4.875 % Vref4 5.125 % Vref4 0.0495 % Vref4	Diagnostic enabled AND [(Run/Crank voltage for Time period AND Starter engaged) OR (Run/Crank voltage AND Starter engaged)]	= 1 > 6.41 Volts = 0.02 Seconds = FALSE > 8.41 Volts = TRUE	19 / 39 counts; or 0.1875 sec continuous; 12.5 ms/count in main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Traction Control Torque Request Circuit	P0856	Determines if torque request from the EBTCM is valid	Serial Communication 2's complement message - ($1C7/$1C9 for engine torque, $1CA/$1C6 for axle torque)	Message <> 2's complement of message	Serial communication to EBTCM (U0108) Power Mode Engine Running Status of traction in GMLAN message ($4E9)	No loss of communication = Run = True = Traction Present	>= 6 failures out of 10 Performed on every received message	Type C, No SVS Safety Special Type C
			OR Serial Communication message ($1C7/$1C9 for engine torque, $1CA/ $1C6 for axle torque) rolling count index value	Message rolling count value <> previous message rolling count value plus one			6 rolling count failures out of 10 samples Performed on every received message	
			OR Too many minimum limit torque request transitions occur from TRUE to FALSE to TRUE within a time period	Requested torque intervention type toggles from not increasing request to increasing request			>= 3 multi-transitions out of 5 samples. Performed every 200 ms	
			Torque request greater than torque request diagnostic maximum threshold	> 250 Nm for engine torque based traction torque system, OR > 4,000 Nm for axle torque based traction torque system			>= 4 out of 10 samples Performed on every received message	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Control Module Sensor/ Switch Communication Circuit A Low	P1015	This monitor checks if the Reductant Control Module SENT Sensor protocol is out of range low	The SENT Message Rolling Pulse Count is provided to the ECM by the DEF-C via CAN bus. This monitor detects a Low Circuit Fault in the SENT Communication Circuit.	SENT Message Rolling Pulse Count sample equals to the previous sample AND Sent Circuit Low Error Message equals to TRUE	Engine in Cranking Phase Run/Crank is Active Powertrain relay voltage No loss of CAN communication DEF-C Controller not in initialization condition	FALSE TRUE > 11.00 V CAN_LostComm_FltN_BusB_DEF_C == FALSE TRUE	Time counter: 50.00 fails out of 62.00 samples Task = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Control Module Sensor/ Switch Communication Circuit A High	P1016	This monitor checks if the Reductant Control Module SENT Sensor protocol is out of range high	The SENT Message Rolling Pulse Count is provided to the ECM by the DEF-C via CAN bus. This monitor detects a High Circuit Fault in the SENT Communication Circuit.	SENT Message Rolling Pulse Count sample equals to the previous sample AND Sent Circuit High Error Message equals to TRUE	Engine in Cranking Phase Run/Crank is Active Powertrain relay voltage No loss of CAN communication DEF-C Controller not in initialization condition	FALSE TRUE > 11.00 V CAN_LostComm_FltN_BusB_DEF_C == FALSE TRUE	Time counter: 50.00 fails out of 62.00 samples Task = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Control Module Sensor/ Switch Communication Circuit A Performance	P1017	This monitor checks if the Reductant Control Module SENT Sensor protocol has performance problems	The SENT Message Rolling Pulse Count and the Reductant Quality Sensor SENT Message Age are provided to the ECM by the DEF-C via CAN bus. This monitor checks if the DEF-C recognizes an error in the SENT trasmission and if the age time is coherent with the Rolling Pulse Count increment.	At least one of the following conditions to be verified: 1. SENT Message Rolling Pulse Count sample is different from the previous sample AND Reductant Quality Sensor SENT Message Age > 1.00 s 2. A SENT Fault is present	Engine in Cranking Phase Run/Crank is Active Powertrain relay voltage No loss of CAN communication DEF-C Controller not in initialization condition No electrical fault on DEF Quality Sensor SENT circuit	FALSE TRUE > 11.00 V CAN_LostComm_FltN_BusB_DEF_C == FALSE TRUE DQMR_DEFQS_SENT_ElecFlt == FALSE	Time counter: 50.00 fails out of 62.00 samples Task = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF Quality Sensor 5V Supply Circuit Short to Ground	P1018	This diagnosis verifies DEF Quality Sensor 5V Supply Circuit pin for Short to Ground	The DEF QS 5V Supply Circuit Short to Ground flag is provided to the ECM by the DEF-C via CAN bus. This monitor checks if there is a short circuit to ground on DEF Quality Sensor 5V Supply Circuit pin.	DEF QS 5V Supply Circuit Short to Ground flag status == TRUE	Engine in Cranking Phase Run/Crank is Active Powertrain relay voltage No loss of CAN communication DEF-C Controller not in initialization condition No electrical fault on DEF Quality Sensor SENT circuit No performance fault on DEF Quality Sensor SENT circuit	FALSE TRUE > 11.00 V CAN_LostComm_FltN_BusB_DEF_C == FALSE TRUE DQMR_DEFQS_SENT_ElecFA == FALSE DQMR_DEFQS_SENT_PerfFA == FALSE	Time counter: 40.00 fails out of 50.00 samples Task = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF Quality Sensor 5V Supply Circuit Short to Battery	P1019	This diagnosis verifies DEF Quality Sensor 5V Supply Circuit pin for Short to Battery	The DEF QS 5V Supply Circuit Short to Battery flag is provided to the ECM by the DEF-C via CAN bus. This monitor checks if there is a short circuit to battery on DEF Quality Sensor 5V Supply Circuit pin.	DEF QS 5V Supply Circuit Short to Battery flag status == TRUE	Engine in Cranking Phase Run/Crank is Active Powertrain relay voltage No loss of CAN communication DEF-C Controller not in initialization condition No electrical fault on DEF Quality Sensor SENT circuit No performance fault on DEF Quality Sensor SENT circuit	FALSE TRUE > 11.00 V CAN_LostComm_FltN_BusB_DEF_C == FALSE TRUE DQMR_DEFQS_SENT_ElecFA == FALSE DQMR_DEFQS_SENT_PerfFA == FALSE	Time counter: 40.00 fails out of 50.00 samples Task = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF Quality Sensor Return Circuit Short to Battery	P101A	This diagnosis verifies DEF Quality Sensor Return Circuit pin for Short to Battery	The DEF QS Ground Circuit Short to Battery flag is provided to the ECM by the DEF-C via CAN bus. This monitor checks if there is a short circuit to battery on DEF Quality Sensor Return Circuit pin.	DEF QS Ground Circuit Short to Battery flag status == TRUE	Engine in Cranking Phase Run/Crank is Active Powertrain relay voltage No loss of CAN communication DEF-C Controller not in initialization condition No electrical fault on DEF Quality Sensor SENT circuit No performance fault on DEF Quality Sensor SENT circuit	FALSE TRUE > 11.00 V CAN_LostComm_FltN_BusB_DEF_C == FALSE TRUE DQMR_DEFQS_SENT_ElecFA == FALSE DQMR_DEFQS_SENT_PerfFA == FALSE	Time counter: 40.00 fails out of 50.00 samples Task = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Pump Driver High Temperature	P103F	This diagnosis verifies that the Motor Mosfet Driver Temperature is too High	Motor Mosfet Driver Temperature too High Error status == FAULT	VeSCRR_e_PmpDrvrHiTemp == FAULT	Test enabled by calibration Key on (OR engine running) Engine is not cranking Battery voltage No loss of CAN communication Motor Mosfet Driver Temperature too High Error status provided by DEF control module different from INDETERMINATE	1.00 [Boolean] > 11.00 [V] U010E, Lost Communication With Reductant Control Module	40.00 failures out of 50.00 samples Time basis = 100ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Pump A Control Circuit Shorted	P1040	This diagnosis verifies that the DEF pump phases are shorted	Motor Pump Phases Shorted Error status provided by DEF control module == FAULT	VeSCRR_e_PmpMtrShorted==FAULT	Test enabled by calibration Key on (OR engine running) Engine is not cranking Battery voltage No loss of CAN comunication Motor Pump Phases Shorted Error status provided by DEF control module different from indeterminate	1.00 > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR)	20.00 failures out of 25.00 samples Time basis = 100ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Injection Valve Supply Voltage Circuit Low Bank 1 Unit 1	P1048	This diagnosis verifies if a DEF dosing valve high side short to ground occurred	HWIO interface DEFMV_ENABLE_GROUND_SHORT = Fault	VeHWIO_e_DEFMV_Enbl_Gsht == CeSCRR_e_Fault	Test enabled by calibration Key on (OR engine running) Engine is not cranking Battery voltage HWIO interface DEFMV_ENABLE_GROUND_SHORT different from INDETERMINATE	1.00 > 11.00 [V]	30.00 failures out of 60.00 samples Time basis = 100ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Injection Valve Supply Voltage Circuit High Bank 1 Unit 1	P1049	This diagnosis verifies if a DEF dosing valve high side short to power occurred	HWIO interface DEFMV_ENABLE_POWER_SHORT = Fault	VeHWIO_e_DEFMV_Enbl_Psht == CeSCRR_e_Fault	Test enabled by calibration Key on (OR engine running) Engine is not cranking Battery voltage HWIO interface DEFMV_ENABLE_POWER_SHORT different from INDETERMINATE	1.00 > 11.00 [V]	30.00 failures out of 60.00 samples Time basis = 100ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Heater 1 Driver Over Temperature Fault	P1051	This diagnosis verifies if the driver of the DEF tank heater is affected by overtemperature	Tank Heater driver over temperature flag reports a fail	VeSCRR_e_HeatA_OverTemp == CeSCRR_e_fault	Test enabled by calibration Temperature used by the heating strategy to switch on the heaters Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN communication DEF Temperature sensor not in fault Tank Heater driver over temperature flag different from INDETERMINATE	1.00 < 60.00 [°C] > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR) (GetCANR_b_LostComm_FltN= FALSE) SCR_DEFTS_FA == FALSE	8.00 failures out of 10.00 samples Time basis = 500ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Heater 2 Driver Over Temperature Fault	P1052	This diagnosis verifies if the driver of the DEF dosing line heater is affected by overtemperature	Line Heater driver over temperature flag reports a fail	VeSCRR_e_HeatB_OverTemp == CeSCRR_e_fault	Test enabled by calibration Temperature used by the heating strategy to switch on the heaters Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN communication Line Heater driver over temperature flag different from INDETERMINATE	1.00 == TRUE < 60.00 > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR)	8.00 failures out of 10.00 samples Time basis = 500ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Pump A Speed Low	P105A	This diagnosis verifies that the DEF pump rotor is stalled	DEF pump commanded to move forward or reverse AND DEF Pump Motor speed within calibrated range	VeSCRR_n_PmpMtrSpd > -650.00 AND VeSCRR_n_PmpMtrSpd < 650.00	Test enabled by calibration Engine is not cranking Battery voltage Key on (OR engine running) PWM_pump_command not in fault DEF motor pump not in fault No loss of CAN communication Tank Defrost phase completed DEF pump commanded to move forward or reverse	1.00 > 11.00 [V] SCR_DEF_PumpCmdFA == FALSE SCR_DEFPM_FA == FALSE U010E, Lost Communication With Reductant Control Module (SCR) pct duty cycle inside: (39.00 ; 81.00) [%] or (11.00 ; 31.00)[%]	160.00 failures out of 200.00 samples Time basis = 25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Injector Temperature - Exhaust Gas Temperature Not Plausible	P10D1	This monitor measures the temperature of DEF injector coil and compares to reference temperature after long soak.	Difference between coil temperature and reference temperature greater than calibratable value.	> 55.00	Test enabled by calibration (TRUE->Enable False -> Disable) DEF Injector Fault State (No fault on injector) Powertrain relay in range Long Engine off soak period has elapsed (sec) Service Test Run/Crank is Active Engine in Cranking Phase Powertrain Relay in-Range Diag System Disable Coil Temp Rationality Diag Inhibited Coil Temperature Estimation Available	1.00 == FALSE == TRUE >= 28,800.00 == FALSE == TRUE == FALSE == TRUE == FALSE == FALSE == TRUE	Single decision criteria. Function Task: 25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Coolant Temperature Sensor Not Plausible	P111E	This DTC detects either a biased high or low ECT (Engine Coolant temperature) sensor. This is done by comparing the ECT sensor output to two other temperature sensor outputs after a soak condition.	**Sensor usage definitions:** **Sensor1 =** CeECTR_e_ECT_Snsr (Sensor1 is the temp sensor most impacted by the block heater (if equipped)) **Sensor2 =** CeECTR_e_IAT_Snsr **Sensor3 =** CeECTR_e_OAT_Snsr ========== A failure will be reported if any of the following occur: 1) Sensor1 power up absolute temp difference to Sensor2 and Sensor3 is (Sensor1 fast fail) . 2) Sensor1 power up temp is greater than Sensor2 and Sensor3 in this range: (and a block heater has not been detected) 3) Sensor1 power up temp is lower than Sensor2 and Sensor3 by this amount: 4) Sensor1 power up temp is ≥ Sensor2 and	 ≥ 60.0 ºC ≥ 20.0 and < 60.0 ºC ≤ 20.0 Deg ºC	No Active DTC's Engine Off Soak Time Propulsion Off Soak Time Non-volatile memory initization Test complete this trip Test aborted this trip Test disabled this trip Ambient LowFuelCondition Diag ========== Block Heater detection is **enabled** when either of the following occurs: 1) Sensor1 power up temp is greater than Sensor2 and Sensor3 in this range: 2) Cranking time ==========	VehicleSpeedSensor_FA IAT_SensorCircuitFA THMR_RCT_Sensor_Ckt_FA ECT_Sensor_Ckt_FA EngineModeNotRunTimerError EngineModeNotRunTimer_FA OAT_PtEstFiltFA OAT_PtEstRawFA PSAR_PropSysInactveCrs_FA DRER_DiagSystemDsbl > 28,800 seconds > 25,200 seconds = Not occurred = False = False = False ≥ -9 ºC = False ========== ≥ 20.0 ºC and < 60.0 ºC < 14.0 Seconds ==========	1 failure to set DTC 1 sec/ sample Once per valid cold start	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Sensor3 by 20.0 ºC and the time spent cranking the engine without starting is ≥ 14.0 seconds with the LowFuelConditionDiag	= False	Block Heater is **detected** and diagnostic is aborted when 1) or 2) occurs. 1a) IAT monitoring is enabled after the following Vehicle drive constraints 1b) Drive time 1c) Vehicle speed 1d) Additional Vehicle drive time is provided to 1b when Vehicle speed is below 1c as follows: 1e) IAT drops from power up IAT 2a) ECT monitoring is enabled after engine start in the following engine run time window 2b) Sensor1 temp derivative during the test is: 2c) Consectutive samples of 2b) being true are: ========== Diagnostic is **aborted** when 3) or 4) occurs: 3) Engine run time with vehicle speed below 1b 4) Engine off time (i.e. auto stop) during Block heater detection	 > 400 Seconds with > 14.9 MPH and 1.00 times the seconds with vehicle speed below 1b ≥ 8.0 ºC 1.0 <= seconds <= 40.0 < -0.04 ºC/sec ≥ 4 samples ========== ≥ 1,800 Seconds ≥ 300.0 Seconds		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 O2 Reference Voltage Circuit	P115E	This diagnosis verifies Upstream NOx gen3 sensor O2 binary reference voltage pin for Open Load Circuit	Check if there is an open circuit on NOx Sensor 1 O2 Binary reference voltage (P+ pin)	open circuit on P+ pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 O2 Reference Voltage Circuit Low Voltage	P115F	This diagnosis verifies Upstream NOx gen3 sensor binary reference voltage pin for Short to Ground	Check if there is a short circuit to ground on NOx Sensor 1 O2 Binary reference voltage (P+ pin)	groundshort on P+ pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 O2 Reference Voltage Circuit High Voltage	P1160	This diagnosis verifies Upstream NOx gen3 sensor binary reference voltage pin for Short to Battery	Check if there is a short circuit to power supply on NOx Sensor 1 O2 Binary reference voltage (P+ pin)	powershort on P+ pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 O2 Signal Circuit	P116A	This diagnosis verifies Upstream NOx gen3 sensor linear lambda circuit pin for Open Load Circuit	Check if there is an open circuit on NOx Sensor 1 O2 Linear pin (P-)	open circuit on P- pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 O2 Signal Circuit Low Voltage	P116B	This diagnosis verifies Upstream NOx gen3 sensor linear lambda circuit pin for Short to Ground	Check if there is a short circuit to ground on NOx Sensor 1 O2 Linear pin (P-)	groundshort on P- pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 O2 Signal Circuit High Voltage	P116C	This diagnosis verifies Upstream NOx gen3 sensor linear lambda circuit pin for Short to Battery	Check if there is a short circuit to power supply on NOx Sensor 1 O2 Linear pin (P-)	powershort on P- pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 O2 Pump Current Control Circuit	P116D	This diagnosis verifies Upstream NOx gen3 sensor O2 reference circuit pin for Open Load Circuit	Check if there is an open circuit on NOx Sensor 1 O2 Reference pin(M1, auxiliary pumping current)	open circuit on M1 pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 O2 Pump Current Control Circuit Low Voltage	P116E	This diagnosis verifies Upstream NOx gen3 sensor O2 reference circuit pin for Short to Ground	Check if there is a short circuit to ground on NOx Sensor 1 O2 Reference pin (M1, auxiliary pumping current)	groundshort on M1 pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 O2 Pump Current Control Circuit High Voltage	P116F	This diagnosis verifies Upstream NOx gen3 sensor O2 reference circuit pin for Short to Battery	Check if there is a short circuit to power supply on NOx Sensor 1 O2 Reference pin (M1, auxiliary pumping current)	powershort on M1 pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 O2 Low Reference Circuit	P1192	This diagnosis verifies Upstream NOx gen3 sensor Low Reference Circuit for Open Load Circuit	Check if there is an open circuit on NOx Sensor 1 Low Reference pin (Ref)	open circuit on Ref pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 O2 Low Reference Circuit Low Voltage	P1193	This diagnosis verifies Upstream NOx gen3 sensor Low Reference Circuit for Short to Ground	Check if there is an short circuit to ground on NOx Sensor 1 Low Reference pin (Ref)	groundshort on Ref pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 O2 Low Reference Circuit High Voltage	P1194	This diagnosis verifies Upstream NOx gen3 sensor Low Reference Circuit for Short to Battery	Check if there is an short circuit to power supply on NOx Sensor 1 Low Reference pin (Ref)	powershort on Ref pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 Signal Circuit	P119A	This diagnosis verifies Upstream NOx gen3 sensor NOx Circuit for Open Load Circuit	Check if there is an open circuit on NOx Sensor 1 NOx-related measurement pin (M2)	open circuit on M2	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 Signal Circuit Low Voltage	P119B	This diagnosis verifies Upstream NOx gen3 sensor NOx Circuit for Short to Ground	Check if there is a short circuit to ground on NOx Sensor 1 NOx-related measurement pin (M2)	groundshort on M2 pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 Signal Circuit High Voltage	P119C	This diagnosis verifies Upstream NOx gen3 sensor NOx Circuit for Short to Battery	Check if there is a short circuit to power supply on NOx Sensor 1 NOx-related measurement pin (M2)	powershort on M2 pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 Signal Circuit	P119D	This diagnosis verifies Downstream NOx gen3 sensor NOx Circuit for Open Load Circuit	Check if there is an open circuit on NOx Sensor 2 NOx-related measurement pin (M2)	open circuit on M2 pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 Signal Circuit Low Voltage	P119E	This diagnosis verifies Downstream NOx gen3 sensor NOx Circuit for Short to Ground	Check if there is a short circuit to ground on NOx Sensor 2 NOx-related measurement pin (M2)	groundshort on M2 pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 Signal Circuit High Voltage	P119F	This diagnosis verifies Downstream NOx gen3 sensor NOx Circuit for Short to Battery	Check if there is a short circuit to power supply on NOx Sensor 2 NOx-related measurement pin (M2)	powershort on M2 pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 O2 Reference Voltage Circuit	P11BE	This diagnosis verifies Dowstream NOx gen3 sensor binary reference voltage pin for Open Load Circuit	Check if there is an open circuit on NOx Sensor 2 O2 Binary reference voltage (P+ pin)	open circuit on P+ pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:P30B5	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 O2 Reference Voltage Circuit Low Voltage	P11BF	This diagnosis verifies Downstream NOx gen3 sensor binary reference voltage pin for Short to Ground	Check if there is a short circuit to ground on NOx Sensor 2 O2 Binary reference voltage (P+ pin)	groundshort on P+ pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 O2 Reference Voltage Circuit High Voltage	P11C0	This diagnosis verifies Downstream NOx gen3 sensor binary reference voltage pin for Short to Battery	Check if there is an short circuit to power supply on NOx Sensor 2 O2 Binary reference voltage (P+ pin)	powershort on P+ pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached P30B5No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 Heater Ground Circuit	P11C5	This diagnosis verifies Upstream NOx gen3 sensor heater ground circuit open	Check if there is an open circuit on NOx Sensor 1 heater reference pin (H-)	open circuit on H- pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 Heater Ground Circuit High Voltage	P11C6	This diagnosis verifies Upstream NOx gen3 sensor heater ground circuit Short to Battery	Check if there is short circuit to power supply on NOx Sensor 1 heater reference pin (H-)	powershort on H-	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 Heater Ground Circuit	P11C7	This diagnosis verifies Downstream NOx gen3 sensor heater ground circuit open	Check if there is an open circuit on NOx Sensor 2 heater reference pin (H-)	open circuit on H- pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 Heater Ground Circuit High Voltage	P11C8	This diagnosis verifies Dowmstream NOx gen3 sensor heater ground circuit Short to Battery	Check if there is a short circuit to power on NOx Sensor 2 heater reference pin (H-)	powershort on H- pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Performance - Signal Low Bank 1 Sensor 1	P11CC	This diagnosis verifies the plausibility of Upstream NOx sensor signal	Check if (Upstream NOx Sensor signal - NOx Model)/NOx Model with EWMA filter is above or below two calibratable thresholds	< -50 % OR > 125.00 %	Engine is running Powertrain relay voltage No failure on any NOx model inputs Injection small quantity adjustment (SQA) learning is not active No failure on NOx1 CAN communication No electrical failure on NOx1 Sensor No out of range low failure on NOx1 Sensor No out of range high failure on NOx1 Sensor No current control failure on NOx1 Sensor No offset failure on NOx1 Sensor No increasing dynamic failure on NOx1 Sensor No decreasing dynamic failure on NOx1 Sensor	TRUE > 11.00 V EXM_NOxMdl_ExhMnfdNotVld ==FALSE FAD_SQA_LrnET_Enbl ==FALSE CAN_LostComm_FltN_BusB_NOxSnsr_A ==FALSE NOX_Snsr1_FltSt ==FALSE NOX_NOx1_OutOfRngLoFlt ==FALSE NOX_NOx1_OutOfRngHiFlt ==FALSE NOX_NOx1_StBitChkFlt ==FALSE NOX_NOx1_OfstMontrFlt ==FALSE NOX_NOx1_IncrDynChkFlt ==FALSE NOX_NOx1_DecrDynChkFlt ==FALSE	Test per trip: 1 If Fast Initial Response EWMA is active then 1 test per trip are allowed If Rapid Response EWMA is active then 1 test per trip are allowed The signal for the monitor check is calculated at first collecting and averaging 200.00 samples, than filtering the resulting mean value by means of a first-order filter. The filter gain calibration (1) can assume the following values: - 0.65 if FIR is active - 0.65 if RR is active - 0.25 if neither FIR and RR are active	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No DTC set:	P30B4	(1) The EWMA filter is active if the filter gain is calibrated with a value lower than 1, otherwise EWMA filter is cal-out.	
					No failure on outside air temperature Sensor	OAT_PtEstFiltFA ==FALSE		
					No failure on ambient air temperature Sensor	AmbPresDfltdStatus ==FALSE		
					no falut on upstream catalyst exhaust pressure model inputs	EGP_PresCatUpFlt ==FALSE		
					No failure on engine coolant temperature Sensor	ECT_Sensor_FA ==FALSE		
					No failure on injectors	FUL_GenericInjSysFlt ==FALSE		
					No failure on high pressure fuel rail system	FHP_InjLeakageFA ==FALSE		
					No failure on intake manifold absolute pressure Sensor	MAP_SensorFA==FALSE		
					Modeled Engine Out NOx concentration	> 100 ppm		
					Steady state detection: a) Modeled Engine Out NOx concentration step at 100 ms.	< 5 ppm		
					b) condition a) is fulfilled for time	> 5.00 sec		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Ambient air pressure	> 75 kPa < 120 kPa		
					Outside air temperature	> -20 °C < 80 °C		
					Combustion mode dependent enabling flag	**NOX_S1_PlausChkEnblCmbMode**		
					Intake manifold absolute pressure	< 250 kPA		
					Injection fuel quantity requested	For normal combustion mode: > 17.00 mm^3 < 50.00 mm^3 For other combustion modes: > 17 mm^3 < 50 mm^3		
					Engine speed	For normal combustion mode: > 1,500 rpm < 2,000 rpm For other combustion modes: > 1,500 rpm < 2,000 rpm		
					Engine coolant temperature	> 70 °C < 120 °C		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Sensor dewpoint is reached Diagnostic test results during EWMA FIR mode	TRUE < 1		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 O2 Signal Circuit	P11D0	This diagnosis verifies Dowstream NOx gen3 sensor O2 reference circuit pin for Open Load Circuit	Check if there is an open circuit on NOx Sensor 2 O2 Linear pin (P-)	open circuit on P-	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 O2 Signal Circuit Low Voltage	P11D1	This diagnosis verifies Downstream NOx gen3 sensor linear lambda circuit pin for Short to Ground	Check if there is a short circuit to ground on NOx Sensor 2 O2 Linear pin (P-)	groundshort on P- pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 O2 Signal Circuit High Voltage	P11D2	This diagnosis verifies Downstream NOx gen3 sensor linear lambda circuit pin for Short to Battery	Check if there is a short circuit to power supply on NOx Sensor 2 O2 Linear pin (P-)	powershort on P- pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Offset Learning At Min Limit - Bank 1 Sensor 1	P11D3	This diagnosis verifies if Upstream NOx sensor raw signal is affected by an offset	Check if NOx1 signal has an offset by learning the raw value in stable conditions during fuel cut off maneuver. A fault is detected if one of the following conditions is true: 1. Mean of all NOx sensor readings (where every reading is the mean value of a sampling window) OR 2. Mean of all NOx sensor readings (where every reading is the mean value of a sampling window)	< -20.00 ppm > 50.00 ppm	Combustion mode dependent enabling flag Engine is running Engine is not cranking Powertrain relay voltage NOx Sensor Bus relay is commanded ON Upstream NOx Sensor is present in the exhaust Sensor heater is in range: a) (Sensor heater raw resistance - sensor heater target resistance) / sensor heater target resistence b) condition a) is fulfilled for time Sensor supply in range Sensor dewpoint is reached Injection small quantity adjustment (SQA) learning is not active EGR measured position Exhaust mass flow is within a range DEF injection is within a range Engine speed is within a	**NOX_S1_OfstMntrEnblCmbMode** TRUE TRUE > 11.00 V TRUE TRUE < 0.03 % > - 0.03 % > 10.00 sec > 10.80 V TRUE FAD_SQA_LrnET_Enbl ==FALSE < 100.00 % < 75.00 g/s > 0.00 g/s < 150.00 mg/s > -1.00 mg/s < 3,500.00 rpm	The monitor runs after fuel cut off maneuver, when air mass integral exceeds 0.00 g and Upstream NOx signal is stable for at least 0.00 s. The NOx value used for the monitor is calculated after sampling up to 35.00 sampling windows (each one made up of 10.00 samples), averaging the mean values of every window. Once computed this value, the diagnostic provides a result. Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					range	> 0.00 rpm		
					Upstream NOx sensor temperature is within a range	< 600.00 °C > 200.00 °C		
					Fuel request is steady state when all the following conditions are verified: a) Fuel request derivative b) Fuel request within a range c) conditions a) and b) are fulfilled for a time	 < 0.01 mm^3/s < 0.10 mm^3 > -1.00 mm^3 > 2.00 s		
					Intake manifold absolute pressure	< 950.00 kPa		
					No failure on intake manifold absolute pressure sensor	MAP_SensorFA==FALSE NOX_Snsr1_FltSt ==FALSE		
					No electrical failure on NOx1 sensor	NOX_NOx1_StBitChkFlt ==FALSE		
					No current control failure on NOx1 sensor	NOX_NOx1_OutOfRngLo Flt ==FALSE		
					No out of range low failure on NOx1 sensor	NOX_NOx1_OutOfRngHi Flt ==FALSE		
					No out of range high failure on NOx1 sensor	NOX_NOx1_NOxPlausFlt ==FALSE		
					No failure on NOx1 sensor signal plausibility	NOX_NOx1_DynChkFlt ==FALSE		
					No failure on NOx1 CAN communication	CAN_LostComm_FltN_Bu sB_NOxSnsr_A		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						==FALSE		
					No failure on EGR valve actuator	EGR_PstnShtOffReqFA ==FALSE		
					No failure on high pressure fuel rail system	FHP_InjLeakageFA ==FALSE		
					No failure on injectors	FUL_GenericInjSysFlt ==FALSE		
					No fault on any exhaust mass flow model input	EXM_TurbFlowNotValid ==FALSE		
					No failure on air control system	AIC_AirShtOffReq ==FALSE		
					No failure on NOx Sensor Bus relay circuit	SBR_RlyFA==FALSE		
					No failure on Upstream SCR temperature sensor	NOX_Snsr1_TempFlt ==FALSE		
					No DTC set:	P30B4		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Offset Learning At Min Limit - Bank 1 Sensor 2	P11D5	This diagnosis verifies if Downstream NOx sensor raw signal is affected by an offset	Check if NOx2 signal has an offset by learning the raw value in stable conditions during fuel cut off maneuver. A fault is detected if one of the following conditions is true: 1. Mean of all NOx sensor readings (where every reading is the mean value of a sampling window) OR 2. Mean of all NOx sensor readings (where every reading is the mean value of a sampling window)	 < -25.00 ppm > 400.00 ppm	Combustion mode dependent enabling flag Engine is running Engine is not cranking Powertrain relay voltage NOx Sensor Bus relay is commanded ON Post Catalyst NOx Sensor is present in the exhaust Sensor heater is in range: a) (Sensor heater raw resistance - Sensor heater target resistance) / Sensor heater target resistence b) condition a) is fulfilled for time Sensor supply in range Sensor dewpoint is reached Injection small quantity adjustment (SQA) learning is not active EGR measured position Exhaust mass flow is within a range DEF injection is within a range	**NOX_S2_OfstMntrEnblCmbMode** TRUE TRUE > 11.00 V TRUE TRUE < 0.03 % > - 0.03 % > 10.00 sec > 10.80 V TRUE FAD_SQA_LrnET_Enbl ==FALSE < 100.00 % < 75.00 g/s > 0.00 g/s < 100.00 mg/s > -1.00 mg/s	The monitor runs after fuel cut off maneuver, when air mass integral exceeds 0.00 g and Post Catalyst NOx signal is stable for at least 0.00 s. The NOx value used for the monitor is calculated after sampling up to 10.00 sampling windows (each one made up of 10.00 samples), averaging the mean values of every window. Once computed this value, the diagnostic provides a result. Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Engine speed is within a range	< 3,500.00 rpm > 0.00 rpm		
					Post Catalyst NOx Sensor temperature is within a range	< 330.00 °C > 225.00 °C		
					Time after DPF regen modes	> 120.00 s		
					Fuel request is steady state when all the following conditions are verified: a) Fuel request derivative b) Fuel request within a range c) conditions a) and b) are fulfilled for a time	 < 0.01 mm^3/s < 0.10 mm^3 > -1.00 mm^3 > 2.00 s		
					Intake manifold absolute pressure	< 950.00 kPa		
					No failure on intake manifold absolute pressure Sensor	MAP_SensorFA==FALSE		
					No electrical failure on NOx2 Sensor	NOX_Snsr2_FltSt ==FALSE		
					No current control failure on NOx2 Sensor	NOX_NOx2_StBitChkFlt ==FALSE		
					No out of range low failure on NOx2 Sensor	NOX_NOx2_OutOfRngLo Flt ==FALSE		
					No out of range high failure on NOx2 Sensor	NOX_NOx2_OutOfRngHi Flt ==FALSE		
					No failure on NOx2	NOX_NOx2_SelfDiagFlt		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Sensor signal plausibility	==FALSE		
					No failure on NOx2 Sensor signal dynamic	NOX_NOx2_DynChkFlt ==FALSE		
					No failure on NOx2 CAN communication	CAN_LostComm_FltN_BusB_NOxSnsr_B ==FALSE		
					No failure on EGR valve actuator	EGR_PstnShtOffReqFA ==FALSE		
					No failure on high pressure fuel rail system	FHP_InjLeakageFA ==FALSE		
					No failure on injectors	FUL_GenericInjSysFlt ==FALSE		
					No fault on any exhaust mass flow model input	EXM_TurbFlowNotValid ==FALSE		
					No failure on air control system	AIC_AirShtOffReq ==FALSE		
					No failure on NOx Sensor Bus relay circuit	SBR_RlyFA==FALSE		
					Upstream SCR temperature is steady state: a) Upstream SCR temperature derivative within a range b) conditions a) is fulfilled for a time	 < 12.00 °C/s > -50.00 °C/s > 120.00 s		
					No failure on Downstream SCR temperature Sensor	NOX_Snsr2_TempFlt ==FALSE		
					No failure on upstream SCR temperature	EGT_TempSCR_UpFlt ==FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No O2 plausibility in load fault on NOx2 No DTC set:	OXY_NOx2ChkLoadFlt ==FALSE P30B5		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 O2 Pump Current Control Circuit	P11D8	This diagnosis verifies Downstream NOx gen3 sensor O2 reference circuit pin for Open Load Circuit	Check if there is an open circuit on NOx Sensor 2 O2 Reference pin (M1, auxiliary pumping current)	open circuit on M1 pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 O2 Pump Current Control Circuit Low Voltage	P11D9	This diagnosis verifies Downstream NOx gen3 sensor O2 reference circuit pin for Short to Ground	Check if there is a short circuit to ground on NOx Sensor 2 O2 Reference pin (M1, auxiliary pumping current)	groundshort on M1 pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 O2 Pump Current Control Circuit High Voltage	P11DA	This diagnosis verifies Downstream NOx gen3 sensor O2 reference circuit pin for Short to Battery	Check if there is a short circuit to power supply on NOx Sensor 2 O2 Reference pin (M1, auxiliary pumping current)	powershort on M1 pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Current Range/ Performance - Bank 1 Sensor 1	P11DB	This diagnosis verifies that Upstream NOx sensor embedded current control circuit status is healthy	Check if the NOx1 sensor embedded stability criteria of Nox/Lambda current control circuit are violated	Stability flag for NOx signal is set to OFF if one of the following condition is not fulfilled: a) V2 within an interval of 40mV around its set point b) Delta Ip2 < 426nA/10msec c) Ip1 within the interval of -40 uA... 19 uA d) Delta Ip1 < 2.4 uA aorund its set point Stability flag for Lambda signal is set to OFF if one of the following condition is not fulfilled: a) Ip1 within the interval of -40uA... 19uA b) Delta Ip0 < 300 uA /10 msec c) Delta Ip1 z 2.4 uA around its set point > 1 % > 1 %	Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Engine is not cranking Sensor dewpoint is reached Sensor heater is in range: a) (Sensor heater raw resistance - sensor heater target resistance) / sensor heater target resistence b) condition a) is fulfilled for time Engine is running No electrical failure on NOx1 sensor Combustion mode dependent enabling flag Fuel request: a) fuel request derivative is within a range b) condition a) is fulfilled for time	> 11.00 V TRUE FALSE > 10.80 V TRUE TRUE < 0.03 % >- 0.03 % > 10.00 sec TRUE NOX_Snsr1_FltSt ==FALSE **NOX_S1_StBitChkEnblCmbMode** <= 100.00 mm^3/s >= -100.00 mm^3/s > 0.00 sec	NOx stability flag time counter: 1 fails out of 1 samples Lambda stability flag time counter: 1 fails out of 1 samples Task=12.5ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Current Range/ Performance - Bank 1 Sensor 2	P11DC	This diagnosis verifies that Downstream NOx sensor embedded current control circuit status is healthy	Check if the NOx2 sensor embedded stability criteria of Nox/Lambda current control circuit are violated NOx stability flag: (OFF_Time/TOTAL_time) Lambda stability flag: (OFF_Time/TOTAL_time) Note:	Stability flag for NOx signal is set to OFF if one of the following condition is not fulfilled: a) V2 within an interval of 40mV around its set point b) Delta Ip2 < 426nA/10msec c) Ip1 within the interval of -40 uA... 19 uA d) Delta Ip1 < 2.4 uA aorund its set point Stability flag for Lambda signal is set to OFF if one of the following condition is not fulfilled: a) Ip1 within the interval of -40uA... 19uA b) Delta Ip0 < 300 uA /10 msec c) Delta Ip1 z 2.4 uA around its set point > 1 % > 1 %	Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Engine is not cranking Sensor dewpoint is reached Sensor heater is in range: a) (Sensor heater raw resistance - sensor heater target resistance) / sensor heater target resistence b) condition a) is fulfilled for time Engine is running No electrical failure on NOx2 sensor Combustion mode dependent enabling flag Fuel request: a) fuel request derivative is within a range b) condition a) is fulfilled for time	> 11.00 V TRUE FALSE > 10.80 V TRUE TRUE < 0.03 % >- 0.03 % > 10.00 sec TRUE NOX_Snsr2_FltSt ==FALSE **NOX_S2_StBitChkEnblCmbMode** <= 100.00 mm^3/s >= -100.00 mm^3/s > 0.00 sec	NOx stability flag time counter: 1 fails out of 1 samples Lambda stability flag time counter: 1 fails out of 1 samples Task=12.5ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			TOTAL_time= ON_time +OFF_Time					

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 O2 Low Reference Circuit	P11FC	This diagnosis verifies Dowstream NOx gen3 sensor Low Reference Circuit for Open Load Circuit	Check if there is an open circuit on NOx Sensor 2 Low Reference pin (Ref)	open circuit on Ref pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 O2 Low Reference Circuit Low Voltage	P11FD	This diagnosis verifies Downstream NOx gen3 sensor Low Reference Circuit for Short to Ground	Check if there is a short circuit to ground on NOx Sensor 2 Low Reference pin (Ref)	groundshort on Ref pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 O2 Low Reference Circuit High Voltage	P11FE	This diagnosis verifies Downstream NOx gen3 sensor Low Reference Circuit for Short to Battery	Check if there is a short circuit to power supply on NOx Sensor 2 Low Reference pin (Ref)	powershort on Ref pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 1 Positive Voltage Control Circuit Shorted to Control Circuit	P1248	This DTC detects a shorted load on Injector 1	Voltage high across low side and High side drivers during on state indicates low side shorted to high side	the time to reach the 2 A threshold of the injector current is shorter than 2 us	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderA and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderA	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] ==TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 2 Positive Voltage Control Circuit Shorted to Control Circuit	P1249	This DTC detects a shorted load on Injector 2	Voltage high across low side and High side drivers during on state indicates low side shorted to high side	the time to reach the 2 A threshold of the injector current is shorter than 2 us	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderB and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderB	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] ==TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 3 Positive Voltage Control Circuit Shorted to Control Circuit	P124A	This DTC detects a shorted load on Injector 3	Voltage high across low side and High side drivers during on state indicates low side shorted to high side	the time to reach the 2 A threshold of the injector current is shorter than 2 us	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderH and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderH	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] ==TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector 4 Positive Voltage Control Circuit Shorted to Control Circuit	P124B	This DTC detects a shorted load on Injector 4	Voltage high across low side and High side drivers during on state indicates low side shorted to high side	the time to reach the 2 A threshold of the injector current is shorter than 2 us	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and FUL_OutEnblCyl_CiEPSR_CylinderE and At least one injection pulse is requested by the application software (FUL_FuelInjectedCyl_CiEPSR_CylinderE	== 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] ==TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Rail Pressure (FRP) Sensor B Circuit Low Voltage	P127C	Determine when a short circuit to ground affects fuel rail pressure (secondary) sensor.	Fuel rail pressure sensor output (as percentage of supply voltage)	< 4.0 %	Starter motor is not engaged OR Starter motor has been engaged for a time OR Run crank voltage Rail PRessure Sensor configuration calibrated as *Double Track*	 ≥ 15 s > 8.4 V	38 failures out of 55 samples OR 22 continuous failures out of 55 samples 6.25 ms/samples	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Rail Pressure (FRP) Sensor B Circuit High Voltage	P127D	Determine when a short circuit to voltage affects fuel rail pressure (secondary) sensor.	Fuel rail pressure sensor output (as percentage of supply voltage)	> 94.8 %	Starter motor is not engaged OR Starter motor has been engaged for a time OR Run crank voltage Rail PRessure Sensor configuration calibrated as *Double Track*	 ≥ 15 s > 8.4 V	38 failures out of 76 samples OR 22 continuous failures out of 76 samples 6.25 ms/samples	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
EGR Slow Response - Increasing Flow (OBDII market only)	P140B	This monitor (in increasing flow direction) detects failures in the air system such to not fulfilll the request of EGR flow in the intake manifold during transient conditions. It works only in closed loop EGR control zone. This monitor is used to detect any malfunction in the EGR system that leads to slow down the air control causing the vehicle's emissions to exceed OBDII limits. The aim of the EGR flow slow response monitor is to detect small leakages in the pipe after the compressor or in the intake/exhaust manifold. This monitor could also detect slow responding EGR valves, or skewed MAF sensor. Slow responding throttle and VGT vanes could also affect the EGR flow response time.	Error difference (absolute value) between the desired EGR rate and the actual EGR rate during transient air control conditions. The error is averaged over a calibrate-able cumulative transient time.	> **P140B: Increasing EGR slow response threshold** [%]	Calibration on diagnostic enabling Engine Running Cranking ignition in range PT Relay voltage in range Air Control is Active (air control in closed loop) Air control active condition lasts for a time Desired EGR rate No active transition from a combustion mode to another one OBD Coolant Enable Criteria Throttle measured position Outside air temperature	**P140B, P140C: EGR slow response enabling** ==TRUE ==TRUE Battery voltage > 11.00 [V] Powertrain relay voltage > 11.00 [V] Refer to "Air Control Active" Free Form > 10.00 [s] > 0 [%] ==TRUE ==TRUE > 90.00 [%] > -20.00 [°C]	Test is evaluated after the enabling conditions are satisfied for a number of samples >= 50.00 sampling time is 25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Ambient air pressure	> 72.00 [kPa]		
					Engine speed in range	> 1,500.00 [rpm] AND < 1,850.00 [rpm]		
					Desired fuel quantity in range	> 35.00 [mm^3] AND < 65.00 [mm^3]		
					Exhaust manifold pressure in range	> 150.00 [kPa] AND < 225.00 [kPa]		
					Desired air request is steady state: AirReq-AirReqOld	> -7.00 [mg/s] AND < -1.00 [mg/s]		
					Air control tracking error (air setpoint-MAF measure)	< 0 [mg]		
					EGR valve position OR it is above that threshold for a time	<= 50.00 [%] >= 100.00 [s]		
					Exhaust manifold pressure is valid	EXM_ExhMnfdPresNotVld ==FALSE		
					Nominal EGR valve total			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					flow is valid	EGR_VlvTotFlowNomNotVld ==FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
EGR Slow Response - Decreasing Flow (OBDII market only)	P140C	This monitor (in decreasing flow direction) detects failures in the air system such to not fulfilll the request of EGR flow in the intake manifold during transient conditions. It works only in closed loop EGR control zone. This monitor is used to detect any malfunction in the EGR system that lead to slow down the air control causing the vehicle's emissions to exceed OBDII limits. The aim of the EGR flow slow response monitor is to detect small obstructions in the exhaust pipe. This monitor could also detect slow responding EGR valves, or skewed MAF sensor. Slow responding throttle and VGT vanes could also affect the EGR flow response time.	Error difference (absolute value) between the desired EGR rate and the actual EGR rate during transient air control conditions. The error is averaged over a calibrate-able cumulative transient time.	> **P140C: Decreasing EGR slow response threshold** [%]	Calibration on diagnostic enabling	**P140B, P140C: EGR slow response enabling** ==TRUE	Test is evaluated after the enabling conditions are satisfied for a number of samples	Type B, 2 Trips
					Engine Running	==TRUE		
					Cranking ignition in range	Battery voltage > 11.00 [V]	>= 50.00 sampling time is 25ms	
					PT Relay voltage in range	Powertrain relay voltage > 11.00 [V]		
					Air Control is Active (air control in closed loop)	Refer to "Air Control Active" Free Form		
					Air control active condition lasts for a time	> 10.00 [s]		
					Desired EGR rate	> 0 [%]		
					No active transition from a combustion mode to another one	==TRUE		
					OBD Coolant Enable Criteria	==TRUE		
					Throttle measured position	> 90.00 [%]		
					Outside air temperature	> -20.00 [°C]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Ambient air pressure	> 72.00 [kPa]		
					Engine speed in range	> 1,400.00 [rpm] AND < 1,700.00 [rpm]		
					Desired fuel quantity in range	> 35.00 [mm^3] AND < 55.00 [mm^3]		
					Exhaust manifold pressure in range	> 150.00 [kPa] AND < 250.00 [kPa]		
					Desired air request is steady state: AirReq-AirReqOld	> 1.00 [mg/s] AND < 22.50 [mg/s]		
					Air control tracking error (air setpoint-MAF measure)	> 0 [mg]		
					Exhaust manifold pressure is valid	EXM_ExhMnfdPresNotVld ==FALSE		
					Nominal valve total flow is valid	EGR_VlvTotFlowNomNotVld ==FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Control System Diagnostic Signals Message Counter Incorrect	P143A	This DTC monitors for an error in communication with the Reductant Control System Diagnostic Signals	Communication of the Alive Rolling Count or Protection Value of the Diesel Exhaust Fluid Controller Diagnostic Information 1 over CAN bus is incorrect for out of total samples Or Communication of the Alive Rolling Count or Protection Value of the Diesel Exhaust Fluid Diagnostic Controller Information 2 over CAN bus is incorrect for out of total samples Or Communication of the Alive Rolling Count or Protection Value of the Diesel Exhaust Fluid Controller Diagnostic Information 3 over CAN bus is incorrect for out of total samples	 >= 8.00 counts >= 10.00 counts >= 8.00 counts >= 10.00 counts >= 8.00 counts >= 10.00 counts	Message frame All the following conditions are met for Power Mode Powertrain Relay Voltage Run/Crank Ignition Voltage	= Is available >= 3,000.00 milliseconds = Run >= 11.00 Volts >= 11.00 Volts	Executes in 10ms loop.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Control System Information Signals Message Counter Incorrect	P143B	This DTC monitors for an error in communication with the Reductant Control System Information Signals	Communication of the Alive Rolling Count or Protection Value of the Diesel Exhaust Fluid Controller Reductant Sensor Data over CAN bus is incorrect for out of total samples Or Communication of the Alive Rolling Count or Protection Value of the Diesel Exhaust Fluid Controller Information 1 over CAN bus is incorrect for out of total samples Or Communication of the Alive Rolling Count or Protection Value of the Diesel Exhaust Fluid Controller Information 2 over CAN bus is incorrect for out of total samples	 >= 8.00 counts >= 10.00 counts >= 8.00 counts >= 10.00 counts >= 8.00 counts >= 10.00 counts	Message frame All the following conditions are met for Power Mode Powertrain Relay Voltage Run/Crank Ignition Voltage	= Is available >= 3,000.00 milliseconds = Run >= 11.00 Volts >= 11.00 Volts	Executes in 10ms loop.	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Switch State Undetermined	P155A	Detects when cruise switch state cannot be determined, such as low voltage conditions	cruise switch state is received as "undetermined" for greater than a calibratable time	fail continuously for greater than 0.5 seconds			fail continuously for greater than 0.5 seconds	Type C, No SVS, Emissions Neutral Diagnostics – special type C

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Sensor Bus Relay Feedback Circuit High Voltage	P157A	Detects unexpected CAN activity on the sensor bus. This diagnostic reports the DTC when controller-specific CAN frames are received while the sensor bus relay is commanded "off."	Continued reception of sensor bus CAN frames during driver off state indicates a stuck on circuit failure. Controller specific received CAN frames are selected to determine continued CAN activity.		Sensor Bus Relay feedback circuit high voltage diagnostic enabled Sensor Bus Relay commanded “OFF” No Sensor Bus active DTCs:	= 1 P16D7, P16D8, P16D9	6 failures out of 10 samples 250ms / Sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cruise Control Calibration Incorrect	P158A	Type of cruise in Body Control Module does not match that in the Engine Control Module for 2.5 seconds	Type of cruise system in GMLAN $4E9 does not match with that in the Engine Control Module for a fix time.	2.5 seconds	DID $40 from BCM says cruise system is present (ECM recieves programmble information from Body Control Module) OR ECM will not receive Programmable information for Cruise from Body Control Module	True	fail continuously for greater than 2.5 seconds.	Type C, No SVS Emissions Neutral Diagnostics – Special Type C

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Internal Control Module Pressure Regulator 1 Control Performance	P163A	Determine when commanded current for Fuel metering Unit valve is out of expected current range.	Current flowing through fuel metering unit valve OR Current flowing through fuel metering unit valve	> 2.80 A < 0.05 A	Powertrain relay voltage Rail pressure is governed by Fuel Metering Unit (refer to *RailPresCntrl*) No active DTC since key is on:	≥ 11.0 V FHP_MU_DrvrCloseTFTKO FHP_MU_DrvrOpenTFTKO	160 failures out of 250 samples 6.25 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Internal Control Module Pressure Regulator 2 Control Performance	P163B	Determine when commanded current for Rail Pressure Regulator valve is out of expected current range.	Current flowing through pressure regulator valve OR Current flowing through pressure regulator valve	> 2.80 A < 0.05 A	Powertrain relay voltage Rail pressure is governed by Pressure Regulator (refer to *RailPresCntrl*) No active DTC since key is on:	≥ 11.0 V FHP_PR_DrvrCloseTFTKO FHP_PR_DrvrOpenTFTKO	160 failures out of 250 samples 6.25 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Ignition Voltage Correlation	P1682	Detect a continuous or intermittent out of correlation between the Run/Crank Ignition Voltage and the Powertrain Relay Ignition Voltage. The diagnostic monitors the difference in voltage between Run/Crank Voltage and the Powertrain Relay Ignition Voltage and fails the diagnostic when the voltage difference is too high. This diagnostic only runs when the powertrain is commanded on and the Run/Crank Voltage is greater than a threshold based on IAT or the powertrain ignition voltage is high enough the Run/Crank voltage is high enough.	|Run/Crank – PT Relay Ignition| >	3.00 Volts		Powertrain commanded on AND (Run/Crank voltage > Table, f(IAT). See supporting tables: **P1682_PT Relay Pull-in Run/Crank Voltage f(IAT)** OR PT Relay Ignition voltage > 5.50 Volts) AND Run/Crank voltage > 5.50 Volts	240 / 480 counts; or 0.175 sec continuous; 12.5 ms/count in main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Ignition Voltage Correlation #2	P16A7	Detect a continuous or intermittent out of correlation between the Run/Crank Ignition Voltage and the Powertrain Relay Ignition Voltage #2. The diagnostic monitors the difference in voltage between Run/Crank Voltage and the Powertrain Relay Ignition Voltage and fails the diagnostic when the voltage difference is too high. This diagnostic only runs when the powertrain is commanded on and the Run/Crank Voltage is greater than a threshold based on IAT or the powertrain ignition voltage is high enough the Run/Crank voltage is high enough. Detect a continuous or intermittent out of correlation between the Run/Crank Ignition Voltage & the Powertrain Relay Ignition Voltage #2.	|Run/Crank – PT Relay Ignition| >	3.00 Volts		Powertrain commanded on AND (Run/Crank voltage > Table, f(IAT). See supporting tables: **P1682_PT Relay Pull-in Run/Crank Voltage f(IAT)** OR PT Relay Ignition voltage > 5.50 Volts) AND Run/Crank voltage > 5.50 Volts	240 / 480 counts; or 0.175 sec continuous; 12.5 ms/count in main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Controls Ignition Relay Feedback Circuit 2 Low Voltage - (GEN III Controllers ONLY)	P16AF	Detects low voltage in the engine controls ignition relay feedback circuit 2. This diagnostic reports the DTC when low voltage is present. Monitoring occurs when run crank voltage is above a calibrated value.	Engine controls ignition relay feedback circuit 2 low voltage	Relay voltage <= 5.00	Powertrain relay low diag enable Powertrain relay voltage Run Crank voltage Powertrain relay state	= 1.00 >= 11.00 > 9.00 = ON	5 failures out of 6 samples 1000 ms / sample	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Engine Controls Ignition Relay Feedback Circuit 2 High Voltage - (GEN III Controllers ONLY)	P16B3	Detects high voltage in the engine controls ignition relay feedback circuit 2. This diagnostic reports the DTC when high voltage is present. Monitoring occurs when the relay state is inactive.	Engine controls ignition relay feedback circuit 2 high voltage	Relay voltage >= 4.00	Powertrain relay high diag enable Powertrain relay state	= 1.00 = INACTIVE	50 failures out of 63 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Sensor Bus Relay Control Circuit Open	P16D7	Detects an open circuit in the sensor bus relay circuit. This diagnostic reports the DTC when an open circuit is present. A decision is made by comparing a voltage measurement to a controller specific voltage threshold.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	Open Circuit: ≥ 200 K Ω ohms impedance between output and controller ground	Run/Crank Voltage	Voltage ≥ 11.00 volts	8 failures out of 10 samples 250 ms / sample	Type A, 1 Trips Note: In certain controllers P16D8 may also set (Sensor Bus Relay Control Circuit Low).

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Sensor Bus Relay Control Circuit Low	P16D8	Detects a short to ground in the sensor bus relay circuit. This diagnostic reports the DTC when a short to ground is present. A decision is made by comparing a voltage measurement to a controller specific voltage threshold.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	Short to ground: ≤ 0.5 Ω impedance between output and controller ground	Run/Crank Voltage	Voltage ≥ 11.00 volts	8 failures out of 10 samples 250 ms / sample	Type A, 1 Trips Note: In certain controllers P16D7 may also set (Sensor Bus Relay Control Circuit Open).

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Sensor Bus Relay Control Circuit High	P16D9	Detects a short to power in the sensor bus relay circuit. This diagnostic reports the DTC when a short to power is present. A decision is made by comparing a voltage measurement to a controller specific voltage threshold.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	Short to power: ≤ 0.5 Ω impedance between output and controller power	Run/Crank Voltage	Voltage ≥ 11.00 volts	8 failures out of 10 samples 250 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Control Module Serial Peripheral Interface Bus 1	P16F0	This DTC detects intermitent and continuous invalid SPI messages. This is based on the detection of missing or invalid receive message within the main processor before receiving a valid message.	This function detects a serial communications fault based upon the detection of missing or invalid (receive) message within the main processor before receiving a valid message.		Run/Crank voltage	> 6.41 Volts	39 / 399 counts continuous; 12.5 ms /count in the ECM main processor	Type A, 1 Trips
			This function detects a serial communications fault based upon the detection of missing or invalid (receive) message within the main processor after receiving a valid message.		Run/Crank voltage	> 6.41 Volts	159 / 399 counts continuous; 12.5 ms /count in the ECM main processor	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Internal Control Module Redundant Memory Performance (Diesel)	P16F3	Detect Processor Calculation faults due to RAM corruptions, ALU failures and ROM failures For all of the following cases: If the individual diagnostic threshold is equal to 2048 ms, this individual case is not applicable. If any of the following cases are X out of Y diagnostics and the fail (x) is greater than the sample (Y), this individual case is also not applicable.	Torque Learn offset is out of bounds given by threshold range	High Threshold 0.00 Nm Low Threshold 0.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	Type A, 1 Trips
			Commanded Predicted Engine Torque and its dual store do not match	N/A	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Zero pedal axle torque is out of bounds given by threshold range	High Threshold 3,000.00 Nm Low Threshold -65,535.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Creep Coast Axle Torque is out of bounds given by threshold range	High Threshold 3,000.00 Nm Low Threshold -65,535.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Rate limited vehicle speed and its dual store do not equal	N/A		Time since first CAN message with vehicle speed >= 0.500 sec	10 / 40 counts; 25.0msec/count	
			Commanded engine torque due to fast actuators and its dual store do not equal	N/A	Ignition State	Accessory, run or crank	Up/down timer 446 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Commanded engine torque due to slow actuators and its dual store do not equal	N/A	Ignition State	Accessory, run or crank	Up/down timer 446 ms continuous, 0.5 down time multipier	
			TOS to wheel speed conversion factor is out of bounds given by threshold range	High Threshold: 1.10 T/C Range Hi 0.10 T/C Range Lo Low Threshold: 1.10 T/C Range Hi 0.10 T/C Range Lo	Ignition State	Accessory, run or crank	5 / 15 counts; 25.0msec/count	
			TOS to wheel speed conversion factor is out of bounds given by threshold	N/A	Ignition State	Accessory, run or crank Transfer case range valid	7.00 / 10.00 counts; 25.0msec/count	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			range Transfer case neutral request from four wheel drive logic does not match with operating conditions			and not over-ridden FWD Apps only		
			Driver progression mode and its dual store do not equal	N/A	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Predicted torque for uncorrected zero pedal determination is greater than calculated limit.	Table, f(Engine, Oil Temp). **P16F3_Speed Control External Load f(Oil Temp, RPM)** + 105.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Engine Predicted Request	4,096.00	Ignition State	Accessory, run or crank	Up/down timer	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Without Motor is greater than its redundant calculation plus threshold	Nm			2,048 ms continuous, 0.5 down time multipier	
			Engine Immediate Request Without Motor is greater than its redundant calculation plus threshold	104.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 146 ms continuous, 0.5 down time multipier	
			Commanded Predicted Engine Request is greater than its redundant calculation plus threshold	4,096.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, down time multipier 0.5	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Commanded Hybrid Predicted Crankshaft Request is greater than its redundant calculation plus threshold	4,096.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Commanded Hybrid Immediate Crankshaft Request is less than its redundant calculation minus threshold	4,096.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Commanded Immediate Engine Request is greater than its redundant calculation plus threshold	105.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Engine Speed Lores Intake Firing (event based) calculation not equal its redundant calculation	N/A		Engine speed greater than 0rpm	Up/down timer 146 ms continuous, 0.5 down time multipier	
			Engine Speed Lores Intake Firing timing (event based) calculation not equal its redundant calculation	N/A		Engine speed greater than 0rpm	Up/down timer 146 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Idle speed control calculated predicted minimum torque request exceeds calculated torque limit	Minimum value (**P16F3_Speed Control External Load f(Oil Temp, RPM)** , **P16F3_Speed Control External Load Max f (Vehicle Speed, RPM)** + **P16F3_Speed Control External Load Offset f(Vehicle Sped, Transmission Oil Temp)**) + 105.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Idle speed control calculated predicted minimum torque without reserves exceeds calculated torque limit	Minimum value (**P16F3_Speed Control External Load f(Oil Temp, RPM)** , **P16F3_Speed Control External Load Max f (Vehicle Speed, RPM)** + **P16F3_Speed Control External Load Offset f(Vehicle Sped, Transmission Oil Temp)**) + 105.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Difference between Driver Requested Immediate Torque primary path and its secondary exceeds threshold	3,000.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Driver Immediate Request is less than its redundant calculation minus threshold	3,000.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Commanded Immediate Request is greater than its redundant calculation plus threshold OR Commanded Immediate Request is less than its redundant calculation minus threshold	3,000.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Commanded Immediate Response Type is set to Inactive	N/A	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Difference between Cruise Axle Torque Arbitrated Request and Cruise Axle Torque Request exceeds threshold	112.50 Nm		Cruise has been engaged for more than 4.00 seconds	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Desired engine torque request greater than redundant calculation plus threshold	104.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Absolute difference of adjustment factor based on temperature and its dual store above threshold	550.50 m/s	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			1. Absolute difference of redundant calculated engine speed above threshold	500 RPM		Engine speed greater than 0 RPM	Up/down timer 146 ms continuous, 0.5 down time multipier	
			Speed Control's Preditcted Torque Request and its dual store do not match	N/A	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Engine oil temperature and its dual store do not match	N/A	Ignition State	Accessory, run or crank	Up/down timer 357 ms continuous, 0.5 down time multipier	
			Difference of base friction torque and its redundant calculation is out of bounds given by threshold range	High Threshold 105.00 Nm Low Threshold - 105.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			AC friction torque is greater than commanded by AC control software or less than threshold limit	High Threshold 35.00 Nm Low Threshold 0.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Generator friction torque is out of bounds given by threshold range	High Threshold 105.00 Nm Low Threshold 0.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Engine Torque Closed Loop Fuel Quantity Correction higher then threshold OR Engine Torque Closed Loop Fuel Quantity Correction lower then threshold	9.67 mm3 - 9.67 mm3	Engine cranking or engine running		Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			1. Difference of reserve torque value and its redundant calculation exceed threshold OR 2. Reserve request does not agree with operating conditions or Difference of final predicted torque and its redundant calculation exeed threshold OR 3. Rate of change of reserve torque exceeds threshold, increasing direction only	1. 104.00 Nm 2. N/A 3. 104.00 Nm 4. 104.00 Nm	3. & 4.: Ignition State	1. & 2.: Torque reserve (condition when spark control greater than optimum to allow fast transitions for torque disturbances) > 105.00 Nm 3. & 4.: Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			OR 4. Reserve engine torque above allowable capacity threshold					
			Min. Axle Torque Capacity is greater than threshold	0.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 175 ms continuous, 0.5 down time multipier	
			Driver Predicted Request is greater than its redundant calculation plus threshold OR Driver Predicted Request is less than its redundant calculation minus threshold	3,000.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Predicted torque for zero pedal determination is	Table, f(Oil Temp, RPM, Vehicle Speed).	Ignition State	Accessory, run or crank	Up/down timer 2,048	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			greater than calculated limit.	See supporting tables: min (**P16F3_Speed Control External Load f(Oil Temp, RPM)** , Sum (**old P16F3_Speed Control External Load Max f(Vehicle Speed, RPM)** , **old P16F3_Speed Control External Load Offset f(Vehicle Sped, Transmission Oil Temp)**) + 105.00 Nm			ms continuous, 0.5 down time multipier	
			Commanded Predicted Axle Torque and its dual store do not match	1 Nm	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Rate limited cruise axle torque request and its dual store do not match within a threshold	112.50 Nm	Ignition State	Accessory, run or crank	Up/down timer 163 ms continuous, 0.5 down time multipier	
			1. Absolute difference of Calculated accelerator pedal position compensated for carpet learn and error conditions and its redundant calculation is out of bounds given by threshold range OR 2. Absolute difference of Calculated accelerator pedal position compensated for carpet learn and error conditions and its dual store do not equal OR 3. Absolute difference of Calculated accelerator pedal position and its dual store do not equal	1. 5.00 % 2. N/A 3. N/A	Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Commanded axle torque is greater than its redundant calculation by threshold	3,000.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Commanded axle torque is less than its redundant calculation by threshold	4,500.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			AC friction torque is greater than commanded by AC control software	35.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 2,048 ms continuous, 0.5 down time multipier	
			Engine Speed Lores Intake Firing (time based) calculation does not equal	N/A		Engine speed >0rpm	Up/down timer 175 ms continuous,	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			its redundant calculation				0.5 down time multipier	
			Transmission Torque Request cacluations do not equal their dual stores	N/A		Run or Crank = TRUE > 0.50 s	16 / 32 counts; 25.0msec/count	
			Pedal learns and their redundant calculation do not equal		Ignition State	Accessory, run or crank	Up/down timer 475 ms continuous, 0.5 down time multipier	
			Requested fuel mass is greater or equal to its redundant calculation plus threshold	16.15 mg	Engine running No rich combustion mode No cranking phase No fuel cut off request		Up/down timer 446.41 ms continuous, 0.5 down time multiplier	
			Engine friction torque is greater than its redundant calculation plus threshold OR Engine friction torque is lower than its redundant	105.00 Nm 105.00 Nm	Engine running		Up/down timer 475.00 ms continuous, 0.5 down time multiplier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			calculation minus threshold					
			High Pressure Pump Torque Load is greater than threshold OR High Pressure Pump Torque Load is lower than threshold	105.00 Nm 0.00 Nm	Engine running		Up/down timer 475.00 ms continuous, 0.5 down time multiplier	
			Pumping Losses is lower than threshold OR Pumping Losses rate of change signal greater than P2D2 threshold	0.00 Nm/task_100ms 6.56 Nm	Engine running		Up/down timer 475.00 ms continuous, 0.5 down time multiplier	
			Start Up Engine Friction Compensation rate of change haher than a threshold AND Start Up Engine Friction Compensation higher than threshold	52.50 Nm/task_12.5 81.00 Nm	Engine running		Up/down timer 151.88 ms continuous, 0.5 down time multiplier	
			Limited Immediate Indicated Torque request is greater than its redundant calculation plus threshold	105.00 Nm	Engine running		Up/down timer 446.41 ms continuous, 0.5 down time multiplier	
			Active damping torque reduction greater than threshold	105.00 Nm	Engine running		Up/down timer 146.41 ms continuous, 0.5	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			OR Active damping torque reduction lower than threshold	-105.00 Nm			down time multiplier	
			Fuel volume request greater than its redundant calculation plus threshold	19.34 mm3	Engine running No rich combustion mode		Up/down timer 446.41 ms continuous, 0.5 down time multiplier	
			Absolute value of the sum of the Fuel Volumes in the pulse train minus Fuel Volume Request minus Main Correction greater than threshold	19.34 mm3	Engine Running No rich combustion mode Main pulse quantity already compensated with main correction is greater than or equal to zero		Up/down timer 146.41 ms continuous, 0.5 down time multiplier	
			Cumulative Programmed Energizing Time greater then its redundant calculation plus threshold (Note: when an emission test is performed OR CSERS test is performed the threshold is incremented by a further value)	211.50 us additional value for emission tests: 0.00 us additional value fro CSERS test 0.00 us	Engine running		Up/down timer 146.41 ms continuous, 0.5 down time multiplier	
			Cumulative Desired Energizing Time greater than its redundant calculation plus threshold (Note: when an emission test is performed OR	211.50 us additional value for emission tests:	Engine Running		Up/down timer 146.41 ms continuous, 0.5 down time multiplier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			CSERS test is performed the threshold is incremented by a further value)	0.00 us additional value fro CSERS test 0.00 us				
			Difference between Fuel Rail Pressure Event Based Signal and Fuel Rail Pressure Time Based signal higher than threshold OR Difference between Fuel Rail Pressure Event Based Signal and Fuel Rail Pressure Time Based signal lower than threshold	300.00 MPa -40.00 MPa	Engine running Delta Filtered Pressure value lower than AND Delta Filtered Pressure value greater than	2,300.00 MPa/s -2,200.00 MPa/s	Up/down timer 446.41 ms continuous, 0.5 down time multiplier	
			Absolute difference between Main Correction and its redundant calculation greater than or equal to threshold	19.34 mm3	Engine running No rich combustion mode		Up/down timer 146.41 ms continuous, 0.5 down time multiplier	
			Cylinder Balancing Fuel Quantity Compensation converted in Energizing Time greater than its redundant calculation plus threshold OR (only if cylinder balancing detected a fault) Cylinder Balancing Fuel Quantity Compensation converted in Energizing	**P16F3_CB safety deadband threshold f (Fuel Rail Pressure)** us **P16F3_CB safety deadband threshold f (Fuel Rail Pressure)** us	Engine running		Up/down timer 146.41 ms continuous, 0.5 down time multiplier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Time greater than threshold					
			Absolute value of the difference between the calculated EIA compensation and its redundant calculation greater than threshold	**P16F3_EIA safety deadband threshold f (Fuel Rail Pressure)** us	Engine cranking or engine running		Up/down timer 146.41 ms continuous, 0.5 down time multiplier	
			Absolute value of the difference between the calculated EIA compensation and its redundant calculation greater than threshold	19.34 mm3	Engine cranking or engine running		Up/down timer 146.41 ms continuous, 0.5 down time multiplier	
			Absolute value of the weighted delta energizing time greater then threshold	**P16F3_SQA safety deadband threshold f (Fuel Rail Pressure)** us	Ignition State	Accessory, run or crank	Up/down timer 446.41 ms continuous, 0.5 down time multiplier	
			Oil Pump Low Pressure Offset Friction greater then zero OR Oil Pump Low Pressure Offset Friction lower then threshold	 -3.00 Nm	Engine running		Up/down timer 475.00 ms continuous, 0.5 down time multiplier	
			Absolute value of fuel mass compensated for air temperature greater then threshold	8.08 mg	Engine running No rich combustion mode No cranking phase No fuel cut off request	Accessory, run or crank	Up/down timer 446.41 ms continuous, 0.5 down time multiplier	
			Absolute value of Main correction compensation	9.67 mm3	Engine Running		Up/down timer 146.41	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			based on coolant temperature greater then threshold		No rich combustion mode		ms continuous, 0.5 down time multiplier	
			Rail Pressure Wave Compensation greater than threshold	**P16F3_Rail Pressure Wave Compensation f(Fuel Rail Pressure, Fuel Quantity)** MPa	Engine cranking or running		Up/down timer 2,047.97 ms continuous, 0.5 down time multiplier	
			Injector Valve Closing Adjustment energizing time correction greater then threshold OR Injector Valve Closing Adjustment energizing time correction lower then threshold	**P16F3_VCA safety max deadband threshold f(Fuel Rail Pressure)** us **P16F3_VCA safety min deadband threshold f(Fuel Rail Pressure)** us	Engine Cranking or engine running		Up/down timer 446.41 ms continuous, 0.5 down time multiplier	
			Desired Immediate Indicated torque greater then its redundant calculation plus threshold	105.00 Nm	Engine running		Up/down timer 446.41 ms continuous, 0.5 down time multiplier	
			Fuel Temperature Energizing Time Compensation greater then its redundant calculation plus threshold	**P16F3_FTD safety deadband threshold f (Fuel Rail Pressure)** us	(Engine running OR engine cranking occurred in current driving cycle) AND FUL_InjLeakTempValid	 = TRUE	Up/down timer 151.88 ms continuous, 0.5 down time multiplier	
			Absolute value of the diffence between current	2,047.94 °C/100ms	Engine cranking or engine running		Up/down timer 2,047.97	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			and previous Fuel Injector Backflow Temperature greater then threshold		ECT_Sensor_FA AND FTS_FTS_CktFA AND FTS_FTS_PlFA AND XOY_SecurityFlt_CeXOYR_e_FULR_FTD_RateLimFlt AND XOY_SecurityFlt_CeXOYR_e_ETMR_FTD_RedntCalcFlt	= FALSE = FALSE = FALSE = FALSE = FALSE	ms continuous, 0.5 down time multiplier	
			Increase of pumping losses due to exhaust brake actuation less then threshold	0.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 475.00 ms continuous, 0.5 down time multiplier	
			Exhaust Brake Torque Capacity less then Threshold	0.00 Nm	Ignition State	Accessory, run or crank	Up/down timer 475.00 ms continuous, 0.5 down time multiplier	
			Delta Engine Fuel Temperature less than zero		Engine Fuel Temperature below threshold Engine cranking or engine	80.00 ° C	Up/down timer 462.50 ms continuous, 0.5	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					running		down time multiplier	
			Combustion Mode Arbitration Winner is higher than the maximum expected combustion mode OR Previous Combustion Mode Arbitration Winner is higher than the maximum expected combustion mode OR Combustion Mode Arbitration Winner is equal to Previous Combustion Mode Arbitration Winner and not equal to Normal combustion Mode		Engine cranking or engine running		Up/down timer 162.50 ms continuous, 0.5 down time multiplier	
			The sum of Low, Middle and High Barometric Correction Factors greater than 1		Engine cranking or engine running		Up/down timer 462.50 ms continuous, 0.5 down time multiplier	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Transfer Case Control Module Transfer Case Command State Rationality - 4WD high or 4WD low command not 4wd high or 4WD low ratio	P17D4	The diagnostic monitor compares measured transfer case ratio to the transfer case control module commanded transfer case state. When the measured transfer case gear ratio is 4WD neutral ratio, while, the transfer case control module command state is 4WD high ratio or 4WD low ratio, the DTC is set. The 4WD neutral ratio regions are considered ratios outside the nominal 4WD high and nominal 4WD low ratios. The 4WD ratio is calculated as transmission output shaft speed divided by the transfer case output shaft speed, both speed are measured values based on speed sensors.	transfer case contol module transfer case command state AND measured transfer case ratio is NOT in 4WD low ratio window AND measured transfer case ratio is NOT in 4WD high window AND measured transfer case ratio is NOT in 4WD low ratio window AND measured transfer case ratio is NOT in 4WD high window OR vehicle is stopped: transfer case output shaft speed transmission output shaft speed vehicle stopped secondary parameter thresholds met (measured transfer case ratio = transmission output speed / transfer case output speed)	≠ 4WD neutral 4WD low ratio window ≤ 3.00 ≥ 2.40 4WD high ratio window ≤ 1.30 ≥ 0.70 ≥ 2.90 ≤ 2.00 ≥ 1.20 ≤ 0.80 ≤ 10.0 RPM ≥ 200.0 RPM	vehicle stopped: transmission output shaft speed engine torque engine speed accelerator pedal position accelerator pedal position brake pedal position transmssion gear is forward gear: transmission output shaft speed engine torque engine speed accelerator pedal position accelerator pedal position brake pedal position transmssion gear is reverse gear: transmission output shaft speed engine torque engine speed accelerator pedal position accelerator pedal position brake pedal position diagnsotic monitor enable PTO active engine power limited DTCs not fault active	≥ 500.0 RPM ≥ 100.0 Nm ≥ 300.0 RPM ≥ 5.0 % hysteresis high NOT ≤ 3.0 % hysteresis low ≤ 100.0 % ≥ 200.0 RPM ≥ -20.0 Nm ≥ 0.0 RPM ≥ 0.0 % hysteresis high NOT ≤ 0.0 % hysteresis low ≤ 100.0 % ≥ 500.0 RPM ≥ 90.0 Nm ≥ 300.0 PRM ≥ 6.0 % hysteresis high NOT ≤ 3.0 % hysteresis low ≤ 100.0 % = 1 Boolean = FALSE = FALSE CrankSensor_FA VehicleSpeedSensor_FA EngineTorqueEstInaccurate P057B, P057C, P057D,	fail time ≥ 10.50 seconds out of sample time ≥ 15.00 seconds update rate 12.5 milliseconds	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			update rate 12.5 milliseconds			P057E, P279A, P279B, P279C, P0502, P0503, P0722, P0723, P2160, P2161		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Axle Torque Secondary Signal Message Counter Incorrect	P1899	This DTC monitors for an error in communication with the Axle Torque Secondary Signal	Communication of the Alive Rolling Count or Protection of the Axle Torque Secondary Signal over CAN bus is incorrect for out of total samples	 >= 10.00 counts >= 10.00 counts	Message frame All the following conditions are met for Power Mode Powertrain Relay Voltage Run/Crank Ignition Voltage	= Is available >= 3,000.00 milliseconds = Run >= 11.00 Volts >= 11.00 Volts	Executes in 10ms loop.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Four Wheel Drive Range Secondary Signal Message Counter Incorrect	P189A	This DTC monitors for an error in communication with the Secondary Axle Operational Mode Signal	Communication of the Alive Rolling Count or Protection of the Secondary Axle Operational Mode Signal over CAN bus is incorrect for out of total samples	>= 10.00 counts >= 10.00 counts	Message frame All the following conditions are met for Power Mode Powertrain Relay Voltage Run/Crank Ignition Voltage	= Is available >= 3,000.00 milliseconds = Run >= 11.00 Volts >= 11.00 Volts	Executes in 10ms loop.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Park Assistance System Performance	P18CB	Determines if Park assist active bit from EBCM is valid	Speed Error - APA active ($1C6/$1C7) above a vehicle speed threshold	> 10.00	Serial communication to EBTCM (U0108) Engine Running Status of traction in GMLAN message ($4E9)	No loss of communication = Run = Traction Present	>= 4 failures out of 10 Performed every 12.5ms	Type C, No SVS
			OR Initialization Error - APA active ($1C6/$1C7) without an active torque request	APA active boolean transitions from False to True with Torque Intervention = No request			>= 4 failures out of 10 Performed every 12.5ms	
			OR Exit Error - APA transitions to inactive during active torque request above a vehicle speed threshold	APA active boolean transitions from True to False with Torque Intervention <> No request when vehicle speed is > 1.00			When transition occurs, no number of samples Performed every 12.5ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Level Sensor Circuit Range/ Performance	P203B	This monitor detects when a fault is causing this readiness signal being equal “Don’t use data’ for excessive times.	Ratio between amount of "Don't use data" readiness signal samples and total readiness signal samples for DEF level sensor	> 0.98	Sensor Bus Wake Up signal is active At least one message has been received by DEF device (Engine off timer AND Tank Temperature sampled at init AND UTLC Temperature sampled at init AND Tank Temperature AND UTLC Temperature) OR (Tank Temperature AND UTLC Temperature) Vehicle speed Absolute derivative of vehicle speed for a minimum time Estimated tank level volume No fault for: - serial communication with DEF device (SCRPM) - sensor bus wake up signal - level sensor out of range	 > 14,400 s > -6.0 °C > -6.0 °C > -9.0 °C > -9.0 °C > -4.0 °C > -2.0 °C > 10.0 km/h < 0.75 m/s^2 > 2 s > 2.0 l U010E SCR_DEFLS_ElecFltSt	Travelled distance with Enable Conditions met > 5.0 km	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					- DEF tank temperature sensor - UTLC temperature sensor - vehicle speed	SCR_DEFTS_FA		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Level Sensor Circuit Low Voltage	P203C	This diagnosis verifies if an short to ground or open circuit occurred in the DEF level sensor	DEF level sensor raw signal is below a calibrated threshold	< 0.20	Test enabled by calibration Key on (OR engine running) Engine is not cranking Battery voltage No loss of CAN comunication	1.00 == TRUE > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR)	40.00 failures out of 50.00 samples Time basis = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Level Sensor Circuit High Voltage	P203D	This diagnosis verifies that the short to battery occurred in the DEF level sensor	DEF level sensor raw signal is above a calibrated threshold	> 99.80	Test enabled by calibration Key on (OR engine running) Engine is not cranking Battery voltage No loss of CAN comunication	1.00 == TRUE > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR)	40.00 failures out of 50.00 samples Time basis = 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Injector Circuit / Open Bank 1 Unit 1	P2047	This diagnosis verifies if a DEF dosing valve open circuit occurred	HWIO interface DEFMV_OPEN = Fault	VeHWIO_e_DEFMV_ Open == CeSCRR_e_Fault	Test enabled by calibration Key on (OR engine running) Engine is not cranking Battery voltage HWIO interface DEFMV_OPEN different from INDETERMINATE	1.00 > 11.00 [V]	30.00 failures out of 60.00 samples Time basis = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Injector Circuit Low Bank 1 Unit 1	P2048	This diagnosis verifies if a DEF dosing valve low side short to ground occurred	HWIO interface DEFMV_GROUND_SHORT = Fault	VeHWIO_e_DEFMV_Gsht == CeSCRR_e_Fault	Test enabled by calibration Key on (OR engine running) Engine is not cranking Battery voltage HWIO interface DEFMV_GROUND_SHORT different from INDETERMINATE	1.00 > 11.00 [V]	30.00 failures out of 60.00 samples Time basis = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Injector Circuit High Bank 1 Unit 1	P2049	This diagnosis verifies if a DEF dosing valve low side short to battery occurred	HWIO interface DEFMV_POWER_SHORT = Fault	VeHWIO_e_DEFMV_Psht == CeSCRR_e_Fault	Test enabled by calibration Key on (OR engine running) Engine is not cranking Battery voltage HWIO interface DEFMV_ENABLE_POWER_SHORT different from INDETERMINATE	1.00 > 11.00 [V]	30.00 failures out of 60.00 samples Time basis = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Pressure Sensor Performance	P204B	This diagnosis verifies if the DEF tank Pressure sensor is affected by rationality fault (offset)	At the end of driving cycle, with DEF line empty and pressure compensation phase done, DEF pressure sensor signal is not equal (with tolerance) to the ambient pressure DEF Pressure signal outside the range:	(7.50 ; 18.50) [KPa]	Test enabled by calibration DEF dosing valve not in fault No electrical fault on pressure sensor SCR System Stand-By recovery action not activated No DEF Pump Rotor Stall fault No DEF Pressure Governor Deviation High fault DEF temperature sensor higher than a calibrated threshold End of trip process executed SCR pressure compensation performed during afterrun DEF metering valve HWIO interface provides INDETERMINATE OR NO-FAULT during After-Run state	1.00 SCR_DEFMV_FA == FALSE SCR_DEFPS_FA == FALSE SCR_DEFPM_FA == FALSE SCR_PresGovDvtnHiFA == FALSE > -7.00	160.00 failures out of 200.00 samples Time basis = 25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Powertrain Relay Voltage is in range At least one DEF pressure sample has been received from ECM			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Pressure Sensor Circuit Low Voltage	P204C	This diagnosis verifies that the DEF pressure sensor is affected by open circuit or short circuit to ground	The DEF pressure sensor raw signal is a voltage, expressed as percentage of the sensor's supply voltage. DEF pressure sensor raw signal is below a calibrated threshold	< 5.00 [%]	Test enabled by calibration Battery voltage > 11V Key on Engine is not cranking	1.00 == TRUE > 11.00 [V]	100.00 failures out of 125.00 samples Time basis = 25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Pressure Sensor Circuit High Voltage	P204D	This diagnosis verifies that the DEF pressure sensor is affected by short circuit to battery	The DEF pressure sensor raw signal is a voltage, expressed as percentage of the sensor's supply voltage. DEF pressure sensor raw signal is above a calibrated threshold	> 98.00 [%]	Test enabled by calibration Battery voltage > 11V Key on Engine is not cranking	1.00 == TRUE > 11.00 [V]	100.00 failures out of 125.00 Time basis = 25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Tank Temperature Sensor Performance	P205B	This diagnosis verifies that the DEF tank temperature sensor is affected by rationality fault (gain or offset)	Difference between temperature sensor signal and system average temperature (provided by the Exhaust Gas Temperature sensors) is greater than a calibrated threshold	> 35.00	Test enabled by calibration Battery voltage Key on (OR engine running) No loss of CAN comunication Average exhaust gas temperature available or not available for a time Engine speed = 0 rpm No electrical fault on DEF temperature sensor Time elapsed since last key off Tank Refill is not detected DEF temperature sensor signal is not outside the DEF freezing temperature range (with tollerance). Test not performed in this driving cycle No electrical malfunction detected:	1.00 == TRUE > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR) < 8 s SCR_DEFTS_FA == FALSE > 28,800.00 [(-90.00 - 1.00) ; (-90.00 + 1.00)] [°C] SCR_DEFTS_ElecHiErr, SCR_DEFTS_ElecLoErr	8.00 failures out of 10.00 samples Time basis = 500ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Tank Temperature Sensor Circuit Low Voltage	P205C	This diagnosis verifies that the DEF tank temperature sensor is affected by open circuit or short circuit to ground	The DEF tank temperature sensor raw output is a resistance expressed in [ohm] DEF temperature sensor raw signal is below a calibrated threshold	< 200.00 [ohm]	Test enabled by calibration Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN comunication DEF Tank heater not in fault	1.00 > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR) SCR_DEFTH_FA == FALSE	8.00 failures out of 10.00 samples Time basis = 500ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Tank Temperature Sensor Circuit High Voltage	P205D	This diagnosis verifies that the DEF tank temperature sensor is affected by short circuit to battery	The DEF tank temperature sensor raw output is a resistance expressed in [ohm] DEF temperature sensor raw signal is above a calibrated threshold	> 60,000.00	Test enabled by calibration Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN comunication DEF Tank heater not in fault Defrost phase is completed	1.00 > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR) SCR_DEFTH_FA== FALSE	8.00 failures out of 10.00 samples Time basis = 500ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF temperature sensor Self Correlated diagnostic	P205E	This diagnosis verifies that the DEF temperature sensor signal has not a plausible time evolution	DEF temperature sensor signal time evolution not plausible (intermittent signal)		Test enabled by calibration Run Crank active Run Crank in range No loss of CAN comunication No electrical fault on tank Temperature sensor	1.00 U010E, Lost Communication With Reductant Control Module (SCR) SCR_DEFTS_ElecFltSt == FALSE	8.00 failures out of 10.00 samples Time basis = 500ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF Quality Sensor Performance	P206B	This diagnosis checks if the DEF Quality Sensor has performance problems	The Quality sensor ready flag is provided to the ECM by the DEF-C via CAN bus. This monitor checks if the reflected sound waves are not heard by the sensor (for example, if the sensor is contaminated).	Quality sensor ready flag status equals to FALSE	Run/Crank is Active Powertrain relay voltage Engine in Cranking Phase No loss of CAN communication No fault messages from the DEF-C Controller DEF Level Estimation DEF QS thermistor temperature No electrical fault on DEF QS is present No electrical low fault on DEF Quality Sensor SENT circuit No performance fault on DEF Quality Sensor SENT circuit No fault on DEF QS thermistor is present No electrical fault on Quality sensor PZT is present	TRUE > 11.00 V FALSE CAN_LostComm_FltN_BusB_DEF_C == FALSE TRUE > 5.00 l > 2.00 °C DQMR_DEFQS_ElecFlt == FALSE DQMR_DEFQS_SENT_ElecFA == FALSE DQMR_DEFQS_SENT_PerfFA == FALSE DQMR_DEFQS_TempFlt == FALSE DQMR_DEFQS_PZT_ElecFlt == FALSE	Time counter: 4,200.00 fails out of 4,300.00 samples Task = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Quality Sensor Circuit Low	P206C	This diagnosis verifies if DEF Quality Sensor read out of range low	The Reductant Quality Sensor PZT Input Voltage Low error status is provided to the ECM by the DEF-C via CAN bus. This monitor checks if the DEF-C Sensor read out of range low.	Reductant Quality Sensor PZT Input Voltage < 0.15 V (Input to Speed of Sound Signal Conditioning)	Run/Crank is Active Engine in Cranking Phase Powertrain relay voltage No loss of CAN communication No fault messages from the DEF-C Controller	TRUE FALSE > 11.00 V CAN_LostComm_FltN_BusB_DEF_C == FALSE TRUE	Time counter: 40.00 fails out of 50.00 samples Task = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Quality Sensor Circuit High	P206D	This diagnosis verifies if DEF Quality Sensor sensor read out of range high	The Reductant Quality Sensor PZT Input Voltage High error status is provided to the ECM by the DEF-C via CAN bus. This monitor checks if the DEF-C Sensor read out of range high.	Reductant Quality Sensor PZT Input Voltage > 4.5 V (Input to Speed of Sound Signal Conditioning)	Run/Crank is Active Engine in Cranking Phase Powertrain relay voltage No loss of CAN communication No fault messages from the DEF-C Controller	TRUE FALSE > 11.00 V CAN_LostComm_FltN_BusB_DEF_C == FALSE TRUE	Time counter: 40.00 fails out of 50.00 samples Task = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Pump Control Circuit	P208A	This diagnosis verifies that the DEF pump phases are open	Motor Pump Phase Open Error status provided by DEF control module == FAULT		Test enabled by calibration Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN comunication Motor Pump Phase Open Error status provided by DEF control module different from indeterminate	1.00 > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR)	32.00 failures out of 40.00 samples Time basis = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Pump Control Circuit Low Voltage	P208C	This diagnosis verifies that the DEF pump phases are shorted to ground	Motor Pump Phase Shorted To Ground Error status provided by DEF control module == FAULT	VeSCRR_e_PmpMtrShrtToGND==FAULT	Test enabled by calibration Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN comunication Motor Pump Phase Shorted To Ground Error status provided by DEF control module different from indeterminate	1.00 > 11.00 [V] (VeLVTR_b_PT_RelayInRange== TRUE) VePMDR_b_RunCrankActive==TRUE VeEMDR_b_EngModeCrank == FALSE U010E, Lost Communication With Reductant Control Module (SCR) (GetCANR_b_LostComm_FltN= FALSE) VeSCRR_e_PmpMtrShrtToGND != Indeterminate	20.00 failures out of 25.00 samples Time basis = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Pump Control Circuit High Voltage	P208D	This diagnosis verifies that the DEF pump phases are shorted to battery	Motor Pump Phase Shorted To Battery Error status provided by DEF control module == FAULT		Test enabled by calibration Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN comunication Motor Pump Phase Shorted To Battery Error status provided by DEF control module different from indeterminate	1.00 > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR)	20.00 failures out of 25.00 samples Time basis = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Heater 1 Control Circuit	P20B9	This diagnosis verifies if the DEF tank heater is affected by open circuit	Tank Heater Open circuit status == FAULT		Test enabled by calibration Temperature used by the heating strategy to switch on the heaters < threshold Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN comunication DEF Temperature sensor not in fault Open circuit status provided by DEF control module different from indeterminate	1.00 < 60.00 > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR) SCR_DEFTS_FA== FALSE	8.00 failures out of 10.00 samples Time basis = 500ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF tank heater plausibility check	P20BA	This diagnosis verifies that the DEF tank heater resistance value is not plausible	DEF tank heater resistance not plausible (too different from the nominal one) DEF tank heater resistance outside the range	 (1.05 ; 1.93) [ohm]	Test enabled by calibration Battery voltage Key on (OR engine running) Engine is not cranking No SCR Power Module CAN loss of communication No electrical faults affecting the tank heater Heating strategy is requesting the Heater to be activated Time passed since heater activation > threshold Tank heater supply under-voltage fault not present Tank heater supply over-voltage fault not present	1.00 > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR) SCR_DEFTH_ElecFltSt == FALSE > 1.00 [s] SCR_TankHeatSplyVoltFA == FALSE SCR_DEFTH_SplyVoltHiFA	16.00 failures out of 20.00 samples Time basis = 500ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Heater 1 Control Circuit Low Voltage	P20BB	This diagnosis verifies if the DEF tank heater is affected by short circuit to ground	Tank Heater Short to Ground Low Side / High Side status == FAULT		Test enabled by calibration Temperature used by the heating strategy to switch on the heaters < threshold Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN comunication DEF Temperature sensor not in fault Short to Ground Low Side / High Side status provided by DEF control module different from indeterminate	1.00 < 60.00 > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR) SCR_DEFTS_FA== FALSE	8.00 failures out of 10.00 samples Time basis = 500ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Heater 1 Control Circuit High Voltage	P20BC	This diagnosis verifies if the DEF tank heater is affected by short circuit to battery	Tank Heater Short to Battery Low Side / High Side status == FAULT		Test enabled by calibration Temperature used by the heating strategy to switch on the heaters < threshold Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN comunication DEF Temperature sensor not in fault Short to Battery Low Side / High Side status provided by DEF control module different from indeterminate	1.00 failures out of < 60.00 10.00 samples > 11.00 [V] Time basis = 500ms U010E, Lost Communication With Reductant Control Module (SCR) SCR_DEFTS_FA== FALSE	8.00	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Heater 2 Control Circuit	P20BD	This diagnosis verifies if the DEF line heater is affected by open circuit	Line Heater Open circuit status == FAULT		Test enabled by calibration Temperature used by the heating strategy to switch on the heaters < threshold Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN comunication Open circuit status provided by DEF control module different from indeterminate	1.00 < 60.00 > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR)	8.00 failures out of 10.00 samples Time basis = 500ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF line heater plausibility check	P20BE	This diagnosis verifies that the DEF line heater resistance value is not plausible	DEF line heater resistance value not plausible (too different from the nominal one)	(Heater supply voltage/ Heater Current) > 3.68 OR (Heater supply voltage/ Heater Current) < 1.22	Test enabled by calibration Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN comunication No electrical faults affecting the line heater Heating strategy is requesting the Heater to be activated Time since heater activation > threshold Line heater supply under-voltage fault not present Line heater supply under-voltage fault not present	1.00 > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR) SCR_DEFLH_ElecFltSt ==FALSE VeSCRR_b_HeatB_On == TRUE > 1.00 SCR_LineHeatSplyVoltFA == FALSE SCR_DEFLH_SplyVoltHiFA	16.00 failures out of 20.00 samples Time basis = 500ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Heater 2 Control Circuit Low Voltage	P20BF	This diagnosis verifies if the DEF line heater is affected by short circuit to ground	Line Heater Short to Ground Low Side / High Side status == FAULT		Test enabled by calibration Temperature used by the heating strategy to switch on the heaters < threshold Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN comunication Short to Ground Low Side / High Side status provided by DEF control module different from indeterminate	1.00 < 60.00 > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR)	8.00 failures out of 10.00 samples Time basis = 500ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Heater 2 Control Circuit High Voltage	P20C0	This diagnosis verifies if the DEF line heater is affected by short circuit to battery	Line Heater Short to Battery Low Side / High Side status == FAULT		Test enabled by calibration Temperature used by the heating strategy to switch on the heaters < threshold Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN comunication Short to Battery Low Side / High Side status provided by DEF control module different from indeterminate	1.00 < 60.00 > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR)	8.00 failures out of 10.00 samples Time basis = 500ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Pressure Too Low	P20E8	This diagnosis verifies that the DEF pressure is lower than the target value set by the control	(Test 1) Too attemps of pressure build up (Test 2) DEF pressure setpoint - DEF measured pressure > calibrateable threshold	(Test 1) > 2.00 (Test 2) > 166.00	Test enabled by calibration Battery voltage Key on (OR engine running) Defrost complete Motor pump rotor stall fault not present No fault on DEF pressure sensor No fault on PWM command No electrical fault on DEF pump No electrical fault on DEF dosing valve Motor pump is no more green (some build pressure attempts already performed since the beginning of vehicle life). Time elapsed from the first build up attempt	1.00 > 11.00 [V] SCR_PmpRtrStlFA == FALSE SCR_DEFPS_FA== FALSE SCR_DEF_PumpCmdFA == FALSE SCR_DEFPM_FA == FALSE SCR_DEFMV_FA == FALSE > 1,200.00 [s]	40.00 failures out of 50.00 samples Time basis = 500ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					(Test 1) Pressure Build-Up state is released for the first time during the driving cycle AND Test-Pass OR Test-Fail has not been reported for this test (Test 2) DEF pressure control is in pressure closed loop			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Pressure Too High	P20E9	This diagnosis verifies that the DEF pressure in the dosing line is too high	Difference between "DEF line pressure" and "DEF line pressure set point" > Threshold AND Pump rotor speed < Threshold	> 150.00 < 3,200.00	Test enabled by calibration Battery voltage Key on (OR engine running) DEF pressure sensor not in fault PWM_pump_command not in fault DEF pressure control status equal to “Closed loop control” DEF motor pump not in fault Pump motor speed signal valid on CAN	1.00 > 11.00 [V] SCR_DEFPS_FA== FALSE SCR_DEF_PumpCmdFA == FALSE VeSCRC_e_SCR_PresState == CeSCRC_e_PresCntrlCLC SCR_DEFPM_FA	200.00 failures out of 250.00 samples Time basis = 25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
SCR NOx Catalyst Efficiency Below Threshold Bank 1 - EWMA Enabled	P20EE	The diagnosis checks if there is a malfunction in the SCR NOx conversion system measuring its SCR NOx conversion efficiency. SCR NOx conversion efficiency is evaluated by two NOx sensors (upstream & downstream SCR). The monitoring is executed by comparing measured NOx conversion efficiency and reference efficiency: - Measured NOx conversion efficiency is calculated as $\eta\_Eff\_Msrd = 1 - [\int NOx\_Dwn\_Msrd / \int NOx\_Up\_Msrd]$ - Reference efficiency is evaluated as $\eta\_Eff\_Ref = 1 - [\int NOx\_Dwn\_Ref / \int NOx\_Up\_Msrd]$ NOx_Dwn_Ref is calsulated as	EWMA filtering is applied to the difference between measured SCR NOx conversion efficiency (η_Eff_Msrd)) and reference efficiency (η_Eff_Ref). For the calculation of η_Eff_Ref, a fixed value of SCR_eff_estimated equal to 1 is used if 0.00 == 1 [Boolean]. Otherwise, the estimated efficiency provided by model (SCR_eff_estimated) is used.	Fail threshold is = 0, Repass threshold is = 0	Test enabled by calibration; No active DTCs; Debounce time elapsed after SCR chemical model is healed; Debounce time elapsed after exiting from transient dosing forced by remedial action (conditions active only if Market ≠ USA_CARB); Diagnostic system not disabled; Test not yet executed on current key cycle except the case where EWMA filtering is in Rapid Response (RR) or Fast Initial Response (FIR) state; Tests per trip up to calibratable value when EWMA filter is in Fast Initial Response (FIR)	CalOut = 1 [Boolean]; ≠ NOX_Snsr1_NOx_Flt ≠ NOX_NOx_SnsrSCR_DwnFlt ≠ EGT_TempSCR_UpFlt ≠ EGP_PresSCR_UpFlt ≠ EXM_TurbFlowNotValid ≠ SCR_RDP_Flt ≠ SCR_TipStuckFltSt ≠ SCR_DEFMV_FA ≠ SCR_ChemicalMdlFlt; Debounce = 300 [sec]; Debounce = 300 [sec]; NotDsbl = True [Boolean]; NotRun = True [Boolean]; FIR test trip < 1 ;	One failure to set the DTC.	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		NOx_Dwn_Ref = NOx_Up_Msrd * (1 - (SCR_eff_estimated - offset)) SCR_eff_estimated comes from SCR chemical model and it takes into account the estimated amount of NOx at SCR outlet: SCR_eff_estimated = 1 - (NOx_Dwn_Est / NOx_Up_Msrd) The offset (**K_EffOffset**) is calibrated in order to detect a malfunction. Test is performed when NOx integral upstream SCR reaches 500.00 [mg]. Use this section if EWMA filter is enabled (1.00 == 1 [Boolean]).			state; Total tests executed in Fast Initial Response (FIR) state up to calibratable value; Tests per trip up to calibratable value when EWMA filter is in Rapid Response (RR) state; Total tests executed in Rapid Response (RR) state up to calibratable value; DEF system ready to inject; Urea inside the tank not frozen; Debounce time elapsed after DEF defrost has been completed; Engine torque request higher than calibration; Rate of change of estimated efficiency (from SCR catalyst model) less than or equal to a calibratable value; Debounce time elapsed when estimated efficiency stable condition becomes true;	FIR tot tests < 2 ; RR test trip < 6 ; RR tot tests < 6 ; DEF ready = True [Boolean]; DEF tank status = DEF_TankNotFrozen [Enumerative]; Debounce = 300 [sec]; Torque >= 65 [Nm]; |Rate of change of estimated efficiency| <= 1 [-] Debounce = 0 [sec];		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Upstream SCR NOx sensor measurement reliable;	Reliable = True [Boolean];		
					Downstream SCR NOx sensor measurement reliable;	Reliable = True [Boolean];		
					Slip detection reliable;	Slip reliable = True [Boolean];		
					Number of DPF regeneration events successfully completed after vehicle exits from assembly plant (SCR catalyst de-greened);	DPF Rgn Compt > 1 [-];		
					SCR service bay test not active;	Service Bay Test == ServNotRunning [Enumerative];		
					Debounce time elapsed after exiting from SCR service bay test;	Debounce = 300 [sec];		
					Outside ambient temperature higher than calibration with hysteresis;	OAT > -20 [°C]; -21 [°C] < hysteresis range < -20 [°C]		
					Ambient pressure higher than calibration with hysteresis;	Pressure > 70 [kPa]; 70 [°C] < hysteresis range < 70 [°C]		
					Urea dosing activation by SCR mean temperature condition;	SCR mean temperature > 190 [°C]; 180 [°C] < hysteresis range < 190 [°C]		
					Debounce time elapsed after urea dosing activation by SCR mean	Debounce = 180 [sec];		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					temperature becomes true; Difference between SCR upstream and SCR downstream temperatures: - higher than first calibration curve (f[SCR mean temperature]) AND - lower than second calibration curve (f[SCR mean temperature]); Debounce time elapsed when difference between SCR upstream and SCR downstream temperature condition becomes in range; Exhaust mass flow and SCR average temperature within calibratable limits defined by 2 size table (f [exhaust mass flow, SCR average temperature]), enabled if table output is greater than calibration; Debounce time elapsed when exhaust mass flow and SCR average temperature conditions get within limits; SCR mean temperature time derivative within limits defined by	SCR up/down diff temperature > **T_MinTempGrad** [°C] Temperature < **T_MaxTempGrad** [°C]; Debounce = 25 [sec]; **K_EffExhFlowCond** > 1 [-]; Debounce = 25 [sec]; -5 < Delta temperature < 3 [°C/sec];		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					maximum and minimum calibrations and debounce time elapsed based on following logic: - while SCR mean temperature time derivative is outside the limits, the system continuously evaluates the debounce time based on calibration curve (f[SCR mean temperature time derivative]) and records the maximum value; - instead when SCR mean temperature time derivative gets within the limits, countdown starts until debounce time has been reached;	Debounce = **t_DerTempDsblTmr** [sec];		
					Upstream SCR NOx flow measurement lower than calibration and debounce time elapsed based on following logic: - while SCR NOx flow measurement higher than calibration, the system continuously evaluates the NOx average flow; - instead when SCR NOx flow measurement gets lower than calibration, debounce time based on calibration curve (f[NOx average flow, time spent with NOx flow higher than calibration]) is evaluated and countdown starts until debounce time	NOx up flow < 110 [mg/s]; Debounce = **t_NOxFlowIncDsblTmr** [sec]; Max debounce = 5 [sec];		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					has been elapsed. Limitation on the debouce time is always applied;			
					Upstream SCR NOx flow measurement higher than calibration;	NOx up flow > 18 [mg/s];		
					Upstream SCR NOx sensor measurement higher than calibration;	NOx up > 200 [ppm];		
					Upstream SCR NOx sensor measurement lower than calibration;	NOx up < 800 [ppm];		
					Downstream SCR NOx sensor measurement higher than calibration;	NOx dwn > -1 [ppm];		
					Upstream SCR absolute NOx flow derivative lower than calibration;	Delta NOx up flow < 35 [mg/sec^2];		
					NO2/NOx ratio: - higher than first calibratable value AND - lower than second calibratable value;	 NO2/NOx > 0 [-] NO2/NOx < 1 [-];		
					Debounce time elapsed when all NOx conditions (except upstream SCR NOx flow measurement lower than calibration) become true;	Debounce = 0 [sec];		
					Slip conditions: - debounce time elapsed when no slip is detected any more,	Debounce = 30 [sec]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					OR - when slip is active NOx upstream flow accumulated shall be greater than a calibration curve (f[SCR temperature]);	∫ NOx_Up > **m_SlipNOxIntglThrsh** [mg];		
					DPF / DeHC combustion modes not active;	Cmb ≠ DPF_HiO2 | DPF_LoO2 | DPF_EngPrtct_HiO2 | DPF_EngPrtct_LoO2 | DPF_PN | DPF_RichIdle | DeHC_Drive | DeHC_Park [Enumerative];		
					Debounce time elapsed after exiting from DPF / DeHC combustion modes;	Debounce = 300 [sec];		
					NH3 storage deviation error: - higher than first calibration curve (f[SCR average temperature]) AND - lower than second calibration curve (f[SCR average temperature]);	NH3 deviation > **m_NH3_StrgDevErrMinThrsh** [g] NH3 deviation < **m_NH3_StrgDevErrMaxThrsh** [g];		
					NH3 storage: - higher than first calibration curve (f[SCR average temperature]) AND - lower than second calibration curve (f[SCR average temperature]);	NH3 storage > **m_NH3_StrgMinThrsh** [g] NH3 storage < **m_NH3_StrgMaxThrsh** [g];		
					Debounce time elapsed when NH3 storage	Debounce = 0 [sec];		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					deviation error or NH3 storage condition becomes in range; SCR dosing in NH3 storage control or in intrusive NH3 storage control; Debounce time elapsed when switching to NH3 storage control or intrusive NH3 storage control; Diesel Exhaust Fluid quality measurement (concentration read by DEF quality sensor) higher than calibration with hysteresis (condition active only if DEF quality sensor is available);	Dos = NH3_StrgCntrl | Intrsv_NH3_StrgCntrl [Enumerative]; Debounce = 0 [sec]; DEF concentration > 29 [Pct]; 26 [Pct] < hysteresis range < 29 [Pct] DEFQS present= 1 [Boolean];		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Accelerator Pedal Position (APP) Sensor 1 Lo	P2122	Detects a continuous or intermittent short low or open in the APP sensor #1 by monitoring the APP1 sensor percent Vref and failing the diagnostic when the APP1 percent Vref is too low. This diagnostic only runs when battery voltage is high enough. Detects a continuous or intermittent short low or open in the APP sensor #1 on the Main processor.	APP1 percent Vref	< 0.4625 % Vref	Run/Crank voltage No 5V reference error or fault for # 4 5V reference circuit	> 6.41 Volts P06A3	19 / 39 counts; or 14 counts continuous; 12.5 ms/count in the main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Accelerator Pedal Position (APP) Sensor 1 Hi	P2123	Detects a continuous or intermittent short high in the APP sensor #1 by monitoring the APP1 sensor percent Vref and failing the diagnostic when the APP1 percent Vref is too high. This diagnostic only runs when battery voltage is high enough. Detect a continuous or intermittent short high in the APP sensor #1 on the Main processor.	APP1 percent Vref >	4.7500 % Vref	Run/Crank voltage No 5V reference error or fault for # 4 5V reference circuit	> 6.41 Volts P06A3	19 / 39 counts; or 14 counts continuous; 12.5 ms/count in the main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Accelerator Pedal Position (APP) Sensor 2 Lo	P2127	Detects a continuous or intermittent short low or open in the APP sensor #2 by monitoring the APP2 sensor percent Vref and failing the diagnostic when the APP2 percent Vref is too low. This diagnostic only runs when battery voltage is high enough. Detects a continuous or intermittent short low or open in the APP sensor #2 on the Main processor.	APP2 percent Vref <	0.3250 % Vref	Run/Crank voltage No 5V reference error or fault for # 4 5V reference circuit	> 6.41 Volts P0697	19 / 39 counts; or 14 counts continuous; 12.5 ms/count in the main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Accelerator Pedal Position (APP) Sensor 2 Hi	P2128	Detects a continuous or intermittent short high in the APP sensor #2 by monitoring the APP2 sensor percent Vref and failing the diagnostic when the APP2 percent Vref is too high. This diagnostic only runs when battery voltage is high enough. Detect a continuous or intermittent short high in the APP sensor #2 on the Main processor.	APP2 percent Vref >	2.6000 % Vref	Run/Crank voltage No 5V reference error or fault for # 4 5V reference circuit	> 6.41 Volts P0697	19 / 39 counts; or 14 counts continuous; 12.5 ms/count in the main processor	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Accelerator Pedal Position (APP) Sensor 1-2 Correlation	P2138	Detect a continuous or intermittent correlation fault between APP sensors #1 and #2 on Main processor. 1.) The diagnostic monitors the difference in position between APP1 and the APP2 and fails the diagnostic when the difference is too high. This diagnostic only runs when the battery voltage is high enough. 2.) The diagnostic also monitors the difference in reference voltage between normalized min APP1 and the normalized min APP2 and fails the diagnostic when the difference is too high. This diagnostic only runs when the battery voltage is high enough. Detects a continuous or intermittent correlation fault between APP sensors #1 and #2 on Main processor	Difference between APP1 displaced and APP2 displaced >	5.000 % offset at min. pedal position with a linear threshold to 10.001 % at max. pedal position	Run/Crank voltage No APP sensor faults No 5V reference errors or faulst for # 3 & # 4 5V reference circuits	> 6.41 Volts (P2122, P2123,P2127, P2128) (P06A3, P0697)	19 / 39 counts intermittent; or 15 counts continuous, 12.5 ms/count in the main processor	Type A, 1 Trips
			Difference between (normalized min APP1) and (normalized min APP2) >	5.000 % Vref	Run/Crank voltage No APP sensor faults No 5V reference errors or faulst for # 3 & # 4 5V reference circuits	> 6.41 Volts (P2122, P2123,P2127, P2128) (P06A3, P0697)	19 / 39 counts intermittent; or 15 counts continuous, 12.5 ms/count in the main processor	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector Positive Voltage Control Circuit Group 1 Low Voltage	P2147	This DTC detects a short circuit to ground of the high side driver circuit of the Bank 1 (injector 1 and 4)	Voltage high across High Side Driver of bank 1 (injector 1 and 4) during On state indicates short to ground	impedence between HS pin of injector 1 and controller ground <= 0.5 [Ohm] OR impedence between HS pin of injector 4 and controller ground <= 0.5 [Ohm]	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and (FUL_OutEnblCyl_CiEPSR_CylinderA OR FUL_OutEnblCyl_CiEPSR_CylinderE) and (FUL_FuelInjectedCyl_CiEPSR_CylinderA OR FUL_FuelInjectedCyl_CiEPSR_CylinderE)	= 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] == 0 [Boolean] == TRUE); == TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector Positive Voltage Control Circuit Group 1 High Voltage	P2148	This DTC detects a short circuit to high voltage of high side driver circuit of the Bank 1 (injector 1 and 4)	Voltage low across High side drive of bank 1 (injector 1 and 4) during off state indicates short to power	impedence between HS pin of injector 1 and controller power <= 0.5 [Ohm] OR impedence between HS pin of injector 4 and controller power <= 0.5 [Ohm]	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and (FUL_OutEnblCyl_CiEPSR_CylinderA OR FUL_OutEnblCyl_CiEPSR_CylinderE) and (FUL_FuelInjectedCyl_CiEPSR_CylinderA OR FUL_FuelInjectedCyl_CiEPSR_CylinderE)	= 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] == 0 [Boolean] == TRUE); == TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Pump A Current Too High	P214E	This diagnosis verifies that the DEF pump current flow is too high	Motor High Current Error status provided by DEF control module == FAULT OR Motor Current Limit Error status provided by DEF control module == FAULT		Test enabled by calibration Battery voltage Key on (OR engine running) Engine is not cranking No loss of CAN comunication Motor High Current Error status provided by DEF control module different from indeterminate	1.00 > 11.00 [V] U010E, Lost Communication With Reductant Control Module (SCR)	20.00 failures out of 25.00 samples OR 20.00 failures out of 25.00 samples Time basis = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector Positive Voltage Control Circuit Group 2 Low Voltage	P2150	This DTC detects a short circuit to ground of the high side driver circuit of the Bank 2 (injector 2 and 5)	Voltage high across High Side Driver of bank 2 (injector 2 and 5) during On state indicates short to ground	impedence between HS pin of injector 2 and controller ground <= 0.5 [Ohm] OR impedence between HS pin of injector 5 and controller ground <= 0.5 [Ohm]	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and (FUL_OutEnblCyl_CiEPSR_CylinderB OR FUL_OutEnblCyl_CiEPSR_CylinderF) and (FUL_FuelInjectedCyl_CiEPSR_CylinderB OR FUL_FuelInjectedCyl_CiEPSR_CylinderF)	= 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] == 0 [Boolean] == TRUE); == TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Injector Positive Voltage Control Circuit Group 2 High Voltage	P2151	This DTC detects a short circuit to high voltage of high side driver circuit of the Bank 2 (injector 2 and 5)	Voltage low across High side drive of bank 2 (injector 2 and 5) during off state indicates short to power	impedence between HS pin of injector 2 and controller power <= 0.5 [Ohm] OR impedence between HS pin of injector 5 and controller power <= 0.5 [Ohm]	Test enabled by calibration; and Battery voltage and Key ON and Engine is not cranking and Engine Running and (FUL_OutEnblCyl_CiEPSR_CylinderB OR FUL_OutEnblCyl_CiEPSR_CylinderF) and (FUL_FuelInjectedCyl_CiEPSR_CylinderB OR FUL_FuelInjectedCyl_CiEPSR_CylinderF)	= 1 [Boolean] > 11.00 [V] - - >= 1.00 [s] == 0 [Boolean] == 0 [Boolean] == TRUE); == TRUE);	5 failures out of 10 samples 100 ms/sample Continuous	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Transfer Case Speed Sensor Output (TCSS)	P2160	The diagnostic monitor detects no activity in the TCSS circuit due to an electrical fault, wiring fault or sensor fault. The TCSS signal is rationalized against operating conditions of the vehicle. If the vehicle is in motion, accelerator pedal, engine torque, transmission in gear, and no vehicle braking, and the TCSS signal registers below a threshold, the DTC will set.	transfer case output shaft speed sesnor raw speed	≤ 25.0 RPM	diagnotic monitor enable calibration transmission gear selector position AND engine torque AND engine torque NOT AND accelerator pedal position AND accelerator pedal position NOT transmission gear selector position AND engine torque AND engine torque NOT AND accelerator pedal position AND accelerator pedal position NOT run/crank voltage run/crank voltage engine power limited PTO active engine speed transmission output shaft speed update range change delay time when condition A or condition B or condition C (25 millisecond update rate):	= 1 Boolean = PARK OR NEUTRAL ≥ 8,191.75 Nm ≤ 8,191.75 Nm ≥ 100.00 % ≤ 8.00 % ≠ PARK AND ≠ NEUTRAL ≥ 80.00 Nm ≤ 35.00 ≥ 5.00 % ≤ 3.00 % ≥ 6.0 volts for 25 milliseconds ≥ 9.0 volts = FALSE Boolean = FALSE Boolean ≥ 300.0 RPM ≥ 181.0 RPM	fail time ≥ 4.50 seconds 25 millisecond update rate range change delay time ≥	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					condition A: transmission range state transmission range state previous loop (25 millisecond) condition B: test when transmission range state is reverse enable calibration AND transmission range state transmission range state previous loop (25 millisecond) condition C: test when transmission range state is neutral enable calibration AND transmission range state transmission range state previous loop (25 millisecond) P2161 test fail this key on P2160 test fail this key on P2160 fault active DTCs not fault active	 = drive8 or less = drive8 or less = 0 Boolean = REVERSE = REVERSE = 0 Boolean = NEUTRAL = NEUTRAL = FALSE Boolean = FALSE Boolean = FALSE Boolean Transmission Output Shaft Angular Velocity Validity CrankSensor_FA EngineTorqueEstInaccurate	**P2160 range change delay time** seconds Refer to "Transmission Supporting Tables" for details	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Transfer Case Speed Sensor Output (TCSS)	P2161	The diagnostic monitor detects an unrealistic drop in the TCSS signal due to a sudden electrical fault, wiring fault or sensor fault. The TCSS signal is rationalized against operating conditions of the vehicle. If the vehicle is in motion, accelerator pedal, engine torque, transmission in gear, and no vehicle braking, and the TCSS signal drops above a delta threshold, a fail timer is enabled. When a TCSS drop occurs it is possible to enable the P2160 fail time as well as the PP2161 fail time. With both P2160 and P2161 fail timers active it is a race condition to either DTC.	transfer case speed sesnor raw speed delta, 25 millisecond update rate	≥ 650.0 RPM	diagnotic monitor enable calibration update range change delay time when condition A or condition B or condition C (25 millisecond update rate): condition A: transmission range state transmission range state previous loop (25 millisecond) condition B: test when transmission range state is reverse enable calibration AND transmission range state transmission range state previous loop (25 millisecond) condition C: test when transmission range state is neutral enable calibration AND transmission range state transmission range state previous loop (25 millisecond)	= 1 Boolean = drive8 or less = drive8 or less = 0 Boolean = REVERSE = REVERSE = 0 Boolean = NEUTRAL = NEUTRAL	fail time ≥ 3.00 seconds, 25 millisecond update rate, increment fail count fail count ≥ 5 counts, 25 millisecond update rate range change delay time ≥ **P2161 range change delay time** seconds Refer to "Transmission Supporting Tables" for details	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					run/crank voltage	≥ 6.0 volts for 25 milliseconds		
					run/crank voltage	≥ 9.0 volts		
					PTO active	= FALSE Boolean		
					transfer case mode	≠ transfer case mode previos loop (25 millisecond) update 4WD range change time		
					4WD range change time	≥ 5.00 seconds		
					engine speed	≥ 500.0 RPM		
					transmission output shaft speed loop to loop delta (25 millisecond)	≤ 4,095.0 RPM		
					AND			
					transmission output shaft speed	≥ 350.0 RPM		
					update stability time	≥ 0.00 seconds		
					stability time			
					transfer case raw output speed	> 150.0 RPM		
					AND			
					transfer case raw output speed last loop (25 millisecond)	> 150.0 RPM		
					update stability time			
					stability time	≥ 6.00 seconds		
					P2160 test fail this key on	= FALSE		
					P2160 fault active	= FALSE		
					DTCs not fault active	CrankSensor_FA TransmissionEngagedState_FA Transmission Output Shaft Angular Velocity Validity		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Intake Air Temperature Sensor 1 / 2 Correlation	P2199	Detects when the Intake Air Temperature (IAT) sensor and IAT2 sensor values do not correlate with each other. These two temperature sensors are both in the induction system, although they do have different sensor time constants and different positional relationships with components that produce heat. If these two temperature values differ by a large enough amount, the Intake Air Temperature 1 / 2 Correlation Diagnostic will fail. This diagnostic is enabled if the Powertrain Relay voltage is high enough.	ABS (IAT - IAT2)	> 55.0 deg C	Powertrain Relay Voltage for a time No Active DTCs:	>= 11.0 Volts >= 0.9 seconds PowertrainRelayFault	40 failures out of 50 samples 1 sample every 100 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Level Sensor Stuck (continuous sensor)	P21C5	Continuous level sensor is able to measure small changes in height of DEF tank fluid so variation of level value is expected when fast accelerations or decelerations cause fluid sloshing. This monitor detects when a fault is causing measurements being constant during steep variations of vehicle speed.This diagnosis verifies that the DEF level sensor signal is stuck in range.	Difference between maximum and minimum DEF level values, sampled while vehicle is strongly accelerating	> 0.3 %	Sensor Bus Wake Up signal is active At least one message has been received by DEF device (Engine off timer AND Tank Temperature sampled at init AND UTLC Temperature sampled at init AND Tank Temperature greater AND UTLC Temperature) OR (Tank Temperature AND UTLC Temperature) Amount of valid level values since last test has run, sampled while vehicle is strongly accelerating, Absolute derivative of vehicle speed Estimated tank level volume No fault for: - serial communication with DEF device (SCRPM)	 > 14,400 s > -6.0 °C > -6.0 °C > -9.0 °C > -9.0 °C > -4.0 °C > -2.0 °C > 15 samples < 99.00 m/s^2 0.2 l < volume < 99.0 l U010E	14.00 failures out of 15.00 samples Time basis = 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					- sensor bus wake up signal - level sensor out of range - DEF tank temperature sensor - UTLC temperature sensor - vehicle speed	SCR_DEFLS_ElecFltSt SCR_DEFTS_FA		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
SCRPM supply under-voltage monitoring	P21CB	This diagnosis verifies that the SCRPM supply voltage is under the threshold of correct functioning	SCRPM supply under-voltage (System Battery Voltage - SCRPM Supply Voltage value)	> 3.00	Test enabled by calibration Powertrain relay in range Run Crank Active Cranking phase excluded No SCR Power Module CAN loss of communication	1.00 U010E, Lost Communication With Reductant Control Module (SCR)	40.00 failures out of 50.00 samples Time basis = 100ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Circuit Low Bank 1 Sensor 1	P2202	This diagnosis verifies Upstream NOx sensor read out of range low	Check if the NOx1 sensor NOx concentration raw read is out of lower range: NOx raw read	< -90 ppm	Fuel injection quantity request Powertrain relay voltage NOx Sensor Bus relay is commanded ON No failure on NOx1 CAN communication Sensor supply in range Sensor dewpoint is reached No current control failure on NOx1 sensor No electrical failure on NOx1 sensor Combustion mode dependent enabling flag	> 10 mm^3 > 11.00 V TRUE CAN_LostComm_FltN_BusB_NOxSnsr_A > 10.80 V TRUE NOX_NOx1_StBitChkFlt ==FALSE NOX_Snsr1_ElecFA ==FALSE **NOX_S1_OutRngMinCmbMode**	Time counter: 100 fails out of 200 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Circuit High Bank 1 Sensor 1	P2203	This diagnosis verifies Upstream NOx sensor read out of range high	Check if the NOx1 sensor NOx concentration raw read is out of higher range: NOx raw read	 > 2,500 ppm	Powertrain relay voltage NOx Sensor Bus relay is commanded ON No failure on NOx1 CAN communication Sensor supply in range Sensor dewpoint is reached No current control failure on NOx1 sensor No electrical failure on NOx1 sensor Combustion mode dependent enabling flag Engine running for a time longer than	> 11.00 V TRUE CAN_LostComm_FltN_BusB_NOxSnsr_A > 10.80 V TRUE NOX_NOx1_StBitChkFlt ==FALSE NOX_Snsr1_ElecFA ==FALSE **NOX_S1_OutRngMaxCmbMode** 0.00 s	Time counter: 200 fails out of 250 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 Heater Control Circuit	P2205	This diagnosis verifies Upstream NOx gen3 sensor Heater Supply pin Open Load Circuit	Check if there is an open circuit on NOx Sensor 1 Heater Supply pin (H+)	open circuit on H+ pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 Heater Control Circuit Low Voltage	P2206	This diagnosis verifies Upstream NOx gen3 sensor Heater Supply pin for Short to Ground	Check if there is an short circuit to ground on NOx Sensor 1 Heater Supply pin (H+)	groundshort on H+ pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 Heater Control Circuit High Voltage	P2207	This diagnosis verifies Upstream NOx gen3 sensor Heater Supply pin for Short to Battery	Check if there is an short circuit to power supply on NOx Sensor 1 Heater Supply pin (H+)	powershort on H+ pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 Heater Sense Circuit	P2208	This diagnosis verifies Upstream NOx gen3 sensor Heater sense resistance measurement pin for Open Load Circuit	Check if there is an open circuit on NOx Sensor 1 Heater Sense pin (HTemp)	open circuit on HTemp pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Heater Sense Circuit Range/ Performance Bank 1 Sensor 1	P2209	This diagnosis verifies if the Upstream NOx sensor Heater raw resistance is in range	This diagnosis verifies if the Upstream NOx sensor Heater raw resistance is out of speficied range: (Sensor heater raw resistance - Sensor heater target resistance) / Sensor heater target resistence	> 0.03 <- 0.03	Powertrain relay voltage No loss of communcation with Engine Out Nox Sensor No plausibility failure on NOx signal from NOx Sensor No offset failure on NOx signal from NOx Sensor No increasing dynamic failure on NOx signal coming from NOx Sensor No decreasing dynamic failure on NOx signal coming from NOx Sensor No circuit failure on NOx Sensor No out of range high failulre on NOx Signal No out of range low failulre on NOx Signal No DTC set: No failure on NOx Sensor Bus relay circuit NOx Sensor Bus relay is commanded ON Delay timer once sensor	> 11.00 V CAN_LostComm_FltN_BusB_NOxSnsr_A ==FALSE NOX_NOx1_NOxPlausFlt ==FALSE NOX_NOx1_OfstMontrFlt ==FALSE NOX_NOx1_IncrDynChkFlt ==FALSE NOX_NOx1_DecrDynChkFlt ==FALSE NOX_NOx1_StBitChkFlt ==FALSE NOX_NOx1_OutOfRngHiFlt ==FALSE NOX_NOx1_OutOfRngLoFlt ==FALSE P30B4 SBR_RlyFA==FALSE TRUE > 45 sec	Time counter: 50 fails out of 100 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					supply is in range (> 10.8 V) Delay timer once sensor dewpoint is reached Delay timer once engine is overrun Delay timer once DPF combustion mode is not active	 > 180 sec > 5 sec 30 sec		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Supply Voltage Circuit Bank 1 Sensor 1	P220A	This diagnosis verifies if the supply voltage of the Upstream Nox sensor is out of range	Check if NOx Sensor 1 supply voltage status is out of range	Sensor supply voltage < 10.80 V	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON a) NOx sensor Dewpoint is reached b) condition a) shall be fulfilled for time CAN_LostComm_FltN_BusB_NOxSnsr_A No DTC active:	TRUE > 11.00 V TRUE TRUE > 30 sec FALSE P30B4	Time counter: 240 fails out of 480 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Supply Voltage Circuit Bank 1 Sensor 2	P220B	This diagnosis verifies if the supply voltage of the Downstream Nox sensor is out of range	Check if NOxSensor 2 supply voltage status is out of range	Sensor supply voltage < 10.80 V	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON a) NOx sensor Dewpoint is reached b) condition a) shall be fulfilled for time CAN_LostComm_FltN_BusB_NOxSnsr_B No DTC active:	TRUE > 11.00 V TRUE TRUE > 30 sec FALSE P30B5	Time counter: 240 fails out of 480 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 Heater Sense Circuit Low Voltage	P2210	This diagnosis verifies Upstream NOx gen3 sensor Heater sense resistance measurement pin for Short to Ground	Check if there is a short circuit to ground on NOx Sensor 1 Heater Sense pin (HTemp)	groundshort on HTemp pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 1 Heater Sense Circuit High Voltage	P2211	This diagnosis verifies Upstream NOx gen3 sensor Heater sense resistance measurement pin for Short to Battery	Check if there is a short circuit to power supply NOx Sensor 1 Heater Sense pin (HTemp)	powershort on HTemp pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_A Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B4	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Barometric Pressure (BARO) Sensor Performance (3 intake air pressure sensor configuration)	P2227	This monitor is used to identify BARO sensor internal faults (measurement with an offset or a drift). The plausibility monitor compares the BARO, MAP and TCIAP pressures in two different conditions: - at idle (part of the test enabled when the engine is running) - between key off and when the engine starts running (part of the test enabled when the engine is not running). If BARO sensor is not in agreement with the other two the monitor is able to pinpoint BARO as the faulty sensor.	Difference (absolute value) in measured pressure between BARO sensor and TCIAP sensor AND Difference (absolute value) in measured pressure between BARO sensor and MAP sensor AND Difference (absolute value) in measured pressure between TCIAP sensor and MAP sensor	> **P0106, P2227, P227B, P00C7: Maximum pressure difference** [kPa] > **P0106, P2227, P227B, P00C7: Maximum pressure difference** [kPa] <= **P0106, P2227, P227B, P00C7: Maximum pressure difference** [kPa]	Correlation diagnostic enabled by calibration Engine is running Run Crankrelay supply voltage in range Engine speed Requested fuel Throttle measured position Engine Coolant Temperature No faults are present	== 0.00 > 11.00 [V] < 1.00 [rpm] < 1.00 [mm^3] > 100.00 [%] > 200.00 [°C] CrankSensor_FA ==FALSE FUL_GenericInjSysFA ==FALSE TPS_PstnSnsrFA ==FALSE MAP_SensorCircuitFA ==FALSE AAP2_SnsrCktFA ==FALSE AAP_AAP5_SnsrCktFA ==FALSE AAP_AAP2_SnsrStabFA ==FALSE AAP_AAP5_SnsrStabFA ==FALSE ECT_Sensor_FA	500.00 fail counters over 400.00 sample counters sampling time is 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						==FALSE MAF_MAF_SnsrFA ==FALSE		
			BARO Pressure OR BARO Pressure OR Difference (absolute value) in measured pressure between BARO sensor and TCIAP sensor AND Difference (absolute value) in measured pressure between BARO sensor and MAP sensor AND Difference (absolute value) in measured pressure between TCIAP sensor and MAP sensor	< 50.0 [kPa] > 115.0 [kPa] > 10.0 [kPa] > 10.0 [kPa] <= 10.0 [kPa]	Time between current ignition cycle and the last time the engine was running Engine is not rotating No Active DTCs: No Pending DTCs:	> 10.0 [s] EngineModeNotRunTimer Error MAP_SensorCircuitFA AAP_SnsrCktFA MAP_SensorCircuitFP AAP_SnsrCktFP	4 fail counters over 5 sample counters sampling time is 12.5 ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Barometric Pressure (BARO) Sensor Circuit Low (Diesel, pull-down)	P2228	Detects a continuous short to ground or open circuit in the Barometric Pressure (BARO) signal circuit by monitoring the BARO sensor output voltage and failing the diagnostic when the BARO voltage is too low. The BARO sensor is a pressure transducer which outputs a voltage proportional to the absolute pressure.	BARO Voltage	< 35.5 % of 5 Volt Range (This is equal to 50.0 kPa)			320 failures out of 400 samples 1 sample every 12.5 msec	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Barometric Pressure (BARO) Sensor Circuit High (Diesel, pull-down)	P2229	Detects a continuous short to power in the Barometric Pressure (BARO) signal circuit by monitoring the BARO sensor output voltage and failing the diagnostic when the BARO voltage is too high. The BARO sensor is a pressure transducer which outputs a voltage proportional to the absolute pressure.	BARO Voltage	> 94.1 % of 5 Volt Range (This is equal to 115.1 kPa)			320 failures out of 400 samples 1 sample every 12.5 msec	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Water in Fuel Sensor Circuit (Analog/ Active, Wired to ECM)	P2264	Monitor verifies that sensor output voltage is within expected range.	Water In Fuel sensor output (as percentage of supply voltage)	≥ 80 %	Powertrain relay voltage Ignition off time Ignition on time Software and Calibration versions match (refer to '*MEMR FNA Matched Flag*' free form) No error for Engine Not Running timer	≥ 11.0 V > 70.0 s > 0.10 s	5 failure out of 10 samples 100 ms/sample	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Turbocharger Inlet Pressure (TCIAP) Sensor Performance (3 intake air pressure sensor configuration)	P227B	This monitor is used to identify TCIAP sensor internal faults (measurement with an offset or a drift). The plausibility monitor compares the BARO, MAP and TCIAP pressures in two different conditions: - at idle (part of the test enabled when the engine is running) - between key off and when the engine starts running (part of the test enabled when the engine is not running) If TCIAP sensor is not in agreement with the other two the monitor is able to pinpoint TCIAP as the faulty sensor.	Difference (absolute value) in measured pressure between BARO sensor and TCIAP sensor AND Difference (absolute value) in measured pressure between TCIAP sensor and MAP sensor AND Difference (absolute value) in measured pressure between BARO sensor and MAP sensor	> **P0106, P2227, P227B, P00C7: Maximum pressure difference** [kPa] > **P0106, P2227, P227B, P00C7: Maximum pressure difference** [kPa] <= **P0106, P2227, P227B, P00C7: Maximum pressure difference** [kPa]	Correlation diagnostic enabled by calibration Engine is running Run Crank relay supply voltage in range Engine speed Requested fuel Throttle measured position Engine Coolant Temperature No faults are present	== 0.00 > 11.00 [V] < 1.00 [rpm] < 1.00 [mm^3] > 100.00 [%] > 200.00 [°C] CrankSensor_FA ==FALSE FUL_GenericInjSysFA ==FALSE TPS_PstnSnsrFA ==FALSE MAP_SensorCircuitFA ==FALSE AAP2_SnsrCktFA ==FALSE AAP_AAP5_SnsrCktFA ==FALSE AAP_AAP2_SnsrStabFA ==FALSE AAP_AAP5_SnsrStabFA ==FALSE	500.00 fail counters over 400.00 sample counters sampling time is 12.5 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						ECT_Sensor_FA ==FALSE MAF_MAF_SnsrFA ==FALSE		
			TCIAP Pressure OR TCIAP Pressure OR Difference (absolute value) in measured pressure between BARO sensor and TCIAP sensor AND Difference (absolute value) in measured pressure between TCIAP sensor and MAP sensor AND Difference (absolute value) in measured pressure between BARO sensor and MAP sensor	< 50.0 [kPa] > 115.0 [kPa] > 10.0 [kPa] > 10.0 [kPa] <= 10.0 [kPa]	Time between current ignition cycle and the last time the engine was running Engine is not rotating No Active DTCs: No Pending DTCs:	> 10.0 [s] EngineModeNotRunTimer Error MAP_SensorCircuitFA AAP_SnsrCktFA AAP2_SnsrCktFA AAP3_SnsrCktFA MAP_SensorCircuitFP AAP_SnsrCktFP AAP2_SnsrCktFP AAP3_SnsrCktFP	4 fail counters over 5 sample counters sampling time is 12.5ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Barometric Pressure Sensor Circuit C Low (Diesel, pull-up)	P227C	Detects a continuous short to ground in the Barometric Pressure (BARO) C signal circuit by monitoring the BARO C sensor output voltage and failing the diagnostic when the BARO C voltage is too low. The BARO C sensor is a pressure transducer which outputs a voltage proportional to the absolute pressure.	BARO C Voltage	< 39.0 % of 5 Volt Range (This is equal to 49.7 kPa)			320 failures out of 400 samples 1 sample every 12.5 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Barometric Pressure Sensor Circuit C High (Diesel, pull-up)	P227D	Detects a continuous short to power or open circuit in the Barometric Pressure (BARO) C signal circuit by monitoring the BARO C sensor output voltage and failing the diagnostic when the BARO C voltage is too high. The BARO C sensor is a pressure transducer which outputs a voltage proportional to the absolute pressure.	BARO C Voltage	> 90.0 % of 5 Volt Range (This is equal to 115.0 kPa)			320 failures out of 400 samples 1 sample every 12.5 msec	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Barometric Pressure Sensor C Circuit Intermittent/ Erratic	P227E	Detects a noisy or erratic signal in the barometric pressure (BARO) C circuit by monitoring the BARO C sensor and failing the diagnostic when the BARO C signal has a noisier output than is expected. When the value of BARO C in kilopascals (kPa) is determined, a delta is calculated between the current reading and the previous reading. The absolute value of these deltas is summed over a number of BARO C readings. The result of this summation is called a “string length”. Since the BARO C signal is anticipated to be relatively smooth, a string length of a particular magnitude indicates a noisy or erratic BARO C signal. The diagnostic will fail if the string length is too high.	String Length Where: "String Length" = sum of "Diff" calculated over And where: "Diff" = ABS(current BARO C reading - BARO C reading from 12.5 milliseconds previous)	> 150 kPa 80 consecutive BARO C readings			4 failures out of 5 samples Each sample takes 1.0 seconds	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Pressure Regulator 1 - Forced Engine Shutdown	P228A	Determine when rail pressure is lower than desired setpoint and metering unit actuator has achieved its maximum authority.	Rail pressure setpoint - measured rail pressure Commanded fuel flow for metering unit	> 40 MPa ≥ Maximum flow deliverable by high pressure pump (refer to *RailPresCntrl* section)	Run crank voltage Engine running Rail pressure is governed by Fuel Metering Unit (refer to *RailPresCntrl*) No DTC active since key is on:	≥ 11.0 V P000F	250 failures out of 750 samples 12.5 ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Pressure Regulator 2 - Forced Engine Shutdown	P228B	Determine when rail pressure is lower than desired setpoint and rail pressure regulator has achieved its maximum authority.	Rail pressure setpoint - measured rail pressure Commanded pressure for pressure regulator valve	> 40 MPa ≥ 30 to 210 MPa (see table **P228B Pressure Regulator completely closed command**)	Run crank voltage Engine running Pressure Regulator controlled in closed loop (refer to *RailPresCntrl*)	≥ 11.0 V	640 failures out of 800 samples 12.5 ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Pressure Regulator 1 Exceeded Control Limits - Pressure Too Low	P228C	Determine when rail pressure is lower than desired setpoint.	Rail pressure setpoint - measured rail pressure	> 12 to 80 MPa (see table **P228C Positive rail pressure deviation (MU)**)	Run crank voltage Engine running Fuel Metering Unit controlled in closed loop (refer to *RailPresCntrl*) Fuel injected quantity (Low fuel level calibrated as enabling condition OR LowFuelConditionDiagnostic (Air ambient pressure calibrated as enabling condition OR Air ambient pressure (Air ambient temperature calibrated as enabling condition OR Air ambient temperature No DTC active since key is on:	≥ 11.0 V > 20.0 mm^3/stroke == 1.00 == FALSE == 1.00 ≥ 60.00 == 1.00 ≥ -20.00 P000F	350 failures out of 750 samples 12.5 ms/sample	Type B, 2 Trips MIL is illuminated according to 'similar engine conditions' criteria.
			Rail pressure setpoint -		Run crank voltage	≥ 11.0 V	350 failures out	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			measured rail pressure	> 12 to 80 MPa (see table **P229A Positive rail pressure deviation (PR)**)	Engine running Pressure Regulator controlled in closed loop (refer to *RailPresCntrl*) Fuel injected quantity (Low fuel level calibrated as enabling condition OR LowFuelConditionDiagnostic (Air ambient pressure calibrated as enabling condition OR Air ambient pressure (Air ambient temperature calibrated as enabling condition OR Air ambient temperature	 > 20.0 mm^3/stroke == 1.00 = FALSE) == 1.00 ≥ 60 kPa) == 1.00 ≥ -20 °C)	of 750 samples 12.5 ms/sample	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Pressure Regulator 1 Exceeded Control Limits - Pressure Too High	P228D	Determine when rail pressure is greater than desired setpoint.	Rail pressure setpoint - measured rail pressure	< -80 to -15 MPa (see table **P228D Negative rail pressure deviation (MU)**	Run crank voltage Engine running Fuel Metering Unit controlled in closed loop (refer to *RailPresCntrl*) Fuel injected quantity Fuel temperature (Low fuel level calibrated as enabling condition OR LowFuelConditionDiagnostic (Air ambient pressure calibrated as enabling condition OR Air ambient pressure (Air ambient temperature calibrated as enabling condition OR Air ambient temperature	≥ 11.0 V > 20.0 mm^3/stroke > -40 °C == 1.00 = FALSE) == 1.00 ≥ 60.00 kPa) == 1.00 ≥ -20.00 °C)	350 failures out of 750 samples 12.5 ms/sample	Type B, 2 Trips MIL is illuminated according to 'similar engine conditions' criteria.
			Rail pressure setpoint - measured rail pressure	< -15 MPa	Run crank voltage Engine running	≥ 11.0 V	350 failures out of 750 samples	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Pressure Regulator controlled in closed loop (refer to RailPresCntrl) Fuel injected quantity (Low fuel level calibrated as enabling condition OR LowFuelConditionDiagnostic (Air ambient pressure calibrated as enabling condition OR Air ambient pressure (Air ambient temperature calibrated as enabling condition OR Air ambient temperature	 > 20.0 mm^3/stroke == 1.00 = FALSE) == 1.00 ≥ 60 kPa) == 1.00 ≥ -20 °C)	12.5 ms/sample	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Pressure Regulator 2 Performance	P2293	Determine when rail pressure is above maximum threshold when pressure is governed by Pressure Regulator valve.	Rail pressure	> 67 to 217 MPa (see table **P2293 Maximum rail pressure with PR**)	Run crank voltage Rail pressure is governed by Pressure Regulator (refer to *RailPresCntrl*)	≥ 11.0 V	160 failures out of 229 samples OR 160 continuous failures out of 229 samples 6.25 ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Pressure Regulator Solenoid 2 Control Circuit	P2294	Controller specific output driver circuit diagnoses the Rail Pressure Regulator valve low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit: impedance between signal and controller ground	≥ 200 kΩ	Powertrain relay voltage Run crank voltage Engine not cranking Pressure Regulator calibrated as present	≥ 11.0 V > 6.0 V	44 failures out of 88 samples 6.25 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Pressure Regulator Solenoid 2 Control Circuit Low Voltage	P2295	Controller specific output driver circuit diagnoses the Rail Pressure Regulator valve low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground: impedance between signal and controller ground	≤ 0.5 Ω	Powertrain relay voltage Run crank voltage Engine not cranking Pressure Regulator calibrated as present	≥ 11.0 V > 6.0 V	44 failures out of 88 samples 6.25 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Pressure Regulator Solenoid 2 Control Circuit High Voltage	P2296	Controller specific output driver circuit diagnoses the Rail Pressure Regulator valve low sided driver for a short to power failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power: impedance between signal and controller power	≤ 0.5 Ω	Powertrain relay voltage Run crank voltage Engine not cranking Pressure Regulator calibrated as present	≥ 11.0 V > 6.0 V	44 failures out of 88 samples 6.25 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Circuit Low Bank 1 Sensor 2	P22A0	This diagnosis verifies Downstream NOx sensor read out of range low	Check if the NOx2 sensor NOx concentration raw read is out of lower range: NOx raw read	< -90 ppm	Fuel injection quantity request Powertrain relay voltage NOx Sensor Bus relay is commanded ON No failure on NOx2 CAN communication Sensor supply in range Sensor dewpoint is reached No current control failure on NOx2 sensor No electrical failure on NOx2 sensor Combustion mode dependent enabling flag No O2 plausibility in load fault on NOx2	> 10 mm^3 > 11.00 V TRUE CAN_LostComm_FltN_BusB_NOxSnsr_B > 10.80 V TRUE NOX_NOx2_StBitChkFlt ==FALSE NOX_Snsr2_ElecFA ==FALSE **NOX_S2_OutRngMinCmbMode** OXY_NOx2ChkLoadFlt ==FALSE	Time counter: 100 fails out of 200 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Circuit High Bank 1 Sensor 2	P22A1	This diagnosis verifies Downstream NOx sensor read out of range high	Check if the NOx1 sensor NOx concentration raw read is out of higher range: NOx raw read	 > 2,500 ppm	Powertrain relay voltage NOx Sensor Bus relay is commanded ON No failure on NOx2 CAN communication Sensor supply in range Sensor dewpoint is reached No current control failure on NOx2 sensor No electrical failure on NOx2 sensor Combustion mode dependent enabling flag No O2 plausibility in load fault on NOx2	> 11.00 V TRUE CAN_LostComm_FltN_BusB_NOxSnsr_B > 10.80 V TRUE NOX_NOx2_StBitChkFlt ==FALSE NOX_Snsr2_ElecFA ==FALSE **NOX_S2_OutRngMaxCmbMode** OXY_NOx2ChkLoadFlt ==FALSE	Time counter: 200 fails out of 250 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 Heater Control Circuit	P22A3	This diagnosis verifies Downstream NOx gen3 sensor Heater Supply pin Open Load Circuit	Check if there is an open circuit on NOx Sensor 2 Heater Supply pin (H+)	open circuit on H+ pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 Heater Control Circuit Low Voltage	P22A4	This diagnosis verifies Downstream NOx gen3 sensor Heater Supply pin for Short to Ground	Check if there is a short circuit to ground on NOx Sensor 2 Heater Supply pin (H+)	groundshort on H+ pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 Heater Control Circuit High Voltage	P22A5	This diagnosis verifies Downstream NOx gen3 sensor Heater Supply pin for Short to Battery	Check if there is a short circuit to power supply on NOx Sensor 2 Heater Supply pin (H+)	powershort on H+ pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 Heater Sense Circuit	P22A6	This diagnosis verifies Downstream NOx gen3 sensor Heater sense resistance measurement pin for Open Load Circuit	Check if there is an open circuit on NOx Sensor 2 Heater Sense pin (HTemp)	open circuit on HTemp pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Heater Sense Circuit Range/ Performance Bank 1 Sensor 2	P22A7	This diagnosis verifies if the Downstream NOx sensor Heate raw resistance is in range	This diagnosis verifies if the Post Catalyst NOx Sensor Heater raw resistance is out of speficied range: (Sensor heater raw resistance - Sensor heater target resistance) / Sensor heater target resistence	< 0.03 >- 0.03	Powertrain relay voltage No loss of communcation with Nox2 Sensor No offset failure on NOx signal from NOx Sensor No circuit failure on NOx Sensor No out of range high failulre on NOx Signal No out of range low failulre on NOx Signal No DTC set: No failure on NOx Sensor Bus relay circuit NOx Sensor Bus relay is commanded ON Delay timer once Sensor supplyisin range (> 10.8 V) Delay timer once Sensor dewpoint is reached Delay timer once engine is overrun Delay timer once DPF combustion mode is not active	> 11.00 V CAN_LostComm_FltN_BusB_NOxSnsr_B ==FALSE NOX_NOx2_OfstMontrFlt ==FALSE NOX_NOx2_StBitChkFlt ==FALSE NOX_NOx2_OutOfRngHiFlt ==FALSE NOX_NOx2_OutOfRngLoFlt ==FALSE P30B5 SBR_RlyFA==FALSE TRUE > 45 sec > 180 sec > 5 sec 30 sec	Time counter: 50 fails out of 100 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 Heater Sense Low Voltage	P22A8	This diagnosis verifies Downstream NOx gen3 sensor Heater sense resistance measurement pin for Short to Ground	Check if there is a short circuit to ground on NOx Sensor 2 Heater Sense pin (HTemp)	groundshort on HTemp	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor 2 Heater Sense High Voltage	P22A9	This diagnosis verifies Downstream NOx gen3 sensor Heater sense resistance measurement pin for Short to Battery	Check if there is a short circuit to power supply on NOx Sensor 2 Heater Sense (HTemp)	powershort on HTemp pin	NOx sensor is Gen3.0 Powertrain relay voltage NOx Sensor Bus relay is commanded ON CAN_LostComm_FltN_BusB_NOxSnsr_B Sensor supply in range Sensor dewpoint is reached No DTC active:	TRUE > 11.00 V TRUE FALSE > 10.80 V TRUE P30B5	Time counter: 20 fails out of 40 samples Task=25ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Performance - Sensing Element Bank 1 Sensor 2	P22FE	This diagnosis verifies the Downstream NOx sensor sensing cells integrity during afterrun	Check if there is any clogging in the Downstream NOx sensor measurement cavities that could result in reduced NOx-sensitivity. The sensor internal operating current set-points are changed such way, that the O2 concentration in 2nd sensor cavity is around 1000ppm. One test result is measured in fresh sensor state (at supplier plant) and stored in the sensor E2prom as diagnosis reference value. The diagnosis result is the ratio of current diagnosis value/reference value. The diagnosis result is processed with EWMA logic.	> 150 % OR < 50 %	No electrical failure on NOx2 Sensor No out of range low failure on NOx2 Sensor No out of range high failure on NOx2 Sensor No failure on NOx2 CAN communication No offset failure on NOx2 Sensor No DTC active: No failure on NOx1 Sensor No failure on O2 from NOx1 plausibility diagnostics No failure on SCR system No failure on downstream SCR HC model inputs No failure on crank Sensor No failure on exhaust temperature Sensor (downstream SCR)	NOX_Snsr2_ElecFA ==FALSE NOX_NOx2_OutOfRngLoFlt ==FALSE NOX_NOx2_OutOfRngHiFlt ==FALSE CAN_LostComm_FltN_BusB_NOxSnsr_B ==FALSE NOX_NOx2_OfstMontrFlt ==FALSE P30B5 NOX_Snsr1_NOx_Flt ==FALSE OXY_NOx1_O2_Flt ==FALSE EXF_TotExhSCR_UpFlt ==FALSE SCR_HC_SCR_DwnFlt ==FALSE CrankSensor_FA ==FALSE EGT_TempSCR_DwnFlt ==FALSE HCI_GenericShtOffReq	Test per trip: 1 If Fast Initial Response EWMA is active then 2 test per trip are allowed If Fast Initial Response EWMA is active then 4 test per trip are allowed	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No failure on HC injector	==FALSE		
					No failure on Vehicle Speed Sensor	VehicleSpeedSensor_FA ==FALSE		
					No failure on NOx2 dynamic check	NOX_NOx2_DynChkFlt ==FALSE		
					No failure on any input of SCR chemical model	SCR_ChemicalMdlFlt ==FALSE		
					No current control failure on NOx2 Sensor	NOX_NOx2_StBitChkFlt ==FALSE		
					No failure on O2 from NOx2 plausibility diagnostics	OXY_NOx2_O2_Flt ==FALSE		
					No failure on NOx Sensor Bus relay circuit	SBR_RlyFA==FALSE		
					Powertrain relay voltage	> 11.00 V		
					NOx2 sensor supply in range	> 10.80 V		
					NOx2 sensor dewpoint is reached	TRUE		
					(NOx2 Sensor heater raw resistance - NOx2 Sensor heater target resistance) / NOx2 Sensor heater target resistence	< 0.03 % >- 0.03 %		
					a)combustion mode dependent enabling flag	**NOX_NOx2SelfTstEnblCmbMode**		
					b) condition a) is fulfilled for time	> 5 sec		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						> 0 rpm		
					c) engine speed	< 1,500 rpm		
						> 1 sec		
					d) condition c) is fulfilled for time			
						> 0 sec		
					e) After injection pulse is not used for time			
						> -7 °C		
					f) exhaust temperature Sensor (downstream SCR)	< 400 °C		
						< 20 g/s		
					g) exhaust mass flow	< 100 ppm		
					h) NH3 concentration	> 5 sec		
					j) conditions f) g) h) are fulfilled for time	> 10 %		
					k) O2 concentration from NOx1	< 400 ppm		
					i) NOx concentration from NOx1	> 1 sec		
					l) conditions k) i) are fulfilled for time	< 1 %		
					m) duty cycle applied to the HC injector driver	> 5 sec		
					n) condition m) is fulfilled for time	> 15 sec		
					o) time between key off and last overrun	> 15 sec		
					p) time between key off and last DPF regen	< 1,100 rpm		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					q) engine speed in idle range	< 20 mm^3		
					r) fuel request in idle range	< 1,800 sec		
					s) conditions q) r) is fulfillled for time			
					t) timer of condition s) is reset if one of the following condition is fulfilled (idle off recognition - t) conditions):	> 200 °C		
						> 5 sec		
					t.1) exhaust temperature (downstream SCR)			
					t.2) condition t.1) is fulfilled for time (once idle has been detected)	> 5 mph		
						> 5 sec		
					t.3) vehicle speed			
					t.4) condition t.3) is fulfilled for time (once idle has been detected)	> 20 g/sec		
						> 5 sec		
					t.5) exhaust mass flow			
					t.6) condition t.5) is fulfilled for time (once idle has been detected)	< 10 g/s		
					u) HC mass flow (SCR downstream)			
					Once u) condition is fulfilled the following additional u.x) conditions shall be fulfilled to enable	> 200 g/s		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					the monitor (AND logic) u.1) exhaust temperature (downstream SCR) u.2) condition u.1) is fulfilled for time (once condition u) has been detected) u.3) vehicle speed u.4) condition u.3) is fulfilled for time (once condition u) has been detected) u.5) exhaust mass flow u.6) condition u.5) is fulfilled for time (once condition u) has been detected) v) deceleration before keyoff. w) condition v) could be ignored if idle engine condition w.x) is fulfilled w.1) engine speed in idle range w.2) condition w.1) fulfilled for time Once all conditions above are fulfilled during the driving cycle, ECM requires diagnostic test	> 5 sec >= 5 mph > 10 sec > 20 g/s > 5 sec < 3.00 m/s < 5.00 rpm < 50.00 rpm > 5.00 s		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					execution at key off			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF tank heater supply undervoltage monitoring	P248A	This diagnosis verifies that the tank heater supply voltage is under the threshold of correct functioning	Tank heater supply under-voltage (System Battery voltage - Tank heater Supply Voltage value)	> 3.00	Test enabled by calibration Powertrain relay in range Run Crank Active Cranking phase excluded No SCR Power Module CAN loss of communication Heating strategy is requesting the Heater to be activated	1.00 U010E, Lost Communication With Reductant Control Module (SCR) VeSCRR_b_HeatA_On == TRUE	16.00 failures out of 20.00 samples Time basis = 500ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF tank heater supply overvoltage monitoring	P248B	This diagnosis verifues that the tank heater supply voltage is over the threshold of correct functioning	Tank heater supply voltage - PT relay voltage	> 2.0 V	Run Crank in range PT relay voltage (Run Crank voltage OR Engine running) Engine not cranking Tank heater commanded on None of following DTC present:	≥ 11.0 V ≥ 11.0 V > 6.0 V U010E	16 failures out of 20 samples 500 ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF line heater supply undervoltage monitoring	P248C	This diagnosis verifues that the line heater supply voltage is under the threshold of correct functioning	Line heater supply under-voltage (System Battery voltage - Line heater Supply Voltage value)	> 3.00	Test enabled by calibration Powertrain relay in range Run Crank Active Cranking phase excluded No SCR Power Module CAN loss of communication Heating strategy is requesting the Heater to be activated	1.00 U010E, Lost Communication With Reductant Control Module (SCR)	16.00 failures out of 20.00 samples Time basis = 500ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF line heater supply overvoltage monitoring	P248D	This diagnosis verifues that the line heater supply voltage is over the threshold of correct functioning	Line heater supply voltage - PT relay voltage	> 2.0 V	Run Crank in range PT relay voltage (Run Crank voltage OR Engine running) Engine not cranking Tank heater commanded on None of following DTC present:	≥ 11.0 V ≥ 11.0 V > 6.0 V U010E	16 failures out of 20 samples 500 ms/sample	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Closed Loop Reductant Injection Control At Limit - Flow Too Low	P249D	This diagnosis checks if the DEF injection system has exceeded the limit of correction authority. The monitoring is executed by comparing the long-term adaptation factor (LTAF) with a calibratable threshold: LTAF > OBD high threshold. The long-term adaptation factor is calculated based on the information given by the NH3 storage correction strategy. This factor represents the measured deviation of the complete SCR system and shall be used to compensate it by making a correction over the DEF injection quantity.	Long-term adaptation factor (LTAF) higher than calibratable threshold	LTAF > 1.69	Test enabled by calibration;	CalOut = 1 [Boolean];	One failure to set the DTC.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Closed Loop Reductant Injection Control At Limit - Flow Too High	P249E	This diagnosis checks if the DEF injection system has exceeded the limit of correction authority. The monitoring is executed by comparing the long-term adaptation factor (LTAF) with a calibratable threshold: LTAF < OBD low threshold. The long-term adaptation factor is calculated based on the information given by the NH3 storage correction strategy. This factor represents the measured deviation of the complete SCR system and shall be used to compensate it by making a correction over the DEF injection quantity.	Long-term adaptation factor (LTAF) lower than calibratable threshold	LTAF < 0.41	Test enabled by calibration;	CalOut = 1 [Boolean];	One failure to set the DTC.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Transmission Control Torque Request Circuit	P2544	Determines if the torque request from the TCM is valid	Protect error - Serial Communication message 2's complement not equal ($189/$199)	Message <> two's complement of message	Diagnostic Status	Enabled	>= 16 failures out of 20 samples.	Type B, 2 Trips
					Power Mode	= Run	Performed on every received message	
			OR Rolling count error - Serial Communication message ($189/$199) rolling count index value	Message <> previous message rolling count value + one	Ignition Voltage	> 6.41 volts	>= 6 Rolling count errors out of 10 samples.	
					Engine Running	= True		
			OR		Run/Crank Active	> 0.50 Sec	Performed on every received message	
			Range Error - Serial Communication message - ($189/$199) TCM Requested Torque Increase	> 500 Nm	No Serial communication loss to TCM (U0101)	No loss of communication	>= 6 range errors out of 10 samples.	
							Performed on every received message	
			OR					
			Multi-transition error - Trans torque intervention type request change	Requested torque intervention type toggles from not increasing request to increasing request			>= 3 multi-transitions out of 5 samples. Performed every 200 msec	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Unmetered Fuel - Forced Engine Shutdown	P25BD	Determines if engine overspeed condition is occuring when no fuel is being delivered	Engine Speed exceeds a threshold for a period of time	Fail Condition: Engine Speed > 5,000 RPM		Engine Speed > 1,500 RPM	Fail threshold: Overspeed condition TRUE > 499.0 milliseconds	Type A, 1 Trips
			Engine Speed less than a threshold for a period of time	Pass Condition: Engine Speed < (5,000 - 300) RPM		Engine Speed > 1,500 RPM	Pass threshold: Overspeed condition FALSE > 499.0 milliseconds	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Control Module Power Off Timer Performance	P262B	This DTC determines if the hardware timer does not initialize or count properly. There are two tests to ensure proper functioning of the timer: Count Up Test (CUT) and Range Test (RaTe). Count Up Test (CUT): Verifies that the HWIO timer is counting up with the proper increment. Range Test (RaTe): When the run/crank is not active both the hardware and mirror timers are started. The timers are compared when module shutdown is initiated or run/crank becomes active.	Count Up Test: Time difference between the current read and the previous read of the timer Range Test: The variation of the HWIO timer and mirror timer is	> 1.50 seconds > 0.25 %.			Count Up Test: 4 failures out of 20 samples 1 sec / sample Continuous while run/crank is not active and until controller shutdown is initiated. Range Test: Once per trip when controller shutdown is initiated or run/crank becomes active.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Malfunction Indicator Lamp (MIL) Control Circuit (ODM) Low	P263A	Detects an inoperative malfunction indicator lamp control circuit. This diagnostic reports the DTC when a short to ground is detected.	Voltage low during driver off state (indicates short-to-ground)	Short to ground: ≤ 0.5 Ω impedance between output and controller ground	Run/Crank Voltage Remote Vehicle Start is not active	Voltage ≥ 11.00 volts	1 failures out of 1 samples 50 ms / sample	Type B, No MIL NO MIL Note: In certain controllers P0650 may also set (MIL Control Open Circuit)

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Malfunction Indicator Lamp (MIL) Control Circuit (ODM) High	P263B	Detects an inoperative malfunction indicator lamp control circuit. This diagnostic reports the DTC when a short to power is detected.	Voltage high during driver on state (indicates short to power)	Short to power: ≤ 0.5 Ω impedance between output and controller power	Run/Crank Voltage Remote Vehicle Start is not active	Voltage ≥ 11.00 volts	4 failures out of 5 samples 50 ms / sample	Type B, No MIL NO MIL

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Shared High Side Drive #2 Control Circuit Low (STG) - (GEN III Controllers ONLY)	P2670	Controller specific output driver circuit diagnoses the shared high sided driver # 2 for a short to ground failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	- Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. - Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	≤ 0.5 Ω impedance between output and controller ground	Shared high side drive #2 low diag enable Powertrain relay voltage Run Crank voltage Powertrain relay state	= 1 >= 11.00 > 6.00 = ON	5 failures out of 10 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Shared High Side Drive #2 Control Circuit High (STP) - (GEN III Controllers ONLY)	P2671	Controller specific output driver circuit diagnoses the shared high sided driver # 2 for a short to power failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	- Voltage measurement outside of controller specific acceptable range during driver off state indicates short to power failure. - Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	≤ 0.5 Ω impedance between output and controller power	Shared high side drive #2 diag enable Powertrain relay voltage Run Crank voltage Powertrain relay state	= 1 >= 11.00 > 6.00 = ON	20 failures out of 25 samples 100 ms / sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Supply Heater Control Circuit/Open	P2687	Controller specific output driver circuit diagnoses the Fuel Supply Heater Control Relay low sided driver for an open circuit failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit: impedance between signal and controller ground	≥ 200 kΩ	Powertrain relay voltage Run crank voltage Engine not cranking	≥ 11.0 V > 6.0 V	25 failures out of 50 samples 100ms/sample	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Supply Heater Control Circuit Low	P2688	Controller specific output driver circuit diagnoses the Fuel Supply Heater Control Relay low sided driver for a short to ground failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver off state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground: impedance between signal and controller ground	≤ 0.5 Ω	Powertrain relay voltage Run crank voltage Engine not cranking	≥ 11.0 V > 6.0 V	25 failures out of 50 samples 100ms/sample	Type C, SVS one trip

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Supply Heater Control Circuit High	P2689	Controller specific output driver circuit diagnoses the Fuel Supply Heater Control Relay low sided driver for a short to power failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power: impedance between signal and controller power	≤ 0.5 Ω	Powertrain relay voltage Run crank voltage Engine not cranking	≥ 11.0 V > 6.0 V	25 failures out of 50 samples 100ms/sample	Type C, No SVS

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Transfer Case Control Module Transfer Case Command State Rationality - 4WD high command not 4WD high ratio	P279A	Monitor measured transfer case gear ratio is 4WD low ratio or neutral while the transfer case control module command state is 4WD high. The 4WD measured transfer case ratio is calculated as transmission output shaft speed divided by the transfer case output shaft speed, both speed are measured values based on speed sensors.	transfer case contol module transfer case command state AND measured transfer case ratio is in 4WD low ratio window OR measured transfer case ratio is in neutral window AND measured transfer case ratio is in 4WD low ratio window (measured transfer case ratio = transmission output speed / transfer case output speed) update rate 12.5 milliseconds	= 4WD high 4WD low ratio window ≤ 3.00 ≥ 2.40 neutral ratio window ≥ 1.30 ≤ 0.70 OR ≥ 3.00 ≤ 2.40 4WD low ratio window ≤ 2.90 ≥ 2.50	transmssion gear is forward gear: transmission output shaft speed engine torque engine speed accelerator pedal position brake pedal position transmssion gear is reverse gear: transmission output shaft speed engine torque engine speed accelerator pedal position brake pedal position diagnsotic monitor enable PTO active engine power limited DTCs not fault active	≥ 500.0 RPM ≥ 80.0 Nm ≥ 300.0 RPM ≥ 5.0 % ≤ 100.0 % ≥ 500.0 RPM ≥ 80.0 Nm ≥ 300.0 PRM ≥ 5.0 % ≤ 100.0 % = 1 Boolean = FALSE = FALSE CrankSensor_FA VehicleSpeedSensor_FA EngineTorqueEstInaccurate P057B, P057C, P057D, P057E P17D4, P279B, P279C P0502, P0503, P0722, P0723, P2160, P2161	fail time ≥ 7.00 seconds out of sample time ≥ 10.00 seconds update rate 12.5 milliseconds	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Transfer Case Control Module Transfer Case Command State Rationality - 4WD low command not 4WD low ratio	P279B	Monitor measures transfer case gear ratio is 4WD high ratio or neutral while the transfer case control module command state is 4WD low. The 4WD measured transfer case ratio is calculated as transmission output shaft speed divided by the transfer case output shaft speed, both speed are measured values based on speed sensors.	transfer case contol module transfer case command state AND measured transfer case ratio is in 4WD high ratio window OR measured transfer case ratio is in neutral window AND measured transfer case ratio is in 4WD high ratio window (measured transfer case ratio = transmission output speed / transfer case output speed) update rate 12.5 milliseconds	= 4WD low 4WD high ratio window ≤ 1.30 ≥ 0.70 neutral ratio window ≥ 1.30 ≤ 0.70 OR ≥ 3.00 ≤ 2.40 4WD high ratio window ≤ 1.20 ≥ 0.80	transmssion gear is forward gear: transmission output shaft speed engine torque engine speed accelerator pedal position brake pedal position transmssion gear is reverse gear: transmission output shaft speed engine torque engine speed accelerator pedal position brake pedal position diagnsotic monitor enable PTO active engine power limited DTCs not fault active	≥ 500.0 RPM ≥ 80.0 Nm ≥ 300.0 RPM ≥ 5.0 % ≤ 100.0 % ≥ 500.0 RPM ≥ 80.0 Nm ≥ 300.0 PRM ≥ 5.0 % ≤ 100.0 % = 1 Boolean = FALSE = FALSE CrankSensor_FA VehicleSpeedSensor_FA EngineTorqueEstInaccurate P057B, P057C, P057D, P057E P17D4, P279A, P279C P0502, P0503, P0722, P0723, P2160, P2161	fail time ≥ 7.00 seconds out of sample time ≥ 10.00 seconds update rate 12.5 milliseconds	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Transfer Case Control Module Transfer Case Command State Rationality - 4WD neutral command not 4WD neutral ratio	P279C	Monitor measured transfer case gear ratio is 4WD high ratio or 4WD low ratio while the transfer case control module command state is 4WD neutral. The 4WD measured transfer case ratio is calculated as transmission output shaft speed divided by the transfer case output shaft speed, both speed are measured values based on speed sensors.	transfer case contol module transfer case command state AND measured transfer case ratio is in 4WD low ratio window OR measured transfer case ratio is in 4WD high window AND measured transfer case ratio is in 4WD low ratio window or in 4WD high ratio window (measured transfer case ratio = transmission output speed / transfer case output speed) update rate 12.5 milliseconds	= 4WD neutral 4WD low ratio window ≤ 3.00 ≥ 2.40 4WD high ratio window ≥ 1.30 ≤ 0.70 4WD neutral ratio window ≤ 2.90 ≥ 2.50 OR ≤ 1.20 ≥ 0.80	transmssion gear is forward gear: transmission output shaft speed engine torque engine speed accelerator pedal position brake pedal position transmssion gear is reverse gear: transmission output shaft speed engine torque engine speed accelerator pedal position brake pedal position diagnsotic monitor enable PTO active engine power limited DTCs not fault active	≥ 300.0 RPM ≥ -20.0 Nm ≥ 0.0 RPM ≥ 0.0 % ≤ 100.0 % ≥ 500.0 RPM ≥ 80.0 Nm ≥ 300.0 PRM ≥ 5.0 % ≤ 100.0 % = 1 Boolean = FALSE = FALSE CrankSensor_FA VehicleSpeedSensor_FA EngineTorqueEstInaccurate P057B, P057C, P057D, P057E P17D4, P279A, P279B P0502, P0503, P0722, P0723, P2160, P2161	fail time ≥ 10.50 seconds out of sample time ≥ 15.00 seconds update rate 12.5 milliseconds	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF Quality Sensor Temperature Offset Monitor	P2ADA	Determine when the DEF Quality Sensor Temperature Offset is not plausible	This monitor checks if the difference between Tref (the average temperature of all the temperature sensors in the exhaust) and the temperature meausured by the QS thermistor is bigger than a threshold. |Tref – QS thermistor temperature|	> 35.00 °C	Engine in Cranking Phase Powertrain relay voltage Run/Crank is Active Tref signal is available (usually calculated after 8 hours vehicle soak) DEF QS thermistor temperature signal not equals the DEF freezing temperature (with tolerance) Time elapsed since last key off No fault on engine mode-not-run timer Urea Refill is not detected No loss of CAN communication DEF-C Controller not in initialization condition No electrical fault on DEF QS is present No electrical fault on DEF Quality Sensor SENT circuit No performance fault on DEF Quality Sensor SENT circuit	FALSE > 11.00 V TRUE TRUE > (-90.00 + 1.00)°C OR < (-90.00 - 1.00)°C > 28,800.00 s EngineModeNotRunTimerError TRUE CAN_LostComm_FltN_BusB_DEF_C == FALSE TRUE DQMR_DEFQS_ElecFlt == FALSE DQMR_DEFQS_SENT_ElecFA == FALSE DQMR_DEFQS_SENT_PerfFA == FALSE	Time counter: 40.00 fails out of 50.00 samples Task = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No fault on DEF QS thermistor is present	DQMR_DEFQS_TempFlt == FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF Quality Sensor Temperature OOR Low	P2ADB	This diagnosis verifies if DEF Quality Temperature Sensor read out of range low	This monitor checks if the DEF Quality Temperature Sensor signal is out of lower range. DEF QS thermistor temperature value	< -49.00 °C	Engine in Cranking Phase Powertrain relay voltage Run/Crank is Active No loss of CAN communication DEF-C Controller not in initialization condition No electrical fault on DEF QS is present No electrical fault on DEF Quality Sensor SENT circuit No performance fault on DEF Quality Sensor SENT circuit DEF QS thermistor temperature	FALSE > 11.00 V TRUE CAN_LostComm_FltN_BusB_DEF_C == FALSE TRUE DQMR_DEFQS_ElecFlt == FALSE DQMR_DEFQS_SENT_ElecFA == FALSE DQMR_DEFQS_SENT_PerfFA == FALSE > -7.0 °C	Time counter: 40.00 fails out of 50.00 samples Task = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF Quality Sensor Temperature OOR High	P2ADC	This diagnosis verifies if DEF Quality Temperature Sensor read out of range high	This monitor checks if the DEF Quality Temperature Sensor signal is out of higher range. DEF QS thermistor temperature value	> 89.00 °C	Engine in Cranking Phase Powertrain relay voltage Run/Crank is Active No loss of CAN communication DEF-C Controller not in initialization condition No electrical fault on DEF QS is present No electrical fault on DEF Quality Sensor SENT circuit No performance fault on DEF Quality Sensor SENT circuit	FALSE > 11.00 V TRUE CAN_LostComm_FltN_BusB_DEF_C == FALSE TRUE DQMR_DEFQS_ElecFlt == FALSE DQMR_DEFQS_SENT_ElecFA == FALSE DQMR_DEFQS_SENT_PerfFA == FALSE	Time counter: 40.00 fails out of 50.00 samples Task = 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
DEF Quality Sensor Erratic Temperature	P2ADD	This diagnosis verifies if the DEF Quality Temperature Sensor signal dynamic is plausible.	This monitor checks if the dynamic behaviour of the DEF Quality Sensor signal is out of calibratable thresholds. QS thermistor raw value OR QS thermistor raw value	 > (1-α) * 155.00 °C + (Last good sample * α) - measurement error < (1-α) * -55.00 °C + (Last good sample * α) with: α = e^[-(amount of consecutive bad samples * 0.08)] measurement error as per **P2ADD_Measure_Error** supporting table	Powertrain relay voltage Run/Crank is Active Engine in Cranking Phase No electrical fault on DEF QS thermistor is present No loss of CAN communication DEF-C Controller not in initialization condition No electrical fault on DEF QS is present No electrical fault on DEF Quality Sensor SENT circuit No performance fault on DEF Quality Sensor SENT circuit	> 11.00 V TRUE FALSE DQMR_DEFQS_PZT_ElecFlt == FALSE CAN_LostComm_FltN_BusB_DEF_C == FALSE TRUE DQMR_DEFQS_ElecFlt == FALSE DQMR_DEFQS_SENT_ElecFA == FALSE DQMR_DEFQS_SENT_PerfFA == FALSE	Time counter: 80.00 fails out of 125.00 samples Task = 500ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Delivery Performance (Non EWMA filtered)	P2BAA	This diagnostic checks the DEF hydraulic system for faults that can lead to diminished DEF delivery.	Measured DEF pressure drop after the injection has been performed is lower than the expected pressure drop. The expected pressure drop depends on the motorpump efficiency (that is estimated based on the average commanded duty cycle). Measured DEF pressure drop	< **P2BAA RDP Min Press Drop** table	Ambient Air Temperature Barometric Pressure DEF Injector Component Management Ready DEF Injector Cooling Request DPF Regeneration Active DEF Injector Temperature DEF Injector Temperature variation of DEF Injector temperature within a time period Integrated DEF Injected Mass Integrated DEF Injected Mass Integrated Upstream NOx Flow Upstream SCR Exhaust Flow DEF System Hydraulic System Shutoff No DEF Mass Flow less than calibratable mass for calibratable time DEF Tank Status	> -20.00 °C > 70.00 kPa == TRUE == FALSE == FALSE > 250.00 °C < 500.00 °C < 3.00 °C = 100ms * 100.00 > 6,600.00 mg < 10,000,000.00 mg >= 0.00 mg > 8.00 g/s == FALSE < 100.00 mg/s >= 100ms * 5.00 = NOT FROZEN	Function Task: 25ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No fault for Upstream DEF Injector Temperature No fault for Outside Air Temperature No fault for Upstream SCR Exhaust Flow No fault for Barometric Pressure No fault for Upstream NOx Sensor Concentration No fault for Vehicle Speed Sensor Vehicle Speed below calibratable threshold for calibratable time No DEF Metering Valve Tip Stuck Fault Engine Mode (Fuel injection quantity request OR Idle speed control active) (Engine speed OR Idle speed control active) (DEF pressure deviation (actual - desired) when no	[OAT_PtEstFiltFA or OAT_OAT_SnsrNonEmissFA] EXF_TotExhSCR_UpFlt AAP_AmbientAirPresDfltd == FALSE VehicleSpeedSensor_FA <= 0.00 km/h >= 100ms * 30.00 SCR_TipStuckFltSt == RUNNING < 1,000.0 mm^3 0 < rpm < 10,000		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					dosing OR amount of no dosing phase cycles)	<= 8 kPa >= 3		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Reductant Temperature Too Low	P2D45	This monitoring detects when DEF tank heater is affected by a fault that causes low temperature increase rate.	Maximum difference between current tank temperature and tank temperature sampled at begin of driving	< 0.5 °C	Sensor Bus Wake Up signal is active No test status has been reported for this monitoring since begin of driving cycle No fault for serial communication with DEF device (SCRPM) (e.g. ARC/Checksum) No fault for sensor bus wake up signal No fault for DEF tank temperature sensor No electrical fault for tank heater Tank heater active DEF tank temperature at begin of driving cycle [(Tank heater has been continuously commanded active AND battery system voltage (RunCrank) is continuously greater than 11 V for a time) OR (Tank heater has been continuously commanded active AND battery system voltage (RunCrank) is	< -15.0 °C ≥ 600.00 s	As enable conditions are met.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					continuously greater than 11 V for a time since begin of driving cycle AND difference between current tank temperature and tank temperature sampled at begin of driving cycle)] Engine soak time	< 600.00 s > 0.5 °C ≥ 36,000.00 s		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Signal Message Counter Incorrect Bank 1 Sensor 1	P30B4	This DTC monitors for an error in communication with the Bank 1 Sensor 1 NOx Sensor Signal Message.	Communication of the Alive Rolling Count or Protection Value of the NOx Sensor Oxygen Engine Out data over CAN bus is incorrect for out of total samples Or Communication of the Alive Rolling Count or Protection Value of the Engine Out NOx Sensor Data 1 data over CAN bus is incorrect for out of total samples Or Communication of the Alive Rolling Count or Protection Value of the Engine Out NOx Sensor Data 2 data over CAN bus is incorrect for out of total samples Or Communication of the Alive Rolling Count or Protection Value of the Engine Out NOx Sensor Data 3 data over CAN bus is incorrect for out of total samples	>= 8.00 counts >= 10.00 counts >= 8.00 counts >= 10.00 counts >= 8.00 counts >= 10.00 counts >= 8.00 counts >= 10.00 counts	Message frame All the following conditions are met for Power Mode Powertrain Relay Voltage Run/Crank Ignition Voltage	= Is available >= 3,000.00 milliseconds = Run >= 11.00 Volts >= 11.00 Volts	Executes in 10ms loop.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			Or Communication of the Alive Rolling Count or Protection Value of the NOx Sensor Error Engine Out data over CAN bus is incorrect for out of total samples	 >= 8.00 counts >= 10.00 counts				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
NOx Sensor Signal Message Counter Incorrect Bank 1 Sensor 2	P30B5	This DTC monitors for an error in communication with the Bank 1 Sensor 2 NOx Sensor Signal Message.	Communication of the Alive Rolling Count or Protection Value of the NOx Sensor Oxygen Post Catalyst data over CAN bus is incorrect for out of total samples Or Communication of the Alive Rolling Count or Protection Value of the Post Catalyst NOx Sensor Self Diagnostic Feedback Status 1 data over CAN bus is incorrect for out of total samples Or Communication of the Alive Rolling Count or Protection Value of the Post Catalyst NOx Sensor Self Diagnostic Result data over CAN bus is incorrect for out of total samples Or Communication of the Alive Rolling Count or Protection Value of the NOx Sensor Lambda Binary Voltage Post Catalyst data over CAN	>= 8.00 counts >= 10.00 counts >= 8.00 counts >= 10.00 counts >= 8.00 counts >= 10.00 counts	Message frame All the following conditions are met for Power Mode Powertrain Relay Voltage Run/Crank Ignition Voltage	= Is available >= 3,000.00 milliseconds = Run >= 11.00 Volts >= 11.00 Volts	Executes in 10ms loop.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			bus is incorrect for out of total samples Or Communication of the Alive Rolling Count or Protection Value of the NOx Sensor Error Post Catalyst data over CAN bus is incorrect for out of total samples	>= 8.00 counts >= 10.00 counts >= 8.00 counts >= 10.00 counts				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Control Module Status Signal Message Counter Incorrect	P30BC	This DTC monitors for an error in communication with the Particulate Matter Sensor Control Module Status Signal Message.	Communication of the Alive Rolling Count or Protection Value of the Soot Sensor Regeneration Setpoint Temperature data over CAN bus is incorrect for out of total samples Or Communication of the Alive Rolling Count or Protection Value of the Soot Sensor Control Unit Information data over CAN bus is incorrect for out of total samples Or Communication of the Alive Rolling Count or Protection Value of the Braking System Vehicle Top Speed Limit Request Type data over CAN bus is incorrect for out of total samples Or Communication of the Alive Rolling Count or Protection Value of the Transmission Neutral Locked Turbine Function Active over CAN bus is	>= 8.00 counts >= 10.00 counts >= 8.00 counts >= 10.00 counts >= 8.00 counts >= 10.00 counts	Message frame All the following conditions are met for Power Mode Powertrain Relay Voltage Run/Crank Ignition Voltage	= Is available >= 3,000.00 milliseconds = Run >= 11.00 Volts >= 11.00 Volts	Executes in 10ms loop.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			incorrect for out of total samples	>= 8.00 counts >= 10.00 counts				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Control Module Communication Bus A Off	U0073	This DTC monitors for a BUS A off condition	Bus off failures equals or exceeds before the sample time of is reached	5 counts (equivalent to 0.83 seconds) 0.83 seconds	General Enable Criteria: Starter motor engaged for Or Run/Crank ignition voltage All below criteria have been met for Normal CAN transmission on Bus Controller not in programming mode If bus type = Sensor Bus: Sensor bus relay is on Otherwise: If power mode = Run/ Crank: Power Mode If calibratable low voltage disable mode is not Never Disabled Low voltage disable mode: OBDII If OBDII: Run/Crank ignition voltage	 > 15.00 milliseconds > 8.41 Volts >= 5.00 seconds Enabled = Run >= 11.00 Volts	Diagnostic runs in 12.5 ms loop	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					If EOBD: Run/Crank ignition voltage If Secure: Starter motor engaged for Or Run/Crank ignition voltage If Hybrid Secure: Run/Crank ignition voltage If power mode = Accessory Off key cycle diagnostics are enabled Or Controller is an OBD controller Controller shutdown impending Power Mode Battery voltage	>= 9.00 Volts > 15.00 milliseconds > 8.41 Volts >= 6.41 Volts Enabled OBD Controller = False = Not crank >= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Control Module Communication Powertrain Sensor CAN Bus Off	U0076	This DTC monitors for a Powertrain Sensor Bus S off condition	Bus off failures equals or exceeds before the sample time of is reached	5 counts (equivalent to 0.83 seconds) 0.83 seconds	General Enable Criteria: Starter motor engaged for Or Run/Crank ignition voltage All below criteria have been met for Normal CAN transmission on Bus Controller not in programming mode If bus type = Sensor Bus: Sensor bus relay is on Otherwise: If power mode = Run/ Crank: Power Mode If calibratable low voltage disable mode is not Never Disabled Low voltage disable mode: OBDII If OBDII: Run/Crank ignition voltage	 > 15.00 milliseconds > 8.41 Volts >= 5.00 seconds Enabled = Run >= 11.00 Volts	Diagnostic runs in 12.5 ms loop	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					If EOBD: Run/Crank ignition voltage If Secure: Starter motor engaged for Or Run/Crank ignition voltage If Hybrid Secure: Run/Crank ignition voltage If power mode = Accessory Off key cycle diagnostics are enabled Or Controller is an OBD controller Controller shutdown impending Power Mode Battery voltage	>= 9.00 Volts > 15.00 milliseconds > 8.41 Volts >= 6.41 Volts Enabled OBD Controller = False = Not crank >= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With TCM	U0101	This DTC monitors for a loss of communication with the Transmission Control Module.	Message is not received from controller for		General Enable Criteria:		Diagnostic runs in 12.5 ms loop	Type A, 1 Trips
			Message $0BD	≥ 10.00 seconds	If message is on Bus A: U0073	Not Active		
			Message $0C7	≥ 0.50 seconds	If message is on Bus B: U0074	Not Active		
			Message $0F9	≥ 0.50 seconds				
			Message $189	≥ 0.50 seconds	If message is on Bus S: U0076	Not Active		
			Message $199	≥ 0.50 seconds	Starter motor engaged for	> 15.00 milliseconds		
			Message $19D	≥ 0.50 seconds	Or Run/Crank ignition voltage	> 8.41 Volts		
			Message $1AF	≥ 0.50 seconds				
			Message $1F5	≥ 0.50 seconds	Bus is enabled for	>= 0.40 seconds		
			Message $4C9	≥ 10.00 seconds	The following criteria have been enabled for	>= 5.00 seconds		
					Normal CAN transmission on Bus	Enabled		
					Transition from accessory mode to off is pending	= False		
					Controller not in programming mode			
					If bus type = Sensor Bus:			
					Battery voltage	> 11.00 Volts		
					Sensor Bus Relay	= On		
					Otherwise:			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					If power mode = Run/ Crank:			
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII:			
					Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD:			
					Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure:			
					Starter motor engaged for Or	> 15.00 milliseconds		
					Run/Crank ignition voltage	> 8.41 Volts		
					If Hybrid Secure:			
					Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled Or	Enabled		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Controller is an OBD controller Controller shutdown impending Power Mode Battery voltage	OBD Controller = False = Not crank >= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With Transfer Case Control Module	U0102	This DTC monitors for a loss of communication with the transfer case control module	Message is not received from controller for Message $1CB Message $1CC	 ≥ 10.00 seconds ≥ 0.50 seconds	General Enable Criteria: If message is on Bus A: U0073 If message is on Bus B: U0074 If message is on Bus S: U0076 Starter motor engaged for Or Run/Crank ignition voltage Bus is enabled for The following criteria have been enabled for Normal CAN transmission on Bus Transition from accessory mode to off is pending Controller not in programming mode If bus type = Sensor Bus: Battery voltage Sensor Bus Relay Otherwise: If power mode = Run/ Crank:	 Not Active Not Active Not Active > 15.00 milliseconds > 8.41 Volts >= 0.40 seconds >= 5.00 seconds Enabled = False > 11.00 Volts = On	Diagnostic runs in 12.5 ms loop	Type C, No SVS "Emissions Neutral Diagnostics – Type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII: Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD: Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure: Starter motor engaged for Or Run/Crank ignition voltage	> 15.00 milliseconds > 8.41 Volts		
					If Hybrid Secure: Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled Or Controller is an OBD controller	Enabled OBD Controller		
					Controller shutdown impending	= False		
					Power Mode	= Not crank		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Battery voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With Reductant Control Module (SCR)	U010E	This DTC monitors for a loss of communication with the Reductant Control Module (SCR)	Message is not received from controller for Message $092 Message $4CC Message $4CD Message $4E5 Message $4E6 Message $4E7 Message $4E8 Message $4E9	 ≥ 10.00 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 10.00 seconds	General Enable Criteria: If message is on Bus A: U0073 If message is on Bus B: U0074 If message is on Bus S: U0076 Starter motor engaged for Or Run/Crank ignition voltage Bus is enabled for The following criteria have been enabled for Normal CAN transmission on Bus Transition from accessory mode to off is pending Controller not in programming mode If bus type = Sensor Bus: Battery voltage Sensor Bus Relay Otherwise: If power mode = Run/ Crank:	 Not Active Not Active Not Active > 15.00 milliseconds > 8.41 Volts >= 0.40 seconds >= 5.00 seconds Enabled = False > 11.00 Volts = On	Diagnostic runs in 12.5 ms loop	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII: Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD: Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure: Starter motor engaged for Or Run/Crank ignition voltage	> 15.00 milliseconds > 8.41 Volts		
					If Hybrid Secure: Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled Or Controller is an OBD controller	Enabled OBD Controller		
					Controller shutdown impending	= False		
					Power Mode	= Not crank		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Battery voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With Anti-Lock Brake System (ABS) Control Module	U0121	This DTC monitors for a loss of communication with the Anti-Lock Brake System (ABS) Control Module (Non-OBD Module ID 243).	Message is not received from controller for Message $0C1 Message $0C5 Message $1C7 Message $1E9 Message $2F1 Message $2F9	 ≥ 0.50 seconds ≥ 0.50 seconds ≥ 0.50 seconds ≥ 0.50 seconds ≥ 10.00 seconds ≥ 0.50 seconds	General Enable Criteria: If message is on Bus A: U0073 If message is on Bus B: U0074 If message is on Bus S: U0076 Starter motor engaged for Or Run/Crank ignition voltage Bus is enabled for The following criteria have been enabled for Normal CAN transmission on Bus Transition from accessory mode to off is pending Controller not in programming mode If bus type = Sensor Bus: Battery voltage Sensor Bus Relay Otherwise: If power mode = Run/ Crank:	 Not Active Not Active Not Active > 15.00 milliseconds > 8.41 Volts >= 0.40 seconds >= 5.00 seconds Enabled = False > 11.00 Volts = On	Diagnostic runs in 12.5 ms loop	Type C, No SVS "Emissions Neutral Diagnostics – Type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII: Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD: Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure: Starter motor engaged for Or Run/Crank ignition voltage	> 15.00 milliseconds > 8.41 Volts		
					If Hybrid Secure: Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled Or Controller is an OBD controller	Enabled OBD Controller		
					Controller shutdown impending	= False		
					Power Mode	= Not crank		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Battery voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With Power Steering Control Module	U0131	This DTC monitors for a loss of communication with the Power Steering Control Module	Message is not received from controller for Message $1E5	≥ 10.00 seconds	General Enable Criteria: If message is on Bus A: U0073 If message is on Bus B: U0074 If message is on Bus S: U0076 Starter motor engaged for Or Run/Crank ignition voltage Bus is enabled for The following criteria have been enabled for Normal CAN transmission on Bus Transition from accessory mode to off is pending Controller not in programming mode If bus type = Sensor Bus: Battery voltage Sensor Bus Relay Otherwise: If power mode = Run/ Crank:	 Not Active Not Active Not Active > 15.00 milliseconds > 8.41 Volts >= 0.40 seconds >= 5.00 seconds Enabled = False > 11.00 Volts = On	Diagnostic runs in 12.5 ms loop	Type C, No SVS "Safety Emissions Neutral Diagnostic"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII: Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD: Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure: Starter motor engaged for Or Run/Crank ignition voltage	> 15.00 milliseconds > 8.41 Volts		
					If Hybrid Secure: Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled Or Controller is an OBD controller	Enabled OBD Controller		
					Controller shutdown impending	= False		
					Power Mode	= Not crank		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Battery voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With Body Control Module	U0140	This DTC monitors for a loss of communication with the Body Control Module.	Message is not received from controller for Message $0F1 Message $12A Message $1E1 Message $1F1 Message $1F3 Message $3C9 Message $3CB Message $3F1 Message $451 Message $4D7 Message $4E1 Message $4E9	 ≥ 0.50 seconds ≥ 1.00 seconds ≥ 0.50 seconds ≥ 0.50 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 0.50 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 10.00 seconds	General Enable Criteria: If message is on Bus A: U0073 If message is on Bus B: U0074 If message is on Bus S: U0076 Starter motor engaged for Or Run/Crank ignition voltage Bus is enabled for The following criteria have been enabled for Normal CAN transmission on Bus Transition from accessory mode to off is pending Controller not in programming mode If bus type = Sensor Bus: Battery voltage Sensor Bus Relay Otherwise: If power mode = Run/ Crank:	 Not Active Not Active Not Active > 15.00 milliseconds > 8.41 Volts >= 0.40 seconds >= 5.00 seconds Enabled = False > 11.00 Volts = On	Diagnostic runs in 12.5 ms loop	Type C, No SVS "Emissions Neutral Diagnostics – Type C"

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII: Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD: Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure: Starter motor engaged for Or Run/Crank ignition voltage	> 15.00 milliseconds > 8.41 Volts		
					If Hybrid Secure: Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled Or Controller is an OBD controller	Enabled OBD Controller		
					Controller shutdown impending	= False		
					Power Mode	= Not crank		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Battery voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With Gateway A	U0146	This DTC monitors for a loss of communication with Gateway A.	Message is not received from controller for Message $3CF	 ≥ 10.00 seconds	General Enable Criteria: If message is on Bus A: U0073 If message is on Bus B: U0074 If message is on Bus S: U0076 Starter motor engaged for Or Run/Crank ignition voltage Bus is enabled for The following criteria have been enabled for Normal CAN transmission on Bus Transition from accessory mode to off is pending Controller not in programming mode If bus type = Sensor Bus: Battery voltage Sensor Bus Relay Otherwise: If power mode = Run/ Crank:	 Not Active Not Active Not Active > 15.00 milliseconds > 8.41 Volts >= 0.40 seconds >= 5.00 seconds Enabled = False > 11.00 Volts = On	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII: Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD: Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure: Starter motor engaged for Or Run/Crank ignition voltage	> 15.00 milliseconds > 8.41 Volts		
					If Hybrid Secure: Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled Or Controller is an OBD controller	Enabled OBD Controller		
					Controller shutdown impending	= False		
					Power Mode	= Not crank		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Battery voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With NOx Sensor A	U029D	This DTC monitors for a loss of communication with NOx Sensor A.	Message is not received from controller for Message $0B0 Message $0B1 Message $0B5 Message $0B7 Message $289 Message $296 Message $591	 ≥ 0.50 seconds ≥ 0.50 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 0.50 seconds ≥ 0.50 seconds ≥ 10.00 seconds	General Enable Criteria: If message is on Bus A: U0073 If message is on Bus B: U0074 If message is on Bus S: U0076 Starter motor engaged for Or Run/Crank ignition voltage Bus is enabled for The following criteria have been enabled for Normal CAN transmission on Bus Transition from accessory mode to off is pending Controller not in programming mode If bus type = Sensor Bus: Battery voltage Sensor Bus Relay Otherwise: If power mode = Run/ Crank:	 Not Active Not Active Not Active > 15.00 milliseconds > 8.41 Volts >= 0.40 seconds >= 5.00 seconds Enabled = False > 11.00 Volts = On	Diagnostic runs in 12.5 ms loop	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII: Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD: Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure: Starter motor engaged for Or Run/Crank ignition voltage	> 15.00 milliseconds > 8.41 Volts		
					If Hybrid Secure: Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled Or Controller is an OBD controller	Enabled OBD Controller		
					Controller shutdown impending	= False		
					Power Mode	= Not crank		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Battery voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With NOx Sensor B (post catalyst NOx sensor)	U029E	This DTC monitors for a loss of communication with NOx Sensor B.	Message is not received from controller for Message $0A4 Message $0B2 Message $0B6 Message $0B8 Message $28B Message $297 Message $592	 ≥ 0.50 seconds ≥ 0.50 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 0.50 seconds ≥ 0.50 seconds ≥ 10.00 seconds	General Enable Criteria: If message is on Bus A: U0073 If message is on Bus B: U0074 If message is on Bus S: U0076 Starter motor engaged for Or Run/Crank ignition voltage Bus is enabled for The following criteria have been enabled for Normal CAN transmission on Bus Transition from accessory mode to off is pending Controller not in programming mode If bus type = Sensor Bus: Battery voltage Sensor Bus Relay Otherwise: If power mode = Run/ Crank:	 Not Active Not Active Not Active > 15.00 milliseconds > 8.41 Volts >= 0.40 seconds >= 5.00 seconds Enabled = False > 11.00 Volts = On	Diagnostic runs in 12.5 ms loop	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII: Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD: Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure: Starter motor engaged for Or Run/Crank ignition voltage	> 15.00 milliseconds > 8.41 Volts		
					If Hybrid Secure: Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled Or Controller is an OBD controller	Enabled OBD Controller		
					Controller shutdown impending	= False		
					Power Mode	= Not crank		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Battery voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With PM Sensor (Diesel Particulate)	U02A3	This DTC monitors for a loss of communication with the PM Sensor (Diesel Particulate).	Message is not received from controller for Message $3A3 Message $3A5 Message $3A8 Message $3A9 Message $3AA Message $3AB Message $497	 ≥ 10.00 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 10.00 seconds ≥ 10.00 seconds	General Enable Criteria: If message is on Bus A: U0073 If message is on Bus B: U0074 If message is on Bus S: U0076 Starter motor engaged for Or Run/Crank ignition voltage Bus is enabled for The following criteria have been enabled for Normal CAN transmission on Bus Transition from accessory mode to off is pending Controller not in programming mode If bus type = Sensor Bus: Battery voltage Sensor Bus Relay Otherwise: If power mode = Run/ Crank:	 Not Active Not Active Not Active > 15.00 milliseconds > 8.41 Volts >= 0.40 seconds >= 5.00 seconds Enabled = False > 11.00 Volts = On	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Power Mode	= Run		
					If calibratable low voltage disable mode is not Never Disabled			
					Low voltage disable mode: OBDII			
					If OBDII: Run/Crank ignition voltage	>= 11.00 Volts		
					If EOBD: Run/Crank ignition voltage	>= 9.00 Volts		
					If Secure: Starter motor engaged for Or Run/Crank ignition voltage	> 15.00 milliseconds > 8.41 Volts		
					If Hybrid Secure: Run/Crank ignition voltage	>= 6.41 Volts		
					If power mode = Accessory			
					Off key cycle diagnostics are enabled Or Controller is an OBD controller	Enabled OBD Controller		
					Controller shutdown impending	= False		
					Power Mode	= Not crank		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Battery voltage	>= 11.00 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
CGM Lost Communication with ECM	U18D5	This DTC monitors for a CGM Lost Communication with ECM error as determined by the CGM	The CGM Diagnostic Status Message signal in GMLAN frame $3CF indicates that the CGM Lost Communication with ECM DTC has set in the CGM.		General Enable Criteria: Message $3CF Central Gateway Module ECM	 is being received is present on the bus is present on the bus	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
CGM Lost Communication with TCM	U18D7	This DTC monitors for a CGM Lost Communication with TCM error as determined by the CGM	The CGM Diagnostic Status Message signal in GMLAN frame $3CF indicates that the CGM Lost Communication with TCM DTC has set in the CGM.		General Enable Criteria: Message $3CF Central Gateway Module TCM	 is being received is present on the bus is present on the bus	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Central Gateway Module High Speed CAN Bus Off	U2413	This DTC monitors for a Central Gateway Module High Speed CAN Bus Off error as determined by the CGM	The CGM Diagnostic Status Message signal in GMLAN frame $3CF indicates that the Central Gateway Module High Speed CAN Bus Off DTC has set in the CGM.		General Enable Criteria: Message $3CF Central Gateway Module	 is being received is present on the bus	Diagnostic runs in 12.5 ms loop	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Turbocharger VGT A Position Exceeded Learning Limit (Single and Two stage VGT DC Motor)	P003A	This monitor checks if the VGT position SENT sensor has an offset with respect to the nominal positions where the valve does the learning procedure (fully closed and/or fully open)	SENT position raw voltage when the valve is in fully closed position < low threshold OR SENT position raw voltage when the valve is in fully closed position > high threshold OR SENT position raw voltage when the valve is in wide open position < low threshold OR SENT position raw voltage when the valve is in wide open position > high threshold	< 86.00 [%5V] OR > 95.00 [%5V] OR < 16.06 [%5V] OR > 36.35 [%5V]	Test enabled by calibration Key signal is off Learning procedure at key off in fully closed and/or wide open positions have been successfully completed: -engine coolant temperature in range; - no faults present on coolant temperature sensor. No faults present on VGT position sensor, VGT valve, VGTposition deviation. End Of Trip event has elapsed	== 1.00 >= 0.00 (°C) <= 117.00 (°C) ECT_Sensor_FA ==FALSE VGT_PstnSnsrFA ==FALSE VGT_ActCktFA==FALSE VGT_PstnCntrlFA ==FALSE	No debounce is present: DTC sets as soon as the error is present Function task: at key off	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Turbocharger VGT A Control Circuit (Single and Two stage VGT DC Motor)	P0045	This monitor checks if the DC-Motor VGT commands are in open circuit	Load resistance higher than a threshold (error information provided by HWIO)	> 200 [kOhm]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range H-Bridge driver is OFF HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V]	24.00 fail counts out of 30.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Turbocharger VGT A Performance (Single and Two stage VGT DC Motor)	P0046	This monitor detects an obstruction on the actuator (obstruction found during the vanes opening or closing) checking the setpoint position against the position measured by the VGT Position Sensor	Absolute value of position tracking error (setpoint position - measured position)	> 10.00 [%]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range VGT position closed loop control active (no faults present on VGT position sensor, VGT vanes, VGT position control deviation) VGT position setpoint in steady state conditions for minimum time Engine coolant temperature higher or equal to minimum threshold OR Engine cooling system target temperature reached (thermostat opening) No faults present on engine coolant temperature sensor	== 1.00 > 11.00 [V] VGT_PstnSnsrFA ==FALSE VGT_ActCktFA==FALSE VGT_PstnCntrlFA ==FALSE > -44.00 [%/s] < 44.00 [%/s] for >= 0.50 [s] >= 0.00 [°C] ECT_Sensor_FA ==FALSE	800.00 fail counts out of 1,000.00 sample counts Function task: 6.25 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Outside air temperature higher or equal to minimum threshold No faults present on outside air temperature sensor No mechanical stop soft approach in progress No anti-sticking procedure in progress	>= -60.00 [°C] OAT_PtEstFiltFA ==FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Charge Air Cooler Temperature Sensor Up Circuit Performance	P007B	This monitor checks if the CAC up air temperature sensor is irrational at key on when compared with two reference temperature sensors after a long soak time	Charge air cooler up air temperature is compared at power up with an average temperature calculated using the intake manifold air temperature sensor and the fuel temperature sensor over a calibratable number of samples	> 20.00 [°C]	Test enabled by calibration	== 1.00	Test executed after a counter of 1.00 samples	Type B, 2 Trips
					Key on and engine not running or engine running for less than a calibratable time	>= 0.10 [s]	Functional task: 100 ms	
					Runk Crank Relay voltage in range	> 11.00 [V]		
					The engine has not run for a calibratable time since last key off	>= 28,800.00 [s]		
					No faults detected on engine off timer	EngineModeNotRunTimerError ==FALSE		
					Absolute value of the difference between intake manifold air temperature and fuel temperature smaller than a calibratable threshold	< 45.00 [°C]		
					No electrical or self-correlated faults detected on charge air cooler up air temperature sensors	CIT_CAC_UpCktFA ==FALSE CIT_CAC_UpSelfCorFA ==FALSE		
					No faults detected on intake manifold air temperature sensor	MnfdTempSensorFA ==FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No faults detected on fuel temperature sensor	FTS_FTS_Flt==FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Charge Air Cooler Temperature Sensor Up Circuit Low	P007C	This monitor checks if the CAC up air temperature sensor is out of electrical range low	Charge air cooler up air temperature resistance value < low threshold	< 7.00 [ohm]	Test enabled by calibration Engine not cranking Runk Crank Relay voltage in range	== 1.00 > 11.00 [V]	50.00 fail counter over 63.00 sample counter Functional task: 100 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Charge Air Cooler Temperature Sensor Up Circuit High	P007D	This monitor checks if the CAC up air temperature sensor is out of electrical range high	Charge air cooler up air temperature resistance value > high threshold	> 1,020,852.00 [ohm]	Test enabled by calibration Engine not cranking Runk Crank Relay voltage in range	== 1.00 > 11.00 [V]	50.00 fail counter over 63.00 sample counter Functional task: 100 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Charge Air Cooler Temperature Sensor Up Circuit Intermittent/ Erratic	P007E	This monitor checks if the CAC up air temperature has an intermittent fault	Charge air cooler up air temperature value > T_MAX_threshold Charge air cooler up air temperature value < T_MIN_threshold where - T_MAX_threshold = (1 - alpha)*T_MAX + alpha*T_last_good - T_MIN_threshold = (1 - alpha)*T_MIN + alpha*T_last_good - alpha = e^(#fails + 1)*(ts/ tau) - #fails = number of consecutive samples where the test failed - ts = sensor sampling time - tau = sensor filter response time - T_MAX = sensor maximum actual reading - T_MIN = sensor minimum actual reading - T_last_good = last good temperature measured by the sensor	> 300.00 [°C] < -40.00 [°C]	Test enabled by calibration Engine not cranking Runk Crank Relay voltage in range No electrical faults detected on CAC up air temperature sensor	== 1.00 > 11.00 [V] CIT_CAC_UpCktFA ==FALSE	50.00 fail counter over 63.00 sample counter Functional task: 100 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Mass Air Flow (MAF) Sensor Performance	P0101	This monitor checks if the MAF sensor measure is coherent with MAF estimation when the HP EGR and LP EGR (if present) are closed. It is able to detect MAF sensor wiring harness poor contacts, MAF sensor internal fault (offset), leaks from the induction air circuit, leaks from the recirculation exhuast gas circuit. For OBDII market, it is used to detect a PCV disconnection. The standard test can be calibrated to run when engine conditions are recognised as IDLE, OVERRUN or HIGH LOAD. An intrusive test can be enabled, to force the HP EGR to close when particular conditions are encountered, to allow the monitoring to run in idle.	Drift high check: drift of the mass air flow Drift low check: drift of the mass air flow The drift of the mass air flow is calculated as the ratio between the MAF sensor reading and the estimated mass air flow. The ratio is averaged over a calibrate-able cumulative transient time. If, by calibration, CeMAFD_e_ArflAdj ==CeMAFD_e_ArflRaw, the MAF sensor reading is given by the raw MAF value multiplied by the **P0101: Pulsation Map**	> 1.20 [ratio] < 0.80 [ratio]	Calibration on diagnostic enabling PT relay supply voltage in range Share High Side driver closed Estimated mass air flow is valid No Electrical or offset fault present on MAF sensor OBDII Market: Outside Ambient Temperature in range OR Fault present on Ouside Air temperature EOBD Market: Outside Ambient Temperature in range AND No Fault present on Ouside Air temperature	**P0101: MAF performance enabling** ==TRUE > 11.00 [V] ==TRUE MAF_AirFlowEstdSS_NotVld ==FALSE MAF_MAF_SnsrCktOffstFA ==FALSE MAF_MAF_SnsrCktOffstTFKO ==FALSE > -7.00 [°C] OAT_PtEstFiltFA==TRUE > -7.00 [°C] OAT_OAT_SnsrNonEmissFA ==FALSE	Test is evaluated after the enabling conditions are satisfied for a number of samples == 400.00 Sampling time is: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Induction air temperature	> -7.00 [°C]		
					No fault present on induction air temperature sensor	IAT_SensorFA ==FALSE IAT_SensorTFTKO ==FALSE		
					(Engine Coolant Temperature OR OBD Coolant Enable Criteria), AND Engine Coolant Temperature	> 50.00 [°C] ==TRUE < 117.00 [°C]		
					No faults detected on engine coolant temperature sensor	ECT_Sensor_FA ==FALSE ECT_Sensor_TFTKO ==FALSE		
					Barometric pressure	> 69.60 [kPa]		
					No faults detected on barometric pressure sensor	AAP_AmbientAirPresDfltd ==FALSE AAP_AmbPresSnsrTFTKO ==FALSE		
					Throttle valve position	> 85.00 [%]		
					No faults detected on Throttle valve position sensor	TPS_PstnSnsrFA ==FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					HP EGR valve position	<= 0.40 [%]		
					No faults detected on HP EGR valve position sensor	EGR_PstnSnsrFA ==FALSE		
					LP EGR (if present) valve position	<= 1.00 [%]		
					No faults detected on LP EGR (if present) valve position sensor	LPE_PstnSnsrFA ==FALSE		
					Engine works in IDLE, OVERRUN or HIGH LOAD condition	Refer to "Engine conditions" Free Form		
			Drift high check: drift of the mass air flow Drift low check: drift of the mass air flow The drift of the mass air flow is calculated as the ratio between the MAF sensor reading and the estimated mass air flow. The ratio is averaged over a calibrate-able cumulative transient time. If, by calibration, CeMAFD_e_ArflAdj	> 1.20 [ratio] < 0.80 [ratio]	Intrusive Test enabled by calibration MAF rationality monitoring enabled by calibration Diagnostic has not run in current driving cycle yet Calibratable SCR dosing condition	0.00 ==TRUE **P0101: MAF performance enabling** ==TRUE ==TRUE IF 0.00 ==TRUE: SCR dosing condition is NH3 storage control OR intrusive NH3 storage control OR transient dosing control.	Test is evaluated after the enabling conditions are satisfied for a number of samples == 400.00 Sampling time is: 12.5 ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			==CeMAFD_e_ArflRaw, the MAF sensor reading is given by the raw MAF value multiplied by the **P0101: Pulsation Map**			IF 0.00 ==FALSE: No restrictions on SCR dosing		
					SCR predicted NOx conversion efficiency	> 0.85 [ratio]		
					Air control is working only in EGR control: Desired EGR rate	= 100%		
					Vehicle speed	< 3.00 [kph]		
					No faults detected on vehicle speed sensor	VehicleSpeedSensor_FA ==FALSE		
					Desired fuel in range, with hysteresis OR (Speed Control Mode is Idle AND No faults detected on Speed Control) (OBDII market only)	Enabled if < 40.00 [mm^3] AND > 5.00 [mm^3] Disabled if > 45.00 [mm^3] OR < 0.00 [mm^3] ==TRUE FUL_IFM_IdleFuelQntyFA ==FALSE		
					PT relay supply voltage in range	> 11.00 [V]		
					Share High Side driver closed	==TRUE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Estimated mass air flow is valid	MAF_AirFlowEstdSS_NotVld ==FALSE		
					No Electrical or offset fault present on MAF sensor	MAF_MAF_SnsrCktOffstFA ==FALSE MAF_MAF_SnsrCktOffstTFKO ==FALSE		
					OBDII Market: Outside Ambient Temperature in range OR Fault present on Ouside Air temperature	> -7.00 [°C] OR OAT_PtEstFiltFA==TRUE		
					EOBD Market: Outside Ambient Temperature in range AND No Fault present on Ouside Air temperature	> -7.00 [°C] AND OAT_OAT_SnsrNonEmissFA ==FALSE		
					Induction air temperature	> -7.00 [°C]		
					No fault present on induction air temperature sensor	IAT_SensorFA ==FALSE IAT_SensorTFTKO ==FALSE		
					(Engine Coolant Temperature OR	> 50.00 [°C] ==TRUE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					OBD Coolant Enable Criteria), AND Engine Coolant Temperature	< 117.00 [°C]		
					No faults detected on engine coolant temperature sensor	ECT_Sensor_FA ==FALSE ECT_Sensor_TFTKO ==FALSE		
					Barometric pressure	> 69.60 [kPa]		
					No faults detected on barometric pressure sensor	AAP_AmbientAirPresDfltd ==FALSE AAP_AmbPresSnsrTFTKO ==FALSE		
					Throttle valve position	> 85.00 [%]		
					No faults detected on Throttle valve position sensor	TPS_PstnSnsrFA ==FALSE		
					LP EGR (if present) valve position	<= 1.00 [%]		
					No faults detected on LP EGR (if present) valve position sensor	LPE_PstnSnsrFA ==FALSE		
					Engine speed in range OR	> 700.00 [rpm] < 1,200.00 [rpm]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					(Speed Control Mode is Idle AND No faults detected on Speed Control) (OBDII market only) for a time Intake manifold pressure in range Intake manifold pressure is in steady state (SS) Once all the conditions above are satisfied, additional conditions on HP EGR valve must be verified within a time limit HP EGR valve position No faults detected on HP EGR valve position sensor All conditions are verified for a time	==TRUE IAC_SystemRPM_FA ==FALSE >= 1.00 [s] > 70.00 [kPa] < 150.00 [kPa] when SS is OFF, the first value of Intake manifold pressure is taken as reference (p_ref); then, | Intake manifold pressure - p_ref| < 6.00 [kPa] for maintaining the SS ON < 1.00 [s] <= 0.40 [%] EGR_PstnSnsrFA ==FALSE > 5.00 [s]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Mass Air Flow (MAF) Sensor Circuit Low	P0102	This monitor checks if the MAF sensor is out of electrical range low. The MAF sensor is out of electrical range low in case of sensor internal fault or wiring harness faults.	MAF frequency value	< 276.00 [Hz]	Test enabled by calibration Engine speed PT relay supply voltage in range Share High Side Driver closed All conditions are valid for a time	1.00 ==TRUE >= 650.00 [rpm] > 11.00 [V] ==TRUE >= 1.00 [s]	100.00 fail counts out of 125.00 sample counts Function task: 100 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Mass Air Flow (MAF) Sensor Circuit High	P0103	This monitor checks if the MAF sensor is out of electrical range high. The MAF sensor is out of electrical range high in case of sensor internal fault or wiring harness faults.	MAF frequency value	> 12,500.00 [Hz]	Test enabled by calibration Engine speed PT relay supply voltage in range Share High Side Driver closed All conditions arevalid for a time	1.00 ==TRUE >= 650.00 [rpm] > 11.00 [V] ==TRUE >= 1.00 [s]	100.00 fail counts out of 125.00 sample counts Function task:100 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Trim System Lean Bank 1	P0171	This DTC monitors if FSA control system has reached its maximum authority and cannot achieve the target. An error shall be detected when the fuel adjustment value (mm3) released by FSA is saturatedat its minimum value.	Released FSA fuel correction value	< refer to supporting table (**KtFADC_V_FSA_FuelMin**) [mm3]	System voltage in range FSA correction release enabled (FSA Learning is active OR DFSA Learning is active) for a time Ambient air pressure OBD Coolant Enable Criteria OR Engine coolant temperature Ambient air temperature No Low fuel tank level indication No pending or confirmed DTCs	> 11.00 [V] refer to "FSA Control Flag" Free Form FAD_FSA_NormRngCrtnValid refer to "FSA Control Flag" Free Form (FAD_FSA_EnblLrn OR FAD_DFSA_EnblLrn) > 1.00 [s] > 67.00 [kPa] = TRUE > 45.00 [°C] > -20.00 [°C] LowFuelConditionDiagnostic AmbPresDfltdStatus (ECT_Sensor_TFTKO AND ECT_Sensor_FA) OAT_PtEstFiltFA	Time counter: 280 failures out of 400 samples. Time task 25[ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Trim System Rich Bank 1	P0172	This DTC monitors if FSA control system has reached its maximum authority and cannot achieve the target. An error shall be detected when the fuel adjustment value (mm3) released by FSA is saturatedat its maximum value.	Released FSA fuel correction value	> refer to supporting table (**KtFADC_V_FSA_FuelMax**)[mm3]	System voltage in range FSA correction release enabled (FSA Learning is active OR DFSA Learning is active) for a time Ambient air pressure OBD Coolant Enable Criteria OR Engine coolant temperature Ambient air temperature No Low fuel tank level indication No pending or confirmed DTCs	> 11.00 [V] refer to "FSA Control Flag" Free Form FAD_FSA_NormRngCrtnValid refer to "FSA Control Flag" Free Form (FAD_FSA_EnblLrn OR FAD_DFSA_EnblLrn) > 1.00 [s] > 67.00 [kPa] = TRUE > 45.00 [°C] > -20.00 [°C] LowFuelConditionDiagnostic AmbPresDfltdStatus (ECT_Sensor_TFTKO AND ECT_Sensor_FA) OAT_PtEstFiltFA	Time counter: 280 failures out of 400 samples. Time task 25[ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 1 Injection Timing Perfomance - Over Retarded	P01CB	This diagnosis is able to detect an excessive negative drift on fuel injection quantity and timing affecting injector 1. During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the angular acceleration produced during the combustion phase. By comparing the angular acceleration value produced during the combustion phase with the angular acceleration that would be produced during the combustion of a nominal fuel quantity (e.g. 1,5mm3), the SQA is able to calculate the drift, in term of energizing time, on injector 1. Several injections, with different injection quantities, are performed in order to define the correct DeltaET to reach the target crank wheel angular acceleration and obtain the injector behavior in the small	Suspicious confidence level of tested injector (To fail suspicious), function of Current Energizing time calculated with SSQA and delta Energizing time calculated in the previous test: **KtFADD_Pct_SSQA_InjSuspConfLvl** (Delta Enegizing Time, Delta Energizing Time old) In case the first test fails: Delta Energizing time calculated with VSQA (To fail Validation)	< 50.00 [%] > 80.00 [us]	SQA Diagnosis enabled SSQA and VSQA enabled via calibration Baro Pressure Ambient temp No Low Fuel level tank indication AND Boolean Flag used to enable low fuel level check is TRUE XSQA Learning conditions enabled Power Take Off not active AND Boolean Flag used to disable SQA in case of power take off active	1.00 1.00 >= 72.00 [kPa] >= -20.00 [°C] LowFuelConditionDiagnostic 1.00 FAD_XSQA_LrnCondEnbl = 0.00	Inj_To_PassFail_SSQA Number of injections in case sospicious pass or (if sospicious fails) Inj_To_PassFail_SSQA +Inj_To_PassFail_VSQA number of injections to pass or fail validation Once per Trip if suspicious and validations (in case of sospicious injectors detected) have been already completed in the previous driving cycle, otherwise the diagnosis starts from the interrupted status. Sample Rate: [1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		quantity area. This energizing time is then used for the diagnostic test that is performed in two different steps: The first is the suspicious (SSQA) in which all the injectors are classified as suspicious or not suspicious. During this phase several injections are performed on all the injectors in order to calculate the drift, in term of energizing time, of each injector. The drift found is then used together with the drift found in the previous test to enter a calibrate-able map in which a confidence level between 0 and 100% is given to each injector. The confidence levels depends on the delta energizing time between two consecutive tests. An injector is considered suspicious if the confidence level is lower than a calibrate-able threshold. The suspicious phase can only report test pass for not suspicious injectors while the injectors that fail the						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		suspicious are tested by means of VSQA (Validation Small Quantity Adjustment) in order to validate or not the fault. The validation starts from the most suspicious injector (using the distance of current DeltaET from the VSQA calibrate-able thresholds) found during Suspicious phase and performs a calibrate-able number of injections, generally higher than the number of injection performed during suspicious, in order to find out a more accurate drift value for the tested injector. If the Delta Energizing time calculated during this phase is higher than a calibrate-able threshold a DTC is set.						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 1 Injection Timing Perfomance - Over Advanced	P01CC	This diagnosis is able to detect an excessive positive drift on fuel injection quantity and timing affecting injector 1. During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the angular acceleration produced during the combustion phase. By comparing the angular acceleration value produced during the combustion phase with the angular acceleration that would be produced during the combustion of a nominal fuel quantity (e.g. 1,5mm3), the SQA is able to calculate the drift, in term of energizing time, on injector 1. Several injections, with different injection quantities, are performed in order to define the correct DeltaET to reach the target crank wheel angular acceleration and obtain the injector behavior in the small	Suspicious confidence level of tested injector (To fail suspicious), function of Current Energizing time calculated with SSQA and delta Energizing time calculated in the previous test: **KtFADD_Pct_SSQA_InjSuspConfLvl** (Delta Enegizing Time, Delta Energizing Time old) In case the first test fails: Delta Energizing time calculated with VSQA (To fail Validation)	< 50.00 [%] < -80.00 [us]	SQA Diagnosis enabled SSQA and VSQA enabled via calibration Baro Pressure Ambient temp No Low Fuel level tank indication AND Boolean Flag used to enable low fuel level check is TRUE XSQA Learning conditions enabled Power Take Off not active AND Boolean Flag used to disable SQA in case of power take off active	1.00 1.00 >= 72.00 [kPa] >= -20.00 [°C] LowFuelConditionDiagnostic 1.00 FAD_XSQA_LrnCondEnbl = 0.00	Inj_To_PassFail_SSQA Number of injections in case sospicious pass or (if sospicious fails) Inj_To_PassFail_SSQA +Inj_To_PassFail_VSQA number of injections to pass or fail validation Once per Trip if suspicious and validations (in case of sospicious injectors detected) have been already completed in the previous driving cycle, otherwise the diagnosis starts from the interrupted status. Sample Rate: [1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		quantity area. This energizing time is then used for the diagnostic test that is performed in two different steps: The first is the suspicious (SSQA) in which all the injectors are classified as suspicious or not suspicious. During this phase several injections are performed on all the injectors in order to calculate the drift, in term of energizing time, of each injector. The drift found is then used together with the drift found in the previous test to enter a calibrate-able map in which a confidence level between 0 and 100% is given to each injector. The confidence levels depends on the delta energizing time between two consecutive tests. An injector is considered suspicious if the confidence level is lower than a calibrate-able threshold. The suspicious phase can only report test pass for not suspicious injectors while the injectors that fail the						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		suspicious are tested by means of VSQA (Validation Small Quantity Adjustment) in order to validate or not the fault. The validation starts from the most suspicious injector (using the distance of current DeltaET from the VSQA calibrate-able thresholds) found during Suspicious phase and performs a calibrate-able number of injections, generally higher than the number of injection performed during suspicious, in order to find out a more accurate drift value for the tested injector. If the Delta Energizing time calculated during this phase is lower than a calibrate-able threshold a DTC is set.						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 2 Injection Timing Perfomance - Over Retarded	P01CD	This diagnosis is able to detect an excessive negative drift on fuel injection quantity and timing affecting injector 2. During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the angular acceleration produced during the combustion phase. By comparing the angular acceleration value produced during the combustion phase with the angular acceleration that would be produced during the combustion of a nominal fuel quantity (e.g. 1,5mm3), the SQA is able to calculate the drift, in term of energizing time, on injector 2. Several injections, with different injection quantities, are performed in order to define the correct DeltaET to reach the target crank wheel angular acceleration and obtain the injector behavior in the small	Suspicious confidence level of tested injector (To fail suspicious), function of Current Energizing time calculated with SSQA and delta Energizing time calculated in the previous test: **KtFADD_Pct_SSQA_InjSuspConfLvl** (Delta Enegizing Time, Delta Energizing Time old) In case the first test fails: Delta Energizing time calculated with VSQA (To fail Validation)	< 50.00 [%] > 80.00 [us]	SQA Diagnosis enabled SSQA and VSQA enabled via calibration Baro Pressure Ambient temp No Low Fuel level tank indication AND Boolean Flag used to enable low fuel level check is TRUE XSQA Learning conditions enabled Power Take Off not active AND Boolean Flag used to disable SQA in case of power take off active	1.00 1.00 >= 72.00 [kPa] >= -20.00 [°C] LowFuelConditionDiagnostic 1.00 FAD_XSQA_LrnCondEnbl = 0.00	Inj_To_PassFail_SSQA Number of injections in case sospicious pass or (if sospicious fails) Inj_To_PassFail_SSQA +Inj_To_PassFail_VSQA number of injections to pass or fail validation Once per Trip if suspicious and validations (in case of sospicious injectors detected) have been already completed in the previous driving cycle, otherwise the diagnosis starts from the interrupted status. Sample Rate: [1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		quantity area. This energizing time is then used for the diagnostic test that is performed in two different steps: The first is the suspicious (SSQA) in which all the injectors are classified as suspicious or not suspicious. During this phase several injections are performed on all the injectors in order to calculate the drift, in term of energizing time, of each injector. The drift found is then used together with the drift found in the previous test to enter a calibrate-able map in which a confidence level between 0 and 100% is given to each injector. The confidence levels depends on the delta energizing time between two consecutive tests. An injector is considered suspicious if the confidence level is lower than a calibrate-able threshold. The suspicious phase can only report test pass for not suspicious injectors while the injectors that fail the						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		suspicious are tested by means of VSQA (Validation Small Quantity Adjustment) in order to validate or not the fault. The validation starts from the most suspicious injector (using the distance of current DeltaET from the VSQA calibrate-able thresholds) found during Suspicious phase and performs a calibrate-able number of injections, generally higher than the number of injection performed during suspicious, in order to find out a more accurate drift value for the tested injector. If the Delta Energizing time calculated during this phase is higher than a calibrate-able threshold a DTC is set.						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 2 Injection Timing Perfomance - Over Advanced	P01CE	This diagnosis is able to detect an excessive positive drift on fuel injection quantity and timing affecting injector 2. During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the angular acceleration produced during the combustion phase. By comparing the angular acceleration value produced during the combustion phase with the angular acceleration that would be produced during the combustion of a nominal fuel quantity (e.g. 1,5mm3), the SQA is able to calculate the drift, in term of energizing time, on injector 2. Several injections, with different injection quantities, are performed in order to define the correct DeltaET to reach the target crank wheel angular acceleration and obtain the injector behavior in the small	Suspicious confidence level of tested injector (To fail suspicious), function of Current Energizing time calculated with SSQA and delta Energizing time calculated in the previous test: **KtFADD_Pct_SSQA_InjSuspConfLvl** (Delta Enegizing Time, Delta Energizing Time old) In case the first test fails: Delta Energizing time calculated with VSQA (To fail Validation)	< 50.00 [%] < -80.00 [us]	SQA Diagnosis enabled SSQA and VSQA enabled via calibration Baro Pressure Ambient temp No Low Fuel level tank indication AND Boolean Flag used to enable low fuel level check is TRUE XSQA Learning conditions enabled Power Take Off not active AND Boolean Flag used to disable SQA in case of power take off active	1.00 1.00 >= 72.00 [kPa] >= -20.00 [°C] LowFuelConditionDiagnostic 1.00 FAD_XSQA_LrnCondEnbl = 0.00	Inj_To_PassFail_SSQA Number of injections in case sospicious pass or (if sospicious fails) Inj_To_PassFail_SSQA +Inj_To_PassFail_VSQA number of injections to pass or fail validation. Once per Trip if suspicious and validations (in case of sospicious injectors detected) have been already completed in the previous driving cycle, otherwise the diagnosis starts from the interrupted status. Sample Rate: [1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		quantity area. This energizing time is then used for the diagnostic test that is performed in two different steps: The first is the suspicious (SSQA) in which all the injectors are classified as suspicious or not suspicious. During this phase several injections are performed on all the injectors in order to calculate the drift, in term of energizing time, of each injector. The drift found is then used together with the drift found in the previous test to enter a calibrate-able map in which a confidence level between 0 and 100% is given to each injector. The confidence levels depends on the delta energizing time between two consecutive tests. An injector is considered suspicious if the confidence level is lower than a calibrate-able threshold. The suspicious phase can only report test pass for not suspicious injectors while the injectors that fail the						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		suspicious are tested by means of VSQA (Validation Small Quantity Adjustment) in order to validate or not the fault. The validation starts from the most suspicious injector (using the distance of current DeltaET from the VSQA calibrate-able thresholds) found during Suspicious phase and performs a calibrate-able number of injections, generally higher than the number of injection performed during suspicious, in order to find out a more accurate drift value for the tested injector. If the Delta Energizing time calculated during this phase is lowerthan a calibrate-able threshold a DTC is set.						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 3 Injection Timing Perfomance - Over Retarded	P01CF	This diagnosis is able to detect an excessive negative drift on fuel injection quantity and timing affecting injector 3. During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the angular acceleration produced during the combustion phase. By comparing the angular acceleration value produced during the combustion phase with the angular acceleration that would be produced during the combustion of a nominal fuel quantity (e.g. 1,5mm3), the SQA is able to calculate the drift, in term of energizing time, on injector 3. Several injections, with different injection quantities, are performed in order to define the correct DeltaET to reach the target crank wheel angular acceleration and obtain the injector behavior in the small	Suspicious confidence level of tested injector (To fail suspicious), function of Current Energizing time calculated with SSQA and delta Energizing time calculated in the previous test: **KtFADD_Pct_SSQA_InjSuspConfLvl** (Delta Enegizing Time, Delta Energizing Time old) In case the first test fails: Delta Energizing time calculated by VSQA (To fail Validation)	< 50.00 [%] > 80.00 [us]	SQA Diagnosis enabled SSQA and VSQA enabled via calibration Baro Pressure Ambient temp No Low Fuel level tank indication AND Boolean Flag used to enable low fuel level check is TRUE XSQA Learning conditions enabled Power Take Off not active AND Boolean Flag used to disable SQA in case of power take off active	1.00 1.00 >= 72.00 [kPa] >= -20.00 [°C] LowFuelConditionDiagnostic 1.00 FAD_XSQA_LrnCondEnbl = 0.00	Inj_To_PassFail_SSQA Number of injections in case sospicious pass or (if sospicious fails) Inj_To_PassFail_SSQA +Inj_To_PassFail_VSQA number of injections to pass or fail validation Once per Trip if suspicious and validations (in case of sospicious injectors detected) have been already completed in the previous driving cycle, otherwise the diagnosis starts from the interrupted status. Sample Rate: [1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		quantity area. This energizing time is then used for the diagnostic test that is performed in two different steps: The first is the suspicious (SSQA) in which all the injectors are classified as suspicious or not suspicious. During this phase several injections are performed on all the injectors in order to calculate the drift, in term of energizing time, of each injector. The drift found is then used together with the drift found in the previous test to enter a calibrate-able map in which a confidence level between 0 and 100% is given to each injector. The confidence levels depends on the delta energizing time between two consecutive tests. An injector is considered suspicious if the confidence level is lower than a calibrate-able threshold. The suspicious phase can only report test pass for not suspicious injectors while the injectors that fail the						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		suspicious are tested by means of VSQA (Validation Small Quantity Adjustment) in order to validate or not the fault. The validation starts from the most suspicious injector (using the distance of current DeltaET from the VSQA calibrate-able thresholds) found during Suspicious phase and performs a calibrate-able number of injections, generally higher than the number of injection performed during suspicious, in order to find out a more accurate drift value for the tested injector. If the Delta Energizing time calculated during this phase is higher than a calibrate-able threshold a DTC is set.						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 3 Injection Timing Perfomance - Over Advanced	P01D0	This diagnosis is able to detect an excessive positive drift on fuel injection quantity and timing affecting injector 3. During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the angular acceleration produced during the combustion phase. By comparing the angular acceleration value produced during the combustion phase with the angular acceleration that would be produced during the combustion of a nominal fuel quantity (e.g. 1,5mm3), the SQA is able to calculate the drift, in term of energizing time, on injector 3. Several injections, with different injection quantities, are performed in order to define the correct DeltaET to reach the target crank wheel angular acceleration and obtain the injector behavior in the small	Suspicious confidence level of tested injector (To fail suspicious), function of Current Energizing time calculated with SSQA and delta Energizing time calculated in the previous test: **KtFADD_Pct_SSQA_InjSuspConfLvl** (Delta Enegizing Time, Delta Energizing Time old) In case the first test fails: Delta Energizing time calculated by VSQA (To fail Validation)	< 50.00 [%] < -80.00 [us]	SQA Diagnosis enabled SSQA and VSQA enabled via calibration Baro Pressure Ambient temp No Low Fuel level tank indication AND Boolean Flag used to enable low fuel level check is TRUE XSQA Learning conditions enabled Power Take Off not active AND Boolean Flag used to disable SQA in case of power take off active	1.00 1.00 >= 72.00 [kPa] >= -20.00 [°C] LowFuelConditionDiagnostic 1.00 FAD_XSQA_LrnCondEnbl = 0.00	Inj_To_PassFail_SSQA Number of injections in case sospicious pass or (if sospicious fails) Inj_To_PassFail_SSQA +Inj_To_PassFail_VSQA number of injections to pass or fail validation. Once per Trip if suspicious and validations (in case of sospicious injectors detected) have been already completed in the previous driving cycle, otherwise the diagnosis starts from the interrupted status. Sample Rate: [1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		quantity area. This energizing time is then used for the diagnostic test that is performed in two different steps: The first is the suspicious (SSQA) in which all the injectors are classified as suspicious or not suspicious. During this phase several injections are performed on all the injectors in order to calculate the drift, in term of energizing time, of each injector. The drift found is then used together with the drift found in the previous test to enter a calibrate-able map in which a confidence level between 0 and 100% is given to each injector. The confidence levels depends on the delta energizing time between two consecutive tests. An injector is considered suspicious if the confidence level is lower than a calibrate-able threshold. The suspicious phase can only report test pass for not suspicious injectors while the injectors that fail the						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		suspicious are tested by means of VSQA (Validation Small Quantity Adjustment) in order to validate or not the fault. The validation starts from the most suspicious injector (using the distance of current DeltaET from the VSQA calibrate-able thresholds) found during Suspicious phase and performs a calibrate-able number of injections, generally higher than the number of injection performed during suspicious, in order to find out a more accurate drift value for the tested injector. If the Delta Energizing time calculated during this phase is lowerthan a calibrate-able threshold a DTC is set.						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 4 Injection Timing Perfomance - Over Retarded	P01D1	This diagnosis is able to detect an excessive negative drift on fuel injection quantity and timing affecting injector 4. During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the angular acceleration produced during the combustion phase. By comparing the angular acceleration value produced during the combustion phase with the angular acceleration that would be produced during the combustion of a nominal fuel quantity (e.g. 1,5mm3), the SQA is able to calculate the drift, in term of energizing time, on injector 4. Several injections, with different injection quantities, are performed in order to define the correct DeltaET to reach the target crank wheel angular acceleration and obtain the injector behavior in the small	Suspicious confidence level of tested injector (To fail suspicious), function of Current Energizing time calculated with SSQA and delta Energizing time calculated in the previous test: **KtFADD_Pct_SSQA_InjSuspConfLvl** (Delta Enegizing Time, Delta Energizing Time old) In case the first test fails: Delta Energizing time calculated by VSQA (To fail Validation)	< 50.00 [%] > 80.00 [us]	SQA Diagnosis enabled SSQA and VSQA enabled via calibration Baro Pressure Ambient temp No Low Fuel level tank indication AND Boolean Flag used to enable low fuel level check is TRUE XSQA Learning conditions enabled Power Take Off not active AND Boolean Flag used to disable SQA in case of power take off active	1.00 1.00 >= 72.00 [kPa] >= -20.00 [°C] LowFuelConditionDiagnostic 1.00 FAD_XSQA_LrnCondEnbl = 0.00	Inj_To_PassFail_SSQA Number of injections in case sospicious pass or (if sospicious fails) Inj_To_PassFail_SSQA +Inj_To_PassFail_VSQA number of injections to pass or fail validation Once per Trip if suspicious and validations (in case of sospicious injectors detected) have been already completed in the previous driving cycle, otherwise the diagnosis starts from the interrupted status. Sample Rate: [1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		quantity area. This energizing time is then used for the diagnostic test that is performed in two different steps: The first is the suspicious (SSQA) in which all the injectors are classified as suspicious or not suspicious. During this phase several injections are performed on all the injectors in order to calculate the drift, in term of energizing time, of each injector. The drift found is then used together with the drift found in the previous test to enter a calibrate-able map in which a confidence level between 0 and 100% is given to each injector. The confidence levels depends on the delta energizing time between two consecutive tests. An injector is considered suspicious if the confidence level is lower than a calibrate-able threshold. The suspicious phase can only report test pass for not suspicious injectors while the injectors that fail the						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		suspicious are tested by means of VSQA (Validation Small Quantity Adjustment) in order to validate or not the fault. The validation starts from the most suspicious injector (using the distance of current DeltaET from the VSQA calibrate-able thresholds) found during Suspicious phase and performs a calibrate-able number of injections, generally higher than the number of injection performed during suspicious, in order to find out a more accurate drift value for the tested injector. If the Delta Energizing time calculated during this phase is higher than a calibrate-able threshold a DTC is set.						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 4 Injection Timing Perfomance - Over Advanced	P01D2	This diagnosis is able to detect an excessive positive drift on fuel injection quantity and timing affecting injector 4. During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the angular acceleration produced during the combustion phase. By comparing the angular acceleration value produced during the combustion phase with the angular acceleration that would be produced during the combustion of a nominal fuel quantity (e.g. 1,5mm3), the SQA is able to calculate the drift, in term of energizing time, on injector 4. Several injections, with different injection quantities, are performed in order to define the correct DeltaET to reach the target crank wheel angular acceleration and obtain the injector behavior in the small	Suspicious confidence level of tested injector (To fail suspicious), function of Current Energizing time calculated with SSQA and delta Energizing time calculated in the previous test: **KtFADD_Pct_SSQA_InjSuspConfLvl** (Delta Enegizing Time, Delta Energizing Time old) In case the first test fails: Delta Energizing time calculated by VSQA (To fail Validation)	< 50.00 [%] < -80.00 [us]	SQA Diagnosis enabled SSQA and VSQA enabled via calibration Baro Pressure Ambient temp No Low Fuel level tank indication AND Boolean Flag used to enable low fuel level check is TRUE XSQA Learning conditions enabled Power Take Off not active AND Boolean Flag used to disable SQA in case of power take off active	1.00 1.00 >= 72.00 [kPa] >= -20.00 [°C] LowFuelConditionDiagnostic 1.00 FAD_XSQA_LrnCondEnbl = 0.00	Inj_To_PassFail_SSQA Number of injections in case sospicious pass or (if sospicious fails) Inj_To_PassFail_SSQA +Inj_To_PassFail_VSQA number of injections to pass or fail validation. Once per Trip if suspicious and validations (in case of sospicious injectors detected) have been already completed in the previous driving cycle, otherwise the diagnosis starts from the interrupted status. Sample Rate: [1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		quantity area. This energizing time is then used for the diagnostic test that is performed in two different steps: The first is the suspicious (SSQA) in which all the injectors are classified as suspicious or not suspicious. During this phase several injections are performed on all the injectors in order to calculate the drift, in term of energizing time, of each injector. The drift found is then used together with the drift found in the previous test to enter a calibrate-able map in which a confidence level between 0 and 100% is given to each injector. The confidence levels depends on the delta energizing time between two consecutive tests. An injector is considered suspicious if the confidence level is lower than a calibrate-able threshold. The suspicious phase can only report test pass for not suspicious injectors while the injectors that fail the						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		suspicious are tested by means of VSQA (Validation Small Quantity Adjustment) in order to validate or not the fault. The validation starts from the most suspicious injector (using the distance of current DeltaET from the VSQA calibrate-able thresholds) found during Suspicious phase and performs a calibrate-able number of injections, generally higher than the number of injection performed during suspicious, in order to find out a more accurate drift value for the tested injector. If the Delta Energizing time calculated during this phase is lowerthan a calibrate-able threshold a DTC is set.						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Charge Air Cooler Efficiency Below Threshold (OBDII market only)	P026A	This monitor checks the Charge Air Cooler efficiency deterioration, that would cause vehicle's emissions to exceed specific emission levels.	Charge Air Cooler Efficiency (averaged over a calibrate-able cumulative transient time) is compared with a threshold. Charge Air Cooler Efficiency is computed as the ratio between (CAC upstream temperature - CAC downstream temperature) and (CAC upstream temperature - Reference temperature). Reference temperature can be selected via calibration: if 0.00 ==TRUE, it is the induction air temperature, otherwise it is the outside air temperature.	< 50.00 [%]	Calibration on diagnostic enabling Diagnostic has not run in current driving cycle yet Vehicle speed in range Air mass flow in range Engine coolant temperature in range OR OBD Coolant Enable Criteria Throttle valve position Pressure ratio through the compressor in range Temperature difference between upstream charge air cooler and Reference temperature in range Environmental pressure in range Environmental temperature in range	1.00 ==TRUE ==TRUE > 40.00 [kph] > 20.00 [mg/s] < 2,000.00 [mg/s] > 70.00 [°C] ==TRUE > 90.00 [%] > 1.30 [ratio] > 10.00 [°C] > 69.60 [kPa] > -20.00 [°C]	Test executed after 800.00 samples are collected and their average is computed Function task: 100 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No fault on vehicle speed sensor	VehicleSpeedSensor_FA ==FALSE		
					No fault on engine coolant temperature sensor	ECT_Sensor_FA ==FALSE		
					No fault on throttle position sensor	TPS_PstnSnsrFA ==FALSE		
					No fault on ambient pressure sensor	AAP_AmbientAirPresDfltd ==FALSE		
					No fault on Reference temperature sensor	OAT_PtEstFiltFA ==FALSE OR IAT_SensorFA==FALSE		
					No fault on charge air cooler upstream and downstream temperature sensors	CIT_CAC_UpFA==FALSE CIT_CAC_DwnFA ==FALSE		
					No fault on MAF meter	MAF_MAF_SnsrFA ==FALSE		
					No fault on Intake Manifold Pressure sensor	MAP_SensorFA==FALSE		
					All the enabling conditions last for a time	>= 0.50 [s]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Injection Quantity Lower Than Expected	P026C	An error shall be detected when the fuel adjustment value (mm3) released by FSA is below a calibrated threshold.	Released FSA fuel correction value lower than a threshold A selected based on active combustion mode (refer to supporting table **KaFADR_e_FSA_ECM_CombModeGrp**) multiplied per ambient air pressure correction factor B	< A*B A = (If Group1 is selected: refer to supporting table **KtFADD_V_FSA_ECM_LoThrshGrp1** If Group2 is selected: refer to supporting table **KtFADD_V_FSA_ECM_LoThrshGrp2** If Group3 is selected: refer to supporting table **KtFADD_V_FSA_ECM_LoThrshGrp3**) [mm^3] B = (refer to supporting table **KtFADD_K_FSA_ECM_PresAmbWghtLo**)	Following conditions are met for a calibrated time: a. System voltage in range b. FSA correction release enabled c. (FSA Learning is active) OR (DFSA Learning is active) AND (Boolean Flag used to enable DFSA learningactive check is TRUE)) for a time d. Ambient air pressure e. (Power Take-Off (PTO) is not active OR Boolean flag used to disable FSA in case of PTO active is FALSE) f. (OBD Coolant Enable Criteria OR Engine coolant temperature) g. Ambient air temperature h. Gear engaged	> 0.00 + 4.00 [s] > 11.00 [V] refer to "FSA Control Flag" Free Form FAD_FSA_NormRngCrtn Valid refer to "FSA Control Flag" Free Form (FAD_FSA_EnblLrn) OR ((FAD_DFSA_EnblLrn) AND 1 [boolean]) > 19.00 [s] > 72.00 [kPa] 0 [boolean] = TRUE > 69.00 [°C] > -20.00 [°C]	Time counter: 280 failures out of 560 samples. Time task 25[ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					for a time (only in case of Automatic Transmission)	different from Neutral or Parking > 4.00 [s]		
					i. Engine speed in operating range	> 420 [rpm] < 1,105 [rpm]		
					j. Engine speed gradient for a time	< 500 [rpm/25ms] > 0.00 [s]		
					k. Injected fuel quantity in operating range	> 2 [mm^3] < 120 [mm^3]		
					l. Injected fuel quantity gradient for a time	< 500.00 [mm^3/25ms] > 0.00 [s]		
					m. Vehicle speed in operating range for a time	> -10 [kph] < 3 [kph] > 0.00 [s]		
					n. Difference between FSA estimated error and FSA correction quantity	< 1,000.00 [mm^3]		
					o. Active combustion mode in selected group	refer to supporting table **KaFADR_e_FSA_ECM_** (**CombModeGrp**)		
					p. No Low fuel tank level indication	LowFuelConditionDiagnostic		
					q. No pending or confirmed DTCs	(ECT_Sensor_TFTKO AND ECT_Sensor_FA) OAT_PtEstFiltFA FAD_FSA_LrnShtOffReq		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						OXY_eqr_TurbDwn_FSA _NotVld		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Fuel Injection Quantity Higher Than Expected	P026D	An error shall be detected when the fuel adjustment value (mm^3) released by FSA is above a calibrated threshold.	Released FSA fuel correction value higher than a threshold A selected based on active combustion mode (refer to supporting table **KaFADR_e_FSA_ECM_CombModeGrp**) multiplied per ambient air pressure correction factor B	> A*B A = (If Group1 is selected: refer to supporting table **KtFADD_V_FSA_ECM_HiThrshGrp1** If Group2 is selected: refer to supporting table **KtFADD_V_FSA_ECM_HiThrshGrp2** If Group3 is selected: refer to supporting table **KtFADD_V_FSA_ECM_HiThrshGrp3**) [mm^3] B = (refer to supporting table **KtFADD_K_FSA_ECM_PresAmbWghtHi**)	Following conditions are met for a calibrated time: a. System voltage in range b. FSA correction release enabled c. (FSA Learning is active) OR ((DFSA Learning is active) AND (Boolean Flag used to enable DFSA learningactive check is TRUE)) for a time d. Ambient air pressure e. (Power Take-Off (PTO) is not active OR Boolean flag used to disable FSA in case of PTO active is FALSE) f. (OBD Coolant Enable Criteria OR Engine coolant temperature) g. Ambient air temperature h. Gear engaged	> 0.00 + 4.00 [s] > 11.00 [V] refer to "FSA Control Flag" Free Form FAD_FSA_NormRngCrtn Valid refer to "FSA Control Flag" Free Form (FAD_FSA_EnblLrn) OR ((FAD_DFSA_EnblLrn) AND 1 [boolean])) > 19.00 [s] > 72.00 [kPa] 0 [boolean] = TRUE > 69.00 [°C] > -20.00 [°C] different from Neutral or	Time counter: 280 failures out of 560 samples. Time task 25[ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						Parking		
					for a time (only in case of Automatic Transmission)	> 4.00 [s]		
					i. Engine speed in operating range	> 420 [rpm] < 1,105 [rpm]		
					j. Engine speed gradient for a time	< 500 [rpm/25ms] > 0.00 [s]		
					k. Injected fuel quantity in operating range	> 2 [mm^3] < 120 [mm^3]		
					l. Injected fuel quantity gradient for a time	< 500.00 [mm^3/25ms] > 0.00 [s]		
					m. Vehicle speed in operating range for a time	> -10 [kph] < 3 [kph] > 4.00 [s]		
					n. Difference between FSA estimated error and FSA correction quantity	< 1,000.00 [mm^3]		
					o. Active combustion mode in selected group	refer to supporting table **KaFADR_e_FSA_ECM_** (**CombModeGrp**)		
					p. No Low fuel tank level indication	LowFuelConditionDiagnostic		
					q. No pending or confirmed DTCs	(ECT_Sensor_TFTKO AND ECT_Sensor_FA) OAT_PtEstFiltFA FAD_FSA_LrnShtOffReq		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						OXY_eqr_TurbDwn_FSA _NotVld		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 1 Fuel Injector Offset Learning At Min Limit	P02CC	This diagnosis (Min Authority monitoring) performs a check on the absolute Energizing Time learnt by SQA (Small Quantity Adjustment). During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the torque produced during the combustion phase. Two different learning strategies are used: Target SQA (TSQA): This strategy is a closed loop between fuel quantity injected and torque produced during combustion phase. The fuel quantity injected is increased/decreased until the angular acceleration target is reached. The Delta Energizing Time needed to achieve the target is then stored in SQA Map. Extrapolated SQA (ESQA): With this strategy several injections with different injection quantities are performed and, for	Each time a new value is entered in SQA map the diagnosis checks if: - DeltaET learnt by (x) SQA on cylinder 1. The result of this test is then stored in a boolean NV array cointaing the status of Minimum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for minimum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE.	< **KaFADC_t_SQA_MinAdptDeltET[us]**	SQA Diagnosis enabled (x)SQA injection management enabled	1.00 FAD_SQA_InjMgntEnbld	Time required to perform a learning with (x) SQA. 1 Sample every cylinder firing event.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		each quantity, a delta ET is calculated using the difference between the torque produced during the combustion phase and the torque that would be produced during the combustion of a nominal fuel quantity. The results are then extrapolated in order to find the behaviour in all small quantity area. Each time a new value is entered in SQA map, regardless the strategies used to perform the learning (TSQA, ESQA, …), the diagnosis checks if the DeltaET learned by SQA is lower than a calibrateable threshold. The result of this test is then stored in a boolean NV array containing the status of Minimum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for minimum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE (no saturated values stored in SQA						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		map).						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 1 Fuel Injector Offset Learning At Max Limit	P02CD	This diagnosis (Max Authority monitoring) performs a check on the absolute Energizing Time learnt by SQA (Small Quantity Adjustment). During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the torque produced during the combustion phase. Two different learning strategies are used: Target SQA (TSQA): This strategy is a closed loop between fuel quantity injected and torque produced during combustion phase. The fuel quantity injected is increased/decreased until the angular acceleration target is reached. The Delta Energizing Time needed to achieve the target is then stored in SQA Map. Extrapolated SQA (ESQA): With this strategy several injections with different injection quantities are performed and, for	Each time a new value is entered in SQA map the diagnosis checks if: - DeltaET learnt by (x) SQA on cylinder 1. The result of this test is then stored in a boolean NV array cointaing the status of Maximum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for maximum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE.	> **KaFADC_t_SQA_MaxAdptDeltET[us]**	SQA Diagnosis enabled (x)SQA injection management enabled	1.00 FAD_SQA_InjMgntEnbld	Time required to perform a learning with (x) SQA. [Sample Rate: 1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		each quantity, a delta ET is calculated using the difference between the torque produced during the combustion phase and the torque that would be produced during the combustion of a nominal fuel quantity. The results are then extrapolated in order to find the behaviour in all small quantity area. Each time a new value is entered in SQA map, regardless the strategies used to perform the learning (TSQA, ESQA, …), the diagnosis checks if the DeltaET learned by SQA is higher than a calibrateable threshold. The result of this test is then stored in a boolean NV array containing the status of Maximum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for maximum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE (no saturated values stored in SQA						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		map).						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 2 Fuel Injector Offset Learning At Min Limit	P02CE	This diagnosis (Min Authority monitoring) performs a check on the absolute Energizing Time learnt by SQA (Small Quantity Adjustment). During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the torque produced during the combustion phase. Two different learning strategies are used: Target SQA (TSQA): This strategy is a closed loop between fuel quantity injected and torque produced during combustion phase. The fuel quantity injected is increased/decreased until the angular acceleration target is reached. The Delta Energizing Time needed to achieve the target is then stored in SQA Map. Extrapolated SQA (ESQA): With this strategy several injections with different injection quantities are performed and, for	Each time a new value is entered in SQA map the diagnosis checks if: - DeltaET learnt by (x) SQA on cylinder 2. The result of this test is then stored in a boolean NV array cointaing the status of Minimum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for minimum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE.	< **KaFADC_t_SQA_MinAdptDeltET[us]**	SQA Diagnosis enabled (x)SQA injection management enabled	1.00 FAD_SQA_InjMgntEnbld	Time required to perform a learning with (x) SQA. [Sample Rate: 1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		each quantity, a delta ET is calculated using the difference between the torque produced during the combustion phase and the torque that would be produced during the combustion of a nominal fuel quantity. The results are then extrapolated in order to find the behaviour in all small quantity area. Each time a new value is entered in SQA map, regardless the strategies used to perform the learning (TSQA, ESQA, …), the diagnosis checks if the DeltaET learned by SQA is lower than a calibrateable threshold. The result of this test is then stored in a boolean NV array containing the status of Minimum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for minimum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE (no saturated values stored in SQA						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		map).						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 2 Fuel Injector Offset Learning At Max Limit	P02CF	This diagnosis (Max Authority monitoring) performs a check on the absolute Energizing Time learnt by SQA (Small Quantity Adjustment). During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the torque produced during the combustion phase. Two different learning strategies are used: Target SQA (TSQA): This strategy is a closed loop between fuel quantity injected and torque produced during combustion phase. The fuel quantity injected is increased/decreased until the angular acceleration target is reached. The Delta Energizing Time needed to achieve the target is then stored in SQA Map. Extrapolated SQA (ESQA): With this strategy several injections with different injection quantities are performed and, for	Each time a new value is entered in SQA map the diagnosis checks if: - DeltaET learnt by (x) SQA on cylinder 2. The result of this test is then stored in a boolean NV array cointaing the status of Maximum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for maximum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE.	> **KaFADC_t_SQA_MaxAdptDeltET[us]**	SQA Diagnosis enabled (x)SQA injection management enabled	1.00 FAD_SQA_InjMgntEnbld	Time required to perform a learning with (x) SQA. [Sample Rate: 1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		each quantity, a delta ET is calculated using the difference between the torque produced during the combustion phase and the torque that would be produced during the combustion of a nominal fuel quantity. The results are then extrapolated in order to find the behaviour in all small quantity area. Each time a new value is entered in SQA map, regardless the strategies used to perform the learning (TSQA, ESQA, …), the diagnosis checks if the DeltaET learned by SQA is higher than a calibrateable threshold. The result of this test is then stored in a boolean NV array containing the status of Maximum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for maximum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE (no saturated values stored in SQA						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		map).						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 3 Fuel Injector Offset Learning At Min Limit	P02D0	This diagnosis (Min Authority monitoring) performs a check on the absolute Energizing Time learnt by SQA (Small Quantity Adjustment). During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the torque produced during the combustion phase. Two different learning strategies are used: Target SQA (TSQA): This strategy is a closed loop between fuel quantity injected and torque produced during combustion phase. The fuel quantity injected is increased/decreased until the angular acceleration target is reached. The Delta Energizing Time needed to achieve the target is then stored in SQA Map. Extrapolated SQA (ESQA): With this strategy several injections with different injection quantities are performed and, for	Each time a new value is entered in SQA map the diagnosis checks if: - DeltaET learnt by (x) SQA on cylinder 3. The result of this test is then stored in a boolean NV array cointaing the status of Minimum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for minimum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE.	< **KaFADC_t_SQA_MinAdptDeltET[us]**	SQA Diagnosis enabled (x)SQA injection management enabled	1.00 FAD_SQA_InjMgntEnbld	Time required to perform a learning with (x) SQA. [Sample Rate: 1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		each quantity, a delta ET is calculated using the difference between the torque produced during the combustion phase and the torque that would be produced during the combustion of a nominal fuel quantity. The results are then extrapolated in order to find the behaviour in all small quantity area. Each time a new value is entered in SQA map, regardless the strategies used to perform the learning (TSQA, ESQA, …), the diagnosis checks if the DeltaET learned by SQA is lower than a calibrateable threshold. The result of this test is then stored in a boolean NV array containing the status of Minimum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for minimum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE (no saturated values stored in SQA						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		map).						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 3 Fuel Injector Offset Learning At Max Limit	P02D1	This diagnosis (Max Authority monitoring) performs a check on the absolute Energizing Time learnt by SQA (Small Quantity Adjustment). During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the torque produced during the combustion phase. Two different learning strategies are used: Target SQA (TSQA): This strategy is a closed loop between fuel quantity injected and torque produced during combustion phase. The fuel quantity injected is increased/decreased until the angular acceleration target is reached. The Delta Energizing Time needed to achieve the target is then stored in SQA Map. Extrapolated SQA (ESQA): With this strategy several injections with different injection quantities are performed and, for	Each time a new value is entered in SQA map the diagnosis checks if: - DeltaET learnt by (x) SQA on cylinder 3 The result of this test is then stored in a boolean NV array cointaing the status of Maximum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for maximum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE.	> **KaFADC_t_SQA_Max AdptDeltET[us]**	SQA Diagnosis enabled (x)SQA injection management enabled	1.00 FAD_SQA_InjMgntEnbld	Time required to perform a learning with (x) SQA. [Sample Rate: 1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		each quantity, a delta ET is calculated using the difference between the torque produced during the combustion phase and the torque that would be produced during the combustion of a nominal fuel quantity. The results are then extrapolated in order to find the behaviour in all small quantity area. Each time a new value is entered in SQA map, regardless the strategies used to perform the learning (TSQA, ESQA, …), the diagnosis checks if the DeltaET learned by SQA is higher than a calibrateable threshold. The result of this test is then stored in a boolean NV array containing the status of Maximum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for maximum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE (no saturated values stored in SQA						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		map).						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 4 Fuel Injector Offset Learning At Min Limit	P02D2	This diagnosis (Min Authority monitoring) performs a check on the absolute Energizing Time learnt by SQA (Small Quantity Adjustment). During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the torque produced during the combustion phase. Two different learning strategies are used: Target SQA (TSQA): This strategy is a closed loop between fuel quantity injected and torque produced during combustion phase. The fuel quantity injected is increased/decreased until the angular acceleration target is reached. The Delta Energizing Time needed to achieve the target is then stored in SQA Map. Extrapolated SQA (ESQA): With this strategy several injections with different injection quantities are performed and, for	Each time a new value is entered in SQA map the diagnosis checks if: - DeltaET learnt by (x) SQA on cylinder 4. The result of this test is then stored in a boolean NV array cointaing the status of Minimum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for minimum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE.	< **KaFADC_t_SQA_MinAdptDeltET[us]**	SQA Diagnosis enabled (x)SQA injection management enabled	1.00 FAD_SQA_InjMgntEnbld	Time required to perform a learning with (x) SQA. [Sample Rate: 1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		each quantity, a delta ET is calculated using the difference between the torque produced during the combustion phase and the torque that would be produced during the combustion of a nominal fuel quantity. The results are then extrapolated in order to find the behaviour in all small quantity area. Each time a new value is entered in SQA map, regardless the strategies used to perform the learning (TSQA, ESQA, …), the diagnosis checks if the DeltaET learned by SQA is lower than a calibrateable threshold. The result of this test is then stored in a boolean NV array containing the status of Minimum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for minimum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE (no saturated values stored in SQA						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		map).						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 4 Fuel Injector Offset Learning At Max Limit	P02D3	This diagnosis (Max Authority monitoring) performs a check on the absolute Energizing Time learnt by SQA (Small Quantity Adjustment). During Diesel Fuel Cut-off conditions SQA command the injection of a known quantity on one injector (e.g. 1,5mm^3) and checks, by means of crank-wheel sensor, the torque produced during the combustion phase. Two different learning strategies are used: Target SQA (TSQA): This strategy is a closed loop between fuel quantity injected and torque produced during combustion phase. The fuel quantity injected is increased/decreased until the angular acceleration target is reached. The Delta Energizing Time needed to achieve the target is then stored in SQA Map. Extrapolated SQA (ESQA): With this strategy several injections with different injection quantities are performed and, for	Each time a new value is entered in SQA map the diagnosis checks if: - DeltaET learnt by (x) SQA on cylinder 4 The result of this test is then stored in a boolean NV array cointaing the status of Maximum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for maximum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE.	> **KaFADC_t_SQA_MaxAdptDeltET[us]**	SQA Diagnosis enabled (x)SQA injection management enabled	1.00 FAD_SQA_InjMgntEnbld	Time required to perform a learning with (x) SQA. [Sample Rate: 1 Sample every cylinder firing event].	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		each quantity, a delta ET is calculated using the difference between the torque produced during the combustion phase and the torque that would be produced during the combustion of a nominal fuel quantity. The results are then extrapolated in order to find the behaviour in all small quantity area. Each time a new value is entered in SQA map, regardless the strategies used to perform the learning (TSQA, ESQA, …), the diagnosis checks if the DeltaET learned by SQA is higher than a calibrateable threshold. The result of this test is then stored in a boolean NV array containing the status of Maximum authority test (TRUE=Saturated, FALSE= Not saturated) for all the rail pressure levels defined for SQA. The DTC for maximum authority reached is set if, at least one element of the array is equal to TRUE and is unset when all the elements of the array are equal to FALSE (no saturated values stored in SQA						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
		map).						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Intake Air Flow Control Circuit	P02E0	This monitor checks if the Throttle commands are in open circuit	Load resistance higher than a threshold (error information provided by HWIO)	> 200 [kOhm]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range H-Bridge driver is OFF Valve requested in a position different from wide open (default position) Diagnostic system enabled (no clear code or EOT in progress) HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V]	96.00 fail counts out of 120.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Intake Air Flow Performance	P02E1	This monitor detects an obstruction on the actuator (obstruction found during the Throttle valve opening or closing) checking the setpoint position against the position measured by the Throttle Position Sensor	|Throttle Position Tracking Error| (setpoint position - measured position) > maximum threshold	> 10.00 [%]	Test enabled by calibration Diagnostic system enabled (no clear code or EOT in progress) System out of the cranking phase PT relay supply voltage in range Engine coolant temperature higher or equal to minimum threshold OR Engine cooling system target temperature reached (thermostat opening) No faults present on engine coolant temperature sensor Outside air temperature higher or equal to minimum threshold No faults present on outside air temperature sensor	== 1.00 > 11.00 [V] >= -60.00 [°C] ECT_Sensor_FA ==FALSE >= -60.00 [°C] OAT_PtEstFiltFA ==FALSE	800.00 fail counts out of 1,000.00 sample counts 400.00 fail counts to enable the open circuit check (P02E0) Function task: 6.25 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Throttle position setpoint in steady state conditions for minimum time Throttle position closed loop control active No mechanical stop soft approach in progress No anti-sticking procedure in progress No faults present on Throttle position sensor, Throttle valve, Throttle position control deviation	> -100.00 [%/s] < 44.00 [%/s] for >= 0.50 [s] TPS_PstnShtOffReq == FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Intake Air Flow Stuck Closed	P02E5	This monitor detects the Throttle valve mechanically stuck in a certain position different from its defaulted position (fully open) when the actuator is no longer driven (missing dafaulted position)	Measured Throttle position < minimum threshold	< 80.00 [%]	P02E1 is already set Waiting time after driver shut off > minimum threshold (needed for the spring to drive the valve in its defaulted position) Diagnostic system enabled (no clear code or EOT in progress) No faults present on Throttle position sensor, Throttle valve, Throttle position control deviation	 > 2.00 [s] TPS_PstnShtOffReq == FALSE	No debounce is present: DTC sets as soon as the error is present Function task: 6.25 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Intake Air Flow Position Sensor Circuit Low (SENT position sensor)	P02E8	This monitor checks if the Throttle SENT position sensor is out of electrical range low	SENT position raw voltage < low threshold	< 1.00 [%5V]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range No faults present on Throttle SENT out of range and SENT performance	== 1.00 > 11.00 [V] TPS_SENT_OOR_Flt == FALSE TPS_SENT_PerfFlt == FALSE	192.00 fail counts out of 240.00 sample counts Function task: 6.25 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Intake Air Flow Position Sensor Circuit High (SENT position sensor)	P02E9	This monitor checks if the Throttle SENT position sensor is out of electrical range low	SENT position raw voltage > high threshold	> 99.00 [%5V]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range No faults present on Throttle SENT out of range and SENT performance	== 1.00 > 11.00 [V] TPS_SENT_OOR_Flt== FALSE TPS_SENT_PerfFlt== FALSE	192.00 fail counts out of 240.00 sample counts Function task: 6.25 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Intake Air Flow Current Range/ Performance	P02EB	This monitor checks if an excessive current flows through the Throttle DC-Motor (e.g. shunt circuit between load, Throttle DC-Motor internal faults, etc).	Current flowing through the H-Bridge higher than a threshold (error information provided by HWIO)	> 5.5 [A]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range No faults present on Throttle DC Motor current range/performance H-Bridge driver is ON Diagnostic system enabled (no clear code or EOT in progress) HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V] TPS_MtrCurrLimTFTKO == FALSE	96.00 fail counts out of 120.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Glow Plug/ Heater Indicator Control Circuit Low	P037A	This DTC checks the wait to start lamp circuit for electrical integrity during operation. Wait to start lamp pin shorted to ground.	Test performed by HWIO. A ground short condition shall be detected if the circuit attached to the controller external connection has an impedance R to a voltage source within the Vehicle Ground Voltage Range relative to PWRGND. The short to ground faults are not required to be detected when the Off state diagnostic leakage current source is Disabled.	R = 0.5 Ω	Glow Lamp present Test enabled Run/Crank On Run/Crank voltage Engine cranking	== 1.00 [boolean] == 1.00 [boolean] == True > 11.00 V == False	10.00 failures out of 15.00 samples (*) (*) Ground short monitoring is implemented in HWIO which means no further debouncing is needed in case of short to ground	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Glow Plug/ Heater Indicator Control Circuit High	P037B	This DTC checks the wait to start lamp circuit for electrical integrity during operation. Wait to start lamp pin shorted to high voltage.	Test performed by HWIO. A power short condition shall be detected if the circuit attached to the Controller external connection has an impedance R to a voltage source within the Normal Operating Voltage Range or the High Operating Voltage Range.	R = 0.5 Ω	Glow Lamp present Test enabled Run/Crank On Run/Crank voltage Engine cranking	== 1.00 [boolean] == 1.00 [boolean] == True > 11.00 V == False	10.00 failures out of 20.00 samples Sampling rate: 100 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Glow Plug Sense Circuit Low	P037E	This DTC checks the circuit for electrical integrity during operation of glow plug sub-system. ECU internal fault.	Voltage feedback above threshold depending on system current and RunCrank relay voltage	battery_voltage - voltage_feedback > **KtGLOD_U_VoltLoDelMax (KnGLOD_I_GP_Curr)** [V]	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; Enable_ON interface is true; No electrical fault detected on glow plugs; No faults detected on glow plug system supply; Diagnostic system is not disabled;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; VeGLOO_b_GlowPlugEnbl = TRUE; VeGLOO_b_ElectFlt = FALSE; GLO_GlowPlugSplyVoltCktTFTKO VeDRER_DiagSystemDsbl = FALSE;	60.00 fail samples over 120.00 samples Time task: 50 [ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Glow Plug Sense Circuit High	P037F	This DTC checks the circuit for electrical integrity during operation of glow plug sub-system. ECU internal fault.	Voltage feedback over a threshold depending on RunCrank relay voltage	voltage_feedback > 5.00 [V]	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; Enable_ON interface is true; No electrical fault detected on glow plugs; No faults detected on glow plug system supply; Diagnostic system is not disabled;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; VeGLOO_b_GlowPlugEnbl = TRUE; VeGLOO_b_ElectFlt = FALSE; GLO_GlowPlugSplyVoltCktTFTKO VeDRER_DiagSystemDsbl = FALSE;	40.00 fail samples over 80.00 samples Time task: 50 [ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Glow Plug/ Heater Indicator Control Circuit/Open	P0381	This DTC checks the wait to start lamp circuit for electrical integrity during operation. Wait to start lamp pin open circuit.	Test performed by HWIO. An open circuit condition shall be detected if the circuit attached to the Controller external connection has an impedance Ropendet and shall not be detected if the circuit impedance is less than the Ropmin. The open circuit faults are not required to be detected when the Off state diagnostic leakage current source is Disabled.	Ropendet = 300 Ω Ropmin = 10 Ω	Glow Lamp present Test enabled Run/Crank On Run/Crank voltage Engine cranking	== 1.00 [boolean] == 1.00 [boolean] == True > 11.00 V == False	10.00 failures out of 15.00 samples (*) (*) Open load monitoring is implemented in HWIO which means no further debouncing is needed in case of open load	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation Control Circuit	P0403	This monitor checks if the HP EGR commands are in open circuit	Load resistance higher than a threshold (error information provided by HWIO)	> 200 [kOhm]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range H-Bridge driver is OFF Valve requested in a position different from fully closed (default position) Diagnostic system enabled (no clear code or EOT in progress) HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V]	96.00 fail counts out of 120.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation Position Performance	P0404	This monitor detects an obstruction on the actuator (obstruction found during the HP EGR valve opening or closing) checking the setpoint position against the position measured by the HP EGR Position Sensor	|HP EGR Position Tracking Error| (setpoint position - measured position) > maximum threshold	> 10.00 [%]	Test enabled by calibration Diagnostic system enabled (no clear code or EOT in progress) System out of the cranking phase PT relay supply voltage in range Engine coolant temperature higher or equal to minimum threshold OR Engine cooling system target temperature reached (thermostat opening) No faults present on engine coolant temperature sensor Outside air temperature higher or equal to minimum threshold No faults present on outside air temperature sensor	== 1.00 > 11.00 [V] >= 60.00 [°C] ECT_Sensor_FA ==FALSE > -60.00 [°C] OAT_PtEstFiltFA ==FALSE	800.00 fail counts out of 1,000.00 sample counts 400.00 fail counts to enable the open circuit check (P0403) Function task: 6.25 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					HP EGR position setpoint in steady state conditions for minimum time	> -44.00 [%/s] < 44.00 [%/s] for >= 0.50 [s]		
					HP EGR position closed loop control active			
					No mechanical stop soft approach in progress			
					No anti-sticking procedure in progress			
					No faults present on HP EGR position sensor, HP EGR valve, HP EGR position control deviation	EGR_PstnShtOffReq== FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation Position Sensor Circuit Low Voltage	P0405	This monitor checks if the HP EGR position analog sensor is out of electrical range low	analog position raw voltage < low threshold	< 4.50 [%5V]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range	== 1.00 > 11.00 [V]	192.00 fail counts out of 240.00 sample counts Function task: 6.25 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation Position Sensor Circuit High Voltage	P0406	This monitor checks if the HP EGRposition analog sensor is out of electrical range high	analog position raw voltage > high threshold	> 95.00 [%5V]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range	== 1.00 > 11.00 [V]	192.00 fail counts out of 240.00 sample counts Function task: 6.25 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
EGR Temperature Sensor2 Ckt Range/ Performance	P040B	ECM determines that the EGR temperature Sensor 2 has not moved enought since start (Stuck)	ECM determines that after an allowed amount of amount of engine consumed following a long enough soak, the Down Stream Temperature sensor has not change enough.	ABS(Initial Down stream temperature - final down stream temperature)<= **Down Stream Stk Temp Vrtn**	System supply voltage Engine soak (not run) time No Active DTCs Engine is running	> 11.00 Volts >= 28,800.00 sec P262B	cumulative Time > 9.90 continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
EGR Temperature Sensor2 Ckt Low	P040C	Diagnose the EGR Down Stream Temperature sensor circuit low	The ECM detects that the measured resistance of the temperature sensor is out of range low.	Measured Resistance of the Temperature sensor < 390.00 Ω impedance	System supply voltage Output driver is commanded on Ignition switch is in crank or run position	> 11.00 Volts	40 failures out of 50 samples 100 ms /sample, continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
EGR Temperature Sensor2 Ckt High	P040D	Diagnose the EGR Down Stream Temperature sensor circuit high	The ECM detects that the measured resistance of the temperature sensor is out of range high.	Measured Resistance of the Temperature sensor > 1,460.00 Ω impedance	System supply voltage Output driver is commanded on Ignition switch is in crank or run position	> 11.00 Volts	40 failures out of 50 samples 100 ms /sample, continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
EGR Temperature Sensor2 Ckt Intermittent/ Erratic	P040E	Detects a temperature sensor that is showing erratic or intermittent temperature readings	The absoluted value of the loop to loop (100 ms / sample) resistance change of the temperature sensor is greater than the allowed rate of change.	Delta chage > 60.00 Ω impedance	System supply voltage Output driver is commanded on Ignition switch is in crank or run position	> 11.00 Volts	40 failures out of 50 samples 100 ms /sample, continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
EGR Temperature Sensor1 Ckt Range/ Performance	P041B	ECM determines that the EGR temperature Sensor 1 has not moved enought since start (Stuck)	ECM determines that after an allowed amount of engine consumed airflow following a long enough soak, the Up Stream Temperature sensor has not change enough.	ABS(Initial upstream temperature - final upstream temperature) <= **UP Stream Stk Temp Vrtn**	System supply voltage Engine soak (not run) time No Active DTCs Engine is running	> 11.00 Volts >= 28,800.00 sec P262B	cumulative Time > 0.00 continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
EGR Temperature Sensor1 Ckt Low	P041C	Diagnose the EGR Up Stream Temperature sensor circuit low	The ECM detects that the measured resistance of the temperature sensor is out of range low.	Measured Resistance of the Temperature sensor < 145.00 Ω impedance	System supply voltage Output driver is commanded on Ignition switch is in crank or run position	> 11.00 Volts	40 failures out of 50 samples 100 ms /sample, continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
EGR Temperature Sensor1 Ckt High	P041D	Diagnose the EGR Up Stream Temperature sensor circuit high	The ECM detects that the measured resistance of the temperature sensor is out of range high.	Measured Resistance of the Temperature sensor > 825.00 Ω impedance	System supply voltage Output driver is commanded on Ignition switch is in crank or run position	> 11.00 Volts	40 failures out of 50 samples 100 ms /sample, continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
EGR Temperature Sensor1 Ckt Intermittent/ Erratic	P041E	Detects a temperature sensor that is showing erratic or intermittent temperature readings	The absoluted value of the loop to loop (100 ms / sample) resistance change of the temperature sensor is greater than the allowed rate of change.	Delta chage > 60.00 Ω impedance	System supply voltage Output driver is commanded on Ignition switch is in crank or run position	> 11.00 Volts	40 failures out of 50 samples 100 ms /sample, continuous	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation Control Stuck Open	P042E	This monitor detects the HP EGR valve mechanically stuck in a certain position different from its defaulted position (fully closed) when the actuator is no longer driven (missing dafaulted position)	Measured HP EGR position > maximum threshold	> 10.00 [%]	P0404 is already set Waiting time after driver shut off > minimum threshold (needed for the spring to drive the valve in its defaulted position) Diagnostic system enabled (no clear code or EOT in progress) No faults present on HP EGR position sensor, HP EGR valve, HP EGR position control deviation	 > 2.00 [s] EGR_PstnShtOffReq == FALSE	No debounce is present: DTC sets as soon as the error is present Function task: 6.25 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation Position Exceeded Learning Limit	P049D	This monitor checks if the HP EGR position analog sensor has an offset with respect to the nominal position where the valve does the learning procedure (fully closed)	analog position raw voltage when the valve is in fully closed position < low threshold OR analog position raw voltage when the valve is in fully closed position > high threshold	< 16.40 [%5V] OR > 25.10 [%5V]	Test enabled by calibration Learning procedure at key off in fully closed position has been successfully completed: - engine coolant temperature in range; - no faults present on engine coolant temperature sensor; - valve is in fully closed position (measured position smaller than a threshold); - difference between max and min learned values is smaller than a threshold. Position control in closed loop: battery voltage above a threshold. No faults present on HP EGR position sensor, HP EGR valve, HP EGR position deviation End Of Trip event has elapsed	== 1.00 >= 60.00 [°C] <= 60.00 [°C] ECT_Sensor_FA == FALSE < 100.00 [%] < 100.00 [%] > 5.00 [V] EGR_PstnShtOffReq == FALSE	1.00 fail counts out of 1.00 sample counts Function task: at key off	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 1 out of range monitoring Low	P0545	Controller specific output driver circuit diagnoses t the exhaust gas temperature 1 (EGT1) sensor signal high sided driver for a short to ground failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	< 160 [Ohm]	Test enabled by calibration (TRUE--> enable FALSE --> disable) and with Engine cranking and with Battery voltage and with key on	1 [Boolean] == FALSE > 11.00 [V] == TRUE	10 fail samples over 20 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 1 out of range monitoring High	P0546	Controller specific output driver circuit diagnoses the exhaust gas temperature 1 (EGT1) signal high sided driver for a short to power failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds. Controller specific output driver circuit diagnoses the exhaust gas temperature 1 (EGT1) signal high sided driver for an open circuit failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power. Voltage measurement outside of controller specific acceptable range during driver on state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	> 900 [Ohm]	Test enabled by calibration (TRUE--> enable FALSE --> disable) and with Engine cranking and with Battery voltage and with key on	1 [Boolean] == FALSE > 11.00 [V] == TRUE	10 fail samples over 20 samples Function task: 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 1 Glow Plug Circuit Low	P066A	This DTC checks the circuit for electrical integrity during operation. Glow plug 1 pin short to ground.	Test performed by HWIO A ground short condition shall be detected if the circuit attached to the controller external connection has an impedance Rshortdet to a voltage source within the Vehicle Ground Voltage Range relative to PWRGND. A ground short condition shall not be detected if the circuit impedance is higher than Rload_min. A ground short condition will be set in case of Inrush overcurrent detection. It is intended to detect if the Inrush current profile is beyond the specified value (see **Inrush_current_profile** Table). This detection is only done at key on (once per driving cycle).	Rshortdet = 0.11 [Ohm] Rload_min = 0.19 [Ohm]	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; No faults detected on glow plug system supply; Duty cycle above a calibratable threshold; Diagnostic system is not disabled;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; GLO_GlowPlugSplyVoltCktTFTKO 2.00 [%] VeDRER_DiagSystemDsbl = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips + glow lamp ON

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 1 Glow Plug Circuit High	P066B	This DTC checks the circuit for electrical integrity during operation. Glow plug 1 pin short to high voltage.	Test performed by HWIO • If the Load resistance is higher than 0.65 Ohm a power short condition shall be detected if the circuit attached to the Controller external connection has an impedance below R1 to a voltage source within the Normal Operating Voltage Range or the High Operating Voltage Range. • If the Load resistance is between 0.2 Ohm to 0.65 Ohm a power short condition shall be detected if the circuit attached to the Controller external connection has an impedance below R2 to a voltage source within the Normal Operating Voltage Range or the High Operating Voltage Range.	R1 = 0.5 [Ohm] R2 = 0.14 [Ohm]	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; No faults detected on glow plug system supply; Diagnostic system is not disabled;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; GLO_GlowPlugSplyVoltCktTFTKO VeDRER_DiagSystemDsbl = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips + glow lamp ON

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 2 Glow Plug Circuit Low	P066C	This DTC checks the circuit for electrical integrity during operation. Glow plug 2 pin short to ground.	Test performed by HWIO A ground short condition shall be detected if the circuit attached to the controller external connection has an impedance Rshortdet to a voltage source within the Vehicle Ground Voltage Range relative to PWRGND. A ground short condition shall not be detected if the circuit impedance is higher than Rload_min. A ground short condition will be set in case of Inrush overcurrent detection. It is intended to detect if the Inrush current profile is beyond the specified value (see **Inrush_current_profile** Table). This detection is only done at key on (once per driving cycle).	Rshortdet = 0.11 [Ohm] Rload_min = 0.19 [Ohm]	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; No faults detected on glow plug system supply; Duty cycle above a calibratable threshold; Diagnostic system is not disable;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; GLO_GlowPlugSplyVoltCktTFTKO 2.00 [%] VeDRER_DiagSystemDsbl = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips + glow lamp ON

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 2 Glow Plug Circuit High	P066D	This DTC checks the circuit for electrical integrity during operation. Glow plug 2 pin short to high voltage.	Test performed by HWIO • If the Load resistance is higher than 0.65 Ohma power short condition shall be detected if the circuit attached to the Controller external connection has an impedance below R1 to a voltage source within the Normal Operating Voltage Range or the High Operating Voltage Range. • If the Load resistance is between 0.2 Ohm to 0.65 Ohma power short condition shall be detected if the circuit attached to the Controller external connection has an impedance below R2 to a voltage source within the Normal Operating Voltage Range or the High Operating Voltage Range.	R1 = 0.5 [Ohm] R2= 0.14 [Ohm]	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; No faults detected on glow plug system supply; Diagnostic system is not disabled;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; GLO_GlowPlugSplyVoltCktTFTKO VeDRER_DiagSystemDsbl = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips + glow lamp ON

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 3 Glow Plug Circuit Low	P066E	This DTC checks the circuit for electrical integrity during operation. Glow plug 3 pin short to ground.	Test performed by HWIO A ground short condition shall be detected if the circuit attached to the controller external connection has an impedance Rshortdet to a voltage source within the Vehicle Ground Voltage Range relative to PWRGND. A ground short condition shall not be detected if the circuit impedance is higher than Rload_min. A ground short condition will be set in case of Inrush overcurrent detection. It is intended to detect if the Inrush current profile is beyond the specified value (see **Inrush_current_profile** Table). This detection is only done at key on (once per driving cycle).	Rshortdet = 0.11 [Ohm] Rload_min = 0.19 [Ohm]	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; No faults detected on glow plug system supply; Duty cycle above a calibratable threshold; Diagnostic system is not disable;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; GLO_GlowPlugSplyVoltCktTFTKO 2.00 [%] VeDRER_DiagSystemDsbl = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips + glow lamp ON

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 3 Glow Plug Circuit High	P066F	This DTC checks the circuit for electrical integrity during operation. Glow plug 3 pin short to high voltage.	Test performed by HWIO • If the Load resistance is higher than 0.65 Ohma power short condition shall be detected if the circuit attached to the Controller external connection has an impedance below R1 to a voltage source within the Normal Operating Voltage Range or the High Operating Voltage Range. • If the Load resistance is between 0.2 Ohm to 0.65 Ohma power short condition shall be detected if the circuit attached to the Controller external connection has an impedance below R2 to a voltage source within the Normal Operating Voltage Range or the High Operating Voltage Range.	R1 = 0.5 [Ohm] R2= 0.14 [Ohm]	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; No faults detected on glow plug system supply; Diagnostic system is not disabled;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; GLO_GlowPlugSplyVoltCktTFTKO VeDRER_DiagSystemDsbl = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips + glow lamp ON

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 1 Glow Plug Circuit/Open	P0671	This DTC checks the circuit for electrical integrity during operation. Glow plug 1 pin open load.	Test performed by HWIO. An open circuit condition shall be detected if the circuit attached to the Controller external connection has an impedance R and shall not be detected if the circuit impedance is less than the Ropmin	R = 200 [kOhm] Ropmin = 16 [Ohm]	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; No faults detected on glow plug system supply; Duty cycle above a calibratable threshold; Diagnostic system is not disabled;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; GLO_GlowPlugSplyVoltCktTFTKO 2.00 [%] VeDRER_DiagSystemDsbl = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips + glow lamp ON

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 2 Glow Plug Circuit/Open	P0672	This DTC checks the circuit for electrical integrity during operation. Glow plug 2 pin open load.	Test performed by HWIO. An open circuit condition shall be detected if the circuit attached to the Controller external connection has an impedance R and shall not be detected if the circuit impedance is less than the Ropmin	R = 200 [kOhm] Ropmin = 16 [Ohm]	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; No faults detected on glow plug system supply; Duty cycle above a calibratable threshold; Diagnostic system is not disabled;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; GLO_GlowPlugSplyVoltCktTFTKO 2.00 [%] VeDRER_DiagSystemDsbl = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips + glow lamp ON

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 3 Glow Plug Circuit/Open	P0673	This DTC checks the circuit for electrical integrity during operation. Glow plug 3 pin open load.	Test performed by HWIO. An open circuit condition shall be detected if the circuit attached to the Controller external connection has an impedance R and shall not be detected if the circuit impedance is less than the Ropmin	R = 200 [kOhm] Ropmin = 16 [Ohm]	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; No faults detected on glow plug system supply; Duty cycle above a calibratable threshold; Diagnostic system is not disabled;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; GLO_GlowPlugSplyVoltCktTFTKO 2.00 [%] VeDRER_DiagSystemDsbl = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips + glow lamp ON

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 4 Glow Plug Circuit/Open	P0674	This DTC checks the circuit for electrical integrity during operation. Glow plug 4 pin open load.	Test performed by HWIO. An open circuit condition shall be detected if the circuit attached to the Controller external connection has an impedance R and shall not be detected if the circuit impedance is less than the Ropmin	R = 200 [kOhm] Ropmin = 16 [Ohm]	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; No faults detected on glow plug system supply; Duty cycle above a calibratable threshold; Diagnostic system is not disabled;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; GLO_GlowPlugSplyVoltCktTFTKO 2.00 [%] VeDRER_DiagSystemDsbl = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips + glow lamp ON

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 4 Glow Plug Circuit Low	P067A	This DTC checks the circuit for electrical integrity during operation. Glow plug 4 pin short to ground.	Test performed by HWIO A ground short condition shall be detected if the circuit attached to the controller external connection has an impedance Rshortdet to a voltage source within the Vehicle Ground Voltage Range relative to PWRGND. A ground short condition shall not be detected if the circuit impedance is higher than Rload_min. A ground short condition will be set in case of Inrush overcurrent detection. It is intended to detect if the Inrush current profile is beyond the specified value (see **Inrush_current_profile** Table). This detection is only done at key on (once per driving cycle).	Rshortdet = 0.11 [Ohm] Rload_min = 0.19 [Ohm]	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; No faults detected on glow plug system supply; Duty cycle above a calibratable threshold; Diagnostic system is not disable;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; GLO_GlowPlugSplyVoltCktTFTKO 2.00 [%] VeDRER_DiagSystemDsbl = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips + glow lamp ON

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 4 Glow Plug Circuit High	P067B	This DTC checks the circuit for electrical integrity during operation. Glow plug 4 pin short to high voltage.	Test performed by HWIO • If the Load resistance is higher than 0.65 Ohma power short condition shall be detected if the circuit attached to the Controller external connection has an impedance below R1 to a voltage source within the Normal Operating Voltage Range or the High Operating Voltage Range. • If the Load resistance is between 0.2 Ohm to 0.65 Ohma power short condition shall be detected if the circuit attached to the Controller external connection has an impedance below R2 to a voltage source within the Normal Operating Voltage Range or the High Operating Voltage Range.	R1 = 0.5 [Ohm] R2= 0.14 [Ohm]	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; No faults detected on glow plug system supply; Diagnostic system is not disabled;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; GLO_GlowPlugSplyVoltCktTFTKO VeDRER_b_DiagSystemDsbl = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips + glow lamp ON

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Rail Pressure deviation during cut off	P1089	This diagnosis is able to check if, during SQA learning, the pressure set-point requested by SQA is correctly reached and maintained (in rail pressure range defined for SQA), in order to allow SQA to perform the learning.	Fuel Rail pressure	> SQA Rail Pressure Set-point + **KaFADC_p_SQA_Lrn Delt** OR < SQA Rail Pressure Set-point - **KaFADC_p_SQA_Lrn Delt**	Test enabled by calibration All enabling conditions for SQA learning different from Rail Pressure in range are satified Calibrateable delay time since SQA started to request rail pressure set-point has expired.	1.00 FAD_SQA_LrnPresEnbl 3,500.00	800.00 Fail Samples over 1,143.00 samples. 1 Sample every 12,5ms.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Charge Air Cooler Temperature Sensor Down Circuit Performance	P10D5	This monitor checks if the CAC down air temperature sensor is irrational at key on when compared with two reference temperature sensors after a long soak time	Charge air cooler down air temperature is compared at power up with an average temperature calculated using the intake manifold air temperature sensor and the fuel temperature sensor over a calibratable number of samples	> 20.00 [°C]	Enablement calibration set to TRUE	== 1.00	Test executed after a counter of 1.00 samples	Type B, 2 Trips
					Key on and engine not running or engine running for less than a calibratable time	>= 0.10 [s]	Functional task: 100 ms	
					Runk Crank Relay voltage in range	> 11.00 [V]		
					The engine has not run for a calibratable time since last key off	>= 28,800.00 [s]		
					No faults detected on engine off timer	EngineModeNotRunTimerError ==FALSE		
					Absolute value of the difference between intake manifold air temperature and fuel temperature smaller than a calibratable threshold	< 45.00 [°C]		
					No electrical or self-correlated faults detected on charge air cooler down air temperature sensors	CIT_CAC_DwnCktFA ==FALSE OR CIT_CAC_DwnSelfCorFA ==FALSE		
					No faults detected on intake manifold air	MnfdTempSensorFA ==FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					temperature sensor No faults detected on fuel temperature sensor	 FTS_FTS_Flt==FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Charge Air Cooler Temperature Sensor Down Circuit Low	P10D6	This monitor checks if the CAC down air temperature sensor is out of electrical range low	Charge air cooler down air temperature resistance value < low threshold	< 7.00 [ohm]	Test enabled by calibration Engine not cranking Runk Crank Relay voltage in range	== 1.00 > 11.00 [V]	50.00 fail counter over 63.00 sample counter Functional task: 100 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Charge Air Cooler Temperature Sensor Down Circuit High	P10D7	This monitor checks if the CAC down air temperature sensoris out of electrical range high	Charge air cooler down air temperature resistance value > high threshold	> 1,020,852.00 [ohm]	Test enabled by calibration Engine not cranking Runk Crank Relay voltage in range	== 1.00 > 11.00 [V]	50.00 fail counter over 63.00 sample counter Functional task: 100 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Charge Air Cooler Temperature Sensor Down Circuit Intermittent/ Erratic	P10D8	This monitor checks if the CAC down air temperature has an intermittent fault	Charge air cooler down air temperature value > T_MAX_threshold Charge air cooler down air temperature value < T_MIN_threshold where - T_MAX_threshold = (1 - alpha)*T_MAX + alpha*T_last_good - T_MIN_threshold = (1 - alpha)*T_MIN + alpha*T_last_good - alpha = e^(#fails + 1)*(ts/tau) - #fails = number of consecutive samples where the test failed - ts = sensor sampling time - tau = sensor filter response time - T_MAX = sensor maximum actual reading - T_MIN = sensor minimum actual reading - T_last_good = last good temperature measured by the sensor	> 300.00 [°C] < -40.00 [°C]	Test enabled by calibration Engine not cranking Runk Crank Relay voltage in range No electrical faults detected on CAC down air temperature sensor	== 1.00 > 11.00 [V] CIT_CAC_DwnCktFA ==FALSE	50.00 fail counter over 63.00 sample counter Functional task: 100 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 1 plausibility at key on monitoring	P113B	This diagnosis verify if, at key on, the temperature value read by exhaust gas temperature 1 (EGT1) sensor is almost equal to the reference temperature. Reference temperature is calculated as average value among all the available system temperature sensors (exhaust temperature sensors, coolant temperature sensor, fuel temperature sensor, ambient temperature sensor, intake temperature sensor). The number of sensor used for the average calculation shall be at least 4 but which sensor to use is calibratable and the sensor should not be faulted. The reference temperature is calculated at the system start up after a calibratable engine stop when all the temperature are supposed to be similar.	|Reference temperature at system cold start up (EGT_Avg) – EGT1 temperature|	> 25 [°C]	Test enabled by calibration (TRUE--> enable FALSE --> disable) and with Battery voltage and with No Active DTCs No elettic puntual error and with **Reference temperature calculation done:** - key on and with - minimum engine-off time and with - Minimum number of sensor available for calculation	1 [Boolean] > 11.00 [V] EGT_ExhGas1_CktTFTKO ==TRUE == TRUE > 28,800.00 [sec] >=4	2 fail samples out of 2 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 2 plausibility at key on monitoring	P113C	This diagnosis verify if, at key on, the temperature value read by exhaust gas temperature 2 (EGT2) sensor is almost equal to the reference temperature. Reference temperature is calculated as average value among all the available systemtemperature sensors(exhaust temperature sensors, coolant temperature sensor, fuel temperature sensor, ambient temperature sensor, intake temperature sensor). The number of sensor used for the average calculation shall be at least 4 but which sensor to use is calibratableand the sensor should not be faulted. The reference temperature is calculated at the system start up after a calibratable engine stop when all the temperature are supposed to be similar.	|Reference temperature at system cold start up (EGT_Avg) – EGT2 temperature| See the Description Tab for Reference Temperature, (EGT_Avg) definition.	> 20 [°C]	Test enabled by calibration (TRUE--> enable FALSE --> disable) and with Battery voltage and with No Active DTCs No elettic puntual error and with **Reference temperature calculation done:** - key on and with - minimum engine-off time and with - Minimum number of sensor available for calculation	1 [Boolean] > 11.00 [V] EGT_ExhGas2_CktTFTKO ==TRUE ==TRUE > 28,800.00 [sec] >=4	2 fail samples out of 2 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 3 plausibility at key on monitoring	P113D	This diagnosis verify if, at key on, the temperature value read by exhaust gas temperature 3 (EGT3) sensor is almost equal to the reference temperature. Reference temperature is calculated as average value among all the available systemtemperature sensors(exhaust temperature sensors, coolant temperature sensor, fuel temperature sensor, ambient temperature sensor, intake temperature sensor). The number of sensor used for the average calculation shall be at least 4 but which sensor to use is calibratableand the sensor should not be faulted. The reference temperature is calculated at the system start up after a calibratable engine stop when all the temperature are supposed to be similar.	|Reference temperature at system cold start up (EGT_Avg) – EGT3 temperature| See the Description Tab for Reference Temperature, (EGT_Avg) definition	> 20 [°C]	Test enabled by calibration (TRUE--> enable FALSE --> disable) and with Battery voltage and with No Active DTC No eletrical puntual error and with **Reference temperature calculation done:** - key on and with - minimum engine-off time and with - Number of sensor available for calculation	1 [Boolean] > 11.00 [V] EGT_ExhGas3_CktTFTKO ==TRUE ==TRUE > 28,800.00 [sec] >=4	2 fail samples out of 2 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 4 plausibility at key on monitoring	P113E	This diagnosis verify if, at key on, the temperature value read by exhaust gas temperature 4 (EGT4) sensor is almost equal to the reference temperature. Reference temperature is calculated as average value among all the available systemtemperature sensors(exhaust temperature sensors, coolant temperature sensor, fuel temperature sensor, ambient temperature sensor, intake temperature sensor). The number of sensor used for the average calculation shall be at least 4 but which sensor to use is calibratableand the sensor should not be faulted. The reference temperature is calculated at the system start up after a calibratable engine stop when all the temperature are supposed to be similar.	|Reference temperature at system cold start up (EGT_Avg) – EGT4 temperature| See the Description Tab for Reference Temperature, (EGT_Avg) definition	> 20 [°C]	Test enabled by calibration (TRUE--> enable FALSE --> disable) and with Battery voltage and with No Active DTCs and with No eletrical puntual error Reference temperature calculation done: - key on and with - minimum engine-off time and with - Number of sensor available for calculation	1 [Boolean] > 11.00 [V] EGT_ExhGas4_CktTFTKO ==TRUE ==TRUE > 28,800.00 [sec] >=4	2 fail samples out of 2 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 5 plausibility at key on monitoring	P113F	This diagnosis verify if, at key on, the temperature value read by exhaust gas temperature 5 (EGT5) sensor is almost equal to the reference temperature. Reference temperature is calculated as average value among all the available systemtemperature sensors(exhaust temperature sensors, coolant temperature sensor, fuel temperature sensor, ambient temperature sensor, intake temperature sensor). The number of sensor used for the average calculation shall be at least 4 but which sensor to use is calibratableand the sensor should not be faulted. The reference temperature is calculated at the system start up after a calibratable engine stop when all the temperature are supposed to be similar.	|Reference temperature at system cold start up (EGT_Avg) – EGT5 temperature| See the Description Tab for Reference Temperature, EGT_Avg definition	> 20 [°C]	Test enabled by calibration (TRUE--> enable FALSE --> disable) and with Battery voltage and with No Active DTCs and with No eletrical puntual error and Reference temperature calculation done: - key on and with - minimum engine-off time and with - Number of sensor availablefor calculation	1 [Boolean] > 11.00 [V] EGT_ExhGas5_CktTFTKO ==TRUE ==TRUE > 28,800.00 [sec] >=4	2 fail samples out of 2 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Temperature Not Plausible	P118B	This diagnosis detects a soot sensor temperature sensor damaged or a possible parassitic resistance on the wiring harness between the soot sensor heater and the soot sensor control unit	The absolute value of the difference between the soot sensor electrode temperature at power-up and the average of temperature sensors (EGT_Avg)	> 30.00 °C	Key is turned on Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor No Soot Sensor supply undervoltage detected, i.e. supply sensor voltage for a time No electrical fault detected on Soot Sensor If enabled, the Soot Sensor temperature circuit low and high monitoring reported a test pass Ambient Air pressure Ambient air pressure sensor not faulty Time since Soot Sensor heating off when the sensor temperature has	 > 11.00 NOT(SBR_RlyFA) NOT(U02A3) > 9.00 V > 0.10 s NOT(SOT_ElecIFlt) TPTKO on P1477 TPTKO on P1478 > 51.00 KPa AmbPresDfltdStatus = CeAAPR_e_AmbPresNotDfltd > 600.00 s	No time debounce	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					been stored is Timer since Soot Sensor heating off is not affected by error on module off timer Calculation of the reference temperature at system start up is valid: Minimum time from the previous key off to enable the reference temperature calculation Diagnostic has not yet reported a pass or failure Transmission fault with sensor control unit not present	NOT(ModuleOffTimeErr) EGT_TempAvgVld > 28,800.00 NOT (TPTKO OR TFTKO) on P118B NOT(P30BC)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Temperature Sensor Performance - During Engine Running Test Bank 1 Sensor 1	P118E	This diagnosis compares the measured EGT to a model EGT when entry conditions permit. The difference between the values is averaged over a time window. After this time window has elapsed, the average difference is compared to a threshold. The result is then input to an X out of Y counter.	(Measured EGT1 - Modeled EGT1) >	100.00 degC	Test Enabled by calibration	1.00	240.00 fail samples out of 320.00 Each sample is 0.10 seconds	Type B, 2 Trips
				OR	and			
			(Measured EGT1 - Modeled EGT1) <	-100.00 degC	Battery Voltage	> 11.00 Volts		
					and			
					EGT_EGT1_DiagMdlFlt	== FALSE		
					and			
					Engine Off Timer	> = 0.00 seconds		
					and			
					EGT1 Model Temperature	> 250.00 degC		
					and			
					EGT1 Model Temperature	< 850.00 degC		
					and			
					Dynamick check Valid	==TRUE		
					and			
					No faults on the consumed EGT sensors	EGT_ExhGas1_StkFA and EGT_ExhGas1_StkTFTKO and EGT_ExhGas1_CktFA and		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					and	EGT_ExhGas1_CktTFTKO and EGT_ExhGas2_QckChgFA and EGT_ExhGas1_QckChgTFTKO		
					Time since last DPF regeneration	>= 180.00 seconds		
					and			
					Time after warm up	>= 0.00 seconds		
					and			
					Continuos engine run time	>= 60.00 seconds		
					and			
					Fuel Rate and Engine Speed within bounds, determined by calibration map	**EGT1 DynChk EngPtEnbl**		
					and			
					Model Temperature Rate of change limited to:	7.00 degC		
					over a time period of:	CeEGTR_e_Index1500ms		
					Enabling delay time	1.00 seconds		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Temperature Sensor Performance - During Engine Running Test Bank 1 Sensor 2	P118F	This diagnosis compares the measured EGT to a model EGT when entry conditions permit. The difference between the values is averaged over a time window. After this time window has elapsed, the average difference is compared to a threshold. The result is then input to an X out of Y counter.	(Measured EGT2 - Modeled EGT2) >	100.00 degC	Test Enabled by calibration	1.00	60.00 fail samples out of 80.00 Each sample is 1.00 seconds	Type B, 2 Trips
				OR	and			
			(Measured EGT2 - Modeled EGT2) <	-100.00 degC	Battery Voltage	> 11.00 Volts		
					and			
					EGT_EGT2_DiagMdlFlt	== FALSE		
					and			
					Engine Off Timer	> 0.00 seconds		
					and			
					EGT2 Model Temperature	> -40.00 degC		
					and			
					EGT2 Model Temperature	< 850.00 degC		
					and			
					Dynamick check Valid	==TRUE		
					and			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No faults on the consumed EGT sensors	EGT_ExhGas2_CktFA and EGT_ExhGas2_CktTFTKO and EGT_ExhGas2_QckChgFA and EGT_ExhGas2_QckChgTFTKO and EGT_ExhGas2_QckChgFA		
					Time since last DPF regeneration and Time afert warm up and Continuos engine run time	>= 300.00 seconds >= 0.00 seconds >= 120.00 seconds		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					and Fuel Rate and Engine Speed within bounds, determined by calibration map and Model Temperature Rate of change limited to: over a time period of: Enabling delay time	**EGT2 DynChk EngPtEnbl** < 7.00 degC CeEGTR_e_IndexMax5000ms 5.00 seconds		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Temperature Sensor Performance - During Engine Running Test Bank 1 Sensor 3	P1196	This diagnosis compares the measured EGT to a model EGT when entry conditions permit. The difference between the values is averaged over a time window. After this time window has elapsed, the average difference is compared to a threshold. The result is then input to an X out of Y counter.	Measured EGT3 - Modeled EGT3) >	100.00 degC	Test Enabled by calibration	1.00	60.00 fail samples out of 80.00	Type B, 2 Trips
					and		Each sample is 1.00 seconds	
				OR				
				-100.00 degC	Battery Voltage	> 11.00 Volts		
			Measured EGT3 - Modeled EGT3) <		and			
					EGT_EGT3_DiagMdlFlt	== FALSE		
					and			
					Engine Off Timer	> 0.00 seconds		
					and			
					EGT3 Model Temperature	> -40.00 degC		
					and			
					EGT3 Model Temperature	< 850.00 degC		
					and			
					Dynamick check Valid	==TRUE		
					and			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No faults on the consumed EGT sensors	EGT_ExhGas3_CktFA and EGT_ExhGas3_CktTFTKO		
					and	and EGT_ExhGas3_QckChgFA and EGT_ExhGas3_QckChgTFTKO and EGT_ExhGas3_StkFA and EGT_ExhGas3_StkTFTKO		
					Time since last DPF regeneration	>= 150.00 seconds		
					and			
					Time afert warm up	>= 0.00 seconds		
					and			
					Continuos engine run time	>= 270.00 seconds		
					and			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Fuel Rate and Engine Speed within bounds, determined by calibration map and Model Temperature Rate of change limited to: over a time period of: Enabling delay time	**EGT3 DynChk EngPtEnbl** < 3.00 degC CeEGTR_e_IndexMax5000ms 1.00 seconds		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Temperature Sensor Performance - During Engine Running Test Bank 1 Sensor 4	P1197	This diagnosis compares the measured EGT to a model EGT when entry conditions permit. The difference between the values is averaged over a time window. After this time window has elapsed, the average difference is compared to a threshold. The result is then input to an X out of Y counter.	Measured EGT4 - Modeled EGT4) >	100.00 degC	Test Enabled by calibration	1.00	240.00 fail samples out of 320.00	Type B, 2 Trips
					and		Each sample is 0.10 seconds	
				OR				
				-100.00 degC	Battery Voltage	> 11.00 Volts		
			Measured EGT4 - Modeled EGT4) <		and			
					EGT_EGT4_DiagMdlFlt	== FALSE		
					and			
					Engine Off Timer	> 3,600.00 seconds		
					and			
					EGT4 Model Temperature	> 100.00 degC		
					and			
					EGT4 Model Temperature	< 1,000.00		
					and	degC		
					Dynamick check Valid	==TRUE		
					and			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No faults on the consumed EGT sensors and Time since last DPF regeneration and Time afert warm up and Continuos engine run time and Fuel Rate and Engine Speed within bounds.	EGT_ExhGas4_CktFA and EGT_ExhGas4_CktTFTKO and EGT_ExhGas4_QckChgFA and EGT_ExhGas4_QckChgTFTKO and EGT_ExhGas4_StkFA and EGT_ExhGas4_StkTFTKO >= 300.00 seconds >= 0.00 seconds >= 0.00 seconds **EGT4 DynChk EngPtEnbl**		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					determined by calibration map and Model Temperature Rate of change limited to: over a time period of: Enabling delay time	< 1,000.00 degC CeEGTR_e_IndexMax5000ms 2.00 seconds		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Temperature Sensor Performance - During Engine Running Test Bank 1 Sensor 5	P1198	This diagnosis compares the measured EGT to a model EGT when entry conditions permit. The difference between the values is averaged over a time window. After this time window has elapsed, the average difference is compared to a threshold. The result is then input to an X out of Y counter.	Measured EGT5 - Modeled EGT5) >	100.00 degC	Test Enabled by calibration	1.00	240.00 fail samples out of 320.00	Type B, 2 Trips
					and		Each sample is 0.10	
			Measured EGT5 - Modeled EGT5) <	-100.00 degC	Battery Voltage and	> 11.00 Volts	seconds	
					EGT_EGT5_DiagMdlFlt	== FALSE		
					and			
					Engine Off Timer	> 3,600.00 seconds		
					and			
					EGT5 Model Temperature	> 100.00 degC		
					and			
					EGT5 Model Temperature	< 1,000.00 degC		
					and			
					Dynamick check Valid	==TRUE		
					and			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No faults on the consumed EGT sensors and Time since last DPF regeneration and Time afert warm up and Continuos engine run time and Fuel Rate and Engine Speed within bounds, determined by calibration map	EGT_ExhGas5_CktFA and EGT_ExhGas5_CktTFTKO and EGT_ExhGas5_QckChgFA and EGT_ExhGas5_QckChgTFTKO and EGT_ExhGas5_StkFA and EGT_ExhGas5_StkTFTKO >= 300.00 seconds >= 0.00 seconds >= 0.00 seconds **EGT5 DynChk EngPtEnbl**		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					and Model Temperature Rate of change limited to: over a time period of: Enabling delay time	< 1,000.00 degC CeEGTR_e_IndexMax5000ms 2.00 seconds		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Performance During Deceleration Fuel Cut Off Bank 1 Sensor 2 (SCR: NOx Sensor Downstream Turbine)	P11B3	This DTC aims to detect a drift of Sensor 2 O2 measured value (A) from Sensor 1 O2 measured value (B) when the latter can be considered stable during overrun condition.	EWMA filtered error (A - B) in overrun condition is out of plausible range	> 2.00 [%] < -3.50 [%]	Engine running System voltage in range Sensor is fully operative Sensor 1 is fully operative No pending or confirmed DTCs DTC P2297 is running Air mass flown since P2297	 > 11.00 [V] OXY_O2_NOx2_PresCmpNotRlb ==FALSE OXY_O2_NOx1_PresCmpNotRlb == FALSE NOX_Snsr2_NotVld (MAF_SensorFA AND MAF_SensorTFTKO) OXY_NOx1_O2_Flt OXY_NOx2SignRngChkFlt NOX_Snsr2_PresFlt (see P2297 Fault code) > 60.00 [g]	EWMA filtering: multiple tests per trip are allowed.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Intake Air Flow Supply Circuit	P122B	This monitor checks if the Throttle DC-Motor is correctly supplied	System voltage supply lower than a threshold (error information provided by HWIO)	< 6 [V]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range Diagnostic system enabled (no clear code or EOT in progress) HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V]	96.00 fail counts out of 120.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Intake Air Flow Control Circuit Shorted	P122C	This monitor checks if the Throttle commands are shorted one other	Current flowing through the H-Bridge switches higher than a threshold (error information provided by HWIO)	> 9 [A]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range H-Bridge driver is ON Diagnostic system enabled (no clear code or EOT in progress) HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V]	96.00 fail counts out of 120.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Intake Air Flow Position Sensor Exceeded Learning Limit (SENT position sensor)	P122D	This monitor checks if the Throttle position SENT sensor has an offset with respect to the nominal position where the valve does the learning procedure (fully closed)	SENT position raw voltage when the valve is in fully closed position < low threshold OR SENT position raw voltage when the valve is in fully closed position > high threshold	< 81.75 [%5V] OR > 95.75 [%5V]	Test enabled by calibration Key signal is off Learning procedure enabled: - no faults present on engine coolant temperature sensor; - the engine coolant tempearture is in range. - outside air temperature above a threshold - no faults present on outside air temperature sensor Position control in closed loop: battery voltage above a threshold. No faults present on Throttle position sensor, Throttle valve, Throttle position deviation End Of Trip event has elapsed	== 1.00 ECT_Sensor_FA == FALSE >= 60.00 [°C] <= 117.00 [°C] >= -10.00 [°C] OAT_PtEstFiltFA == FALSE > 5.00 [V] TPS_PstnShtOffReq== FALSE	1.00 fail counts out of 1.00 sample counts Function task: at key off	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 1 electrical resistance rationality check	P1307	Test aim is to detect when individual glow plug no longer operates within the manufacturer's specified limits for normal operation. Glow plug electrical resistance is calculated as a ratio between voltage measure and current measure.	An error shall be detected when glow plug 1 electrical resistance is outside a calibratable range	0.20 < NaGLOD_R_GlowPlug < 2.50	Test enabled by calibration; Diagnostic system is not disabled; Key on and engine running (cranking excluded); Battery voltage in range; Glow plug is commanded on for a calibratable time (Glow Plug system is enabled, no electrical fault on individual glow plug); No fault on glow plugs voltage feedback circuitry;	1.00 VeDRER_b_DiagSystem Dsbl = FALSE; VePMDR_b_RunCrankAc tive = TRUE; VeEMDR_b_EngModeCra nk = FALSE; VeLVTR_b_RunCrankIgnI nRange = TRUE; VaGLOD_b_GlowPlugOn = TRUE; 3.00 VeGLOD_b_RunCrankVol tRec = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 2 electrical resistance rationality check	P1308	Test aim is to detect when individual glow plug no longer operates within the manufacturer's specified limits for normal operation. Glow plug electrical resistance is calculated as a ratio between voltage measure and current measure.	An error shall be detected when glow plug 2 electrical resistance is outside a calibratable range	0.20 < NaGLOD_R_GlowPlug < 2.50	Test enabled by calibration; Diagnostic system is not disabled; Key on and engine running (cranking excluded); Battery voltage in range; Glow plug is commanded on for a calibratable time (Glow Plug system is enabled, no electrical fault on individual glow plug); No fault on glow plugs voltage feedback circuitry;	1.00 VeDRER_b_DiagSystem Dsbl = FALSE; VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; VaGLOD_b_GlowPlugOn = TRUE; 3.00 VeGLOD_b_RunCrankVoltRec= FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 3 electrical resistance rationality check	P1309	Test aim is to detect when individual glow plug no longer operates within the manufacturer's specified limits for normal operation. Glow plug electrical resistance is calculated as a ratio between voltage measure and current measure.	An error shall be detected when glow plug 3 electrical resistance is outside a calibratable range	0.20 < NaGLOD_R_GlowPlug < 2.50	Test enabled by calibration; Diagnostic system is not disabled; Key on and engine running (cranking excluded); Battery voltage in range; Glow plug is commanded on for a calibratable time (Glow Plug system is enabled, no electrical fault on individual glow plug); No fault on glow plugs voltage feedback circuitry;	1.00 VeDRER_b_DiagSystem Dsbl = FALSE; VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; VaGLOD_b_GlowPlugOn = TRUE; 3.00 VeGLOD_b_RunCrankVoltRec = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 4 electrical resistance rationality check	P130A	Test aim is to detect when individual glow plug no longer operates within the manufacturer's specified limits for normal operation. Glow plug electrical resistance is calculated as a ratio between voltage measure and current measure.	An error shall be detected when glow plug 4 electrical resistance is outside a calibratable range	0.20 < NaGLOD_R_GlowPlug < 2.50	Test enabled by calibration; Diagnostic system is not disabled; Key on and engine running (cranking excluded); Battery voltage in range; Glow plug is commanded on for a calibratable time (Glow Plug system is enabled, no electrical fault on individual glow plug); No fault on glow plugs voltage feedback circuitry;	1.00 VeDRER_b_DiagSystem Dsbl = FALSE; VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; VaGLOD_b_GlowPlugOn = TRUE; 3.00 VeGLOD_b_RunCrankVoltRec = FALSE;	10.00 fail samples over 20.00 samples Time task: 100 [ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation Supply Circuit	P1402	This monitor checks if the HP EGR DC-Motor is correctly supplied	System voltage supply lower than a threshold (error information provided by HWIO)	< 6 [V]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range Diagnostic system enabled (no clear code or EOT in progress) HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V]	96.00 fail counts out of 120.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation Control Circuit Shorted	P1407	This monitor checks if the HP EGR commands are shorted one other	Current flowing through the H-Bridge switches higher than a threshold (error information provided by HWIO)	> 8 [A]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range H-Bridge driver is ON Diagnostic system enabled (no clear code or EOT in progress) HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V]	96.00 fail counts out of 120.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation Current Range/ Performance	P140F	This monitor checks if an excessive current flows through the HP EGR DC-Motor (e.g. shunt circuit between load, HP EGR DC-Motor internal faults, etc).	Current flowing through the H-Bridge higher than a threshold (error information provided by HWIO)	> 6.3 [A]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range No faults present on HP EGR DC Motor current range/performance H-Bridge driver is ON Diagnostic system enabled (no clear code or EOT in progress) HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V] EGR_MtrCurrLimTFTKO == FALSE	96.00 fail counts out of 120.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation Motor Overtemperature	P1424	This monitor checks if the temperature of the HP EGR DC-Motor increases too much (e.g. HP EGR DC-Motor internal faults, etc).	H-Bridge driver temperature higher than a threshold (error information provided by HWIO)	> 170 [°C]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range Diagnostic system enabled (no clear code or EOT in progress) HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V]	96.00 fail counts out of 120.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Intake Air Flow Motor Overtemperature	P1425	This monitor checks if the temperature of the Throttle DC-Motor increases too much (e.g. Throttle DC-Motor internal faults, etc).	H-Bridge driver temperature higher than a threshold (error information provided by HWIO)	> 170 [°C]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range Diagnostic system enabled (no clear code or EOT in progress) HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V]	96.00 fail counts out of 120.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
EGR Temperature Sensor1 IAT Not Plausible	P1428	The power up temperatue varies too much from reference sensor after long soak	if the power up initial value of the temp sensor varies more than allowed from the reference temp sensor	Temperature Delta from MAT. at powerup > 20 °C	Engine soak (not run) time No P codes	>= 28,800.00 Sec P262B P0111 P0114 P010B P00E9 P117D P017C P017D P017B P117B P117F P117E P117C P0116 P0117 P0118 P111E P0128 P0119	NA	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
EGR Temperature Sensor2 IAT Not Plausible	P142A	The power up temperatue varies too much from reference sensor after long soak	if the power up initial value of the temp sensor varies more than allowed from the reference temp sensor	Temperature Delta from MAT. at powerup > 20 °C	Engine soak (not run) time No P codes	>= 28,800.00 Sec P262B P0111 P0114 P010B P00E9 P117D P017C P017D P017B P117B P117F P117E P117C P0116 P0117 P0118 P111E P0128 P0119	NA	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Control Module High Temperature	P142B	This diagnosis detects a soot sensor control unit overtemperature caused by an aged solder joint inside soot sensor control unit	Soot Sensor Control Unit Temperature 1 OR Soot Sensor Control Unit Temperature 2	> 140.00 °C > 134.00 °C	Key is turned on Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Engine not in cranking mode Fault not detected on undervoltage for Soot Sensor Control Unit supply No Electrical faults present on Soot Sensor Transmission fault with sensor control unit not present	 > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0) NOT(SOT_ElecIFlt) NOT(P30BC)	Time counter: 20.00 failures out of 40.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Control Module Temperature Sensor A Circuit Low	P142C	This diagnosis detects a short circuit to ground on soot sensor control unit temperature 1 signal line	Diagnosis executed in Soot Sensor Control Unit: Soot Sensor Control Unit Temperature 1 Circuit Signal	< 0,3 V	Soot Sensor Control Unit conditions: no conditions ECU conditions: Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Key is turned on Engine not in cranking mode Fault not active on undervoltage for Soot Sensor Control Unit supply	 > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0)	Time counter: 10.00 consecutive failures OR 18.00 failures out of 36.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Control Module Temperature Sensor A Circuit High	P142D	This diagnosis detects an open circuit on soot sensor control unit temperature 1 signal	Diagnosis executed in Soot Sensor Control Unit: Soot Sensor Control Unit Temperature 1 Circuit Signal	> 4,97 V	Soot Sensor Control Unit conditions: no conditions ECU conditions: Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Key is turned on Engine not in cranking mode Fault not active on undervoltage for Soot Sensor Control Unit supply	 > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0)	Time counter: 10.00 consecutive failures OR 18.00 failures out of 36.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Control Module Temperature Sensor B Circuit Low	P142E	This diagnosis detects a short circuit to ground on soot sensor control unit temperature 2 signal	Diagnosis executed in Soot Sensor Control Unit: Soot Sensor Control Unit Temperature 2 Circuit Signal	< 0,03V	Soot Sensor Control Unit conditions: no conditions ECU conditions: Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Key is turned on Engine not in cranking mode Fault not active on undervoltage for Soot Sensor Control Unit supply	> 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0)	Time counter: 10.00 consecutive failures OR 18.00 failures out of 36.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Control Module Temperature Sensor B Circuit High	P142F	This diagnosis detects an open circuit on soot sensor control unit temperature 2 signal	Diagnosis executed in Soot Sensor Control Unit: Soot Sensor Control Unit Temperature 2 Circuit Signal	> 4,7 V	Soot Sensor Control Unit conditions: no conditions ECU conditions: Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Key is turned on Engine not in cranking mode Fault not active on undervoltage for Soot Sensor Control Unit supply	 > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0)	Time counter: 10.00 consecutive failures OR 18.00 failures out of 36.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Control Module Temperature Sensor A/B Correlation	P1435	This diagnosis detects a drifted soot sensor control unit temperature sensor 1 or drifted soot sensor control unit temperature sensor 2	Absolute value of the difference between Soot Sensor Control Unit Temperature Sensor 1 and Soot sensor Control Unit Temperature Sensor 2	> 10.00 °C	Key is turned on Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Engine not in cranking mode Fault not detected on undervoltage for Soot Sensor Control Unit supply No Electrical faults present on Soot Sensor Transmission fault with sensor control unit not present	 > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0) NOT(SOT_ElecIFlt) NOT(P30BC)	Time counter: 15.00 failures out of 30.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Closed Loop Particulate Filter Regeneration Control At Limit - Stage 2 Temperature Too Low	P144E	DPF Control Temperature Deviation diagnostic monitors the exhaust gas temperature downstream the 1st ccDOC (EGT2 sensor, configuration "**c1**") or upstream the DPF (EGT3 sensor, configuration "**c2**") to determine whether the temperature deviation between the control setpoint and the temperature read by the sensor is within a prescribed deviation range. Temperature deviation diagnostic shall diagnose a too low temperature, that means a Positive temperature deviation temperature. The diagnosis runs during regeneration mode and when the temperature closed loop is active. The monitoring is divided into 2 logics, in particular the DPF warm up state logic and the DPF steady state logic.	**LowTemperature monitoring (Positive Deviation):** **(c1)** Temperature ccDOC Downstream control setpoint - ccDOC Downstream sensor reading (EGT2) **(c2)** Temperature DPF Upstream control setpoint - DPF Upstream sensor reading (EGT3)	> 100.00 degC	Test shall be enabled by calibratable flag Regeneration state in warm up DPF Mode DPF temperature closed loop control shall be enabled Battery voltage No fault on exhaust mass flow **(c1)** No Fault on ccDOC Downstream temperature sensor **(c2)** No Fault on DPF Upstream temperature sensor Combustion mode different from LNT Desox Lean and LNT Engine Protection Temperature deviation monitoring shall be enabled by a boolean flag. The boolean flag shall be the output of a map function of engine	1.00 [Boolean] DPF_DPF_St== Warm_Up EGT_DsblCL== Enable temperature Closed loop control [Boolean] > 11.00 [V] EXM_TurbFlowNotValid [Boolean] EGT_SnsrCatDwnFlt [Boolean] EGT_SnsrDPF_UpFlt [Boolean] **EnginePointEnable_DPF_TempDeviation** [Boolean]	850.00 fail samples out of 1,000.00 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					speed and fuel request			
					Exhaust mass flow AND	< 120.00 [g/s]		
					Exhaust mass flow	> 8.00 [g/s]		
					Filtered Exhaust mass flow variation (absolute value)	< 100.00 [g/s]		
					The system shall not be in cut off for a calibratable timer.	< 30.00 [sec]		
					No fault on ambient temperature sensor (only SCR forward architecture)	OAT_PtEstFiltFA		
					No fault on ambietnt pressure sensor (only SCR forward architecture)	AAP_AmbientAirPresDfltd AND AAP_AmbPresSnsrTFTKO		
					All the above enabling conditions met for at least a calibratable timer	> 20.00 [sec]		
			Low Temperature monitoring (Positive Deviation):		Test shall be enabled by calibratable flag	1.00 [Boolean]	850.00 fail samples out of 1,000.00 samples	
			(c1) Temperature ccDOC Downstream control setpoint - ccDOC Downstream	> 100.00 degC	Regeneration state in Steday state DPF Mode	DPF_DPF_St== Steady state	Function task: 100ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			sensor reading (EGT2) **(c2)** Temperature DPF Upstream control setpoint - DPF Upstream sensor reading (EGT3)		DPF temperature closed loop control shall be enabled	EGT_DsblCL == Enable temperature Closed loop control [Boolean]		
					Battery voltage	> 11.00 [V]		
					No fault on exhaust mass flow	EXM_TurbFlowNotValid [Boolean]		
					(c1) No Fault on ccDOC Downstream temperature sensor	EGT_SnsrCatDwnFlt [Boolean]		
					(c2) No Fault on DPF Upstream temperature sensor	EGT_SnsrDPF_UpFlt [Boolean]		
					Combustion mode different from LNT Desox Lean and LNT Engine Protection			
					Temperature deviation monitoring shall be enabled by a boolean flag. The boolean flag shall be the output of a map function of engine speed and fuel request	**EnginePointEnable_DPF_TempDeviation** [Boolean]		
					Exhaust mass flow AND	< 120.00 [g/s]		
					Exhaust mass flow	> 8.00 [g/s]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Filtered Exhaust mass flow variation (absolute value)	< 100.00 [g/s]		
					The system shall not be in cut off for a calibratable time	< 30.00 [sec]		
					No fault on ambient temperature sensor (only SCR forward architecture)	OAT_PtEstFiltFA		
					No fault on ambietnt pressure sensor (only SCR forward architecture)	AAP_AmbientAirPresDfltd AND AAP_AmbPresSnsrTFTKO		
					All the above enabling conditions met for at least a calibratable timer	> 15.00 [sec]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Electrode Supply Circuit Open	P1474	This diagnosis detects an open circuit on the soot sensor electrode supply line	Diagnosis executed in Soot Sensor Control Unit: Soot Sensor Electode supply voltage signal (i.e. measured ADC voltage for electrode current)	< 0.3 V	Soot Sensor Control Unit conditions: Battery Voltage Soot Sensor Electrode Supply Voltage ECU conditions: Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Key is turned on Engine not in cranking mode Fault not active on undervoltage for Soot Sensor Control Unit supply	 > 9 V = 45,6V > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0)	Time counter: 21.00 consecutive failures OR 40.00 failures out of 80.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Electrode Supply Circuit Low	P1475	This diagnosis detects a short to ground on the soot sensor electrode supply line	Diagnosis executed in Soot Sensor Control Unit: Soot Sensor Electrode supply voltage	U < 41.55 V OR U > 49.72 V	Soot Sensor Control Unit conditions: Battery voltage Soot Sensor Electrode High Voltage Enabled ECU conditions: Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Key is turned on Engine not in cranking mode Fault not active on undervoltage for Soot Sensor Control Unit supply	 > 9 V > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0)	Time counter: 22.00 consecutive failures OR 42.00 failures out of 84.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Electrode Supply Circuit High	P1476	This diagnosis detects a short to power on the soot sensor electrode supply line	Diagnosis executed in Soot Sensor Control Unit: Soot Sensor Electrode voltage signal (measured ADC voltage for electrode current)	> 4.7 V	Soot Sensor Control Unit conditions: Soot Sensor Electrode Voltage Disabled ECU conditions: Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Fault not active on undervoltage for Soot Sensor Control Unit supply	 NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0)	Time counter: 6.00 consecutive failures OR 15.00 failures out of 20.00 samples 100 ms/sample	Type B, 2 Trips
			Diagnosis executed in Soot Sensor Control Unit: Soot Sensor Electrode supply voltage	> 2 V	Soot Sensor Control Unit conditions: Soot Sensor Electrode Voltage Disabled ECU conditions: Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor	 NOT(SBR_RlyFA) NOT(U02A3)	Time counter: 6.00 consecutive failures OR 15.00 failures out of 20.00 samples 100 ms/sample	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Fault not active on undervoltage for Soot Sensor Control Unit supply	NOT(P24D0)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Temperature Circuit Low Input	P1477	This diagnosis detects a short to ground on the soot sensor temperature signal	Diagnosis executed in Soot Sensor Control Unit: Voltage of Soot Sensor temperature meander (TM) signal	< 0.3 V	Soot Sensor Control Unit conditions: no conditions ECU conditions: Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Key is turned on Engine not in cranking mode Fault not active on undervoltage for Soot Sensor Control Unit supply	 > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0)	Time counter: 2.00 consecutive failures OR 2.00 failures out of 2.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Temperature Circuit High Input	P1478	This diagnosis detects a short to power or an open circuit on the soot sensor temperature signal	Diagnosis executed in Soot Sensor Control Unit: Voltage of Soot Sensor temperature meander (TM) signal	> 3 V	Soot Sensor Control Unit conditions: no conditions ECU conditions: Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Key is turned on Engine not in cranking mode Fault not active on undervoltage for Soot Sensor Control Unit supply	 > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0)	Time counter: 2.00 consecutive failures OR 2.00 failures out of 2.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Sensitivity Factor Performance	P1479	This diagnosis detects a soot sensor memory corruption	Soot sensor sensitivity factor is	< -0.25 OR > 0.25	Key is turned on Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor No electrical fault detected on Soot Sensor Transmission fault with sensor control unit not present	 > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(SOT_ElecIFlt) NOT(P30BC)	Time counter: 30.00 failures out of 60.00 samples 1000 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Shunt Circuit High Current	P147B	This diagnosis detects a no more efficient soot sensor	Soot Sensor Electrode raw current	> 5.00 A	Key is turned on Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor No electrical fault detected on Soot Sensor Soot Sensor is in measurement phase Soot Sensor Electrode supply voltage Soot Sensor temperature Soot Sensor Electrode current measurement enabled Transmission fault with sensor control unit not present	 > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(SOT_ElecIFlt) 41.00 V < U < 50.00 V 200.00 °C < T < 425.00 °C NOT(P30BC)	No time debouce	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Protection Tube Performance	P1488	This diagnosis detects a soot sensor that has been removed from exhaust line or is clogged	Integrated derivative of corrected volumetric flow AND Integrated derivative of effective soot sensor heater voltage (i,e, cumulated heater voltage change)	> 3,000.00 < 4.33 V	Key is turned on Ignition voltage in range Engine in running mode Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor No Soot Sensor supply undervoltage detected No electrical fault detected on Soot Sensor No fault on exhaust gas pressure estimation at sensor location No fault on exhaust gas temperature estimation at sensor location No fault on gas mass flow estimation at sensor location Soot Sensor in protection heating operating state Derivative in volumetric flow	 > 11.00 NOT(SBR_RlyFA) (U02A3) NOT(P24D0) NOT(SOT_ElecIFlt) SOT_ExhPresSootSnsrVld SOT_ExhTempSootSnsrVld SOT_TotExhSootSnsrVld 1.00 < d2V < 300.00	No debounce time	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					for a time	> = 2.00 s		
					At InitCntrlr time since engine off	> 28,800.00 s		
					At InitCntrlr time since engine off is valid	NOT EngineModeNotRunTimer Error		
					The time from the Soot Sensor Heater is controlled in closed loop	> 12.00 s		
					As soon as Soot Sensor is supplied the time since PM sensor heating off (module off plus heating off)	> 28,800.00 s		
					Exhaust gas temperature at Soot Sensor	0.00 < T < 300.00 °C		
					Environmental pressure	> 74.0 kPa		
					Diagnostic has not yet reported a pass or failure			
					The sign of derivative in volumetric flow does not change for a time	>= 0.00 s		
					Transmission fault with sensor control unit not present	NOT(P30BC)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Glow Plug Positive Voltage Circuit	P161E	This DTC checks the circuit for electrical integrity during operation. Glow plugs supply pin open circuit or shorted to ground.	Voltage feedback under a calibratable threshold	Voltage_feedback < 6.00	Test enabled by calibration; Key on and engine running (cranking excluded); Battery voltage in range; Enable_On interface is true; Diagnostic system is not disabled;	1.00 [boolean] VePMDR_b_RunCrankActive = TRUE; VeEMDR_b_EngModeCrank = FALSE; VeLVTR_b_RunCrankIgnInRange = TRUE; VeGLOO_b_GlowPlugEnbld = TRUE; VeDRER_DiagSystemDsbl = FALSE;	5.00 fail samples over 10.00 samples Time task: 100 [ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Turbocharger VGT A Supply Circuit (Single and Two stage VGT DC Motor)	P169E	This monitor checks if the VGT DC-Motor is correctly supplied	System voltage supply lower than a threshold (error information provided by HWIO)	< 6 [V]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V]	24.00 fail counts out of 30.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Turbocharger VGT A Control Circuit Shorted (Single and Two stage VGT DC Motor)	P169F	This monitor checks if the VGT commands are shorted one other	Current flowing through the H-Bridge switches higher than a threshold (error information provided by HWIO)	> 8 [A]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range H-Bridge driver is ON HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V]	24.00 fail counts out of 30.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Turbocharger VGT A Current Range/ Performance (Single and Two stage VGT DC Motor)	P16FA	This monitor checks if an excessive current flows through the VGT DC-Motor (e.g. shunt circuit between load, VGTDC-Motor internal faults, etc).	Current flowing through the H-Bridge higher than a threshold (error information provided by HWIO)	> 6.3 [A]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range H-Bridge driver is ON HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V]	24.00 fail counts out of 30.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Turbocharger VGT A Motor Overtemperature (Single and Two stage VGT DC Motor)	P16FC	This monitor checks if the temperature of the VGT DC-Motor increases too much (e.g. VGT DC-Motor internal faults, etc).	H-Bridge driver temperature higher than a threshold (error information provided by HWIO)	> 170 [°C]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range HWIO error status different from INDETERMINATE status	== 1.00 > 11.00 [V]	255.00 fail counts out of 255.00 sample counts Function task: 12.5 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Particulate Filter Efficiency Below Threshold Bank 1 - (EWMA filter used) - (SW 18.19 and beyond)	P2002	This diagnosis detects a cracked Diesel Particulate FIlter	{The predicted soot sensor filtered by using EWMA filter is} OR {The predicted soot sensor filtered by using EWMA filter is AND - DPF Efficiency Below Threshold Bank 1 previously detected (TRUE -> fault active) }	< 0.85 < 0.85 DPF_DPF_EffMontrFA = 1 (true)	Test enabled by calibration (TRUE--> enable FALSE --> disable) Ignition voltage in range for a time Engine running or engine cranking or in auto-stop phase No faults on soot sensor and faults which inhibit sensor to stay in measurement DPF soot loading (ranked model) Engine out soot model realiable Note: the not reliability shall be verified for 1 s before to be declared No faults on downstream DPF temperature sensor or model No faults on downstream DPF mass airflow No faults on engine out soot model Ambient temperature During sensor measurement phase, Number of Autostop	1.00 > 5.00 s NOT (SOT_SootSnsrFlt) > -1.00 % NOT (EXM_PM_TurbFlowNotRlb) SOT_ExhTempSootSnsrVld SOT_TotExhSootSnsrVld NOT (SOT_PM_DPF_UpFlt) > -20.00 °C < 20.00	Test per Trip: 1: If Fast Initial Response (FIR) mode is active then 2.00 test per trip are allowed If Rapid Response (RR) mode is active then 2.00 test per trip are allowed The signal for the monitor check is filtered by means a first-order filter. The filter step change can assume the following values: - 0.70 if FIR is active - 0.40 if RR is active - 0.25 if neither FIR and RR are active Initial filter value: - 0.89 when FIR is activated - 0.89 when RR is activated	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					events During sensor measurement phase, Duration of Autostop phase During sensor measurement phase, no heavy transient manoeuvers detected , i.e. the maximum fuel request during a transient manoeuver is If EWMA filter is enabled (TRUE--> enable FALSE --> disable) AND number of diagnostic run for driving cycle is	< 200.00 s <= 1,000.00 1.00 = 1 (true) < 1 (when FIR and RR are not active) < 1.00 (when FIR is active) < 1.00 (when RR is active)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Particulate Filter Over Temperature Bank (DOC1_SCR_DOC2_DPF)(EGT4)	P200C	This diagnosis verify if the exahust gas temperature on DPF Upstream (EGT_DPF_Up) is above its maximum allowed temperature	**Excursion Event monitoring:** DPF Upstream Exhaust gas temperature	**In Regeneration mode:** > 850.00 [°C] **In Normal mode:** > 850.00 [°C]	Test enabled by calibration (TRUE--> enable FALSE --> disable) and with Battery voltage and with Engine running and with No fault on DPF Upstream Temperature sensor	1.00 [Boolean] > 11.00 [V] == TRUE [Boolean] EGT_SnsrDPF_UpFlt [Boolean]	**In Normal mode**: 300.00 fail samples out of 450.00 samples **In Regeneration mode:** 300.00 fail samples out of 450.00 samples Function task: 100ms	Type A, 1 Trips
			Extreme Event monitoring: DPF Upstream Exhaust gas temperature	> 950.00 [°C]	Test enabled by calibration (TRUE--> enable FALSE --> disable) and with Battery voltage and with Engine running and with No fault on DPF Upstream Temperature sensor	1.00 [Boolean] > 11.00 [V] == TRUE [Boolean] EGT_SnsrDPF_UpFlt [Boolean]	50.00 fail samples out of 70.00 samples Function task: 100ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Catalyst System Over Temperature Bank 1 (DOC1_SCR_DOC2_DPF) (EGT2)	P200E	This diagnosis verify if the exahust gas temperature on ccDOC Downstream (EGT_DOC1_Dwn) is above its maximum allowed temperature	**Excursion Event monitoring:** Exhaust gas temperature on ccDOC Downstream	**In Regeneration mode:** > 850.00 [°C] **In Normal mode:** > 850.00 [°C]	Test enabled by calibration (TRUE--> enable FALSE --> disable) and with Battery voltage and with Engine running and with No fault on ccDOC Downstream Temperature sensor (EGT2)	1.00 > 11.00 == TRUE EGT_SnsrCatDwnFlt	**In Normal mode:** 300.00 fail samples out of 450.00 samples **In Regeneration mode :** 300.00 fail samples out of 450.00 samples Function task: 100ms	Type A, 1 Trips
			Extreme Event monitoring: Exhaust gas temperature on ccDOC Downstream	> 950.00	Test enabled by calibration (TRUE--> enable FALSE --> disable) and with Battery voltage and with Engine running and with No fault on ccDOC Downstream	1.00 > 11.00 == TRUE EGT_SnsrCatDwnFlt	50.00 fail samples out of 70.00 samples Function task: 100ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Temperature sensor (EGT2)			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 2 out of range monitoring Low	P2032	Controller specific output driver circuit diagnoses t the exhaust gas temperature 2 (EGT2) sensor signal high sided driver for a short to ground failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	< 160.00 [Ohm]	Test enabled by calibration (TRUE--> enable FALSE --> disable) and with Engine cranking and with Battery voltage and with key on	1 [Boolean] == FALSE > 11.00 [V] == TRUE	10 fail samples over 20 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 2 out of range monitoring High	P2033	Controller specific output driver circuit diagnoses the exhaust gas temperature 2 (EGT2) signal high sided driver for a short to power failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds. Controller specific output driver circuit diagnoses the exhaust gas temperature 2 (EGT2) signal high sided driver for an open circuit failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power. Voltage measurement outside of controller specific acceptable range during driver on state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	> 900.00 [Ohm]	Test enabled by calibration (TRUE--> enable FALSE --> disable) and with Engine cranking and with Battery voltage and with key on	1 [Boolean] == FALSE > 11.00 [V] ==TRUE	10 fail samples over 20 samples Function task: 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 1 quick change monitoring	P2081	This diagnosis verify if the EGT1 temperature sensor signal (difference between two consecutive signal samples) variation is too big	|EGT1 output reistance - EGT1 output resistance old|	> 10.00 [Ohm]	Test enabled by calibration and with Engine running and with Engine cranking and with Battery voltage and with key on and with No electrical faults on EGT1 sensor in and logic	1 [Boolean] == TRUE == FALSE > 11.00 [V] == TRUE EGT_ExhGas1_TFTKO and with EGT_ExhGas1_FA	20 fail samples out of 40 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 2 quick change monitoring	P2085	This diagnosis verify if the EGT2 temperature sensor signal (difference between two consecutive signal samples) variation is too big	|EGT2 output reistance - EGT2 output resistance old|	> 10.00 [Ohm]	Test enabled by calibration and with Engine running and with Engine cranking and with key on and with Battery voltage and with No electrical faults on EGT2 sensor in and logic	1 [Boolean] == TRUE == FALSE ==TRUE > 11.00 [V] EGT_ExhGas2_TFTKO and with EGT_ExhGas2_FA	20 fail samples out of 40 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Aftertreatment Fuel Injector A Control Circuit/Open	P20CB	This diagnosis detects a HC Injector Command pin /wire in open circuit	HC injector HWIO Open interface fault	=TRUE (i.e. If the voltage at the AUXINJ output in the OFF state stays below Volt (1.95 to 2.175V) and Volt (2.9 V to 3.2 V) for a time longer than tdiag (40µs to 70µs)	Test Enabled by calibration Shared High Side Driver 2 commanded ON (i.e. closed) Powertrain relay voltage in range;	1.00	48.00 failures over 60.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Aftertreatment Fuel Injector A Control Circuit Low	P20CD	This diagnosis detects a HC Injector Command pin /wire shortcut to ground	HC injector HWIO Short To Ground interface fault Note: If DTC failed, it will be healed only after a calibratable counter 1,000,000.00 or after ECU Reset event	=TRUE (i.e If the voltage at the AUXINJ output in the OFF state stays below Vltvt (1,95V to 2,175V) for a time longer than tdiag (40µs to 70µs)	Shared High Side Driver 2 commanded ON (i.e. closed) Powertrain relay voltage in range;		10.00 failures over 30.00 samples 100 ms/samples	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Aftertreatment Fuel Injector A Control Circuit High	P20CE	This diagnosis detects a HC Injector Command pin /wire shortcut to power supply	HC injector HWIO Short To Power Supply interface fault	=TRUE (i.e. If the current through the AUXINJ output in the ON state is higher than Ioc1 (8A to 11A) for a time longer than toc1 = 36µs OR If the current through the AUXINJ output in ON state is higher than Ioc2 (16 A to 22A)	Powertrain relay voltage in range;		48.00 failures over 60.00 100 ms/samples	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Out of Range During Deceleration Bank 1 Sensor 1 (SCR: NOx Sensor Downstream Turbine)	P2297	This DTC aims to detect a drift of measured O2 value (A) from an estimated concentration (B) when the latter can be considered stable during overrun condition.	EWMA filtered error (A - B) in overrun condition is out of plausible range	> 2.50 [%] < -4.85 [%]	Engine running System voltage in range Sensor is fully operative No SQA learning is active Enabled in combustion mode No Exhaust Brake active i.e. intake manifold pressure No pending or confirmed DTCs	 > 11.00 [V] OXY_NOx1_O2_RawNotRlb == FALSE FAD_SQA_LrnET_Enbl == FALSE refer to supporting table (**KaOXYD_b_NOx1OvrnChkCmbModeEnbl**) < 1,000.00 [kPa] NOX_Snsr1_NotVld NOX_Snsr1_PresFlt OXY_O2_NOx1PlausMdlFlt OXY_NOx1SignRngChkFlt FHP_InjLeakageFA EGR_PstnShtOffReqFA LPE_PstnShtOffReqFA (MAF_MAF_SnsrFA AND MAF_MAF_SnsrTFTKO)	Once per trip Note: if EWMA Fast Initial Response is active OR EWMA Rapid Response is active than multiple tests per trip are allowed.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						(MAP_SensorFA AND MAP_SensorTFTKO)		
					Stable fuel cut-off condition has been reached i.e. following conditions are met for a calibrateable time:	> 3.00 [s]		
					a. Engine speed in operating range	> 1,000 [rpm] < 3,000 [rpm]		
					b. EGR position	< 10.00 [%]		
					c. LPE position	< 0.00 [%]		
					c. No fuel injected			
					d. Air mass per cylinder in operating range	> 500.00 [mg] < 1,500.00 [mg]		
					Estimated O2 concentration stable i.e. difference between initial and actual value	< 0.50 [%]		
					Air mass flown since fuel cut-off condition	> 20.00 [g]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Pumping Current Trim Circuit Low Bank 1 Sensor 2 (SCR: NOx Sensor Downstream Turbine)	P22B6	This DTC detects if O2 signal is lower than physical minimum value.	O2 signal lower than a minimum value	< -4.00 [%]	Engine running System voltage in range Sensor is fully operative Enabled in combustion mode No pending or confirmed DTC	 > 11.00 [V] OXY_NOx2_O2_RawNotRlb == FALSE refer to supporting table **KaOXYD_b_NOx2SigRn** (**gEnblCmbMode**) NOX_Snsr2_NotVld	Time counter: 200 failures out of 250 samples. Time task 25[ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Pumping Current Trim Circuit High Bank 1 Sensor 2 (SCR:NOx Sensor Downstream Turbine)	P22B7	This DTC detects if O2 signal is higher than physical maximum value	O2 signal higher than a maximum value	> 27.00 [%]	Engine running System voltage in range Sensor is fully operative Exhaust gas pressure No Exhaust Brake active i.e. intake manifold pressure No pending or confirmed DTCs		Time counter: 100 failures out of 200 samples. Time task 25 [ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 3 out of range monitoring Low	P242C	Controller specific output driver circuit diagnoses t the exhaust gas temperature 3 (EGT3) sensor signal high sided driver for a short to ground failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	< 160.00 [Ohm]	Test enabled by calibration and with Engine cranking and with Battery voltage and with key on	1 [Boolean] == FALSE > 11.00 [V] ==TRUE	10 fail samples over 20 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 3 out of range monitoring High	P242D	Controller specific output driver circuit diagnoses the exhaust gas temperature 3 (EGT3) signal high sided driver for a short to power failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds. Controller specific output driver circuit diagnoses the exhaust gas temperature 3 (EGT3) signal high sided driver for an open circuit failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power. Voltage measurement outside of controller specific acceptable range during driver on state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	> 900.00 [Ohm]	Test enabled by calibration and with Engine cranking and with Battery voltage and with key on	1 [Boolean] == FALSE > 11.00 [V] ==TRUE	10 fail samples over 20 samples Function task: 100ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 3 quick change monitoring	P242E	This diagnosis verify if the EGT3 temperature sensor signal (difference between two consecutive signal samples) variation is too big	|EGT3 output reistance - EGT3 output resistance old|	> 10.00 [Ohm]	Test enabled by calibration and with Engine running and with Engine cranking and with key on and with Battery voltage and with No electrical faults on EGT3 sensorin and logic	1 [Boolean] == TRUE == FALSE ==TRUE > 11.00 [V] EGT_ExhGas3_TFTKO and with EGT_ExhGas3_FA	20 fail samples out of 40 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Particulate Filter Differential Pressure Too Low - (SW 18.19 and beyond)	P244A	This diagnostic detects a DPF pressure sensor pipe disconnected or clogged or blocked or a removed Diesel Particulate Filter	measured DPF absolute pressure	< **Exhaust Gas Pressure Too Low Threshold**	Test enabled by calibration (TRUE--> enable FALSE --> disable) No error on relative to ambient pressure sensor (electrical, rationality and offset) No error on upstream DPF temperature sensor (electrical and rationality) No error on air flow meter No error on atmospheric pressure sensor Exhaust gas volume flow Engine speed (Engine coolant temperature OR OBD Coolant Enable Criteria) Pipe Icing Risk Low	1.00 EGP_DiffPresSnsrRatFlt EGT_SnsrDPF_UpFlt MAF_MAF_SnsrFA OR MAF_MAF_SnsrTFTKO AmbPresDfltdStatus= CeAAPR_e_AmbPresNotDfltd > 65.00 l/s > 800.00 rpm > 69.00 °C OR = TRUE) = TRUE	120.00 failures over 150.00 samples function task: 100 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Catalyst Temperature Too Low During Regeneration	P244C	This diagnosis detects an Injector or a catalyst that is malfunctioning or losses in the exhaust gas system	The DTC is set when: Counter of subsequent Interrupted regeneration The interrupted regeneration counter increases only when the interruption has caused by: - Regeneration process interrupted due to maximum regeneration time elapsed. Maximum time allowed to complete DPF regeneration expired (according to regeneration mission profile) OR - Post injection pulses not enabled in time.Time to release POST injection is expired (according to regeneration mission profile) OR - Regeneration Steady phase not entered in time Time to reach DPF regeneration steady state condition is expired (according to regeneration mission profile) The counter is reset when	> 0.00 > **Maximum allowed time to complete regeneration** > **Maximum allowed time to release post injections for regeneration** > **Maximum allowed time to reach steady state for regeneration**	Test enabled by calibration (TRUE--> enable FALSE --> disable)	1.00	No debounce function task: 100 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			a successful DPF regeneration occurs					

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate filter pressure sensor offset monitoring - 18.19	P2452	This diagnosis verify if the pressure at the DPF inlet measured at the beginning of the driving cycle (when engine is not running), is too big (sensor offset too big)	|Average DPF pressure @beginning of driving cycle|	10 [%]	Test enabled by calibration and with key on and with minimum engine-off time and with Minimum engine not No fault on engine off Timer and with No fault on exhaust gas pressure sensor (electrical, quick change and stuck in range in and logic)	1 [Boolean] ==TRUE > 10.00 [sec] > 0.02 [sec] **EMD_EngModeNotRunTmErr** EGP_DiffPresQckChgFlt and with EGP_DiffPresSnsrCktFlt and with EGP_DiffPresSnsrRatFlt	No debounce Function task: 12.5 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate filter pressure sensor plausibility monitoring - 18.19	P2453	Case1: This diagnosis verify if the current value of the flow resistace is almost equal to the average value of the flow resistance Case2: This diagnosis verify if the pressure at the DPF inlet doesn't change when it is supposed to change (when moving from one engine operating point to another)	|Flow resistance filtered – Average flow resistance|>	> 0.00 [KPa*s/m^3]	Test enabled by calibration and with Engine running and with Engine cranking and with key on and with Battery voltage and with No fault on exhaust gas pressure sensor (electrical, offset, quick change and stuck in range in and logic) and with No fault on air flow meter in and logic and with No fault on DPF Upstream temperature	0 [Boolean] == TRUE == FALSE ==TRUE > 11.00 [V] EGP_DiffPresOfstTFTKO and with EGP_DiffPresQckChgFlt and with EGP_DiffPresSnsrCktFlt and with EGP_DiffPresStkFltPresent MAF_SensorFA and with MAF_SensorTFTKO EGT_SnsrDPF_UpFA and with	30 fail samples out of 50 samples Function task: 12.5 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					sensor (electrical, rationality, quick change and stuck in range in and logic) and with **System in stationary conditions:** - Fuel request and with - Engine speed and with - Air mass quantity per cylinder and with - Air mass quantity per cylinder and with - Deactivation of Flow resistance calculation	EGT_SnsrDPF_UpTFTKO <= 1.00 [mm^3] <= 10.00 [rpm] <= 10.00 [mg] > 0.00 [mg] == FALSE		
			DPF pressure variation	<= 0.80 [%]	Test enabled by calibration and with Engine running and with No fault on exhaust gas pressure sensor (electrical, plausibility,	1 == TRUE EGP_DiffPresOfstTFTKO and with EGP_DiffPresQckChgFlt	7 fail samples out of 10 samples Function task: 12.5 ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					offset and quick change in and logic) and with Engine speed variation greater and with Fuel quantity variation greater	and with EGP_DiffPresSnsrCktFlt and with EGP_DiffPresStkFltPresent > 900.00 [rpm/s] > 60.00 [l/s]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate filter pressure sensor out of range monitoring Low - 18.19	P2454	Controller specific output driver circuit diagnoses the relative to ambient pressure sensor signal s high sided driver for a short to ground failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	< 3.00 [%]	Test enabled by calibration and with Engine running and with Engine cranking and with key on and with Battery voltage	1 [Boolean] == TRUE == FALSE ==TRUE > 11.00 [V]	160 fail samples out of 250 samples Function task: 12.5 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate filter pressure sensor out of range monitoring High - 18.19	P2455	Controller specific output driver circuit diagnoses the relative to ambient pressure sensor signal high sided driver for a short to power failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds. Controller specific output driver circuit diagnoses the relative to ambient pressure sensor signal high sided driver for an open circuit failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	> 97.00 %	Test enabled by calibration and with Engine running and with Engine cranking and with key on and with Battery voltage	1 [Boolean] == TRUE Function task: 12.5 ms == FALSE ==TRUE > 11.00 [V]	160 fail samples out of 250 samples	Type A, 1 Trips
			Voltage measurement outside of controller specific acceptable range during driver on state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	> 97.00 %	Test enabled by calibration and with Engine running and with Engine cranking and with key on and with Battery voltage	1 [Boolean] == TRUE == FALSE ==TRUE > 11.00 [V]	160 fail samples out of 250 samples Function task: 12.5 ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate filter pressure sensor quick change monitoring - 18.19	P2456	This diagnosis verify if the signal (difference between two consecutive signal samples) variation is too big	|DPF pressure raw signal - DPFpressure raw signal old|	> 20.00 %	Test enabled by calibration and with Engine running and with Engine cranking and with key on and with Battery voltage and with No electrical fault on exhaust gas pressure sensor	1 [Boolean] == TRUE == FALSE == TRUE > 11.00 [V] EGP_DiffPresSnsrCktFlt	36 fail samples out of 240 samples Function task: 12.5 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation Cooling System Performance (OBDII market only) (non-MDE applications, from SW 18.xx.136 included)	P2457	This monitor checks the HP EGR Cooler efficiency deterioration, that would cause vehicle's emissions to exceed specific emission levels.	HP EGR Cooler Efficiency (averaged over a calibrate-able cumulative transient time) is compared with a threshold. HP EGR Cooler efficiency is computed as the ratio between (HP EGR cooler upstream temperature - HP EGR cooler downstream temperature) and (HP EGR cooler upstream temperature - Engine coolant temperature).	< 75.00 [%]	Calibration on diagnostic enabling Diagnostic has not run in current driving cycle yet PT Relay voltage in range Engine is running or cranking HP EGR cooler upstream temperature in range Ambient Temperature Ambient pressure Air Control is Active Engine Coolant Temperature (OR OBD Coolant Enable Criteria), AND Engine Coolant Temperature HP EGR Cooler bypass	1.00 ==TRUE ==TRUE Powertrain relay voltage > 11.00 [V] ==TRUE > 300.00 [°C] < 800.00 [°C] >= -20.00 [°C] >= 69.60 [kPa] Refer to "Air Control Active" Free Form > 70.00 [°C] ==TRUE < 117.00 [°C] > 5.00 [s]	Test executed after 250.00 samples are collected and their average is computed functional task 100 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					not active for a time			
					Time after combustion mode change	> 0.00 [s]		
					HP EGR filtered flow in range	< **P2457: Maximum HP EGR filtered flow for HP EGR cooler efficiency monitor enabling** [g/s] > **P2457: Minimum HP EGR filtered flow for HP EGR cooler efficiency monitor enabling** [g/s]		
					for a time	>= **P2457: Minimum time for HP EGR cooler efficiency monitor enabling** [s]		
					HP EGR flow estimation is valid	EGR_VlvTotFlowNotValid ==FALSE		
					Engine speed in range	< 4,250.00 [rpm] > 1,250.00 [rpm]		
					No fault on HP EGR cooler upstream temperature sensor	CET_UPSS_FA==FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					No fault on HP EGR cooler downstream temperature sensor	CET_DNSS_FA==FALSE		
					No fault on Ambient Temperature sensor	OAT_PtEstFiltFA ==FALSE		
					No fault on ambient pressure sensor	AAP_AmbientAirPresDfltd ==FALSE		
					No fault on engine coolant temperature sensor	ECT_Sensor_FA ==FALSE		
					No fault on engine speed	CrankSensor_FA ==FALSE		
					No fault on HP EGR Cooler Bypass	CEB_ActrCktLoFA ==FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Particulate Filter Regeneration Frequency - 18.21	P2459	This diagnostic detects a too high DPF regeneration frequency due to inefficient combustion, inefficient regeneration, soot overestimated by models or leaks in the exhaust or the intake line. When a new regeneration is started, the diagnostic computes a ratio between the soot level estimated by the model that has triggered the regeneration and the soot level estimated by the Nominal Engine Out soot model, which gives information about the expected soot level in the DPF. If the ratio is greater than a threshold, the diagnostic will report a fail. In case the regeneration is started based on miles travelled or time passed since last regeneration, the diagnostic will always report a pass.	When the regeneration is started by a soot model, the ratio between the soot level from that model and the soot level estimated by the Nominal Engine Out model is	>= 15.68	Test enabled by calibration A new DPF regeneration is started At least one successful regeneration has already occurred The previous regeneration was completed successfully The regeneration is requested at service Just before the new regeneration is started, Delta Pressure (Δp) soot model was valid for a time (*) Delta Pressure (Δp) plus Configurable Correction Block (CCB) soot model was valid for a fraction of the soot loading time (*) The Nominal Engine Out soot model was valid for a fraction of the soot loading time (**)	1.00 == TRUE == TRUE == TRUE == FALSE >= 0.00 s > 0.00 > 0.00	No time required, the malfunction criteria are evaluated as soon as a new DPF regeneration is started. Function task: 100 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Run/crank voltage Extreme transient engine operation was not detected, i.e. the delta fuel request during the soot loading time was (*) *Condition is ignored if the regeneration is not triggered by this model* (**) *Condition is ignored if the regeneration is started based on miles or time since last regeneration*	> 11.00 V < 300.00 mm3/s		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation Cooler Bypass Valve Control Circuit Low (ECB Vacuum)	P245C	This monitor checks if the HP EGR cooler bypass valve command is shorted to ground	Resistance to ground lower than a threshold (error information provided by HWIO)	< 0.5 [Ohm]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range Flap is requested in COOLING mode Shared High Side driver driven closed Diagnostic system enabled (no clear code or EOT in progress) HWIO error status different from INDETERMINATE status Key ON or engine running	== 1.00 > 11.00 [V]	24.00 fail counts out of 30.00 sample counts Function task: 100 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation Cooler Bypass Valve Control Circuit High (ECB Vacuum)	P245D	This monitor checks if the HP EGR cooler bypass valve command is shorted to power supply	Resistance to supply lower than a threshold (error information provided by HWIO)	< 0.5 [Ohm]	Test enabled by calibration System out of the cranking phase PT relay supply voltage in range Flap is requested in BYPASS mode Shared High Side driver driven closed Diagnostic system enabled (no clear code or EOT in progress) HWIO error status different from INDETERMINATE status Key ON or engine running	== 1.00 > 11.00 [V]	24.00 fail counts out of 30.00 sample counts Function task: 100 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Particulate Filter Soot Accumulation - (SW 18.19 and beyond)	P2463	This diagnostic detects a clogged DPF needing to be regeneration at service	Soot model based on Delta pressure measure plus configurable correction block (CCB)	> 130.00	Test enabled by calibration (TRUE--> enable FALSE --> disable) No fault on DPF pressure sensor (electrical, rationality and offset) No fault on upstream DPF temperature sensor (electrical and rationality) No fault on air flow meter No fault on atmospheric pressure sensor DPF status insootloading phase (no regeneration ongoing) Engine speed No fault on exhaust mass flow estimation Exhaust gas volume flow greater than a calibrateable threshold for more than a calibratable time Exhaust gas temperature at DPF inlet is between two thresholds for a minimum calibrateable time	1.00 EGP_DiffPresSnsrFlt EGT_SnsrDPF_UpFlt MAF_MAF_SnsrFAOR MAF_MAF_SnsrTFTKO AmbPresDfltdStatus = CeAAPR_e_AmbPresNotDfltd DPF_DPF_St== CeDPFR_e_SootLoading > 600.00 [rpm] EXF_TotExhDPF_UpFA > 30.00 [l/s] for > 2.00 [s] 100.00 [DegC] < Temperature < 400.00 [DegC] for > 0.00 [s]	120.00 failures over 150.00 samples function task: 100 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Engine Coolant Temperature Ambient Temperature Soot model based on Delta Pressure plus configurable correction block (CCB) is valid for a time Soot model based on Delta Pressure is always valid for a time Distance since last completed regeneration	> -256.00 [DegC] > -40.00 [DegC] > = 0.00 % of the soot loading >= 5.00 s > 0.00 km		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 4 out of range monitoring Low	P2470	Controller specific output driver circuit diagnoses t the exhaust gas temperature 4 (EGT4) sensor signal high sided driver for a short to ground failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	< 160 [Ohm]	Test enabled by calibration and with Engine cranking and with Battery voltage and with key on	1 [Boolean] == FALSE > 11.00 [V] == TRUE	10 fail samples over 20 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 4 out of range monitoring High	P2471	Controller specific output driver circuit diagnoses the exhaust gas temperature 4 (EGT4) signal high sided driver for a short to power failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds. Controller specific output driver circuit diagnoses the exhaust gas temperature 4 (EGT4) signal high sided driver for an open circuit failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	> 900 [Ohm]	Test enabled by calibration and with Engine cranking and with Battery voltage and with key on	1 [Boolean] == FALSE > 11.00 [V] == TRUE	10 fail samples over 20 samples Function task: 100ms	Type A, 1 Trips
			Voltage measurement outside of controller specific acceptable range during driver on state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	> 900 [Ohm]	Test enabled by calibration and with Engine cranking and with Battery voltage and with key on	1 [Boolean] == FALSE > 11.00 [V] == TRUE	10 fail samples over 20 samples Function task: 100ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 4 quick change monitoring	P2472	This diagnosis verify if the EGT4 temperature sensor signal (difference between two consecutive signal samples) variation is too big	|EGT4output reistance - EGT4 output resistance old|	> 10.00 [Ohm]	Test enabled by calibration and with Engine running and with Engine cranking and with Battery voltage and with key on and with No electrical faults on EGT4 sensorin and logic	1 [Boolean] == TRUE == FALSE > 11.00 [V] == TRUE EGT_ExhGas4_TFTKO and with EGT_ExhGas4_FA	20 fail samples out of 40 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 5 out of range monitoring Low	P2481	Controller specific output driver circuit diagnoses t the exhaust gas temperature 5 (EGT5) sensor signal high sided driver for a short to ground failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to ground failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to ground.	< 160 [Ohm]	Test enabled by calibration (TRUE--> enable FALSE --> disable) and with Engine cranking and with Battery voltage and with key on	1 [Boolean] == FALSE > 11.00 [V] == TRUE	10 fail samples over 20 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 5 out of range monitoring High	P2482	Controller specific output driver circuit diagnoses the exhaust gas temperature 5 (EGT5) signal high sided driver for a short to power failure when the output is powered off by comparing a voltage measurement to controller specific voltage thresholds. Controller specific output driver circuit diagnoses the exhaust gas temperature 5 (EGT5) signal high sided driver for an open circuit failure when the output is powered on by comparing a voltage measurement to controller specific voltage thresholds.	Voltage measurement outside of controller specific acceptable range during driver on state indicates short to power failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for a short to power.	> 900 [Ohm]	Test enabled by calibration and with Engine cranking and with Battery voltage and with key on	1 [Boolean] == FALSE > 11.00 [V] == TRUE	10 fail samples over 20 samples Function task: 100ms	Type A, 1 Trips
			Voltage measurement outside of controller specific acceptable range during driver on state indicates open circuit failure. Controller specific output driver circuit voltage thresholds are set to meet the following controller specification for an open circuit.	> 900 [Ohm]	Test enabled by calibration and with Engine cranking and with Battery voltage and with key on	1 [Boolean] == FALSE > 11.00 [V] == TRUE	10 fail samples over 20 samples Function task: 100ms	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust gas temperature sensor (EGT) 5 quick change monitoring	P2484	This diagnosis verify if the EGT5 temperature sensor signal (difference between two consecutive signal samples) variation is too big	|EGT5 output reistance - EGT5 output resistance old|	> 10.00 [Ohm]	Test enabled by calibration and with Engine running and with Engine cranking and with Battery voltage and with key on and with No electrical faults on EGT1sensorin and logic	1 [Boolean] == TRUE == FALSE > 11.00 [V] == TRUE EGT_ExhGas5_TFTKO and with EGT_ExhGas5_FA	20 fail samples out of 40 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Closed Loop DPF Regeneration Control At Limit - Temperature Too Low	P24A0	HC Injector Control Temperature Deviation diagnostic monitors the exhaust gas temperature Upstream the DPF (EGT4) to determine whether the temperature deviation between the control setpoint and the temperature read by the sensor is within a prescribed deviation range. Temperature deviation diagnostic shall diagnose a too low temperature, that means a Positive temperature deviation temperature. The diagnosis runs during regeneration mode and when the temperature closed loop is actived. The monitoring is divided into 2 logics, in particular the DPF warm up state logic, that has only the Positive deviation monitoring, and the DPF steady state logic, that has both deviation monitoring.	**Low Temperature monitoring (Positive Deviation):** Temperature DPF Upstream control setpoint - DPF upstream sensor reading (EGT4)	> 100.00 degC	Test shall be enabled by calibratable flag Regeneration state in warm up DPF Mode HCI temperature closed loop control shall be enabled Battery voltage No fault on exhaust mass flow No Fault on DPF upstream temperature sensor Temperature deviation monitoring shall be enabled by a boolean flag. The boolean flag shall be the output of a map function of engine speed and fuel request Exhaust mass flow AND	1.00 [Boolean] DPF_DPF_St == Warm_Up EGT_HC_CL_Enbl [Boolean] > 11.00 [V] EXM_TurbFlowNotValid [Boolean] EGT_SnsrDPF_UpFlt [Boolean] **EnginePointEnable_HC_TempDeviation** [Boolean] < 120.00 [g/s]	1,200.00 fail samples out of 1,500.00 samples Function task: 100 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Exhaust mass flow	> 8.00 [g/s]		
					Filtered Exhaust mass flow variation (absolute value)	< 100.00 [g/s]		
					The system shall not be in cut off for a calibratable timer.	< 30.00 [sec]		
					All the above enabling conditions met for at least a calibratable timer	> 10.00 [sec]		
			Low Temperature monitoring (Positive Deviation): Temperature DPF Upstream control setpoint - DPF upstream sensor reading (EGT4)	> 100.00 degC	Test shall be enabled by calibratable flag	1.00 [Boolean]	1,200.00 fail samples out of 1,500.00 samples Function task: 100ms	
					Regeneration state in Steady state DPF Mode	DPF_DPF_St== Steady_state		
					HCl temperature closed loop control shall be enabled	EGT_HC_CL_Enbl [Boolean]		
					Battery voltage	> 11.00 [V]		
					No fault on exhaust mass flow	EXM_TurbFlowNotValid [Boolean]		
					No Fault on DPF upstream temperature sensor	EGT_SnsrDPF_UpFlt [Boolean]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Temperature deviation monitoring shall be enabled by a boolean flag. The boolean flag shall be the output of a map function of engine speed and fuel request Exhaust mass flow AND Exhaust mass flow Filtered Exhaust mass flow variation (absolute value) The system shall not be in cut off for a calibratable timer. All the above enabling conditions met for at least a calibratable timer	**EnginePointEnable_HC_TempDeviation** [Boolean] < 120.00 [g/s] > 8.00 [g/s] < 100.00 [g/s] < 30.00 [sec] > 10.00 [sec]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Closed Loop DPF Regeneration Control At Limit - Temperature Too High	P24A1	HC Injector Control Temperature Deviation diagnostic monitors the exhaust gas temperature Upstream the DPF (EGT4) to determine whether the temperature deviation between the control setpoint and the temperature read by the sensoris within a prescribed deviation range. Temperature deviation diagnostic shall diagnose a too high temperature, that means a Negative temperature deviation temperature. The diagnosis runs during regeneration mode and when the temperature closed loop is actived. The monitoring runs only in DPF steady state logic	**High Temperature monitoring (Negative Deviation):** Temperature DPF Upstream control setpoint - DPF upstream sensor reading (EGT4)	< -100.00 degC	Test shall be enabled by calibratable flag Regen eration state in Steady state DPF Mode HCI temperature closed loop control shall be enabled Battery voltage No fault on exhaust mass flow No Fault on DPF upstream temperature sensor Temperature deviation monitoring shall be enabled by a boolean flag. The boolean flag shall be the output of a map function of engine speed and fuel request Exhaust mass flow AND	1.00 [Boolean] DPF_DPF_St== Steady_state EGT_HC_CL_Enbl [Boolean] > 11.00 [V] EXM_TurbFlowNotValid [Boolean] EGT_SnsrDPF_UpFlt [Boolean] **EnginePointEnable_HC_ TempDeviation** [Boolean] < 120.00 [g/s] > 8.00 [g/s] < 100.00 [g/s]	1,200.00 fail samples out of 1,500.00 samples Function task: 100ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Exhaust mass flow Filtered Exhaust mass flow variation (absolute value) The system shall not be in cut off for a calibratable timer. All the above enabling conditions met for at least a calibratable timer	< 30.00 [sec] > 10.00 [sec]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Exhaust Gas Recirculation Cooler Bypass Valve Control Stuck (ECB Vacuum)	P24A5	This monitor check if the HP EGR Cooler Bypass is mechanically stuck in bypass or cooling mode.	Gradient temperature downstream HP EGR cooler bypass when the HP EGR cooler bypass flap is moved from cooling to bypass and from bypass to cooling position < low threshold. Each of those phases is averaged over a calibration number of samples (see the "Time Required" column)	< **P24A5: Gradient Temperature Threshold** [°C]	Diagnosis is enabled by calibration Engine speed Vehicle speed Low-pass filtered HP EGR valve total flow Air Control Active Engine Coolant Temperature Combustion Mode selected by calibration and active for a minimum time Fuel request	== 1.00 >= 1,250.00 [rpm] < 2,250.00 [rpm] >= 10.00 [kph] < 128.00 [kph] >= **P24A5: Minimum EGR flow** [mg/s] < **P24A5: Maximum EGR flow** [mg/s] Refer to "Air Control Active" Free Form >= 70.00 [°C] < 117.00 [°C] **P24A5: Combustion mode enabling table** > 20.00 [s] >= 10.00 [mm^3] < 60.00 [mm^3]	Test is executed after 5.00 + 5.00 + 5.00 sample counts Function task: 100 ms	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Fuel gradient	>= -20.00 [mm^3] < 10.00 [mm^3]		
					Gradient (absolute value) of filtered upstream HP EGR cooler temperature, with hysteresis	< 8.00 [°C/s] (ENABLE) > 12.00 [°C/s] (DISABLE)		
					Gradient (absolute value) of filtered engine speed, with hysteresis	< 100.00 [rpm/s] (ENABLE) > 200.00 [rpm/s] (DISABLE)		
					Gradient (absolute value) of filtered vehicle speed, with hysteresis	< 950.00 [m/s^2] (ENABLE) > 1,000.00 [m/s^2] (DISABLE)		
					Gradient (absolute value) of filtered HP EGR flow, with hysteresis	< 6.50 [g/s^2] (ENABLE) > 7.00 [g/s^2] (DISABLE)		
					HP EGR cooler upstream temperature	>= **P24A5: Minimum upstream EGR temperature** [°C] < **P24A5: Maximum upstream EGR temperature** [°C]		
					Outside air temperature			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					HP EGR cooler bypass valve position is steady for a minimum time	>= -9.00 [°C] > 4.55 [s]		
					Diagnostic system enabled (no clear code or EOT in progress)	== TRUE		
					No faults detected on vehicle speed sensor	VehicleSpeedSensor_FA ==FALSE		
					No faults detected on engine coolant temperature sensor	ECT_Sensor_FA=FALSE		
					No faults detected on downstream HP EGR Cooler temperature sensor	CET_DNSS_FA==FALSE		
					No faults detected on upstream HP EGR Cooler temperature sensor	CET_UPSS_FA==FALSE		
					No faults detected on HP EGR Cooler Bypass actuator	CEB_ActrCktFA==FALSE		
					No faults detected on HP EGR valve	EGR_PstnDvtnFA ==FALSE		
					No faults detected on Outside air temperature sensor			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						OAT_PtEstFiltFA ==FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Circuit Low	P24B0	This diagnosis detects an open circuit on the soot sensor electrode signal or a cracked electrode	Soot Sensor Electrode raw current 1 AND Soot Soot Electrode raw current measured at setpoint temperature 1 - Soot Soot Electrode raw current measured at setpoint temperature 2	< 2.00 A < 0.09 A	Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Key is turned on No Electrical faults present on Soot Sensor Soot Sensor is in regeneration phase Soot Sensor temperature Soot Sensor Electrode current measurement enabled Transmission fault with sensor control unit not present	> 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(SOT_ElecIFlt) 560.00 < T < 800.00 °C NOT(P30BC)	No time debounce	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Circuit High	P24B1	This diagnosis detects a short to power the soot sensor electrode signal	Diagnosis executed in Soot Sensor Control Unit: Soot Sensor Electrode supply voltage (measured ADC voltage for electrode current)	> 4.1 V	Soot Sensor Control Unit conditions: no conditions ECU conditions: Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Key is turned on Engine not in cranking mode Fault not active on undervoltage for Soot Sensor Control Unit supply Soot sensor is not in regeneration status	 > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0)	Time counter: 10.00 consecutive failures OR 18.00 failures out of 36.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Heater Control Circuit/Open	P24B3	This diagnosis detects an open circuit on the soot sensor heater line	Diagnosis executed in Soot Sensor Control Unit: Soot Sensor Heater current	I < 0.5 A OR I > 15 A	Soot Sensor Control Unit conditions: Soot Sensor Heater Commanded on, i.e., heater duty cycle No Heater failures detected in the Sensor Control Unit ECU conditions: Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Fault not active on undervoltage for Soot Sensor Control Unit supply	 > 0 % NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0)	Time counter: 20.00 consecutive failures OR 38.00 failures out of 76.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Heater Control Circuit Low	P24B5	This diagnosis detects a short to ground on the soot sensor heater line	Diagnosis executed in Sensor Control Unit: Soot Sensor Heater current	I < 0.5 A OR I > 15 A	Soot Sensor Control Unit conditions: Soot Sensor Heater Commanded on, i.e., heater duty cycle No Soot Sensor Heater failures detected in the Sensor Control Unit ECU conditions: Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Fault not active on undervoltage for Soot Sensor Control Unit supply	 > 0 % NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0)	Time counter: 20.00 consecutive failures OR 38.00 failures out of 76.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Heater Control Circuit High	P24B6	This diagnosis detects a short to power on the soot sensor heater line	Diagnosis executed in Soot Sensor Control Unit: Soot Sensor Heater current OR Soot Sensor Heater switch output (off state) OR Soot Sensor Heater switch input (off state)	 > 0.2 A = 1 (for one of the last 5 measurements) = 1 (for one of the last 5 measurements)	Soot Sensor Control Unit conditions: Soot Sensor Heater Off ECU conditions: Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Key is turned on Engine not in cranking mode Fault not active on undervoltage for Soot Sensor Control Unit supply	 > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(P24D0)	Time counter: 10.00 consecutive failures OR 18.00 failures out of 36.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Diesel Particulate Matter Sensor Temperature Circuit Performance	P24C7	This diagnosis detects a soot sensor removed from the exhaust line, a soot sensor temperature sensor damaged or a possible parassitic resistance on the wiring harness between the soot sensor heater and the soot sensor control unit.	The absolute value of the difference between the Soot Sensor Electrode and the electrode temperature model	> 80.00 °C	Key is turned on Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Engine in running mode No electrical fault detected on Soot Sensor Soot Sensor heater is not commanded Soot Sensor is in measurement operating status Exhaust gas temperature model is valid	 > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(SOT_ElecIFlt) SOT_ExhTempSootSnsrVld AND SOT_TotExhSootSnsrVld AND NOT(OAT_PtEstFiltFA) AND AmbPresDfltdStatus = CeAAPR_e_AmbPresNotDfltd AND NOT (VehicleSpeedSensor_FA	Time counter: 200.00 failures out of 255.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						)		
					Exhaust gas temperature model is reliable, i.e.:	> 55.00 kPa		
					(Ambient air pressure	> -20.00 °C		
						> 50.00 mg/s		
					Ambient air temperature	> 300.00 s		
						OR		
					Exhaust gas volumetric flow at soot sensor	> 80.00 °C		
						> 0.00 °C		
					)			
					Time after sensor regeneration	NOT(P30BC)		
					Temperature estimated by the sensor probe temperature model - Electrode temperature			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					Temperature estimated by the sensor probe temperature model - Outside air temperature Transmission fault with sensor control unit not present			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Supply Voltage Circuit Low	P24D0	This diagnosis detects a short to ground of the soot sensor voltage supply line	Soot Sensor Control Unit supply voltage	< 9.00 V	Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor Key is turned on Engine not in cranking mode (The sensor is in regneration phase OR the time from a regeneration request)	> 11.00 NOT(SBR_RlyFA) NOT(U02A3) > 80.00	Time counter: 5.00 consecutive failures OR 8.00 failures out of 16.00 samples 100 ms/sample	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Particulate Matter Sensor Regeneration Incomplete	P24D1	This diagnosis detects a degradation of the soot sensor heater	the Soot Sensor Electrode Temperature is during the steady state soot sensor regeneration, for a consecutively time	<= (785.00 - 10.00)°C < 43.00 s	Key is turned on Ignition voltage in range Soot Sensor bus relay is commanded on No electrical fault active on Soot Sensor bus relay No faults of CAN communication loss with Soot Sensor No electrical fault detected on Soot Sensor Volumetric flow estimation is valid The power ratio timer the power ratio timer increments during the steady state of soot sensor regeneration, when the ratio between power demand and power available is (Soot sensor transitioned from regeneration to	 > 11.00 NOT(SBR_RlyFA) NOT(U02A3) NOT(SOT_ElecIFlt) SOT_TotExhSootSnsrVld AND SOT_ExhTempSootSnsrVld AND SOT_ExhPresSootSnsrVld < 5.00 s 0.00 <= r <= 1.00	no debouncing time	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
					measurement status OR the time of soot sensor steady state regeneration is) Transmission fault with sensor control unit not present	 >= 150.00 s NOT(P30BC)		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Turbocharger VGT A Position Sensor Circuit Low (analog position sensor)	P2564	This monitor checks if the VGT analog position sensor is out of electrical range low	analog position raw voltage < low threshold	< 3.00 [%]	Test enabled by calibration System out of the cranking phase Run Crank relay supply voltage in range Run crank active	== 1.00 > 11.00 [V]	200.00 fail counts out of 250.00 sample counts Function task: 6.25 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Turbocharger VGT A Position Sensor Circuit High (analog position sensor)	P2565	This monitor checks if the VGT analog position sensor is out of electrical range high	analog position raw voltage > high threshold	> 97.00 [%]	Test enabled by calibration System out of the cranking phase Run Crank relay supply voltage in range Run crank active	== 1.00 > 11.00 [V]	200.00 fail counts out of 250.00 sample counts Function task: 6.25 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Turbocharger VGT A Stuck Closed (Single and Two stage VGT DC Motor)	P2599	This monitor detects the VGT vanes mechanically stuck in a certain position different from their defaulted position (fully open) when the actuator is no longer driven (missing defaulted position)	Position after P0046 has set > threshold	> 20.00 [%]	P0046 is already set Waiting time after driver shut off > minimum threshold (needed for the spring to drive the valve in its defaulted position) VGT position closed loop control active (no faults present on VGT position sensor, VGT vanes, VGT position control deviation)	 > 2.00 [s] VGT_PstnSnsrFA ==FALSE VGT_ActCktFA==FALSE VGT_PstnCntrlFA ==FALSE	No debounce is present: DTC sets as soon as the error is present Function task: 6.25 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Pumping Current Trim Circuit Low Bank 1 Sensor 1 (SCR: NOx Sensor Downstream Turbine)	P2627	This DTC detects if O2 signal is lower than physical minimum value.	O2 signal lower than a minimum value	< -4.00 [%]	Engine running System voltage in range Sensor is fully operative Enabled in combustion mode No pending or confirmed DTC	 > 11.00 [V] OXY_NOx1_O2_RawNotRlb == FALSE refer to supporting table **KaOXYD_b_NOx1SigRn** (**gEnblCmbMode**) NOX_Snsr1_NotVld	Time counter: 200 failures out of 250 samples. Time task 25[ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2 Sensor Pumping Current Trim Circuit High Bank 1 Sensor 1 (SCR: NOx Sensor Downstream Turbine)	P2628	This DTC detects if O2 signal is higher than physical maximum value.	O2 signal higher than a maximum value	> 27.00 [%]	Engine running System voltage in range Sensor is fully operative Exhaust gas pressure No Exhaust Brake active i.e. intake manifold pressure No pending or confirmed DTCs	 > 11.00 [V] OXY_NOx1_O2_RawNotRlb == FALSE < 300.00 [kPa] < 1,000.00 [kPa] NOX_Snsr1_NotVld NOX_Snsr1_PresFlt (MAP_SensorFA AND MAP_SensorTFTKO)	Time counter: 100 failures out of 200 samples. Time task 25[ms]	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 1 Injector Data Incompatible	P268C	This DTC detects if the EIA (End of line Injector Adjustment) code for cylinder 1 has not been programmed. The diagnostic shall report test pass if the EIA code has been succesfully programmed, otherwise only report test fail if the MEC (Manufacturing Enable Counter) is zero.	Cylinder 1 EIA code not written via DID (DID $60).	N/A	Ignition ON Diagnosis enabled via calibration Manufacturer Enable Counter (MEC) == 0	1.00 [Boolean]	N/A	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 2 Injector Data Incompatible	P268D	This DTC detects if the EIA (End of line Injector Adjustment) code for cylinder 2 has not been programmed. The diagnostic shall report test pass if the EIA code has been succesfully programmed, otherwise only report test fail if the MEC (Manufacturing Enable Counter) is zero.	Cylinder 2 EIA code not written via DID (DID $61).	N/A	Ignition ON Diagnosis enabled via calibration Manufacturer Enable Counter (MEC) == 0	1.00 [Boolean]	N/A	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 3 Injector Data Incompatible	P268E	This DTC detects if the EIA (End of line Injector Adjustment) code for cylinder 3 has not been programmed. The diagnostic shall report test pass if the EIA code has been succesfully programmed, otherwise only report test fail if the MEC (Manufacturing Enable Counter) is zero.	Cylinder 3 EIA code not written via DID (DID $62).	N/A	Ignition ON Diagnosis enabled via calibration Manufacturer Enable Counter (MEC) == 0	1.00 [Boolean]	N/A	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Cylinder 4 Injector Data Incompatible	P268F	This DTC detects if the EIA (End of line Injector Adjustment) code for cylinder 4 has not been programmed. The diagnostic shall report test pass if the EIA code has been succesfully programmed, otherwise only report test fail if the MEC (Manufacturing Enable Counter) is zero.	Cylinder 4 EIA code not written via DID (DID $63).	N/A	Ignition ON Diagnosis enabled via calibration Manufacturer Enable Counter (MEC) == 0	 1.00 [Boolean]	N/A	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Circuit Range/ Performance Bank 1 Sensor 1 (SCR: NOx Sensor Downstream Turbine)	P2A00	This DTC aims to detect a drift of measured O2 value (A) from an estimated concentration (B) when the latter can be considered stable during full load condition.	EWMA filtered error (A - B) in full load condition is out of plausible range	> 2.50 [%] < -4.70 [%]	Engine running System voltage in range Sensor is fully operative Enabled in combustion mode (No After injection release AND Boolean Flag used to enable After injection status is TRUE) Engine coolant temperature measure in range No pending or confirmed DTCs	 > 11.00 [V] OXY_NOx1_O2_RawNotRlb == FALSE refer to supporting table (**KaOXYD_b_NOx1LoadChkCmbModeEnbl**) 1 [boolean] > 0.00 [°C] NOX_Snsr1_NotVld NOX_Snsr1_PresFlt OXY_NOx1SignRngChkFlt OXY_O2_NOx1PlausMdlFlt FHP_InjLeakageFA (MAF_MAF_SnsrFA AND MAF_MAF_SnsrTFTKO) EGR_VlvTotFlowFA	Once per trip Note: if EWMA Fast Initial Response is active OR EWMA Rapid Response is active than multiple tests per trip are allowed.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
						LPE_PstnShtOffReqFA (ECT_Sensor_FA AND ECT_Sensor_TFTKO)		
					Stable fuel load condition has been reached i.e. following conditions are met for a calibrateable time: a. Engine speed in operating range b. EGR mass flow c. LPE position e. Injected fuel quantity in operating range f. Air mass per cylinder in operating range g. Estimated O2 concentration in range Estimated O2 concentration stable i.e. difference between initial and actual value Air mass flown since fuel cut-off condition	> 1.00 [s] > 1,500 [rpm] < 2,000 [rpm] < 1,000.00 [mg] < 0.00 [%] > 40.00 [mm^3] < 80.00 [mm^3] > 500.00 [mg] < 1,500.00 [mg] < 21.00 [%] > 0.00 [%] < 0.50 [%] > 20.00 [g]		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
O2S Circuit Range/ Performance Bank 1 Sensor 2 (SCR: NOx Sensor Downstream Turbine)	P2A01	This DTC aims to detect a drift of Sensor 2 O2 measured value (A) from Sensor 1 O2 measured value (B) when the latter can be considered stable during full load condition.	EWMA filtered error (A - B) in full load condition is out of plausible range	> 1.40 [%] < -1.70 [%]	Engine running System voltage in range Sensor is fully operative Sensor 1 is fully operative No pending or confirmed DTCs DTC P2A00 is running Air mass flown since P2A00 is enabled	 > 11.00 [V] OXY_O2_NOx2_PresCmpNotRlb == FALSE OXY_O2_NOx1_PresCmpNotRlb == FALSE NOX_Snsr2_NotVld NOX_Snsr2_PresFlt OXY_NOx2SignRngChkFlt OXY_NOx1_O2_Flt (MAF_SensorFA AND MAF_SensorTFTKO) (see P2A00 Fault code) > 60.00 [g]	EWMA filtering: multiple tests per trip are allowed.	Type B, 2 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Lost Communication With Turbocharger/ Supercharger Boost Control "A" Position Sensor	U0656	This monitor checks if the VGT position sensor protocol is out of range low, out of range high or has performance problems	(HWIO counter of valid VGT SENT position indications no longer updated > threshold (age error = TRUE) AND HWIO VGT SENT position protocol status) OR (HWIO time counter since last valid VGT SENT position was transmitted > threshold (age error = TRUE) AND HWIO VGT SENT position protocol status) OR (HWIO message fault on VGT SENT position == TRUE OR	 > 2.50 [ms] AND == STEADY LOW > 2.50 [ms] AND == STEADY HIGH message error==TRUE OR	Test enabled by calibration VGT SENT position sensor present System out of the cranking phase PT relay supply voltage in range Diagnostic system enabled (no clear code or EOT in progress)	== 1.00 == 1.00 > 11.00 [V]	200.00 fail counts out of 250.00 sample counts Function task: 6.25 ms	Type A, 1 Trips

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
			(number of VGT SENT position counters has been updated AND HWIO time counter since last valid VGT SENT position was transmitted > threshold (age error = TRUE)))	---------- AND > 2.50 [ms]				

Initial Supporting table - DPF_CCB_SootThrsh

Description:

y/x	1,000	1,500	2,000	2,250	2,500	3,000	3,500	4,000	4,500
0	0	0	0	0	0	0	0	0	0
10	0	0	0	0	0	0	0	0	0
15	0	0	0	0	0	0	0	0	0
20	0	0	0	0	0	0	0	0	0
25	0	0	0	0	0	0	0	0	0
35	0	0	0	0	0	0	0	0	0
50	0	0	0	0	0	0	0	0	0
70	0	0	0	0	0	0	0	0	0

Initial Supporting table - DPF_EffRgnHysHi

Description:

y/x	0	7	10	20	40	60	80	100	120	140	160	180	200	220	240
0	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
5	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
10	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
15	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
20	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
25	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
30	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
35	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
40	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
45	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
50	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
55	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
60	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
65	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
70	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
75	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
80	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
90	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
100	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535

Initial Supporting table - DPF_EffRgnHysLo

Description:

y/x	0	7	10	20	40	60	80	100	120	140	160	180	200	220	240
0	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
5	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
10	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
15	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
20	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
25	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
30	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
35	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
40	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
45	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
50	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
55	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
60	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
65	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
70	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
75	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
80	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
90	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
100	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520

Initial Supporting table - DPF_ResistFlowDsblHi

Description:

y/x	600	800	1,200	1,600	2,000	2,400	2,800	3,200
1	130	130	130	130	130	130	130	130

Initial Supporting table - DPF_ResistFlowDsblLo

Description:

y/x	600	800	1,200	1,600	2,000	2,400	2,800	3,200
1	0	0	0	0	0	0	0	0

Initial Supporting table - DPF_SootThrshCrtn

Description:

y/x	10	20	30	40	50	60	70	80
1	1	1	1	1	1	1	1	1

Initial Supporting table - EGT_FuelReqHysHiThrsh_DPF

Description:

y/x	1,000	1,200	1,500	2,000	2,500	3,000	3,500	4,000
1	-2	-2	-2	-2	-2	-2	-2	-2

Initial Supporting table - EGT_FuelReqHysLoThrsh_DPF

Description:

y/x	1,000	1,200	1,500	2,000	2,500	3,000	3,500	4,000
1	-2	-2	-2	-2	-2	-2	-2	-2

Initial Supporting table - EGT_FuelReqMaxThreshold

Description:

y/x	800	1,000	1,500	2,000	2,500	3,000	3,500	4,000
1	0	0	0	0	0	0	0	0

Initial Supporting table - EGT_FuelReqMinThrsh

Description:

y/x	800	1,000	1,500	2,000	2,500	3,000	3,500	4,000
1	0	0	0	0	0	0	0	0

Initial Supporting table - EGT1 DynChk EngPtEnbl

Description: Contains the engine speed and fuel rate enablments for EGT1 Dynamic Check.

y/x	15.9	16.0	20.0	40.0	60.0	80.0	80.1
1,249.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
1,250.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
2,000.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
3,000.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
3,999.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
4,000.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

Initial Supporting table - EGT2 DynChk EngPtEnbl

Description: Contains the engine speed and fuel rate enablments for EGT2 Dynamic Check.

y/x	0.0	10.0	20.0	40.0	60.0	80.0	120.0
1,249.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
1,250.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
2,000.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
3,000.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
3,999.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
4,000.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

Initial Supporting table - EGT3 DynChk EngPtEnbl

Description: Contains the engine speed and fuel rate enablments for EGT3 Dynamic Check.

y/x	0.0	16.0	20.0	40.0	60.0	80.0	120.0
1,249.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
1,250.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
2,000.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
3,000.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
3,999.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
4,000.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

Initial Supporting table - EGT4 DynChk EngPtEnbl

Description: Contains the engine speed and fuel rate enablments for EGT4 Dynamic Check.

y/x	0.0	15.0	20.0	40.0	60.0	80.0	120.0
800.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
1,000.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
1,500.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
2,000.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
2,500.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
3,200.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

Initial Supporting table - EGT5 DynChk EngPtEnbl

Description: Contains the engine speed and fuel rate enablments for EGT5 Dynamic Check.

y/x	0.0	15.0	20.0	40.0	60.0	80.0	120.0
800.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
1,000.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
1,500.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
2,000.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
2,500.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
3,200.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

Initial Supporting table - EnginePointEnable_DPF_TempDeviation

Description:

y/x	980	1,000	2,000	2,500	3,000	3,010	4,000	4,200
0	0	0	0	0	0	0	0	0
5	0	1	1	1	1	0	0	0
10	0	1	1	1	1	0	0	0
15	0	1	1	1	1	0	0	0
20	0	1	1	1	1	0	0	0
30	0	1	1	1	1	0	0	0
40	0	1	1	1	1	0	0	0
60	0	1	1	1	1	0	0	0
61	0	0	0	0	0	0	0	0

Initial Supporting table - EnginePointEnable_HC_TempDeviation

Description:

y/x	980	1,000	1,100	1,200	1,800	2,000	2,800	3,500
0	0	0	0	0	0	0	0	0
8	0	1	1	1	1	1	1	1
10	0	1	1	1	1	1	1	1
15	0	1	1	1	1	1	1	1
20	0	1	1	1	1	1	1	1
50	0	1	1	1	1	1	1	1
80	0	1	1	1	1	1	1	1
120	0	1	1	1	1	1	1	1
140	0	1	1	1	1	1	1	1

Initial Supporting table - Inrush_current_profile

Description: This table shows the Inrush current profile to detect a ground short condition

y/x	1	2
1	Time [s]	Irms [A]
2	0	0
3	0	65
4	0	50
5	0	45
6	0	42
7	0	38
8	1	35
9	1	33
10	1	32
11	1	31
12	1	31
13	1	30
14	1	29
15	1	28
16	1	26
17	1	25
18	2	24
19	2	23
20	2	23
21	2	22
22	2	22
23	2	21
24	2	21
25	2	21
26	2	21
27	2	21
28	3	21
29	3	20
30	3	20
31	3	20
32	3	20
33	3	20
34	3	20
35	3	20

Initial Supporting table - Inrush_current_profile

36	3	20
37	3	20
38	4	20
39	4	20
40	4	20
41	4	20
42	4	20
43	4	20
44	4	20
45	4	20
46	4	20
47	4	20
48	5	20
49	5	20
50	5	20
51	5	20
52	5	20
53	5	20
54	6	15
55	7	13
56	8	13
57	9	13
58	10	13
59	11	13
60	12	13
61	13	13
62	14	13
63	15	13
64	16	13
65	17	13
66	18	13
67	20	13

Initial Supporting table - KaFADC_b_CB_EnblCMBR

Description: Specifies, for the specific combustion mode, if enable or not CB

KaFADC_b_CB_EnblCMBR - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	1	0	0	0

KaFADC_b_CB_EnblCMBR - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

KaFADC_b_CB_EnblCMBR - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	1	1	0	0	0

KaFADC_b_CB_EnblCMBR - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	1	1	0	0	

Initial Supporting table - KaFADC_b_SQC_CWA_EnblLink

Description: Engine speed ranges to be learned with CWA before give a positive report to Zero Torque Coordinator.

y/x	0	1	2	3	4	5
1	0	0	0	0	0	0

Initial Supporting table - KaFADC_n_CB_EngSpdRngThrsh2

Description: Threshold 2 for engine speed range detection in the Cylinder Balancing (driveline-group dependent) [rpm]

Value Units: rpm

KaFADC_n_CB_EngSpdRngThrsh2 - Part 1

y/x	0	1	2	3	4	5	6	7	8	9	10
1	1,250	1,250	1,250	1,250	1,250	1,250	1,250	1,250	1,250	1,250	1,250

KaFADC_n_CB_EngSpdRngThrsh2 - Part 2

y/x	11	12	13	14	15	16	17	18	19	20	
1	1,250	1,250	1,250	1,250	1,250	1,250	1,250	1,250	1,250	1,250	

Initial Supporting table - KaFADC_n_CB_EngSpdRngThrsh3

Description: Threshold 3 for engine speed range detection in the Cylinder Balancing (driveline-group dependent) [rpm].

Value Units: rpm

KaFADC_n_CB_EngSpdRngThrsh3 - Part 1

y/x	0	1	2	3	4	5	6	7	8	9	10
1	1,200	1,200	1,200	1,200	1,200	1,200	1,200	1,200	1,200	1,200	1,200

KaFADC_n_CB_EngSpdRngThrsh3 - Part 2

y/x	11	12	13	14	15	16	17	18	19	20	
1	1,200	1,200	1,200	1,200	1,200	1,200	1,200	1,200	1,200	1,200	

Initial Supporting table - KaFADC_n_DFSA_EngSpdThrsh

Description: Threshold to evaluate the engine speed steady state, as function of the engaged gear

Value Units: rpm

y/x	0	1	2	3	4	5	6	7	8	9	10	11	12
1	5	5	5	5	5	5	5	5	5	5	5	5	5

Initial Supporting table - KaFADC_n_FSA_EngSpdThrsh

Description: Threshold to evaluate the engine speed steady state, as function of the engaged gear

Value Units: rpm

y/x	0	1	2	3	4	5	6	7	8	9	10	11	12
1	1	1	1	1	0	0	0	4	4	4	4	4	4

Initial Supporting table - KaFADC_n_SQC_HiThrshDelt

Description: Engine speed high threshold [rpm] delta for SQC actuators enable function of driveline group

Value Units: rpm

KaFADC_n_SQC_HiThrshDelt - Part 1				
y/x	CeFADR_e_CWA_DrvlnGrpNotAlwd	CeFADR_e_CWA_DrivelineGrp1	CeFADR_e_CWA_DrivelineGrp2	CeFADR_e_CWA_DrivelineGrp3
1	200	200	200	200

KaFADC_n_SQC_HiThrshDelt - Part 2				
y/x	CeFADR_e_CWA_DrivelineGrp4	CeFADR_e_CWA_DrivelineGrp5	CeFADR_e_CWA_DrivelineGrp6	CeFADR_e_CWA_DrivelineGrp7
1	200	200	200	200

KaFADC_n_SQC_HiThrshDelt - Part 3				
y/x	CeFADR_e_CWA_DrivelineGrp8	CeFADR_e_CWA_DrivelineGrp9	CeFADR_e_CWA_DrivelineGrp10	
1	200	200	200	

Initial Supporting table - KaFADC_p_SQA_LrnDelt

Description: Delta Rail Pressure allowed to enable SQA learning [MPa] function of nominal rail pressure setpoint defined for SQA.

Value Units: Mpa

y/x	0	1	2	3	4
1	5	5	5	5	5

Initial Supporting table - KaFADC_t_SQA_MaxAdptDeltET[us]

Description: Upper Energizing time limit for SQA [us] max authority function of rail pressure levels defined for SQA.

Value Units: us

y/x	0	1	2	3	4
1	199	138	90	82	0

Initial Supporting table - KaFADC_t_SQA_MinAdptDeltET[us]

Description: Lower Energizing time limit for SQA max authority [us] function of rail pressure levels defined for SQA.

Value Units: us

y/x	0	1	2	3	4
1	-174	-115	-138	-94	0

Initial Supporting table - KaOXYD_b_NOx1LoadChkCmbModeEnbl

Description: This array indicates what are the combustion mode in which Plausibility Diagnosis in Full Load condition is enabled

KaOXYD_b_NOx1LoadChkCmbModeEnbl - Part 1				
y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions
1	1	0	0	0
KaOXYD_b_NOx1LoadChkCmbModeEnbl - Part 2				
y/x	CeCMBR_e_LNT_DeNOx	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp
1	0	0	0	0
KaOXYD_b_NOx1LoadChkCmbModeEnbl - Part 3				
y/x	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2
1	0	0	0	0
KaOXYD_b_NOx1LoadChkCmbModeEnbl - Part 4				
y/x	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn	CeCMBR_e_HCS_DeHC_Drive
1	0	0	0	0
KaOXYD_b_NOx1LoadChkCmbModeEnbl - Part 5				
y/x	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	

Initial Supporting table - KaOXYD_b_NOx1OvrnChkCmbModeEnbl

Description: This array indicates what are the combustion mode in which Plausibility Diagnosis in Overrun condition is enabled

KaOXYD_b_NOx1OvrnChkCmbModeEnbl - Part 1				
y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions
1	1	0	0	0
KaOXYD_b_NOx1OvrnChkCmbModeEnbl - Part 2				
y/x	CeCMBR_e_LNT_DeNOx	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp
1	0	0	0	0
KaOXYD_b_NOx1OvrnChkCmbModeEnbl - Part 3				
y/x	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2
1	0	0	0	0
KaOXYD_b_NOx1OvrnChkCmbModeEnbl - Part 4				
y/x	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn	CeCMBR_e_HCS_DeHC_Drive
1	0	0	0	0
KaOXYD_b_NOx1OvrnChkCmbModeEnbl - Part 5				
y/x	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	

Initial Supporting table - KaOXYD_b_NOx1SigRngEnblCmbMode

Description: This array indicates what are the combustion mode in which Signal Range Diagnosis is enabled

KaOXYD_b_NOx1SigRngEnblCmbMode - Part 1				
y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions
1	1	0	0	0
KaOXYD_b_NOx1SigRngEnblCmbMode - Part 2				
y/x	CeCMBR_e_LNT_DeNOx	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp
1	0	0	0	1
KaOXYD_b_NOx1SigRngEnblCmbMode - Part 3				
y/x	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2
1	0	0	0	0
KaOXYD_b_NOx1SigRngEnblCmbMode - Part 4				
y/x	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn	CeCMBR_e_HCS_DeHC_Drive
1	0	0	0	0
KaOXYD_b_NOx1SigRngEnblCmbMode - Part 5				
y/x	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	

Initial Supporting table - KaOXYD_b_NOx2SigRngEnblCmbMode

Description: This array indicates what are the combustion mode in which Signal Range Diagnosis is enabled

KaOXYD_b_NOx2SigRngEnblCmbMode - Part 1				
y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions
1	1	0	0	0
KaOXYD_b_NOx2SigRngEnblCmbMode - Part 2				
y/x	CeCMBR_e_LNT_DeNOx	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp
1	0	0	0	1
KaOXYD_b_NOx2SigRngEnblCmbMode - Part 3				
y/x	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2
1	0	0	0	0
KaOXYD_b_NOx2SigRngEnblCmbMode - Part 4				
y/x	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn	CeCMBR_e_HCS_DeHC_Drive
1	0	0	0	0
KaOXYD_b_NOx2SigRngEnblCmbMode - Part 5				
y/x	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	

Initial Supporting table - KtFADC_p_SQA_MAP_HiThrsh

Description: Manifold Air Pressure High Threshold [kPa] to disable SQA Strategy function on Rail Pressure levels defined for SQA

Value Units: kPa

y/x	1,000	1,200	1,700	1,701	2,100
1	160	160	160	160	160

Initial Supporting table - KtFADC_V_CB_HiThrshFuelQnty

Description: Injected quantity high threshold to enable Cylinder Balancing control [mm^3]

Value Units: mm^3

y/x	655	750	1,000	1,250	1,500	1,750	2,000	2,250	2,500	3,000	3,500	4,000
1	0	40	50	60	70	80	90	90	90	80	45	0

Initial Supporting table - KtFADC_V_FSA_FuelMax

Description: Map used to define FSA maximum authority

Value Units: mm^3

y/x	10	20	30	40	50	60	70	80	90	100
800	11	12	14	17	20	23	24	26	27	29
1,000	12	13	15	17	20	23	24	26	27	29
1,250	13	14	16	18	21	24	24	26	27	29
1,500	13	15	17	19	22	24	25	27	28	30
1,750	13	15	17	20	23	25	26	28	29	31
2,000	13	15	17	20	23	26	27	29	30	31
2,250	13	15	17	20	23	26	28	30	31	32
2,500	13	15	17	20	23	26	28	30	31	33
2,750	13	15	17	20	23	26	28	30	31	33
3,000	13	15	17	20	23	26	28	30	31	33

Initial Supporting table - KtFADC_V_FSA_FuelMin

Description: Map used to define FSA minimum authority

Value Units: mm^3

y/x	10	20	30	40	50	60	70	80	90	100
800	-11	-12	-14	-17	-20	-23	-24	-26	-27	-29
1,000	-12	-13	-15	-17	-20	-23	-24	-26	-27	-29
1,250	-13	-14	-16	-18	-21	-24	-24	-26	-27	-29
1,500	-13	-15	-17	-19	-22	-24	-25	-27	-28	-30
1,750	-13	-15	-17	-20	-23	-25	-26	-28	-29	-31
2,000	-13	-15	-17	-20	-23	-26	-27	-29	-30	-31
2,250	-13	-15	-17	-20	-23	-26	-28	-30	-31	-32
2,500	-13	-15	-17	-20	-23	-26	-28	-30	-31	-33
2,750	-13	-15	-17	-20	-23	-26	-28	-30	-31	-33
3,000	-13	-15	-17	-20	-23	-26	-28	-30	-31	-33

Initial Supporting table - KtFADC_V_FSA_MaxFuelFall

Description: Upper bound of fuel quantity range to enable the FSA learning phase depending on the engine speed

Value Units: mm^3

y/x	510	511	1,000	1,600	1,800	2,000	2,400	3,200	3,600	4,000
1	0	65	65	100	100	100	100	100	100	100

Initial Supporting table - KtFADD_p_XSQA_MAP_HiThrsh

Description: Manifold Air Pressure High Threshold [kPa] to disable SQA Emission Correlated Monitoring function on Rail Pressure levels defined for SQA

Value Units: kPa

y/x	1,000	1,200	1,400	1,600	1,800
1	160	160	160	160	160

Initial Supporting table - KtFADD_Pct_SSQA_InjSuspConfLvl

Description: Calibration table to define the suspicious confidence level [%] function of current last raw Delta Energizing Time [us] and previous one [us]

Value Units: %

y/x	-100	-70	-51	-50	-20	0	20	50	51	70	100
-100	0	0	0	0	0	0	0	0	0	0	0
-70	0	0	0	0	0	0	0	0	0	0	0
-51	0	0	0	100	100	100	100	100	0	0	0
-50	0	0	0	100	100	100	100	100	0	0	0
0	0	0	0	100	100	100	100	100	0	0	0
50	0	0	0	100	100	100	100	100	0	0	0
51	0	0	0	0	0	0	0	0	0	0	0
70	0	0	0	0	0	0	0	0	0	0	0
100	0	0	0	0	0	0	0	0	0	0	0

Initial Supporting table - KtGLOD_U_VoltLoDelMax(KnGLOD_I_GP_Curr)

Description: Maximum delta voltage table data for low rationality error check.

y/x	0	4	8	12	16	20	24	28
1	5	5	5	5	5	5	5	5

Initial Supporting table - NOX_NOx2SelfTstEnblCmbMode

Description: Combustion mode dependent diag enable for Downstream NOx sensor selt-test monitoring

NOX_NOx2SelfTstEnblCmbMode - Part 1					
y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

NOX_NOx2SelfTstEnblCmbMode - Part 2					
y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

NOX_NOx2SelfTstEnblCmbMode - Part 3					
y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

NOX_NOx2SelfTstEnblCmbMode - Part 4					
y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - NOX_S1_OfstMntrEnblCmbMode

Description:

NOX_S1_OfstMntrEnblCmbMode - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

NOX_S1_OfstMntrEnblCmbMode - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	0	0	0

NOX_S1_OfstMntrEnblCmbMode - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

NOX_S1_OfstMntrEnblCmbMode - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - NOX_S1_OutRngMaxCmbMode

Description: Combustion mode dependent diag enable for Upstream NOx sensor OOR high monitor

NOX_S1_OutRngMaxCmbMode - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

NOX_S1_OutRngMaxCmbMode - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

NOX_S1_OutRngMaxCmbMode - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

NOX_S1_OutRngMaxCmbMode - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - NOX_S1_OutRngMinCmbMode

Description: Combustion mode dependent diag enable for Upstream NOx sensor OOR low monitor

NOX_S1_OutRngMinCmbMode - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

NOX_S1_OutRngMinCmbMode - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

NOX_S1_OutRngMinCmbMode - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

NOX_S1_OutRngMinCmbMode - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - NOX_S1_PlausChkEnblCmbMode

Description: Combustion mode dependent diag enable for Upstream NOx sensor plausibility

NOX_S1_PlausChkEnblCmbMode - Part 1					
y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0
NOX_S1_PlausChkEnblCmbMode - Part 2					
y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	0	0	0
NOX_S1_PlausChkEnblCmbMode - Part 3					
y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0
NOX_S1_PlausChkEnblCmbMode - Part 4					
y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - NOX_S1_StBitChkEnblCmbMode

Description: Combustion mode dependent diag enable for Upstream NOx sensor stability monitor

NOX_S1_StBitChkEnblCmbMode - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

NOX_S1_StBitChkEnblCmbMode - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

NOX_S1_StBitChkEnblCmbMode - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

NOX_S1_StBitChkEnblCmbMode - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - NOX_S2_OfstMntrEnblCmbMode

Description:

NOX_S2_OfstMntrEnblCmbMode - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

NOX_S2_OfstMntrEnblCmbMode - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

NOX_S2_OfstMntrEnblCmbMode - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

NOX_S2_OfstMntrEnblCmbMode - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - NOX_S2_OutRngMaxCmbMode

Description: Combustion mode dependent diag enable for Downstream NOx sensor OOR high monitor

NOX_S2_OutRngMaxCmbMode - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

NOX_S2_OutRngMaxCmbMode - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

NOX_S2_OutRngMaxCmbMode - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

NOX_S2_OutRngMaxCmbMode - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - NOX_S2_OutRngMinCmbMode

Description: Combustion mode dependent diag enable for Downstream NOx sensor OOR low monitor

NOX_S2_OutRngMinCmbMode - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

NOX_S2_OutRngMinCmbMode - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

NOX_S2_OutRngMinCmbMode - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

NOX_S2_OutRngMinCmbMode - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - NOX_S2_StBitChkEnblCmbMode

Description: Combustion mode dependent diag enable for Downstream NOx sensor stability monitor

NOX_S2_StBitChkEnblCmbMode - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

NOX_S2_StBitChkEnblCmbMode - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

NOX_S2_StBitChkEnblCmbMode - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

NOX_S2_StBitChkEnblCmbMode - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - P0106, P2227, P227B, P00C7: Maximum pressure difference

Description: Maximum delta pressure allowed between the three pressure sensors without setting the fault. It is function of the measured air flow.

Value Units: kPa
X Unit: g/s

y/x	3	10	15	20	25	30	35	40
1	254	254	254	254	254	254	254	254

Initial Supporting table - 1st_FireAftrMisfr_Acel

Description: Used for P0300 - P0308, Multiplier for establishing the expected acceleration of the cylinder after the misfire

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	580	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,400	2,800	3,200	3,800	4,000	4,400
2	0.41	0.44	0.48	0.59	0.53	0.55	0.56	0.73	0.79	0.87	0.63	0.33	0.35	0.22	0.20	0.17	0.20
6	0.49	0.52	0.61	0.73	0.63	0.63	0.73	0.98	1.05	1.02	0.80	0.43	0.38	0.29	0.24	0.21	0.23
8	0.74	0.77	0.80	0.93	0.73	0.81	0.85	1.06	1.43	1.20	1.20	0.61	0.45	0.39	0.28	0.23	0.25
12	0.62	0.62	0.83	0.86	0.80	0.78	0.82	1.29	1.45	1.69	1.65	1.23	0.71	0.53	0.43	0.32	0.31
18	0.56	0.54	0.76	0.71	0.64	0.69	0.73	1.36	1.28	1.28	1.60	1.61	0.92	0.76	0.43	0.42	0.45
24	0.53	0.51	0.74	0.65	0.58	0.65	0.69	1.09	1.19	1.06	1.24	1.50	0.90	0.78	0.44	0.50	0.62
30	0.52	0.49	0.73	0.61	0.55	0.62	0.66	0.95	1.13	0.92	1.13	1.48	0.83	0.70	0.38	0.41	0.56
60	0.54	0.45	0.70	0.53	0.49	0.57	0.60	0.71	0.99	0.64	0.89	1.46	0.69	0.58	0.26	0.31	0.46
98	0.87	0.44	0.69	0.50	0.47	0.55	0.58	0.63	0.92	0.53	0.80	1.46	0.64	0.50	0.21	0.27	0.41

Initial Supporting table - 1st_FireAftrMisfr_Jerk

Description: Used for P0300 - P0308, Multiplier for establishing the expected Jerk of the cylinder after the misfire

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	580	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,400	2,800	3,200	3,800	4,000	4,400
2	-0.33	-0.36	-0.37	-0.44	-0.53	-0.51	-0.44	-0.32	-0.37	-0.42	-0.48	-0.36	-0.29	-0.42	-0.37	-0.28	-0.19
6	-0.63	-0.58	-0.70	-0.65	-0.75	-0.72	-0.67	-0.51	-0.63	-0.62	-0.60	-0.53	-0.44	-0.54	-0.47	-0.34	-0.22
8	-0.72	-0.65	-0.69	-0.67	-0.75	-0.68	-0.66	-0.63	-0.70	-0.78	-0.73	-0.71	-0.58	-0.68	-0.53	-0.38	-0.24
12	-0.89	-0.76	-0.82	-0.72	-0.76	-0.80	-0.65	-0.95	-0.82	-0.70	-0.69	-0.85	-0.68	-0.91	-0.90	-0.65	-0.40
18	-1.04	-0.84	-0.92	-0.76	-0.74	-0.86	-0.58	-0.99	-0.86	-0.80	-0.80	-0.80	-0.71	-0.84	-1.05	-0.88	-0.82
24	-1.13	-0.88	-0.97	-0.77	-0.74	-0.89	-0.55	-0.88	-0.91	-0.87	-0.87	-0.84	-0.79	-0.75	-0.98	-0.92	-0.84
30	-1.18	-0.90	-1.00	-0.78	-0.73	-0.90	-0.53	-0.91	-0.94	-0.91	-0.91	-0.82	-0.81	-0.64	-0.88	-0.96	-0.98
60	-1.00	-0.95	-1.06	-0.80	-0.73	-0.93	-0.50	-0.85	-1.02	-1.00	-0.96	-0.79	-0.87	-0.53	-0.72	-1.02	-1.22
98	-1.00	-1.00	-1.09	-0.81	-0.72	-0.94	-0.49	-0.83	-1.05	-1.02	-0.99	-0.78	-0.89	-0.53	-0.70	-1.03	-1.33

Initial Supporting table - 1stFireAfterMisJerkAFM

Description: Used for P0300 - P0308, Multiplier for establishing the expected jerk of the cylinder after the misfire if Active Fuel Management cylinder deact mode is active

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
8	1	1	1	1	1	1	1	1	1
12	1	1	1	1	1	1	1	1	1
16	1	1	1	1	1	1	1	1	1
20	1	1	1	1	1	1	1	1	1
24	1	1	1	1	1	1	1	1	1
30	1	1	1	1	1	1	1	1	1
40	1	1	1	1	1	1	1	1	1
60	1	1	1	1	1	1	1	1	1
100	1	1	1	1	1	1	1	1	1

Initial Supporting table - 1stFireAftrMisAcelAFM

Description: Used for P0300 - P0308, Multiplier for establishing the expected acceleration of the cylinder after the misfire if Active Fuel Management cylinder deact mode is active

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
8	1	1	1	1	1	1	1	1	1
12	1	1	1	1	1	1	1	1	1
16	1	1	1	1	1	1	1	1	1
20	1	1	1	1	1	1	1	1	1
24	1	1	1	1	1	1	1	1	1
30	1	1	1	1	1	1	1	1	1
40	1	1	1	1	1	1	1	1	1
60	1	1	1	1	1	1	1	1	1
100	1	1	1	1	1	1	1	1	1

Initial Supporting table - Abnormal Cyl Mode

Description: Used for P0300-P0308. Number of consecutive number of decelerating cylinders after the misfire that would be considered abnormal. (Cylinder Mode Equation)

Value Units: Number of consecutive number of decelerating cylinders (integer)
X Unit: thousands of RPM (rpm/1000)

y/x	0	1	2	3	4	5	6	7	8
1	2	2	3	2	2	2	2	2	2

Initial Supporting table - Abnormal Rev Mode

Description: Used for P0300-P0308. Abnormal Rev Mode Number of consecutive number of decelerating cylinders after the misfire that would be considered abnormal. (Rev Mode Equation)

Value Units: Number of consecutive number of decelerating cylinders (integer)
X Unit: thousands of RPM (rpm/1000)

y/x	0	1	2	3	4	5	6	7	8
1	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00	2.00

Initial Supporting table - Abnormal SCD Mode

Description: Used for P0300-P0308. Number of consecutive number of decelerating cylinders after the misfire that would be considered abnormal. (SCD Mode Equation)

Value Units: Number of consecutive number of decelerating cylinders (integer)
X Unit: thousands of RPM (rpm/1000)

y/x	0	1	2	3	4	5	6	7	8
1	2	2	2	2	2	2	2	2	2

Initial Supporting table - AIC_AirCntrlShtOffActn: ECT Too Low Hysteresis High Threshold for DPF

Description: Hysteresis high threshold for engine coolant temperature too low shut off condition evaluation during DPF combustion modes and SCR service warm up combustion mode. It is function of outside air temperature.

Value Units: °C
X Unit: °C

y/x	-20	-10	0	10	20	30
1	48	48	42	29	16	16

Initial Supporting table - AIC_AirCntrlShtOffActn: ECT Too Low Hysteresis High Threshold for others

Description: Hysteresis high threshold for engine coolant temperature too low shut off condition evaluation. It is function of outside air temperature.

Value Units: °C
X Unit: °C

y/x	-23	-22	-10	0	10	20
1	140	68	19	18	17	16

Initial Supporting table - AIC_AirCntrlShtOffActn: ECT Too Low Hysteresis Low Threshold for DPF

Description: Hysteresis low threshold for engine coolant temperature too low shut off condition evaluation during DPF combustion modes and SCR service warm up combustion mode. It is function of outside air temperature.

Value Units: °C
X Unit: °C

y/x	-20	-10	0	10	20	30
1	45	45	39	26	13	13

Initial Supporting table - AIC_AirCntrlShtOffActn: ECT Too Low Hysteresis Low Threshold for others

Description: Hysteresis low threshold for engine coolant temperature too low shut off condition evaluation. It is function of outside air temperature.

Value Units: °C
X Unit: °C

y/x	-23	-22	-10	0	10	20
1	137	65	16	15	14	13

Initial Supporting table - AIC_AirCntrlShtOffActn: Fuel High Threshold for D1 and D3

Description: Hysteresis high threshold for large injected fuel shut off condition evaluation during DPF and HCS combustion modes. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000
1	75	75	75	75	75	75	75	75

Initial Supporting table - AIC_AirCntrlShtOffActn: Fuel High Threshold for D4

Description: Hysteresis high threshold for large injected fuel shut off condition evaluation during DPF rich idle combustion mode. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000
1	75	75	75	75	75	75	75	75

Initial Supporting table - AIC_AirCntrlShtOffActn: Fuel Low Threshold for D1 and D3

Description: Hysteresis low threshold for large injected fuel shut off condition evaluation during DPF and HCS combustion modes. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000
1	70	70	70	70	70	70	70	70

Initial Supporting table - AIC_AirCntrlShtOffActn: Fuel Low Threshold for D4

Description: Hysteresis low threshold for large injected fuel shut off condition evaluation during DPF rich idle combustion mode. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000
1	70	70	70	70	70	70	70	70

Initial Supporting table - AIC_BstCntrlCL: Fuel Request On Threshold for C2

Description: Fuel threshold above which the pressure closed loop control is enabled in C2 mode. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	750	900	1,000	1,100	1,225	1,250	1,500	2,000	2,500	3,000	3,500	4,000
1	66	66	66	64	52	47	46	42	38	33	28	27	27

Initial Supporting table - AIC_BstCntrlCL: Fuel Request On Threshold for D1 and D3

Description: Fuel threshold above which the pressure closed loop control is enabled in DPF high O2, Rich idle and all HC modes and SCR service warm up. It is function of engine speed).

Value Units: mm^3
X Unit: rpm

y/x	500	750	900	1,000	1,100	1,225	1,250	1,500	2,000	2,500	3,000	3,500	4,000
1	30	18	15	14	12	10	10	8	8	8	8	8	8

Initial Supporting table - AIC_BstCntrlCL: Fuel Request On Threshold for D4

Description: Fuel threshold above which the pressure closed loop control is enabled in DPF low O2. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	750	900	1,000	1,100	1,225	1,250	1,500	2,000	2,500	3,000	3,500	4,000
1	30	30	30	15	15	15	15	15	15	15	15	15	15

Initial Supporting table - AIC_BstCntrlCL: Fuel Request On Threshold for others

Description: Fuel threshold above which the pressure closed loop control is enabled. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	750	900	1,000	1,100	1,225	1,250	1,500	2,000	2,500	3,000	3,500	4,000
1	150	150	150	150	150	150	5	5	5	5	5	5	5

Initial Supporting table - AIC_BstCntrlCL: Fuel Request On Threshold for V3

Description: Fuel threshold above which the pressure closed loop control is enabled in SCR temp 1 or DeSOx lean mode. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	750	900	1,000	1,100	1,225	1,250	1,500	2,000	2,500	3,000	3,500	4,000
1	150	150	150	150	150	150	5	5	5	5	5	5	5

Initial Supporting table - AIC_BstCntrlCL: On Threshold for V1

Description: Threshold above which the pressure closed loop control is enabled in SCR temp 3 or DeNOx mode. It is function of engine speed.

Value Units: composite
X Unit: rpm

y/x	500	750	900	1,000	1,100	1,225	1,250	1,500	2,000	2,500	3,000	3,500	4,000
1	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000

Initial Supporting table - AIC_BstCntrlCL: On Threshold for V2

Description: Threshold above which the pressure closed loop control is enabled in SCR temp 2 or DeSOx Rich mode. It is function of engine speed.

Value Units: composite
X Unit: rpm

y/x	500	750	900	1,000	1,100	1,225	1,250	1,500	2,000	2,500	3,000	3,500	4,000
1	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000

Initial Supporting table - AirCntrlTrnstnEnd: Timer threshold

Description: Timer threshold after which an air control transition is considered as ended. It is function of engine speed.

Value Units: s
X Unit: rpm

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000	4,500
1	0	0	0	0	0	0	0	0	0

Initial Supporting table - Bank_SCD_Decel

Description: Used for P0300 - P0308, Mulitplier to SCD decel to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
5	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60
10	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60
20	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60
30	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60
40	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60
50	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60
60	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60
80	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60
100	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60	0.60

Initial Supporting table - Bank_SCD_Jerk

Description: Used for P0300 - P0308, Mulitplier to Medres SCD jerk to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: mulitplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
5	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
10	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
50	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
80	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
100	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - BankCylModeDecel

Description: Used for P0300 - P0308, Mulitplier to Lores Decel to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	580	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,400	2,800	3,200	3,800	4,000	4,400
5	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
10	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
50	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
80	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
100	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - BankCylModeJerk

Description: Used for P0300 - P0308, Mulitplier to Lores Jerk to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	580	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,400	2,800	3,200	3,800	4,000	4,400
5	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
10	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
50	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
80	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
100	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - Cat2_CrtdEffThrsh

Description: Minimum Second Catalyst (UF DOC) conversion efficiency threshold (fault threshold) as function of ambient temperature [K]

y/x	250.00	266.00	282.00	298.00	314.00	330.00
1.00	20.0000	20.0000	20.0000	20.0000	20.0000	20.0000

Initial Supporting table - Cat2_CrtdMaxFuel

Description: Maximum integrated exhaust injected fuel quantity (by HCI) threshold [g], as function of ambient temperature [K], needed to stop Second Catalyst integrators (heat and injected fuel) and calculate the Aging Index

y/x	250.00	266.00	282.00	298.00	314.00	330.00
1.00	120.0000	120.0000	120.0000	120.0000	120.0000	120.0000

Initial Supporting table - Cat2CrtdEffRepEWMA

Description: Minimum Second Catalyst (UF DOC) conversion efficiency threshold (repass fault threshold) as function of ambient temperature [K] in case of Second Catalyst EWMA filter enabled and Second Catalyst conversion inefficiency previously detected (Second Catalyst FA = TRUE)

y/x	250.00	266.00	282.00	298.00	314.00	330.00
1.00	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000

Initial Supporting table - Catalyst_Damage_Misfire_Percentage

Description: Catalyst Damaging Misfire Percentage" Table whenever secondary conditions are met.

Value Units: percent misfire over 200 revolutions (%)
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	0	1,000	2,000	3,000	4,000	5,000	6,000	7,000
0	512.0	512.0	512.0	512.0	512.0	512.0	512.0	512.0
10	512.0	512.0	512.0	512.0	512.0	512.0	512.0	512.0
20	512.0	512.0	512.0	512.0	512.0	512.0	512.0	512.0
30	512.0	512.0	512.0	512.0	512.0	512.0	512.0	512.0
40	512.0	512.0	512.0	512.0	512.0	512.0	512.0	512.0
50	512.0	512.0	512.0	512.0	512.0	512.0	512.0	512.0
60	512.0	512.0	512.0	512.0	512.0	512.0	512.0	512.0
70	512.0	512.0	512.0	512.0	512.0	512.0	512.0	512.0
80	512.0	512.0	512.0	512.0	512.0	512.0	512.0	512.0
90	512.0	512.0	512.0	512.0	512.0	512.0	512.0	512.0
100	512.0	512.0	512.0	512.0	512.0	512.0	512.0	512.0

Initial Supporting table - CatCrtdEffRepEWMA

Description: Minimum Catalyst (CC DOC) conversion efficiency threshold (repass fault threshold) as function of ambient temperature [K] in case of Catalyst EWMA filter enabled and Catalyst conversion inefficiency previously detected (Catalyst FA = TRUE)

y/x	250.00	266.00	282.00	298.00	314.00	330.00
1.00	1.0000	1.0000	1.0000	1.0000	1.0000	1.0000

Initial Supporting table - CatCrtdEffThrsh

Description: Minimum Catalyst (CC DOC) conversion efficiency threshold (fault threshold) as function of ambient temperature [K]

y/x	250.00	266.00	282.00	298.00	314.00	330.00
1.00	7.2500	7.2500	7.2500	7.2500	7.2500	7.2500

Initial Supporting table - CatCrtdMaxFuel

Description: Maximum integrated post injected fuel quantity threshold [g], as function of ambient temperature [K], needed to stop Catalyst integrators (heat and injected fuel) and calculate the Aging Index

y/x	250.00	266.00	282.00	298.00	314.00	330.00
1.00	40.0000	40.0000	40.0000	40.0000	40.0000	40.0000

Initial Supporting table - ClyAfterAFM_Decel

Description: Used for P0300 - P0308, Mulitplier to Lores decel to account for different pattern of misfire after a deactivated cylider. Similar to the second cylinder of consecutive cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
5	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
10	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
50	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
80	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
100	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - ClyBeforeAFM_Jerk

Description: Used for P0300 - P0308, Mulitplier to Lores decel to account for different pattern of misfire before a deactivated cylider, but after an active cylinder that follows an deactive cylinder on engine that supports cylinder deactivation in non even fire patterns.. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
5	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
10	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
50	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
80	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
100	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - CombustModeIdleTbl

Description: Used for P0300 - P0308, Only used on Diesel engines. Combustion modes that will force use of Idle table. A value of CeCMBR_i_CombModesMax means not selected.

Value Units: Enumerated value of differant combustion modes (enumeration)
X Unit: Current Combustion Mode (enumeration)

CombustModeIdleTbl - Part 1						
y/x	0	1	2	3	4	5
1	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax

CombustModeIdleTbl - Part 2						
y/x	6	7	8	9	10	11
1	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax

CombustModeIdleTbl - Part 3						
y/x	12	13	14	15	16	
1	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	

Initial Supporting table - ConsecCylModDecel

Description: Used for P0300 - P0308, Mulitplier to Lores decel to account for different pattern of the second cylinder of consecutive misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	580	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,400	2,800	3,200	3,800	4,000	4,400
6	2.37	1.76	1.88	1.45	1.64	1.44	1.44	1.60	1.30	1.37	1.37	1.17	0.87	0.91	1.09	1.21	0.88
8	2.75	2.12	1.98	1.63	1.72	1.39	1.44	1.60	1.46	1.43	1.36	1.07	0.84	0.99	1.18	1.31	0.93
12	1.74	1.48	1.75	1.46	1.80	1.45	1.31	1.75	1.31	1.77	1.55	1.24	1.17	1.08	1.43	1.59	1.03
16	1.37	1.25	1.52	1.35	1.50	1.32	1.34	1.91	1.36	1.57	1.61	1.46	1.06	0.92	1.32	1.70	1.10
20	1.13	1.10	1.38	1.42	1.53	1.40	1.35	1.72	1.39	1.51	1.44	1.42	0.99	0.81	1.18	1.75	1.15
24	0.99	1.01	1.29	1.44	1.50	1.42	1.36	1.60	1.42	1.45	1.26	1.35	0.94	0.73	1.05	1.66	1.31
30	0.85	0.92	1.20	1.45	1.47	1.43	1.37	1.47	1.45	1.37	1.20	1.28	0.86	0.68	0.69	1.09	1.18
60	0.65	0.75	1.02	1.48	1.42	1.46	1.38	1.29	1.51	1.23	1.19	1.14	0.68	0.67	0.20	0.41	0.84
98	0.90	0.68	0.95	1.50	1.40	1.47	1.39	1.23	1.54	1.20	1.18	1.10	0.62	0.69	0.25	0.32	0.83

Initial Supporting table - ConsecCylModeJerk

Description: Used for P0300 - P0308, Mulitplier to Lores Jerk to account for different pattern of the second cylinder of consecutive misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	580	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,400	2,800	3,200	3,800	4,000	4,400
6	0	0	0	0	0	0	0	0	0	0	0	-1	-1	0	-1	0	0
8	0	0	0	0	0	0	0	0	0	0	0	-1	-1	-1	-1	0	0
12	0	0	0	0	0	0	0	0	0	0	0	-1	-1	-1	-1	-1	0
16	0	0	0	0	0	0	0	0	0	0	0	-1	-1	-1	-1	-1	0
20	0	0	0	0	0	0	0	0	0	0	0	-1	-1	-1	-1	-1	0
24	0	0	0	0	0	0	0	0	0	0	0	-1	-1	-1	-1	-1	0
30	0	0	0	0	0	0	0	0	0	0	0	-1	0	-1	-1	-1	0
60	0	0	0	0	0	0	0	0	0	0	-1	0	0	-2	-1	-1	-1
98	1	0	0	0	0	0	0	0	0	0	-1	0	0	-2	-2	-1	-1

Initial Supporting table - ConsecSCD_Decel

Description: Used for P0300 - P0308, Mulitplier to medres decel to account for different pattern of the second cylinder of consecutive misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
6	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
16	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - ConsecSCD_Jerk

Description: Used for P0300 - P0308, Mulitplier to medres Jerk to account for different pattern of the second cylinder of consecutive misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
6	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
8	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
12	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
16	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
20	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
24	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
30	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
60	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
98	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00

Initial Supporting table - CylAfterAFM_Jerk

Description: Used for P0300 - P0308, Mulitplier to Lores Jerk to account for different pattern of misfire after a deactivated cylider. Similar to the second cylinder of consecutive cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
5	1	1	1	1	1	1	1	1	1
10	1	1	1	1	1	1	1	1	1
20	1	1	1	1	1	1	1	1	1
30	1	1	1	1	1	1	1	1	1
40	1	1	1	1	1	1	1	1	1
50	1	1	1	1	1	1	1	1	1
60	1	1	1	1	1	1	1	1	1
80	1	1	1	1	1	1	1	1	1
100	1	1	1	1	1	1	1	1	1

Initial Supporting table - CylBeforeAFM_Decel

Description: Used for P0300 - P0308, Mulitplier to Lores decel to account for different pattern of misfire before a deactivated cylider, but after an active cylinder that follows an deactive cylinder on engine that supports cylinder deactivation in non even fire patterns.. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
5	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
10	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
50	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
80	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
100	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - CylModeDecel

Description: Used for P0300-P0308. Crankshaft decel threshold. Thresholds are a function of rpm and % engine Load.

Value Units: Delta time per cylinder (usec)
X Unit: RPM
Y Units: percent load of max indicated torque (%)

CylModeDecel - Part 1

y/x	580	655	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,200
2	4,239	2,939	2,042	1,546	1,139	760	632	471	310	211	146	133	116
4	3,746	2,603	1,811	1,362	1,025	670	564	420	271	190	138	123	102
6	3,481	2,406	1,707	1,218	924	640	549	365	231	158	123	104	78
8	2,974	2,062	1,450	1,218	823	611	500	365	231	126	109	85	69
10	4,049	2,748	1,963	1,362	910	611	525	406	227	126	94	79	60
12	5,124	3,413	2,475	1,651	1,084	687	574	489	223	140	83	73	50
14	6,199	4,079	2,988	1,940	1,259	840	673	572	218	154	94	67	53
16	7,267	4,743	3,501	2,229	1,433	993	772	655	214	168	106	76	59
18	8,347	5,414	4,013	2,518	1,607	1,146	871	738	249	182	117	85	65
20	9,417	6,087	4,527	2,807	1,781	1,299	970	821	285	196	128	95	71
22	10,488	6,753	5,036	3,095	1,956	1,452	1,069	904	320	210	140	104	77
24	11,570	7,425	5,551	3,383	2,130	1,605	1,168	987	355	224	151	113	83
26	12,640	8,091	6,066	3,672	2,304	1,758	1,267	1,071	390	238	162	123	89
30	14,782	9,430	7,090	4,251	2,653	2,064	1,465	1,237	461	266	185	141	101
40	20,156	12,779	9,652	5,695	3,523	2,829	1,960	1,652	637	336	242	188	131
60	28,000	19,472	14,776	8,584	5,268	4,359	2,951	2,483	989	476	356	281	191
97	28,000	28,000	24,391	13,997	8,535	7,228	4,806	4,040	1,649	739	569	456	304

CylModeDecel - Part 2

y/x	2,400	2,600	2,800	3,000	3,200	3,400	3,600	3,800	4,000	4,200	4,400	4,600	4,800
2	100	111	76	81	78	59	62	58	58	60	54	54	54
4	87	96	73	71	69	52	56	52	53	56	50	50	50
6	84	82	71	61	61	44	50	47	49	52	46	46	46
8	75	68	71	52	52	41	43	42	44	48	42	42	42
10	66	54	59	52	43	39	40	36	39	44	39	39	39
12	57	54	48	47	40	38	34	32	34	40	35	35	35
14	53	56	48	42	40	36	29	32	32	35	32	32	32
16	50	56	48	41	38	36	30	31	30	32	30	30	30
18	53	56	48	40	36	37	32	31	29	30	28	28	28
20	58	58	48	39	34	38	34	30	28	27	26	26	26
22	64	62	50	43	36	39	37	30	26	24	21	21	21

Initial Supporting table - CylModeDecel

24	69	66	54	47	39	40	39	32	28	25	23	23	23
26	75	70	59	50	43	42	41	35	31	27	24	24	24
30	86	79	67	58	50	47	45	39	35	31	28	28	28
40	114	100	89	78	68	59	56	51	46	40	35	35	35
60	169	142	132	117	104	82	77	75	69	59	51	51	51
97	274	221	213	190	172	127	117	120	110	94	80	80	80

Initial Supporting table - CylModeJerk

Description: Crankshaft jerk threshold. Thresholds are a function of rpm and % engine Load.

Value Units: Change in Delta time per cylinder from last cylinder (usec)
Y Units: percent load of max indicated torque (%)

CylModeJerk - Part 1

y/x	580	655	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,200
2	3,970	2,761	1,912	1,446	1,133	697	581	460	311	215	174	133	124
4	3,476	2,424	1,672	1,272	1,016	650	512	409	302	183	143	124	104
6	4,464	3,098	2,152	1,552	1,251	790	580	487	320	183	143	116	89
8	5,452	3,773	2,507	1,970	1,486	976	706	591	338	215	143	107	73
10	6,854	4,693	3,126	2,426	1,904	1,287	831	695	356	246	174	133	92
12	7,903	5,509	3,746	2,862	2,316	1,632	1,081	903	374	277	206	158	112
14	8,952	6,307	4,365	3,299	2,727	1,977	1,332	1,110	392	311	243	183	131
16	9,983	7,112	4,984	3,736	3,139	2,322	1,582	1,318	483	371	274	206	150
18	11,036	7,910	5,603	4,173	3,551	2,667	1,833	1,525	575	415	305	228	169
20	12,079	8,721	6,222	4,610	3,962	3,012	2,083	1,733	667	458	336	250	188
22	13,123	9,522	6,841	5,046	4,374	3,357	2,334	1,940	759	502	367	272	207
24	14,172	10,324	7,461	5,483	4,785	3,702	2,584	2,147	850	545	397	295	226
26	15,218	11,126	8,080	5,920	5,197	4,047	2,835	2,355	942	589	428	317	245
30	17,305	12,729	9,318	6,794	6,020	4,737	3,335	2,770	1,125	676	490	362	284
40	22,540	16,746	12,414	8,978	8,076	6,461	4,586	3,807	1,584	893	643	473	379
60	28,000	24,771	18,606	13,346	12,195	9,911	7,094	5,882	2,501	1,328	951	697	571
97	28,000	28,000	28,000	21,536	19,910	16,379	11,789	9,770	4,221	2,144	1,527	1,115	929

CylModeJerk - Part 2

y/x	2,400	2,600	2,800	3,000	3,200	3,400	3,600	3,800	4,000	4,200	4,400	4,600	4,800
2	112	113	92	78	75	57	61	57	59	60	53	53	53
4	91	97	81	68	67	49	54	51	54	55	49	49	49
6	87	82	69	58	58	42	48	45	49	51	45	45	45
8	83	75	66	48	50	38	42	40	44	47	41	41	41
10	78	73	64	48	41	38	39	34	39	42	37	37	37
12	94	81	62	58	44	42	36	32	34	38	33	33	33
14	109	97	71	66	47	42	32	34	31	34	30	30	30
16	123	107	80	73	54	43	35	36	33	32	28	28	28
18	138	117	89	80	61	49	40	38	37	34	30	30	30
20	152	128	98	87	67	55	45	41	40	38	33	33	33
22	167	138	107	94	74	61	51	44	43	41	37	37	37

Initial Supporting table - CylModeJerk

24	181	148	116	101	81	67	56	47	46	44	41	41	41
26	195	158	125	108	87	73	61	50	49	47	44	44	44
30	224	178	142	122	101	86	72	56	56	53	49	49	49
40	297	229	187	158	134	117	99	70	72	68	61	61	61
60	441	330	276	228	201	179	152	98	104	98	85	85	85
97	712	520	442	360	325	294	252	152	165	154	130	130	130

Initial Supporting table - DeacCylInversionDecel

Description: Used for P0300 - P0308, Negative Torque can cause crank readings to invert (active cylinders appear weak & deactivated cylinders appear "strong" If deactivated cylinders don't decelerate at least this amount then the crank signal is inverting. Function of speed and load.

Value Units: Delta time per cylinder (usec)
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
5	0	0	0	0	0	0	0	0	0
10	0	0	0	0	0	0	0	0	0
20	0	0	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	0	0	0
50	0	0	0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0	0
80	0	0	0	0	0	0	0	0	0
100	0	0	0	0	0	0	0	0	0

Initial Supporting table - DeacCylInversionJerk

Description: Used for P0300 - P0308, Negative Torque can cause crank readings to invert (active cylinders appear weak & deactivated cylinders appear "strong" If deactivated cylinders don't jerk at least this amount then the crank signal is inverting. Function of speed and load.

Value Units: Change in Delta time per cylinder from last cylinder (usec)
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
5	0	0	0	0	0	0	0	0	0
10	0	0	0	0	0	0	0	0	0
20	0	0	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	0	0	0
50	0	0	0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0	0
80	0	0	0	0	0	0	0	0	0
100	0	0	0	0	0	0	0	0	0

Initial Supporting table - EngineOverSpeedLimit

Description: Engine OverSpeed Limit versus gear

Value Units: RPM
X Unit: Enumeration of transmission gear state (enumeration)

EngineOverSpeedLimit - Part 1

y/x	CeTGRR_e_TransGr1	CeTGRR_e_TransGr2	CeTGRR_e_TransGr3	CeTGRR_e_TransGr4	CeTGRR_e_TransGr5	CeTGRR_e_TransGr6	CeTGRR_e_TransGr9
1	4,800	4,800	4,800	4,800	4,800	4,800	4,800

EngineOverSpeedLimit - Part 2

y/x	CeTGRR_e_TransGr10	CeTGRR_e_TransGrNeut	CeTGRR_e_TransGrRvrs	CeTGRR_e_TransGrPark	CeTGRR_e_TransGr7	CeTGRR_e_TransGr8	
1	4,800	3,900	4,800	3,900	4,800	4,800	

Initial Supporting table - InfrequentRegen

Description: Used for P0300-P0308. Only used on Diesel engines. Initiates a misfire delay when the current combustion mode matchs a selection in the table. A value of CeCMBR_i_CombModesMax means not selected.

Value Units: Enumerated value of differant combustion modes (enumeration)
X Unit: Current Combustion Mode (enumeration)

InfrequentRegen - Part 1						
y/x	0	1	2	3	4	5
1	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax

InfrequentRegen - Part 2						
y/x	6	7	8	9	10	11
1	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax

InfrequentRegen - Part 3						
y/x	12	13	14	15	16	
1	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	CeCMBR_i_CombModesMax	

Initial Supporting table - K_EffExhFlowCond

Description: Enablement table, function of exhaust flow and SCR average temperature [boolean] for SCR NOx catalyst efficiency monitoring (P20EE)

Value Units: boolean
X Unit: °C
Y Units: g/sec

y/x	0	200	235	245	275	290	295	300	315	316	425	450	475	500	550
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
10	0	0	0	1	1	1	1	1	1	0	0	0	0	0	0
20	0	0	0	1	1	1	1	1	1	0	0	0	0	0	0
25	0	0	0	1	1	1	1	1	1	0	0	0	0	0	0
30	0	0	0	1	1	1	1	1	1	0	0	0	0	0	0
35	0	0	0	1	1	1	1	1	1	0	0	0	0	0	0
40	0	0	0	1	1	1	1	1	1	0	0	0	0	0	0
50	0	0	0	1	1	1	1	1	1	0	0	0	0	0	0
60	0	0	0	1	1	1	1	1	1	0	0	0	0	0	0
70	0	0	0	1	1	1	1	1	1	0	0	0	0	0	0
85	0	0	0	1	1	1	1	1	1	0	0	0	0	0	0
86	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
100	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
125	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
150	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
200	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Initial Supporting table - m_NH3_StrgDevErrMaxThrsh

Description: Upper boundary of NH3 storage deviation error [g] for SCR NOx catalyst efficiency monitoring (P20EE)

Value Units: g
X Unit: °C

y/x	100	150	200	250	300	350	400	450
1	0	0	0	0	0	0	0	0

Initial Supporting table - m_NH3_StrgDevErrMinThrsh

Description: Lower boundary of NH3 storage deviation error [g] for SCR NOx catalyst efficiency monitoring (P20EE)

Value Units: g
X Unit: °C

y/x	100	150	200	250	300	350	400	450
1	0	0	0	0	0	0	0	0

Initial Supporting table - m_NH3_StrgMaxThrsh

Description: Upper boundary of estimated NH3 storage [g] for SCR NOx catalyst efficiency monitoring (P20EE)

Value Units: g
X Unit: °C

y/x	250	275	300	325	350	375	400	450
1	3	3	3	3	3	3	3	3

Initial Supporting table - m_NH3_StrgMinThrsh

Description: Lower boundary of estimated NH3 storage [g] for SCR NOx catalyst efficiency monitoring (P20EE)

Value Units: g
X Unit: °C

y/x	250	260	270	280	290	300	310	320
1	1	1	1	1	1	1	1	1

Initial Supporting table - m_SlipNOxIntglThrsh

Description: NOx integral threshold to enable slip condition based on SCR average temperature [mg] for SCR NOx catalyst efficiency monitoring (P20EE)

Value Units: mg
X Unit: °C

y/x	250	300	350	425
1	500	500	500	500

Initial Supporting table - Number of Normals

Description: Used for P0300-P0308. Number of Normals for the Driveline Ring Filter
After a low level misfire, another misfire may not be detectable until driveline ringing ceases. If no ringing seen, stop filter early.

Value Units: Number of Engine cycles after isolated misfire (Engine cycles)
X Unit: thousands of RPM (rpm/1000)

y/x	0	1	2	3	4	5	6	7	8
1	2	2	2	2	2	2	2	2	2

Initial Supporting table - P0101: MAF performance enabling

Description: Calibration map for the enabling of MAF sensor performance monitoring, function of combustion mode.

Value Units: boolean
X Unit: enum

P0101: MAF performance enabling - Part 1					
y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	1	0	0	0

P0101: MAF performance enabling - Part 2					
y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

P0101: MAF performance enabling - Part 3					
y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

P0101: MAF performance enabling - Part 4					
y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - P0101: Manifold pressure High limit in Overrun

Description: Intake manifold pressure high limit in overrun condition, below which the MAF sensor performance monitoring is enabled. It is function of engine speed.

Value Units: kPa
X Unit: rpm

y/x	1	2	3	4	5	6	7	8
1	300	300	300	300	300	300	300	300

Initial Supporting table - P0101: Manifold pressure Low limit in Overrun

Description: Intake manifold pressure low limit in overrun condition, above which the MAF sensor performance monitoring is enabled. It is function of engine speed.

Value Units: kPa
X Unit: rpm

y/x	1	2	3	4	5	6	7	8
1	0	0	0	0	0	0	0	0

Initial Supporting table - P0101: Pulsation Map

Description: Adjustment of the air mass flow measured by the MAF sensor for flow distribution and pulsations. It is function of engine speed (X axis) and fuel request (Y axis)

Value Units: const
X Unit: rpm
Y Units: mm^3

y/x	600	800	1,000	1,250	1,500	1,750	2,000	2,250	2,500	2,750	3,000	3,200	3,400	3,600	3,800	4,200
0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
5	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
10	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
15	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
20	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
25	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
30	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
40	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
50	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
60	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
70	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
80	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
90	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
100	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
120	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1

Initial Supporting table - P0101: VGT position High limit in Overrun

Description: VGT position high limit in overrun condition, below which the MAF sensor performance monitoring is enabled. It is function of engine speed.

Value Units: %
X Unit: rpm

y/x	1	2	3	4	5	6	7	8
1	100	100	100	100	100	100	100	100

Initial Supporting table - P0101: VGT position Low limit in Overrun

Description: VGT position low limit in overrun condition, above which the MAF sensor performance monitoring is enabled. It is function of engine speed.

Value Units: %
X Unit: rpm

y/x	1	2	3	4	5	6	7	8
1	0	0	0	0	0	0	0	0

Initial Supporting table - P0234, P0299: Boost pressure control deviation enabling

Description: Calibration map for the enabling of boost pressure control deviation monitoring, function of combustion mode.

Value Units: boolean

P0234, P0299: Boost pressure control deviation enabling - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	1	0	0	0

P0234, P0299: Boost pressure control deviation enabling - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

P0234, P0299: Boost pressure control deviation enabling - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

P0234, P0299: Boost pressure control deviation enabling - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - P0234, P2263: Overboost barometric correction

Description: Ambient air pressure multiplicative correction to the base threshold for overboost monitoring. It is function of ambient air pressure (Y axis) and desired boost pressure (X axis).

Value Units: const [-8, 8]
X Unit: kPa
Y Units: kPa

y/x	85	100	115	130	145	160	175	190	205	220	235	250	265	280	295
75	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
83	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
97	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
110	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1

Initial Supporting table - P0234: Maximum boost pressure for overboost monitor enabling

Description: Maximum desired boost pressure below which the overboost deviation monitoring is enabled. This map is function of ambient air pressure.

Value Units: kPa
X Unit: kPa

y/x	75	83	97	110
1	200	200	200	200

Initial Supporting table - P0234: Minimum boost pressure for overboost monitor enabling

Description: Minimum desired boost pressure above which the overboost deviation monitoring is enabled. This map is function of ambient air pressure.

Value Units: kPa
X Unit: kPa

y/x	75	83	97	110
1	146	146	120	120

Initial Supporting table - P0234: Negative boost deviation threshold (throttle control active)

Description: Boost pressure deviation threshold for the negative boost pressure control deviation monitor when the throttle control is active. It identifies an overboost faulty condition. It is function of engine speed (Y axis) and desired boost pressure (X axis).

Value Units: kPa
X Unit: kPa
Y Units: rpm

y/x	85	100	115	130	145	160	175	190	205	220	235	250	265	280	295
750	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28
1,000	-28	-28	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23
1,250	-28	-28	-23	-23	-23	-23	-23	-18	-18	-18	-18	-18	-18	-18	-18
1,500	-28	-28	-28	-15	-15	-15	-16	-18	-18	-18	-18	-18	-18	-18	-18
1,750	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
2,000	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
2,250	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
2,500	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
3,000	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20	-30	-40
4,200	-30	-30	-20	-20	-20	-20	-20	-20	-20	-20	-20	-30	-40	-50	-50

Initial Supporting table - P0234: Negative boost deviation threshold (throttle control not active)

Description: Boost pressure deviation threshold for the negative boost pressure control deviation monitor when the throttle control is not active. It identifies an overboost faulty condition. It is function of engine speed (Y axis) and desired boost pressure (X axis).

Value Units: kPa
X Unit: kPa
Y Units: rpm

y/x	85	100	115	130	145	160	175	190	205	220	235	250	265	280	295
750	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28
1,000	-28	-28	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23
1,250	-28	-28	-23	-23	-23	-23	-23	-18	-18	-18	-18	-18	-18	-18	-18
1,500	-28	-28	-28	-15	-15	-15	-16	-18	-18	-18	-18	-18	-18	-18	-18
1,750	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
2,000	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
2,250	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
2,500	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
3,000	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
4,200	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16

Initial Supporting table - P0234: Overboost monitor delay timer

Description: Delay timer before enabling the overboost deviation monitoring once all entry conditions are fulfilled. This map is function of engine speed.

Value Units: s
X Unit: rpm

y/x	750	1,000	1,250	1,500	1,750	2,000	2,250	2,500	3,000	4,200
1	2	2	2	2	2	2	2	2	2	2

Initial Supporting table - P0299, P2263: Underboost barometric correction

Description: Ambient air pressure multiplicative correction to the base threshold for underboost monitoring. It is function of ambient air pressure (Y axis) and desired boost pressure (X axis).

Value Units: const [-8, 8]
X Unit: kPa
Y Units: kPa

y/x	85	100	115	130	145	160	175	190	205	220	235	250	265	280	295
75	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
83	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
97	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
110	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1

Initial Supporting table - P0299: Maximum boost pressure for underboost monitor enabling

Description: Maximum desired boost pressure below which the underboost deviation monitoring is enabled. This map is function of ambient air pressure.

Value Units: kPa
X Unit: kPa

y/x	75	83	97	110
1	250	250	250	250

Initial Supporting table - P0299: Minimum boost pressure for underboost monitor enabling

Description: Minimum desired boost pressure above which the underboost deviation monitoring is enabled. This map is function of ambient air pressure.

Value Units: kPa
X Unit: kPa

y/x	75	83	97	110
1	170	170	150	150

Initial Supporting table - P0299: Positive boost deviation threshold (throttle control active)

Description: Boost pressure deviation threshold for the positive boost pressure control deviation monitor when the throttle control is active. It identifies an underboost faulty condition. It is function of engine speed (Y axis) and desired boost pressure (X axis).

Value Units: kPa
X Unit: kPa
Y Units: rpm

y/x	85	100	115	130	145	160	175	190	205	220	235	250	265	280	295
750	47	47	47	47	47	47	47	47	47	47	47	47	47	37	37
1,000	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42
1,250	42	42	37	37	37	37	37	37	37	32	32	32	32	32	32
1,500	42	42	37	37	37	37	37	37	37	32	32	32	32	32	32
1,750	42	42	37	37	37	37	37	37	37	30	30	30	30	30	30
2,000	42	42	37	37	32	32	30	30	30	30	30	30	30	30	30
2,250	42	42	37	37	32	32	30	30	30	30	30	30	30	30	30
2,500	42	42	37	37	32	32	30	30	30	30	30	30	30	30	30
3,000	37	37	37	37	37	37	37	37	37	37	37	37	37	47	57
4,200	47	47	37	37	37	37	37	37	37	37	37	47	57	67	67

Initial Supporting table - P0299: Positive boost deviation threshold (throttle control not active)

Description: Boost pressure deviation threshold for the positive boost pressure control deviation monitor when the throttle control is not active. It identifies an underboost faulty condition. It is function of engine speed (Y axis) and desired boost pressure (X axis).

Value Units: kPa
X Unit: kPa
Y Units: rpm

y/x	85	100	115	130	145	160	175	190	205	220	235	250	265	280	295
750	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42
1,000	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42
1,250	42	42	37	37	37	37	37	37	37	32	32	32	32	32	32
1,500	42	42	37	37	37	37	37	37	37	32	32	32	32	32	32
1,750	42	42	37	37	37	37	37	37	37	30	30	30	30	30	30
2,000	42	42	37	37	32	32	30	30	30	30	30	30	30	30	30
2,250	42	42	37	37	32	32	30	30	30	30	30	30	30	30	30
2,500	42	42	37	37	32	32	30	30	30	30	30	30	30	30	30
3,000	42	42	37	37	32	32	32	32	32	32	32	32	32	32	32
4,200	42	42	37	37	35	35	35	35	35	35	35	35	35	35	35

Initial Supporting table - P0299: Underboost monitor delay timer

Description: Delay timer before enabling the underboost deviation monitoring once all entry conditions are fulfilled. This map is function of engine speed.

Value Units: s
X Unit: rpm

y/x	750	1,000	1,250	1,500	1,750	2,000	2,250	2,500	3,000	4,200
1	2	2	1	1	1	1	2	2	2	2

Initial Supporting table - P0401, P0402: EGR flow monitor enabling

Description: Calibration map to choose if the excessive/insufficient EGR flow monitor is enabled or not for each combustion mode.

Value Units: boolean
X Unit: enum

P0401, P0402: EGR flow monitor enabling - Part 1					
y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

P0401, P0402: EGR flow monitor enabling - Part 2					
y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

P0401, P0402: EGR flow monitor enabling - Part 3					
y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

P0401, P0402: EGR flow monitor enabling - Part 4					
y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - P0401, P0402: EGR intrusive test enabling

Description: Calibration map to choose if the EGR intrusive test is enabled or not for each combustion mode.

Value Units: boolean
X Unit: enum

P0401, P0402: EGR intrusive test enabling - Part 1					
y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	0	0	0	0	0

P0401, P0402: EGR intrusive test enabling - Part 2					
y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	0	0	0

P0401, P0402: EGR intrusive test enabling - Part 3					
y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

P0401, P0402: EGR intrusive test enabling - Part 4					
y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - P0401: Insufficient EGR flow barometric correction (low level)

Description: Air Temperature correction at low barometric level for OBDII insufficient EGR flow monitor. It is function of air temperature.

Value Units: const [-1,1]
X Unit: °C

y/x	-7	-5	0	5	10	15	20	25	30	35
1	1	1	1	1	1	1	1	1	1	1

Initial Supporting table - P0401: Insufficient EGR flow barometric correction (mid level)

Description: Air Temperature correction at mid barometric level for OBDII insufficient EGR flow monitor. It is function of air temperature.

Value Units: const [-1,1]
X Unit: °C

y/x	-7	-5	0	5	10	15	20	25	30	35
1	1	1	1	1	1	1	1	1	1	1

Initial Supporting table - P0401: Insufficient EGR flow barometric correction (sea level)

Description: Air Temperature correction at sea barometric level for OBDII insufficient EGR flow monitor. It is function of air temperature.

Value Units: const [-1,1]
X Unit: °C

y/x	-7	-5	0	5	10	15	20	25	30	35
1	1	1	1	1	1	1	1	1	1	1

Initial Supporting table - P0401: Insufficient EGR flow barometric table A (low level)

Description: Barometric (low level) calibration table for defining a OBDII threshold for insufficient EGR flow deviation monitoring. It is function of engine speed (X axis) and fuel request (Y axis).

Value Units: mg
X Unit: rpm
Y Units: mm^3

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
0	0	0	0	0	0	0	0	0
5	0	0	0	0	0	0	0	0
15	0	0	0	0	0	0	0	0
25	0	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0	0
45	0	0	0	0	0	0	0	0
50	0	0	0	0	0	0	0	0
55	0	0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0

Initial Supporting table - P0401: Insufficient EGR flow barometric table A (mid level)

Description: Barometric (mid level) calibration table for defining a OBDII threshold for insufficient EGR flow deviation monitoring. It is function of engine speed (X axis) and fuel request (Y axis).

Value Units: mg
X Unit: rpm
Y Units: mm^3

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
0	0	0	0	0	0	0	0	0
5	0	0	0	0	0	0	0	0
15	0	0	0	0	0	0	0	0
25	0	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0	0
45	0	0	0	0	0	0	0	0
50	0	0	0	0	0	0	0	0
55	0	0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0

Initial Supporting table - P0401: Insufficient EGR flow barometric table A (sea level)

Description: Barometric (sea level) calibration table for defining a OBDII threshold for insufficient EGR flow deviation monitoring. It is function of engine speed (X axis) and fuel request (Y axis).

Value Units: mg
X Unit: rpm
Y Units: mm^3

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
0	0	0	0	0	0	0	0	0
5	0	0	0	0	0	0	0	0
15	0	0	0	0	0	0	0	0
25	0	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0	0
45	0	0	0	0	0	0	0	0
50	0	0	0	0	0	0	0	0
55	0	0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0

Initial Supporting table - P0401: Insufficient EGR flow barometric table B (low level)

Description: Barometric (low level) calibration table for defining a OBDII threshold for insufficient EGR flow deviation monitoring. It is function of engine speed (X axis) and fuel request (Y axis).

Value Units: mg
X Unit: rpm
Y Units: mm^3

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
0	-40	-40	-48	-48	-40	-40	-40	-40
5	-40	-40	-48	-48	-40	-40	-40	-40
15	-56	-56	-64	-40	-32	-32	-32	-32
25	-88	-88	-96	-56	-40	-40	-40	-40
30	-88	-88	-96	-56	-48	-48	-48	-48
45	-88	-88	-96	-56	-48	-48	-48	-48
50	-88	-88	-96	-56	-48	-48	-48	-48
55	-88	-88	-96	-56	-48	-48	-48	-48
60	-88	-88	-96	-56	-48	-48	-48	-48

Initial Supporting table - P0401: Insufficient EGR flow barometric table B (mid level)

Description: Barometric (mid level) calibration table for defining a OBDII threshold for insufficient EGR flow deviation monitoring. It is function of engine speed (X axis) and fuel request (Y axis).

Value Units: mg
X Unit: rpm
Y Units: mm^3

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
0	-40	-40	-48	-96	-88	-80	-80	-80
5	-40	-40	-48	-96	-104	-96	-96	-96
15	-40	-40	-48	-96	-120	-112	-112	-112
25	-56	-56	-64	-72	-48	-40	-40	-40
30	-56	-56	-64	-72	-48	-40	-40	-40
45	-56	-56	-64	-72	-48	-40	-40	-40
50	-56	-56	-64	-72	-48	-40	-40	-40
55	-56	-56	-64	-72	-48	-40	-40	-40
60	-56	-56	-64	-72	-48	-40	-40	-40

Initial Supporting table - P0401: Insufficient EGR flow barometric table B (sea level)

Description: Barometric (sea level) calibration table for defining a OBDII threshold for insufficient EGR flow deviation monitoring. It is function of engine speed (X axis) and fuel request (Y axis).

Value Units: mg
X Unit: rpm
Y Units: mm^3

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
0	-112	-112	-120	-160	-144	-112	-112	-112
5	-112	-112	-120	-160	-144	-112	-112	-112
15	-112	-112	-88	-88	-88	-112	-112	-112
25	-112	-112	-88	-88	-88	-112	-112	-112
30	-112	-112	-88	-88	-88	-112	-112	-112
45	-112	-112	-88	-88	-88	-112	-112	-112
50	-112	-112	-88	-88	-88	-112	-112	-112
55	-112	-112	-88	-88	-88	-112	-112	-112
60	-112	-112	-88	-88	-88	-112	-112	-112

Initial Supporting table - P0401: Insufficient EGR flow Max fuel enabling condition

Description: Maximum desired fuel below which the insufficient EGR flow is enabled. It is function of engine speed (X axis) and barometric pressure (Y axis).

Value Units: mm^3
X Unit: rpm
Y Units: kPa

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
72	0	0	25	25	20	1	1	1
74	0	0	25	25	20	1	1	1
77	0	0	20	28	20	1	1	1
80	0	0	20	32	20	1	1	1
83	0	0	20	35	25	1	1	1
86	0	0	23	35	27	1	1	1
89	0	0	26	35	29	1	1	1
92	0	0	29	35	31	1	1	1
95	0	0	32	35	33	1	1	1
98	0	0	35	35	35	1	1	1
100	0	0	35	35	30	1	1	1

Initial Supporting table - P0401: Insufficient EGR flow Max OAT threshold for C1

Description: Maximum desired OAT below which the insufficient EGR flow is enabled, for the Normal combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0401: Insufficient EGR flow Max OAT threshold for C2

Description: Maximum desired OAT below which the insufficient EGR flow is enabled, for the Fully Warm Emissions combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0401: Insufficient EGR flow Max OAT threshold for others

Description: Maximum desired OAT below which the insufficient EGR flow is enabled, for all other combustion modes. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0401: Insufficient EGR flow Max OAT threshold for V2

Description: Maximum desired OAT below which the insufficient EGR flow is enabled, for the Soft Warm Up combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0401: Insufficient EGR flow Min fuel enabling condition

Description: Minimum desired fuel above which the insufficient EGR flow is enabled. It is function of engine speed (X axis) and barometric pressure (Y axis).

Value Units: mm^3
X Unit: rpm
Y Units: kPa

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
72	0	0	15	15	10	0	0	0
74	0	0	15	15	10	0	0	0
77	0	0	10	13	10	0	0	0
80	0	0	10	10	10	0	0	0
83	0	0	10	10	10	0	0	0
86	0	0	9	9	9	0	0	0
89	0	0	8	8	8	0	0	0
92	0	0	6	6	6	0	0	0
95	0	0	5	5	5	0	0	0
98	0	0	5	5	5	0	0	0
100	0	0	5	5	5	0	0	0

Initial Supporting table - P0401: Insufficient EGR flow Min OAT threshold for C1

Description: Minimum desired OAT above which the insufficient EGR flow is enabled, for the Normal combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20

Initial Supporting table - P0401: Insufficient EGR flow Min OAT threshold for C2

Description: Minimum desired OAT above which the insufficient EGR flow is enabled, for the Fully Warm Emissions combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7

Initial Supporting table - P0401: Insufficient EGR flow Min OAT threshold for others

Description: Minimum desired OAT above which the insufficient EGR flow is enabled, for all other combustion modes. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20

Initial Supporting table - P0401: Insufficient EGR flow Min OAT threshold for V2

Description: Minimum desired OAT above which the insufficient EGR flow is enabled, for the Soft Warm Up combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7

Initial Supporting table - P0401: Insufficient EGR intrusive test Max fuel enabling condition

Description: Maximum desired fuel below which the insufficient EGR intrusive test is enabled. It is function of engine speed (X axis) and barometric pressure (Y axis).

Value Units: mm^3
X Unit: rpm
Y Units: kPa

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,500
68	30	30	30	30	30	30	30	30
70	30	30	30	30	30	30	30	30
73	30	30	30	30	30	30	30	30
76	30	30	30	30	30	30	30	30
79	30	30	30	30	30	30	30	30
82	30	30	30	30	30	30	30	30
85	30	30	30	30	30	30	30	30
88	30	30	30	30	30	30	30	30
91	30	30	30	30	30	30	30	30
96	30	30	30	30	30	30	30	30
101	30	30	30	30	30	30	30	30

Initial Supporting table - P0401: Insufficient EGR intrusive test Min fuel enabling condition

Description: Minimum desired fuel above which the insufficient EGR intrusive test is enabled. It is function of engine speed (X axis) and barometric pressure (Y axis).

Value Units: mm^3
X Unit: rpm
Y Units: kPa

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,500
68	10	10	15	15	25	25	25	25
70	10	10	15	15	25	25	25	25
73	10	10	15	15	25	25	25	25
76	10	10	15	15	25	25	25	25
79	10	10	15	15	25	25	25	25
82	10	10	15	15	25	25	25	25
85	10	10	15	15	25	25	25	25
88	10	10	15	15	25	25	25	25
91	10	10	15	15	25	25	25	25
96	10	10	15	15	25	25	25	25
101	10	10	15	15	25	25	25	25

Initial Supporting table - P0401: Minimum desired EGR flow

Description: Minimum desired EGR flow above which the insufficient EGR flow is enabled. It is function of engine speed (X axis) and barometric pressure (Y axis).

Value Units: mg
X Unit: rpm
Y Units: kPa

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
72	216	196	176	184	176	196	216	216
74	216	200	172	184	172	196	216	216
77	216	200	168	184	168	200	216	216
80	216	200	168	176	168	204	216	216
83	216	204	168	176	160	204	216	216
86	216	208	176	184	168	208	216	216
89	216	212	184	184	176	212	216	216
92	216	212	188	192	184	212	216	216
95	216	216	196	196	192	216	216	216
98	216	216	200	200	200	216	216	216
100	216	216	200	200	200	216	216	216

Initial Supporting table - P0402: Excessive EGR flow Max OAT threshold for C1

Description: Maximum desired OAT below which the excessive EGR flow is enabled, for the Normal combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0402: Excessive EGR flow Max OAT threshold for C2

Description: Maximum desired OAT below which the excessive EGR flow is enabled, for the Fully Warm Emissions combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0402: Excessive EGR flow Max OAT threshold for others

Description: Maximum desired OAT below which the excessive EGR flow is enabled, for all others combustion modes. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0402: Excessive EGR flow Max OAT threshold for V2

Description: Maximum desired OAT below which the excessive EGR flow is enabled, for the Soft Warm Up combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0402: Excessive EGR flow Min OAT threshold for C1

Description: Minimum desired OAT above which the excessive EGR flow is enabled, for the Normal combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7

Initial Supporting table - P0402: Excessive EGR flow Min OAT threshold for C2

Description: Minimum desired OAT above which the excessive EGR flow is enabled, for the Fully Warm Emissions combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7

Initial Supporting table - P0402: Excessive EGR flow Min OAT threshold for others

Description: Minimum desired OAT above which the excessive EGR flow is enabled, for all other combustion modes. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7

Initial Supporting table - P0402: Excessive EGR flow Min OAT threshold for V2

Description: Minimum desired OAT above which the excessive EGR flow is enabled, for the Soft Warm Up combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7

Initial Supporting table - P140B, P140C: EGR slow response enabling

Description: Calibration map for the enabling of EGR slow response monitoring, function of combustion mode.

Value Units: boolean

P140B, P140C: EGR slow response enabling - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

P140B, P140C: EGR slow response enabling - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	0	0	0

P140B, P140C: EGR slow response enabling - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

P140B, P140C: EGR slow response enabling - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - P140B: Increasing EGR slow response threshold

Description: Threshold for increasing EGR flow slow response monitoring. It is function of ambient air pressure.

Value Units: %
X Unit: kPa

y/x	75	84	97
1	1	2	3

Initial Supporting table - P140C: Decreasing EGR slow response threshold

Description: Threshold for decreasing EGR flow slow response monitoring. It is function of ambient air pressure.

Value Units: %
X Unit: kPa

y/x	75	84	97
1	2	4	10

Initial Supporting table - P16F3_CB safety deadband threshold f(Fuel Rail Pressure)

Description: Maximum allowable safety deadband on CB Energizing Time compensation (for each torque forming pulse) as a function of Fuel Rail Pressure.

y/x	12	24	36	47	59	71	83	94	106	118	130	141	153	165	177	188	200
1	1,613	1,152	793	607	499	448	398	363	332	309	287	271	255	241	231	220	210

Initial Supporting table - P16F3_EIA safety deadband threshold f(Fuel Rail Pressure)

Description: Maximum allowable safety deadband on EIA Energizing Time compensation (for each torque forming pulse) as function of Fuel Rail Pressure.

y/x	12	24	36	47	59	71	83	94	106	118	130	141	153	165	177	188	200
1	1,621	1,158	797	610	502	450	400	365	333	311	289	272	256	243	232	221	211

Initial Supporting table - P16F3_FTD safety deadband threshold f(Fuel Rail Pressure)

Description: Maximum allowable safety deadband on FTD Energizing Time compensation as function of Fuel Rail Pressure.

y/x	12	24	36	47	59	71	83	94	106	118	130	141	153	165	177	188	200
1	1,621	1,158	797	610	502	450	400	365	333	311	289	272	256	243	232	221	211

Initial Supporting table - P16F3_Rail Pressure Wave Compensation f(Fuel Rail Pressure, Fuel Quantity)

Description: Safety treshold for the Rail Pressure Wave Compensation on each torque forming pulse as a function of Fuel Rail Pressure and Fuel Quantity

y/x	1	2	3	4	5	7	10	20	30	45	60	85	117
16	5	5	5	5	5	5	5	5	5	5	5	5	5
22	11	11	11	11	11	11	11	10	6	5	4	3	2
40	29	29	29	26	24	22	20	14	12	9	7	5	4
60	49	49	42	40	37	34	30	22	18	14	12	9	7
90	79	73	65	62	57	53	48	31	26	21	17	13	11
120	105	98	89	82	75	68	58	34	35	27	21	17	11
150	132	123	112	103	94	86	75	50	43	33	27	21	16
185	165	153	136	124	114	104	89	62	46	40	33	25	19
200	178	165	145	132	122	111	94	65	49	41	36	26	11
210	187	174	152	138	128	116	97	68	54	46	40	30	19

Initial Supporting table - P16F3_Speed Control External Load f(Oil Temp, RPM)

Description: Specifies the external load table for SPDR torque security as a function of engine oil temperature and engine RPM.

y/x	-40	-20	-10	0	50	90
430	239	212	196	158	120	120
530	233	206	190	110	67	67
630	212	185	169	89	46	46
730	205	178	161	82	41	41
750	197	170	154	74	36	36
800	182	156	141	83	45	45
900	164	139	124	88	53	53
1,000	145	121	107	93	60	60
1,100	147	125	113	101	72	72
1,200	149	129	119	109	84	84
1,400	93	73	63	53	28	28
1,600	11	-9	-19	-29	-54	-54
2,000	-220	-220	-220	-220	-220	-220
2,500	-242	-242	-242	-242	-242	-242
3,000	-264	-264	-264	-264	-264	-264
3,500	-286	-286	-286	-286	-286	-286
5,000	-286	-286	-286	-286	-286	-286

Initial Supporting table - P16F3_Speed Control External Load Max f(Vehicle Speed, RPM)

Description: External load calibration table on the basis of engine speed and vehicle speed

y/x	0	6	8	10	20	40	50
500	4,096	4,096	4,096	4,096	4,096	4,096	4,096
800	4,096	4,096	4,096	4,096	4,096	4,096	4,096
1,000	4,096	4,096	200	200	200	200	200
1,500	4,096	4,096	200	0	-100	-100	-100
2,000	4,096	4,096	200	0	-100	-100	-100

Initial Supporting table - P16F3_Speed Control External Load Offset f(Vehicle Sped, Transmission Oil Temp)

Description: The offset load to add to KtSPDC_M_ExtrenalLoadMaxLmt.

y/x	0	6	8	10	20	40	50
-40	0	0	0	0	0	0	0
-20	0	0	0	0	0	0	0
-10	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
50	0	0	0	0	0	0	0
90	0	0	0	0	0	0	0

Initial Supporting table - P16F3_SQA safety deadband threshold f(Fuel Rail Pressure)

Description: Maximum allowable safety deadband on SQA Energizing Time compensation (for each torque forming pulse) as function of Fuel Rail Pressure.

y/x	12	29	46	63	80	97	115	132	149	166	183	200
1	1,669	1,023	730	593	521	458	397	370	344	319	293	275

Initial Supporting table - P16F3_VCA safety max deadband threshold f(Fuel Rail Pressure)

Description: Maximum allowable safety deadband on VCA energizing time correction as function of Fuel Rail Pressure.

y/x	12	24	36	47	59	71	83	94	106	118	130	141	153	165	177	188	200
1	811	579	398	305	251	225	200	183	167	155	144	136	128	121	116	111	106

Initial Supporting table - P16F3_VCA safety min deadband threshold f(Fuel Rail Pressure)

Description: Minimum allowable safety deadband on VCA energizing time correction as function of Fuel Rail Pressure.

y/x	12	24	36	47	59	71	83	94	106	118	130	141	153	165	177	188	200
1	-811	-579	-398	-305	-251	-225	-200	-183	-167	-155	-144	-136	-128	-121	-116	-111	-106

Initial Supporting table - P2457: Maximum HP EGR filtered flow for HP EGR cooler efficiency monitor enabling

Description: Maximum allowed HP EGR filtered flow as a function of ambient air temperature to enable HP EGR cooler efficiency diagnostic.

Value Units: g/s
X Unit: deg C

y/x	1	2	3	4	5	6
1	20	20	20	20	20	20

Initial Supporting table - P2457: Minimum HP EGR filtered flow for HP EGR cooler efficiency monitor enabling

Description: Minimum allowed HP EGR filtered flow as a function of ambient air temperature to enable HP EGR cooler efficiency diagnostic.

Value Units: g/s
X Unit: deg C

y/x	1	2	3	4	5	6
1	3	3	3	3	3	3

Initial Supporting table - P2457: Minimum time for HP EGR cooler efficiency monitor enabling

Description: Minimum allowed time as a function of HP EGR filtered flow to run HP EGR cooler efficiency diagnostic once that all HP EGR flow enabling conditions are reached.

Value Units: s
X Unit: g/s

y/x	1	2	3	4	5	6
1	1	1	1	1	1	1

Initial Supporting table - P24A5: Combustion mode enabling table

Description: Enabling flag for the HP EGR Cooler Bypass Stuck diagnosis, function of combustion mode.

Value Units: boolean

P24A5: Combustion mode enabling table - Part 1					
y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

P24A5: Combustion mode enabling table - Part 2					
y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	0	0	0

P24A5: Combustion mode enabling table - Part 3					
y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

P24A5: Combustion mode enabling table - Part 4					
y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - P24A5: Gradient Temperature Threshold

Description: HP EGR Cooler Bypass Stuck diagnosis gradient temperature threshold map to be applied at HP EGR Cooler Bypass Stuck diagnosis. It is function of the HP EGR valve total flow.

Value Units: °C
X Unit: g/s

y/x	0	2	3	5	6	8	12	20
1	12	12	12	12	12	12	12	12

Initial Supporting table - P24A5: Maximum EGR flow

Description: Maximum HP EGR flow below which the HP EGR cooler bypass stuck monitoring is enabled. It is function of Ambient Temperature.

Value Units: g/s
X Unit: °C

y/x	-9	-5	0	5	15	30
1	25	25	25	25	25	25

Initial Supporting table - P24A5: Maximum upstream EGR temperature

Description: Maximum upstream HP EGR temperature below which the HP EGR cooler bypass stuck monitor is enabled. It is function of Ambient Temperature.

Value Units: °C
X Unit: °C

y/x	-9	-6	-3	0	5	10
1	475	475	475	475	475	475

Initial Supporting table - P24A5: Minimum EGR flow

Description: Minimum HP EGR flow above which the HP EGR cooler bypass stuck monitoring is enabled. It is function of Ambient Temperature.

Value Units: g/s
X Unit: °C

y/x	-9	-5	0	5	15	30
1	9	8	8	8	7	6

Initial Supporting table - P24A5: Minimum upstream EGR temperature

Description: Minimum upstream HP EGR temperature above which the HP EGR cooler bypass stuck monitor is enabled. It is function of Ambient Temperature.

Value Units: °C
X Unit: °C

y/x	-9	-6	-3	0	5	10
1	250	240	235	230	225	220

Initial Supporting table - Pair_SCD_Decel

Description: Used for P0300 - P0308, Mulitplier to SCD_Decel to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
6	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
16	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - Pair_SCD_Jerk

Description: Used for P0300 - P0308, Mulitplier to P0300_SCD_Jerk to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
6	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
16	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - PairCylModeDecel

Description: Used for P0300 - P0308, Mulitplier to Cyl Mode Deceleration to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: mulitplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	580	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,400	2,800	3,200	3,800	4,000	4,400
6	0.79	0.89	0.96	0.88	0.81	0.64	0.78	0.76	0.85	0.82	0.94	0.82	0.94	1.00	1.00	0.82	0.72
8	0.79	0.91	0.90	0.89	0.83	0.71	0.78	0.68	1.00	0.86	0.96	0.77	0.89	1.00	1.00	0.87	0.75
12	0.45	0.53	0.60	0.62	0.72	0.75	0.68	0.92	0.96	1.22	1.19	0.96	1.14	1.06	1.05	1.00	0.81
16	0.52	0.56	0.60	0.68	0.73	0.75	0.67	1.30	0.90	1.05	1.21	1.17	0.85	0.96	0.94	1.00	0.85
20	0.55	0.56	0.63	0.73	0.74	0.76	0.67	1.22	0.87	1.06	1.18	1.15	0.84	0.92	0.81	0.95	0.87
24	0.57	0.56	0.65	0.76	0.74	0.76	0.66	1.17	0.97	1.16	1.18	1.12	0.85	0.88	0.81	0.85	0.93
30	0.58	0.56	0.67	0.80	0.75	0.76	0.66	1.12	1.08	1.24	1.18	1.13	0.89	0.94	0.82	0.85	0.91
60	0.68	0.57	0.71	0.86	0.75	0.77	0.65	1.04	1.34	1.42	1.17	1.07	0.91	0.92	0.86	0.94	0.86
98	1.00	0.57	0.72	0.89	0.76	0.77	0.65	1.01	1.46	1.50	1.17	1.04	0.92	0.91	0.87	0.97	0.83

Initial Supporting table - PairCylModeJerk

Description: Used for P0300 - P0308, Mulitplier to P0300_CylModeJerk to account for different pattern of Paired cylinder misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	580	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,400	2,800	3,200	3,800	4,000	4,400
6	1.49	1.48	1.68	1.48	1.56	1.35	1.37	1.26	1.53	1.53	1.72	1.56	2.01	2.11	2.10	1.77	1.41
8	1.01	1.03	1.14	1.07	1.12	1.03	1.05	0.98	1.20	1.32	1.54	1.60	1.95	2.32	2.24	1.87	1.49
12	0.69	0.76	0.72	0.64	0.66	0.83	0.83	1.17	0.99	1.03	1.01	1.23	1.70	2.14	2.24	2.16	1.70
16	0.84	0.84	0.83	0.70	0.68	0.79	0.76	1.17	0.85	0.98	0.91	1.03	1.00	1.47	1.70	1.92	1.82
20	0.93	0.88	0.89	0.72	0.69	0.77	0.72	1.04	0.78	0.96	0.94	0.99	0.78	1.12	1.20	1.32	1.39
24	1.00	0.90	0.93	0.74	0.69	0.76	0.70	0.97	0.84	0.97	0.93	0.95	0.79	1.03	1.16	1.09	1.06
30	1.07	0.92	0.98	0.76	0.70	0.74	0.68	0.91	0.91	1.03	0.95	0.93	0.88	1.01	1.20	1.15	1.06
60	1.00	0.96	1.06	0.80	0.70	0.72	0.64	0.80	1.05	1.14	0.98	0.88	1.06	0.92	1.32	1.28	1.09
98	1.00	1.00	1.09	0.81	0.71	0.71	0.63	0.76	1.10	1.19	0.99	0.87	1.12	0.89	1.40	1.33	1.10

Initial Supporting table - Random_SCD_Decel

Description: Used for P0300 - P0308, Mulitplier to SCD_Decel to account for different pattern of light level misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
4	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
6	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
18	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - Random_SCD_Jerk

Description: Used for P0300 - P0308, Mulitplier to Random_SCD_Jerk to account for different pattern of light level misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	550	700	800	900	1,000	1,200	1,400	1,600
4	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
6	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
18	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - RandomAFM_Decl

Description: Used for P0300 - P0308, Mulitplier to Cylinder_Decel while in Cylnder Deactivation mode to account for different pattern of light level misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
5	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
10	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
50	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
80	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
100	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - RandomAFM_Jerk

Description: Used for P0300 - P0308, Mulitplier to Cylinder_Jerk while in Cylnder Deactivation mode to account for different pattern of light level misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	800	1,000	1,200	1,600	2,000	2,400	2,600	3,000	3,500
5	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
10	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
20	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
40	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
50	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
80	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
100	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - RandomCylModDecel

Description: Used for P0300 - P0308. Multiplier to CylMode_Decel. account for different pattern of light level misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: Multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	580	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,400	2,800	3,200	3,800	4,000	4,400
4	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.11	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
6	1.36	1.33	1.42	1.36	1.33	1.27	1.43	1.23	1.20	1.12	1.12	1.01	1.00	1.00	1.00	1.00	1.00
8	1.92	1.89	1.72	1.80	1.69	1.67	1.71	1.16	1.67	1.27	1.25	1.07	1.00	1.00	1.00	1.00	1.00
12	1.88	1.86	2.16	2.21	2.55	2.41	2.11	1.05	1.77	1.84	1.87	1.23	1.49	1.22	1.04	1.00	1.00
18	1.87	1.84	2.29	2.34	2.48	2.53	2.22	1.91	2.03	2.01	2.53	2.21	2.02	2.12	1.51	1.30	1.09
24	1.86	1.83	2.35	2.41	2.45	2.58	2.28	2.14	2.35	2.35	2.56	2.34	2.44	2.59	1.86	1.89	1.87
30	1.85	1.82	2.39	2.45	2.43	2.62	2.32	2.27	2.55	2.54	2.61	2.44	2.47	2.59	1.94	1.93	1.93
60	1.00	1.82	2.46	2.53	2.39	2.69	2.38	2.50	3.03	2.95	2.71	2.66	2.52	2.51	2.16	2.04	2.12
98	1.00	1.15	2.00	2.57	2.38	2.71	2.41	2.58	3.24	3.11	2.75	2.75	2.54	2.52	2.22	2.08	2.18

Initial Supporting table - RandomCylModJerk

Description: Used for P0300 - P0308, Multiplier to CylMode_Jerk to account for different pattern of light level misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	580	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,400	2,800	3,200	3,800	4,000	4,400
4	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
6	1.00	1.00	1.04	1.00	1.00	1.12	1.05	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
8	1.00	1.05	1.00	1.00	1.00	1.12	1.04	1.00	1.00	1.00	1.00	1.02	1.00	1.00	1.00	1.00	1.00
12	1.19	1.22	1.18	1.05	1.05	1.25	1.14	1.00	1.00	1.00	1.00	1.00	1.06	1.10	1.00	1.00	1.00
18	1.39	1.33	1.31	1.08	1.06	1.19	1.08	1.00	1.04	1.06	1.07	1.04	1.15	1.19	1.18	1.05	1.00
24	1.50	1.38	1.38	1.10	1.06	1.17	1.05	1.00	1.14	1.14	1.16	1.09	1.20	1.22	1.33	1.16	1.00
30	1.57	1.42	1.42	1.11	1.06	1.16	1.04	1.00	1.19	1.18	1.19	1.09	1.22	1.22	1.34	1.23	1.08
60	1.00	1.49	1.51	1.13	1.07	1.13	1.01	1.00	1.30	1.29	1.25	1.12	1.28	1.15	1.40	1.37	1.31
98	1.00	1.00	1.30	1.13	1.07	1.13	1.01	1.00	1.35	1.33	1.29	1.13	1.30	1.15	1.60	1.43	1.41

Initial Supporting table - RandomRevModDecl

Description: Used for P0300 - P0308, Mulitplier to RevMode_Decel to account for different pattern of light level misfire. Multipliers are a function of engine rpm and % engine Load.

Value Units: multiplier
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	3,000	3,500	4,000	4,500	5,000	5,500	6,000	7,000	8,000
4	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
6	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
8	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
12	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
18	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
24	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
30	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
60	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
98	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - RepetSnapDecayAdjst

Description: Used for P0300 - P0308, If misfire is present in consecutive engine cycles, this multiplier is applied to the misfire jerk threshold and compared to a crankshaft snap value after the misfire has taken place.. Table lookup as a function of engine rpm.

Value Units: multiplier
X Unit: RPM

y/x	730	900	1,200	1,400	1,600	2,000	2,800	3,600	4,400
1	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00

Initial Supporting table - RevMode_Decel

Description: Used for P0300-P0308. Crankshaft decel threshold. Thresholds are a function of rpm and % engine Load.

Value Units: Delta time between revolutions (usec)
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	1,100	1,200	1,400	1,600	1,800	2,000	2,200	2,400	2,600	2,800	3,000	3,100	3,500	4,000	4,500	5,000	5,500	6,500	7,000
2	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
4	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
6	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
8	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
10	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
12	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
14	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
16	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
18	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
20	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
22	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
24	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
26	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
30	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
40	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
60	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
97	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

Initial Supporting table - Ring Filter

Description: Used for P0300-P0308. Driveline Ring Filter
After a low level misfire, another misfire may not be detectable until driveline ringing ceases. If no ringing seen, stop filter early.

Value Units: Number of Engine cycles after isolated misfire (Engine cycles)
X Unit: thousands of RPM (rpm/1000)

y/x	0	1	2	3	4	5	6	7	8
1	5	5	5	5	5	5	5	5	5

Initial Supporting table - SCD_Decel

Description: Used for P0300-P0308 Crankshaft decel threshold. SCD mode uses smaller windows near TDC. Thresholds are a function of rpm and % engine Load.

Value Units: Delta time per cylinder (usec)
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	500	600	700	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000
2	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
4	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
6	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
8	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
10	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
12	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
14	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
16	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
18	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
20	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
22	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
24	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
26	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
30	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
40	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
60	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
97	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

Initial Supporting table - SCD_Jerk

Description: Used for P0300-P0308. Crankshaft jerk threshold. SCD mode uses smaller windows near TDC. Thresholds are a function of rpm and % engine Load.

Value Units: Change in Delta time per cylinder from last cylinder (usec)
X Unit: RPM
Y Units: percent load of max indicated torque (%)

y/x	400	500	600	700	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000
2	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
4	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
6	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
8	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
10	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
12	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
14	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
16	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
18	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
20	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
22	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
24	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
26	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
30	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
40	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
60	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
97	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

Initial Supporting table - SnapDecayAfterMisfire

Description: Used for P0300 - P0308, multiplier times the ddt_jerk value used used to detect misfire at that speed and load to see if size of disturbance has died down as expected of real misfire. Table lookup as a function of engine rpm and trans gear ratio.

Value Units: multiplier
X Unit: RPM
Y Units: gear ratio

y/x	730	900	1,200	1,400	1,600	2,000	2,800	3,600	4,400
1	1.65	1.65	1.65	1.65	1.90	1.80	1.30	1.30	1.30
1	1.20	1.20	1.20	1.20	1.45	1.40	1.00	1.00	1.00
1	1.50	1.50	1.50	2.30	1.00	1.25	1.10	1.00	1.00
2	1.60	1.60	1.40	2.20	1.25	1.00	1.00	1.30	1.10
2	2.40	1.80	2.15	2.15	2.40	1.20	1.25	1.10	1.05
4	2.60	1.80	1.80	1.85	1.65	1.65	1.80	1.40	1.00
5	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
5	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00
8	2.50	2.30	2.15	2.10	2.00	2.00	2.00	1.30	1.00

Initial Supporting table - t_DerTempDsblTmr

Description: Disabling timer based on the time derivative of SCR average temperature [sec] for SCR NOx catalyst efficiency monitoring (P20EE)

Value Units: sec
X Unit: °C/sec

y/x	-10	-5	0	2	5	9	10	12
1	10	10	10	120	180	240	300	360

Initial Supporting table - T_MaxTempGrad

Description: Upper boundary of SCR temperature gradient (difference between SCR upstream and SCR downstream) [°C] for SCR NOx catalyst efficiency monitoring (P20EE)

Value Units: °C
X Unit: °C

y/x	100	150	200	250	300	350	400	450
1	35	35	35	35	45	35	35	35

Initial Supporting table - T_MinTempGrad

Description: Lower boundary of SCR temperature gradient (difference between SCR upstream and SCR downstream) [°C] for SCR NOx catalyst efficiency monitoring (P20EE)

Value Units: °C
X Unit: °C

y/x	225	250	275	300	325	350	400	450
1	-100	-100	-100	-100	-100	-100	-100	-100

Initial Supporting table - t_NOxFlowIncDsblTmr

Description: Debounce time to wait after the NOx flow becomes in range [sec] for SCR NOx catalyst efficiency monitoring (P20EE)

Value Units: sec
X Unit: mg/sec
Y Units: sec

y/x	5	15	30	45	60	90	120
5	0	0	0	0	0	0	0
10	0	0	0	0	0	0	0
15	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0
50	0	0	0	0	0	0	0
100	0	0	0	0	0	0	0
150	0	0	0	0	0	0	0
200	0	0	0	0	0	0	0

Initial Supporting table - TOSSRoughRoadThres

Description: Used for P0300-P0308. Only used if Rough Road source = TOSS: dispersion value on Transmission Output Speed Sensor above which rough road is indicated present

Value Units: change in rpm per sec (rpm)
X Unit: Engine Speed (RPM)
Y Units: Transmission Speed (RPM)

y/x	600	800	1,000	1,200	1,400	1,600	1,800	2,000	2,200	2,400	2,600	2,800	3,000	3,500	4,000	4,500	5,000	5,500	6,000
100	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0
300	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0
600	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0
900	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0
1,200	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0
1,500	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0
1,800	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0
2,100	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0
2,400	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0
2,700	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0
3,000	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0
3,300	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0
3,600	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0
4,200	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0	20.0

Initial Supporting table - WaitToStart

Description: Used for P0300-P0308. Number of engine cycles to delay if diesel engine is cranked before wait to start lamp is extinguished. This lookup table determines the delay length by taking into account the coolant temperature.

Value Units: Number of Engine Cycles (integer)
X Unit: Engine Coolant (deg C)

y/x	-20	-10	0	10	20	30	40	50	60
1	0	0	0	0	0	0	0	0	0

Initial Supporting table - WSSRoughRoadThres

Description: Used for P0300-P0308. Only used if Wheel speed from ABS is used. If difference between wheel speed readings is larger than this limit, rough road is present

Value Units: acceleration
X Unit: Vehicle Speed (KPH)

y/x	0	12	24	36	48	60	72	85	97	109	121	133	145	157	169	181	193
1	1.05005	1.05005	1.05005	1.05005	1.05005	1.05005	1.05005	1.05005	1.05005	1.05005	1.05005	1.05005	1.05005	1.05005	1.05005	1.05005	1.05005

Initial Supporting table - ZeroTorqueAFM

Description: Used for P0300-P0308. Zero torque engine load while in Active Fuel Management. %of Max Brake Torque along the Neutral rev line, as a function of RPM and Baro

Value Units: Percent of Maximum Brake torque (%)
X Unit: RPM
Y Units: Barometric Pressure (kPa)

ZeroTorqueAFM - Part 1

y/x	580	655	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,200
65	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
75	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
85	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
95	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
105	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00

ZeroTorqueAFM - Part 2

y/x	2,400	2,600	2,800	3,000	3,200	3,400	3,600	3,800	4,000	4,200	4,400	4,600	4,800
65	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
75	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
85	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
95	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00
105	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00

Initial Supporting table - ZeroTorqueEngLoad

Description: Used for P0300-P0308. %of Max Brake Torque that represents Zero Brake torque along the Neutral rev line, as a function of RPM and Baro

Value Units: Percent of Maximum Brake torque (%)
X Unit: RPM
Y Units: Barometric Pressure (kPa)

ZeroTorqueEngLoad - Part 1

y/x	580	655	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,200
65	-1.32	-1.45	-1.60	-2.00	-2.53	-2.61	-2.39	-2.08	-3.16	-1.97	-3.04	-3.64	-4.42
75	-1.13	-1.31	-1.35	-1.68	-2.37	-2.27	-2.44	-2.33	-3.36	-2.27	-2.72	-3.78	-3.96
85	-1.05	-1.43	-1.50	-1.99	-2.76	-2.72	-2.30	-2.23	-3.30	-2.45	-3.11	-3.90	-4.37
95	-0.70	-0.99	-1.20	-1.65	-2.13	-1.80	-2.26	-2.75	-4.03	-2.90	-3.03	-3.18	-3.77
105	-0.70	-0.99	-1.20	-1.65	-2.13	-1.80	-2.26	-2.75	-4.03	-2.90	-3.03	-3.18	-3.77

ZeroTorqueEngLoad - Part 2

y/x	2,400	2,600	2,800	3,000	3,200	3,400	3,600	3,800	4,000	4,200	4,400	4,600	4,800
65	-3.41	-2.39	-1.38	-0.37	0.64	1.65	2.67	3.67	4.69	5.70	6.71	7.72	8.73
75	-2.85	-1.85	-0.85	0.15	1.15	2.15	3.16	4.16	5.16	6.16	7.16	8.16	9.16
85	-3.38	-2.39	-1.40	-0.40	0.59	1.57	2.57	3.56	4.55	5.54	6.53	7.52	8.51
95	-2.84	-1.92	-0.99	-0.07	0.85	1.77	2.69	3.61	4.53	5.46	6.38	7.31	8.23
105	-2.84	-1.92	-0.99	-0.07	0.85	1.77	2.69	3.61	4.53	5.46	6.38	7.31	8.23

Initial Supporting table - AIC_AirCntrlShtOffActn: ECT Too Low Hysteresis High Threshold for DPF

Description: Hysteresis high threshold for engine coolant temperature too low shut off condition evaluation during DPF combustion modes and SCR service warm up combustion mode. It is function of outside air temperature.

Value Units: °C
X Unit: °C

y/x	-20	-10	0	10	20	30
1	48	48	42	29	16	16

Initial Supporting table - AIC_AirCntrlShtOffActn: ECT Too Low Hysteresis High Threshold for others

Description: Hysteresis high threshold for engine coolant temperature too low shut off condition evaluation. It is function of outside air temperature.

Value Units: °C
X Unit: °C

y/x	-23	-22	-10	0	10	20
1	140	68	19	18	17	16

Initial Supporting table - AIC_AirCntrlShtOffActn: ECT Too Low Hysteresis Low Threshold for DPF

Description: Hysteresis low threshold for engine coolant temperature too low shut off condition evaluation during DPF combustion modes and SCR service warm up combustion mode. It is function of outside air temperature.

Value Units: °C
X Unit: °C

y/x	-20	-10	0	10	20	30
1	45	45	39	26	13	13

Initial Supporting table - AIC_AirCntrlShtOffActn: ECT Too Low Hysteresis Low Threshold for others

Description: Hysteresis low threshold for engine coolant temperature too low shut off condition evaluation. It is function of outside air temperature.

Value Units: °C
X Unit: °C

y/x	-23	-22	-10	0	10	20
1	137	65	16	15	14	13

Initial Supporting table - AIC_AirCntrlShtOffActn: Fuel High Threshold for D1 and D3

Description: Hysteresis high threshold for large injected fuel shut off condition evaluation during DPF and HCS combustion modes. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000
1	75	75	75	75	75	75	75	75

Initial Supporting table - AIC_AirCntrlShtOffActn: Fuel High Threshold for D4

Description: Hysteresis high threshold for large injected fuel shut off condition evaluation during DPF rich idle combustion mode. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000
1	75	75	75	75	75	75	75	75

Initial Supporting table - AIC_AirCntrlShtOffActn: Fuel Low Threshold for D1 and D3

Description: Hysteresis low threshold for large injected fuel shut off condition evaluation during DPF and HCS combustion modes. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000
1	70	70	70	70	70	70	70	70

Initial Supporting table - AIC_AirCntrlShtOffActn: Fuel Low Threshold for D4

Description: Hysteresis low threshold for large injected fuel shut off condition evaluation during DPF rich idle combustion mode. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000
1	70	70	70	70	70	70	70	70

Initial Supporting table - AIC_BstCntrlCL: Fuel Request On Threshold for C2

Description: Fuel threshold above which the pressure closed loop control is enabled in C2 mode. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	750	900	1,000	1,100	1,225	1,250	1,500	2,000	2,500	3,000	3,500	4,000
1	66	66	66	64	52	47	46	42	38	33	28	27	27

Initial Supporting table - AIC_BstCntrlCL: Fuel Request On Threshold for D1 and D3

Description: Fuel threshold above which the pressure closed loop control is enabled in DPF high O2, Rich idle and all HC modes and SCR service warm up. It is function of engine speed).

Value Units: mm^3
X Unit: rpm

y/x	500	750	900	1,000	1,100	1,225	1,250	1,500	2,000	2,500	3,000	3,500	4,000
1	30	18	15	14	12	10	10	8	8	8	8	8	8

Initial Supporting table - AIC_BstCntrlCL: Fuel Request On Threshold for D4

Description: Fuel threshold above which the pressure closed loop control is enabled in DPF low O2. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	750	900	1,000	1,100	1,225	1,250	1,500	2,000	2,500	3,000	3,500	4,000
1	30	30	30	15	15	15	15	15	15	15	15	15	15

Initial Supporting table - AIC_BstCntrlCL: Fuel Request On Threshold for others

Description: Fuel threshold above which the pressure closed loop control is enabled. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	750	900	1,000	1,100	1,225	1,250	1,500	2,000	2,500	3,000	3,500	4,000
1	150	150	150	150	150	150	5	5	5	5	5	5	5

Initial Supporting table - AIC_BstCntrlCL: Fuel Request On Threshold for V3

Description: Fuel threshold above which the pressure closed loop control is enabled in SCR temp 1 or DeSOx lean mode. It is function of engine speed.

Value Units: mm^3
X Unit: rpm

y/x	500	750	900	1,000	1,100	1,225	1,250	1,500	2,000	2,500	3,000	3,500	4,000
1	150	150	150	150	150	150	5	5	5	5	5	5	5

Initial Supporting table - AIC_BstCntrlCL: On Threshold for V1

Description: Threshold above which the pressure closed loop control is enabled in SCR temp 3 or DeNOx mode. It is function of engine speed.

Value Units: composite
X Unit: rpm

y/x	500	750	900	1,000	1,100	1,225	1,250	1,500	2,000	2,500	3,000	3,500	4,000
1	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000

Initial Supporting table - AIC_BstCntrlCL: On Threshold for V2

Description: Threshold above which the pressure closed loop control is enabled in SCR temp 2 or DeSOx Rich mode. It is function of engine speed.

Value Units: composite
X Unit: rpm

y/x	500	750	900	1,000	1,100	1,225	1,250	1,500	2,000	2,500	3,000	3,500	4,000
1	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000	2,000

Initial Supporting table - AirCntrlTrnstnEnd: Timer threshold

Description: Timer threshold after which an air control transition is considered as ended. It is function of engine speed.

Value Units: s
X Unit: rpm

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,000	4,500
1	0	0	0	0	0	0	0	0	0

Initial Supporting table - KaFADR_e_FSA_CombModeEnblGrp

Description: Enable FSA learning based on the combustion modes and select related maps based on calibrated groups

Value Units: -
X Unit: -

KaFADR_e_FSA_CombModeEnblGrp - Part 1				
y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions
1	CeFADR_e_FSA_Grp1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd
KaFADR_e_FSA_CombModeEnblGrp - Part 2				
y/x	CeCMBR_e_LNT_DeNOx	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp
1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_Grp2
KaFADR_e_FSA_CombModeEnblGrp - Part 3				
y/x	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2
1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd
KaFADR_e_FSA_CombModeEnblGrp - Part 4				
y/x	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn	CeCMBR_e_HCS_DeHC_Drive
1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd
KaFADR_e_FSA_CombModeEnblGrp - Part 5				
y/x	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	

Initial Supporting table - KaFADR_e_FSA_CombModeRelGrp

Description: Enable FSA correction release based on the combustion modes and select related maps based on calibrated groups

Value Units: -
X Unit: -

KaFADR_e_FSA_CombModeRelGrp - Part 1				
y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions
1	CeFADR_e_FSA_Grp1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd
KaFADR_e_FSA_CombModeRelGrp - Part 2				
y/x	CeCMBR_e_LNT_DeNOx	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp
1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_Grp2
KaFADR_e_FSA_CombModeRelGrp - Part 3				
y/x	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2
1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd
KaFADR_e_FSA_CombModeRelGrp - Part 4				
y/x	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn	CeCMBR_e_HCS_DeHC_Drive
1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd
KaFADR_e_FSA_CombModeRelGrp - Part 5				
y/x	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	

Initial Supporting table - KaFADR_e_FSA_ECM_CombModeGrp

Description: Enable P026C and P026D in specific combustion modes and select related threshold maps based on calibrated group

Value Units: -
X Unit: -

KaFADR_e_FSA_ECM_CombModeGrp - Part 1				
y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions
1	CeFADR_e_FSA_Grp1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd
KaFADR_e_FSA_ECM_CombModeGrp - Part 2				
y/x	CeCMBR_e_LNT_DeNOx	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp
1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_Grp2
KaFADR_e_FSA_ECM_CombModeGrp - Part 3				
y/x	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2
1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd
KaFADR_e_FSA_ECM_CombModeGrp - Part 4				
y/x	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn	CeCMBR_e_HCS_DeHC_Drive
1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd
KaFADR_e_FSA_ECM_CombModeGrp - Part 5				
y/x	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	CeFADR_e_FSA_GrpNotAllwd	

Initial Supporting table - KtFADC_V_FSA_FuelMax

Description: Map used to define FSA maximum authority

Value Units: mm^3
X Unit: mm^3
Y Units: rpm

y/x	10	20	30	40	50	60	70	80	90	100
800	11	12	14	17	20	23	24	26	27	29
1,000	12	13	15	17	20	23	24	26	27	29
1,250	13	14	16	18	21	24	24	26	27	29
1,500	13	15	17	19	22	24	25	27	28	30
1,750	13	15	17	20	23	25	26	28	29	31
2,000	13	15	17	20	23	26	27	29	30	31
2,250	13	15	17	20	23	26	28	30	31	32
2,500	13	15	17	20	23	26	28	30	31	33
2,750	13	15	17	20	23	26	28	30	31	33
3,000	13	15	17	20	23	26	28	30	31	33

Initial Supporting table - KtFADC_V_FSA_FuelMin

Description: Map used to define FSA minimum authority

Value Units: mm^3
X Unit: mm^3
Y Units: rpm

y/x	10	20	30	40	50	60	70	80	90	100
800	-11	-12	-14	-17	-20	-23	-24	-26	-27	-29
1,000	-12	-13	-15	-17	-20	-23	-24	-26	-27	-29
1,250	-13	-14	-16	-18	-21	-24	-24	-26	-27	-29
1,500	-13	-15	-17	-19	-22	-24	-25	-27	-28	-30
1,750	-13	-15	-17	-20	-23	-25	-26	-28	-29	-31
2,000	-13	-15	-17	-20	-23	-26	-27	-29	-30	-31
2,250	-13	-15	-17	-20	-23	-26	-28	-30	-31	-32
2,500	-13	-15	-17	-20	-23	-26	-28	-30	-31	-33
2,750	-13	-15	-17	-20	-23	-26	-28	-30	-31	-33
3,000	-13	-15	-17	-20	-23	-26	-28	-30	-31	-33

Initial Supporting table - KtFADD_K_FSA_ECM_PresAmbWghtHi

Description: Curve of the weighting factor dependent on ambient pressure for P026D

Value Units: -
X Unit: kPa

y/x	67	87	100
1	1	1	1

Initial Supporting table - KtFADD_K_FSA_ECM_PresAmbWghtLo

Description: Curve of the weighting factor dependent on ambient pressure for P026C

Value Units: -
X Unit: kPa

y/x	67	87	100
1	1	1	1

Initial Supporting table - KtFADD_V_FSA_ECM_HiThrshGrp1

Description: Map to define P026D threshold for combustion mode Group 1

Value Units: mm^3
X Unit: mm^3
Y Units: rpm

y/x	8	11	13	14	18	19	24	25	28	29
525	3	4	6	6	6	6	6	6	6	6
730	3	4	6	6	6	6	6	6	6	6
800	3	4	6	6	6	6	6	6	6	6
850	4	4	6	6	6	6	6	6	6	6
900	4	4	6	6	6	6	6	6	6	6
1,000	4	4	6	6	6	6	6	6	6	6
1,100	4	4	6	6	6	6	6	6	6	6
1,200	4	4	6	6	6	6	6	6	6	6

Initial Supporting table - KtFADD_V_FSA_ECM_HiThrshGrp2

Description: Map to define P026D threshold for combustion mode Group 2

Value Units: mm^3
X Unit: mm^3
Y Units: rpm

y/x	8	11	13	14	18	19	24	25	28	29
525	4	5	6	7	8	8	8	8	8	8
730	4	5	6	7	8	8	8	8	8	8
800	5	6	7	8	9	9	9	9	9	9
850	6	7	9	9	10	10	10	10	10	10
900	6	7	9	9	10	10	10	10	10	10
1,000	6	7	9	9	10	10	10	10	10	10
1,100	6	7	9	9	10	10	10	10	10	10
1,200	6	7	9	9	10	10	10	10	10	10

Initial Supporting table - KtFADD_V_FSA_ECM_HiThrshGrp3

Description: Map to define P026D threshold for combustion mode Group 3

Value Units: mm^3
X Unit: mm^3
Y Units: rpm

y/x	8	11	13	14	18	19	24	25	28	29
525	5	5	7	10	11	11	11	11	11	11
730	5	5	7	10	11	11	11	11	11	11
800	5	5	7	10	11	11	11	11	11	11
850	5	5	7	10	11	11	11	11	11	11
900	5	5	7	10	11	11	11	11	11	11
1,000	5	5	7	10	11	11	11	11	11	11
1,100	5	5	7	10	11	11	11	11	11	11
1,200	5	5	7	10	11	11	11	11	11	11

Initial Supporting table - KtFADD_V_FSA_ECM_LoThrshGrp1

Description: Map to define P026C threshold for combustion mode Group 1

Value Units: mm^3
X Unit: mm^3
Y Units: rpm

y/x	8	11	13	14	18	19	24	25	28	29
525	-3	-3	-3	-3	-3	-2	-2	-2	-2	-2
730	-3	-3	-3	-3	-3	-2	-2	-2	-2	-2
800	-3	-3	-3	-3	-3	-2	-1	-1	-1	-1
850	-3	-3	-3	-3	-3	-2	-1	-1	-1	-1
900	-3	-3	-3	-3	-3	-2	-1	-1	-1	-1
1,000	-3	-3	-3	-3	-3	-2	-1	-1	-1	-1
1,100	-3	-3	-3	-3	-3	-2	-1	-1	-1	-1
1,200	-3	-3	-3	-3	-3	-2	-1	-1	-1	-1

Initial Supporting table - KtFADD_V_FSA_ECM_LoThrshGrp2

Description: Map to define P026C threshold for combustion mode Group 2

Value Units: mm^3
X Unit: mm^3
Y Units: rpm

y/x	8	11	13	14	18	19	24	25	28	29
525	-8	-8	-8	-8	-8	-8	-8	-7	-7	-7
730	-8	-8	-8	-8	-8	-8	-8	-7	-7	-7
800	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7
850	-6	-6	-6	-6	-6	-6	-6	-6	-6	-6
900	-6	-6	-6	-6	-6	-6	-6	-6	-6	-6
1,000	-6	-6	-6	-6	-6	-6	-6	-6	-6	-6
1,100	-6	-6	-6	-6	-6	-6	-6	-6	-6	-6
1,200	-6	-6	-6	-6	-6	-6	-6	-6	-6	-6

Initial Supporting table - KtFADD_V_FSA_ECM_LoThrshGrp3

Description: Map to define P026C threshold for combustion mode Group 3

Value Units: mm^3
X Unit: mm^3
Y Units: rpm

y/x	8	11	13	14	18	19	24	25	28	29
525	-5	-5	-5	-5	-5	-4	-4	-4	-4	-3
730	-5	-5	-5	-5	-5	-4	-4	-4	-4	-3
800	-5	-5	-5	-5	-5	-4	-4	-4	-4	-3
850	-5	-5	-5	-5	-5	-4	-4	-4	-4	-3
900	-5	-5	-5	-5	-5	-4	-4	-4	-4	-3
1,000	-5	-5	-5	-5	-5	-4	-4	-4	-4	-3
1,100	-5	-5	-5	-5	-5	-4	-4	-4	-4	-3
1,200	-5	-5	-5	-5	-5	-4	-4	-4	-4	-3

Initial Supporting table - P0234, P0299: Boost pressure control deviation enabling

Description: Calibration map for the enabling of boost pressure control deviation monitoring, function of combustion mode.

Value Units: boolean

P0234, P0299: Boost pressure control deviation enabling - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	1	0	0	0

P0234, P0299: Boost pressure control deviation enabling - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

P0234, P0299: Boost pressure control deviation enabling - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

P0234, P0299: Boost pressure control deviation enabling - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - P0234, P2263: Overboost barometric correction

Description: Ambient air pressure multiplicative correction to the base threshold for overboost monitoring. It is function of ambient air pressure (Y axis) and desired boost pressure (X axis).

Value Units: const [-8, 8]
X Unit: kPa
Y Units: kPa

y/x	85	100	115	130	145	160	175	190	205	220	235	250	265	280	295
75	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
83	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
97	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
110	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1

Initial Supporting table - P0234: Maximum boost pressure for overboost monitor enabling

Description: Maximum desired boost pressure below which the overboost deviation monitoring is enabled. This map is function of ambient air pressure.

Value Units: kPa
X Unit: kPa

y/x	75	83	97	110
1	200	200	200	200

Initial Supporting table - P0234: Minimum boost pressure for overboost monitor enabling

Description: Minimum desired boost pressure above which the overboost deviation monitoring is enabled. This map is function of ambient air pressure.

Value Units: kPa
X Unit: kPa

y/x	75	83	97	110
1	146	146	120	120

Initial Supporting table - P0234: Negative boost deviation threshold (throttle control active)

Description: Boost pressure deviation threshold for the negative boost pressure control deviation monitor when the throttle control is active. It identifies an overboost faulty condition. It is function of engine speed (Y axis) and desired boost pressure (X axis).

Value Units: kPa
X Unit: kPa
Y Units: rpm

y/x	85	100	115	130	145	160	175	190	205	220	235	250	265	280	295
750	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28
1,000	-28	-28	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23
1,250	-28	-28	-23	-23	-23	-23	-23	-18	-18	-18	-18	-18	-18	-18	-18
1,500	-28	-28	-28	-15	-15	-15	-16	-18	-18	-18	-18	-18	-18	-18	-18
1,750	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
2,000	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
2,250	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
2,500	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
3,000	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20	-30	-40
4,200	-30	-30	-20	-20	-20	-20	-20	-20	-20	-20	-20	-30	-40	-50	-50

Initial Supporting table - P0234: Negative boost deviation threshold (throttle control not active)

Description: Boost pressure deviation threshold for the negative boost pressure control deviation monitor when the throttle control is not active. It identifies an overboost faulty condition. It is function of engine speed (Y axis) and desired boost pressure (X axis).

Value Units: kPa
X Unit: kPa
Y Units: rpm

y/x	85	100	115	130	145	160	175	190	205	220	235	250	265	280	295
750	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28	-28
1,000	-28	-28	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23	-23
1,250	-28	-28	-23	-23	-23	-23	-23	-18	-18	-18	-18	-18	-18	-18	-18
1,500	-28	-28	-28	-15	-15	-15	-16	-18	-18	-18	-18	-18	-18	-18	-18
1,750	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
2,000	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
2,250	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
2,500	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
3,000	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16
4,200	-28	-28	-28	-13	-13	-13	-15	-16	-16	-16	-16	-16	-16	-16	-16

Initial Supporting table - P0234: Overboost monitor delay timer

Description: Delay timer before enabling the overboost deviation monitoring once all entry conditions are fulfilled. This map is function of engine speed.

Value Units: s
X Unit: rpm

y/x	750	1,000	1,250	1,500	1,750	2,000	2,250	2,500	3,000	4,200
1	2	2	2	2	2	2	2	2	2	2

Initial Supporting table - P0299, P2263: Underboost barometric correction

Description: Ambient air pressure multiplicative correction to the base threshold for underboost monitoring. It is function of ambient air pressure (Y axis) and desired boost pressure (X axis).

Value Units: const [-8, 8]
X Unit: kPa
Y Units: kPa

y/x	85	100	115	130	145	160	175	190	205	220	235	250	265	280	295
75	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
83	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
97	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
110	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1

Initial Supporting table - P0299: Maximum boost pressure for underboost monitor enabling

Description: Maximum desired boost pressure below which the underboost deviation monitoring is enabled. This map is function of ambient air pressure.

Value Units: kPa
X Unit: kPa

y/x	75	83	97	110
1	250	250	250	250

Initial Supporting table - P0299: Minimum boost pressure for underboost monitor enabling

Description: Minimum desired boost pressure above which the underboost deviation monitoring is enabled. This map is function of ambient air pressure.

Value Units: kPa
X Unit: kPa

y/x	75	83	97	110
1	170	170	150	150

Initial Supporting table - P0299: Positive boost deviation threshold (throttle control active)

Description: Boost pressure deviation threshold for the positive boost pressure control deviation monitor when the throttle control is active. It identifies an underboost faulty condition. It is function of engine speed (Y axis) and desired boost pressure (X axis).

Value Units: kPa
X Unit: kPa
Y Units: rpm

y/x	85	100	115	130	145	160	175	190	205	220	235	250	265	280	295
750	47	47	47	47	47	47	47	47	47	47	47	47	47	37	37
1,000	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42
1,250	42	42	37	37	37	37	37	37	37	32	32	32	32	32	32
1,500	42	42	37	37	37	37	37	37	37	32	32	32	32	32	32
1,750	42	42	37	37	37	37	37	37	37	30	30	30	30	30	30
2,000	42	42	37	37	32	32	30	30	30	30	30	30	30	30	30
2,250	42	42	37	37	32	32	30	30	30	30	30	30	30	30	30
2,500	42	42	37	37	32	32	30	30	30	30	30	30	30	30	30
3,000	37	37	37	37	37	37	37	37	37	37	37	37	37	47	57
4,200	47	47	37	37	37	37	37	37	37	37	37	47	57	67	67

Initial Supporting table - P0299: Positive boost deviation threshold (throttle control not active)

Description: Boost pressure deviation threshold for the positive boost pressure control deviation monitor when the throttle control is not active. It identifies an underboost faulty condition. It is function of engine speed (Y axis) and desired boost pressure (X axis).

Value Units: kPa
X Unit: kPa
Y Units: rpm

y/x	85	100	115	130	145	160	175	190	205	220	235	250	265	280	295
750	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42
1,000	42	42	42	42	42	42	42	42	42	42	42	42	42	42	42
1,250	42	42	37	37	37	37	37	37	37	32	32	32	32	32	32
1,500	42	42	37	37	37	37	37	37	37	32	32	32	32	32	32
1,750	42	42	37	37	37	37	37	37	37	30	30	30	30	30	30
2,000	42	42	37	37	32	32	30	30	30	30	30	30	30	30	30
2,250	42	42	37	37	32	32	30	30	30	30	30	30	30	30	30
2,500	42	42	37	37	32	32	30	30	30	30	30	30	30	30	30
3,000	42	42	37	37	32	32	32	32	32	32	32	32	32	32	32
4,200	42	42	37	37	35	35	35	35	35	35	35	35	35	35	35

Initial Supporting table - P0299: Underboost monitor delay timer

Description: Delay timer before enabling the underboost deviation monitoring once all entry conditions are fulfilled. This map is function of engine speed.

Value Units: s
X Unit: rpm

y/x	750	1,000	1,250	1,500	1,750	2,000	2,250	2,500	3,000	4,200
1	2	2	1	1	1	1	2	2	2	2

Initial Supporting table - P0401, P0402: EGR flow monitor enabling

Description: Calibration map to choose if the excessive/insufficient EGR flow monitor is enabled or not for each combustion mode.

Value Units: boolean
X Unit: enum

P0401, P0402: EGR flow monitor enabling - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

P0401, P0402: EGR flow monitor enabling - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

P0401, P0402: EGR flow monitor enabling - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

P0401, P0402: EGR flow monitor enabling - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - P0401, P0402: EGR intrusive test enabling

Description: Calibration map to choose if the EGR intrusive test is enabled or not for each combustion mode.

Value Units: boolean
X Unit: enum

P0401, P0402: EGR intrusive test enabling - Part 1					
y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	0	0	0	0	0

P0401, P0402: EGR intrusive test enabling - Part 2					
y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	0	0	0

P0401, P0402: EGR intrusive test enabling - Part 3					
y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

P0401, P0402: EGR intrusive test enabling - Part 4					
y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - P0401: Insufficient EGR flow barometric correction (low level)

Description: Air Temperature correction at low barometric level for OBDII insufficient EGR flow monitor. It is function of air temperature.

Value Units: const [-1,1]
X Unit: °C

y/x	-7	-5	0	5	10	15	20	25	30	35
1	1	1	1	1	1	1	1	1	1	1

Initial Supporting table - P0401: Insufficient EGR flow barometric correction (mid level)

Description: Air Temperature correction at mid barometric level for OBDII insufficient EGR flow monitor. It is function of air temperature.

Value Units: const [-1,1]
X Unit: °C

y/x	-7	-5	0	5	10	15	20	25	30	35
1	1	1	1	1	1	1	1	1	1	1

Initial Supporting table - P0401: Insufficient EGR flow barometric correction (sea level)

Description: Air Temperature correction at sea barometric level for OBDII insufficient EGR flow monitor. It is function of air temperature.

Value Units: const [-1,1]
X Unit: °C

y/x	-7	-5	0	5	10	15	20	25	30	35
1	1	1	1	1	1	1	1	1	1	1

Initial Supporting table - P0401: Insufficient EGR flow barometric table A (low level)

Description: Barometric (low level) calibration table for defining a OBDII threshold for insufficient EGR flow deviation monitoring. It is function of engine speed (X axis) and fuel request (Y axis).

Value Units: mg
X Unit: rpm
Y Units: mm^3

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
0	0	0	0	0	0	0	0	0
5	0	0	0	0	0	0	0	0
15	0	0	0	0	0	0	0	0
25	0	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0	0
45	0	0	0	0	0	0	0	0
50	0	0	0	0	0	0	0	0
55	0	0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0

Initial Supporting table - P0401: Insufficient EGR flow barometric table A (mid level)

Description: Barometric (mid level) calibration table for defining a OBDII threshold for insufficient EGR flow deviation monitoring. It is function of engine speed (X axis) and fuel request (Y axis).

Value Units: mg
X Unit: rpm
Y Units: mm^3

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
0	0	0	0	0	0	0	0	0
5	0	0	0	0	0	0	0	0
15	0	0	0	0	0	0	0	0
25	0	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0	0
45	0	0	0	0	0	0	0	0
50	0	0	0	0	0	0	0	0
55	0	0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0

Initial Supporting table - P0401: Insufficient EGR flow barometric table A (sea level)

Description: Barometric (sea level) calibration table for defining a OBDII threshold for insufficient EGR flow deviation monitoring. It is function of engine speed (X axis) and fuel request (Y axis).

Value Units: mg
X Unit: rpm
Y Units: mm^3

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
0	0	0	0	0	0	0	0	0
5	0	0	0	0	0	0	0	0
15	0	0	0	0	0	0	0	0
25	0	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0	0
45	0	0	0	0	0	0	0	0
50	0	0	0	0	0	0	0	0
55	0	0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0

Initial Supporting table - P0401: Insufficient EGR flow barometric table B (low level)

Description: Barometric (low level) calibration table for defining a OBDII threshold for insufficient EGR flow deviation monitoring. It is function of engine speed (X axis) and fuel request (Y axis).

Value Units: mg
X Unit: rpm
Y Units: mm^3

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
0	-40	-40	-48	-48	-40	-40	-40	-40
5	-40	-40	-48	-48	-40	-40	-40	-40
15	-56	-56	-64	-40	-32	-32	-32	-32
25	-88	-88	-96	-56	-40	-40	-40	-40
30	-88	-88	-96	-56	-48	-48	-48	-48
45	-88	-88	-96	-56	-48	-48	-48	-48
50	-88	-88	-96	-56	-48	-48	-48	-48
55	-88	-88	-96	-56	-48	-48	-48	-48
60	-88	-88	-96	-56	-48	-48	-48	-48

Initial Supporting table - P0401: Insufficient EGR flow barometric table B (mid level)

Description: Barometric (mid level) calibration table for defining a OBDII threshold for insufficient EGR flow deviation monitoring. It is function of engine speed (X axis) and fuel request (Y axis).

Value Units: mg
X Unit: rpm
Y Units: mm^3

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
0	-40	-40	-48	-96	-88	-80	-80	-80
5	-40	-40	-48	-96	-104	-96	-96	-96
15	-40	-40	-48	-96	-120	-112	-112	-112
25	-56	-56	-64	-72	-48	-40	-40	-40
30	-56	-56	-64	-72	-48	-40	-40	-40
45	-56	-56	-64	-72	-48	-40	-40	-40
50	-56	-56	-64	-72	-48	-40	-40	-40
55	-56	-56	-64	-72	-48	-40	-40	-40
60	-56	-56	-64	-72	-48	-40	-40	-40

Initial Supporting table - P0401: Insufficient EGR flow barometric table B (sea level)

Description: Barometric (sea level) calibration table for defining a OBDII threshold for insufficient EGR flow deviation monitoring. It is function of engine speed (X axis) and fuel request (Y axis).

Value Units: mg
X Unit: rpm
Y Units: mm^3

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
0	-112	-112	-120	-160	-144	-112	-112	-112
5	-112	-112	-120	-160	-144	-112	-112	-112
15	-112	-112	-88	-88	-88	-112	-112	-112
25	-112	-112	-88	-88	-88	-112	-112	-112
30	-112	-112	-88	-88	-88	-112	-112	-112
45	-112	-112	-88	-88	-88	-112	-112	-112
50	-112	-112	-88	-88	-88	-112	-112	-112
55	-112	-112	-88	-88	-88	-112	-112	-112
60	-112	-112	-88	-88	-88	-112	-112	-112

Initial Supporting table - P0401: Insufficient EGR flow Max fuel enabling condition

Description: Maximum desired fuel below which the insufficient EGR flow is enabled. It is function of engine speed (X axis) and barometric pressure (Y axis).

Value Units: mm^3
X Unit: rpm
Y Units: kPa

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
72	0	0	25	25	20	1	1	1
74	0	0	25	25	20	1	1	1
77	0	0	20	28	20	1	1	1
80	0	0	20	32	20	1	1	1
83	0	0	20	35	25	1	1	1
86	0	0	23	35	27	1	1	1
89	0	0	26	35	29	1	1	1
92	0	0	29	35	31	1	1	1
95	0	0	32	35	33	1	1	1
98	0	0	35	35	35	1	1	1
100	0	0	35	35	30	1	1	1

Initial Supporting table - P0401: Insufficient EGR flow Max OAT threshold for C1

Description: Maximum desired OAT below which the insufficient EGR flow is enabled, for the Normal combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0401: Insufficient EGR flow Max OAT threshold for C2

Description: Maximum desired OAT below which the insufficient EGR flow is enabled, for the Fully Warm Emissions combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0401: Insufficient EGR flow Max OAT threshold for others

Description: Maximum desired OAT below which the insufficient EGR flow is enabled, for all other combustion modes. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0401: Insufficient EGR flow Max OAT threshold for V2

Description: Maximum desired OAT below which the insufficient EGR flow is enabled, for the Soft Warm Up combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0401: Insufficient EGR flow Min fuel enabling condition

Description: Minimum desired fuel above which the insufficient EGR flow is enabled. It is function of engine speed (X axis) and barometric pressure (Y axis).

Value Units: mm^3
X Unit: rpm
Y Units: kPa

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
72	0	0	15	15	10	0	0	0
74	0	0	15	15	10	0	0	0
77	0	0	10	13	10	0	0	0
80	0	0	10	10	10	0	0	0
83	0	0	10	10	10	0	0	0
86	0	0	9	9	9	0	0	0
89	0	0	8	8	8	0	0	0
92	0	0	6	6	6	0	0	0
95	0	0	5	5	5	0	0	0
98	0	0	5	5	5	0	0	0
100	0	0	5	5	5	0	0	0

Initial Supporting table - P0401: Insufficient EGR flow Min OAT threshold for C1

Description: Minimum desired OAT above which the insufficient EGR flow is enabled, for the Normal combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20

Initial Supporting table - P0401: Insufficient EGR flow Min OAT threshold for C2

Description: Minimum desired OAT above which the insufficient EGR flow is enabled, for the Fully Warm Emissions combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7

Initial Supporting table - P0401: Insufficient EGR flow Min OAT threshold for others

Description: Minimum desired OAT above which the insufficient EGR flow is enabled, for all other combustion modes. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20	-20

Initial Supporting table - P0401: Insufficient EGR flow Min OAT threshold for V2

Description: Minimum desired OAT above which the insufficient EGR flow is enabled, for the Soft Warm Up combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7

Initial Supporting table - P0401: Insufficient EGR intrusive test Max fuel enabling condition

Description: Maximum desired fuel below which the insufficient EGR intrusive test is enabled. It is function of engine speed (X axis) and barometric pressure (Y axis).

Value Units: mm^3
X Unit: rpm
Y Units: kPa

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,500
68	30	30	30	30	30	30	30	30
70	30	30	30	30	30	30	30	30
73	30	30	30	30	30	30	30	30
76	30	30	30	30	30	30	30	30
79	30	30	30	30	30	30	30	30
82	30	30	30	30	30	30	30	30
85	30	30	30	30	30	30	30	30
88	30	30	30	30	30	30	30	30
91	30	30	30	30	30	30	30	30
96	30	30	30	30	30	30	30	30
101	30	30	30	30	30	30	30	30

Initial Supporting table - P0401: Insufficient EGR intrusive test Min fuel enabling condition

Description: Minimum desired fuel above which the insufficient EGR intrusive test is enabled. It is function of engine speed (X axis) and barometric pressure (Y axis).

Value Units: mm^3
X Unit: rpm
Y Units: kPa

y/x	500	1,000	1,500	2,000	2,500	3,000	3,500	4,500
68	10	10	15	15	25	25	25	25
70	10	10	15	15	25	25	25	25
73	10	10	15	15	25	25	25	25
76	10	10	15	15	25	25	25	25
79	10	10	15	15	25	25	25	25
82	10	10	15	15	25	25	25	25
85	10	10	15	15	25	25	25	25
88	10	10	15	15	25	25	25	25
91	10	10	15	15	25	25	25	25
96	10	10	15	15	25	25	25	25
101	10	10	15	15	25	25	25	25

Initial Supporting table - P0401: Minimum desired EGR flow

Description: Minimum desired EGR flow above which the insufficient EGR flow is enabled. It is function of engine speed (X axis) and barometric pressure (Y axis).

Value Units: mg
X Unit: rpm
Y Units: kPa

y/x	730	1,250	1,500	1,750	2,000	2,500	3,000	4,200
72	216	196	176	184	176	196	216	216
74	216	200	172	184	172	196	216	216
77	216	200	168	184	168	200	216	216
80	216	200	168	176	168	204	216	216
83	216	204	168	176	160	204	216	216
86	216	208	176	184	168	208	216	216
89	216	212	184	184	176	212	216	216
92	216	212	188	192	184	212	216	216
95	216	216	196	196	192	216	216	216
98	216	216	200	200	200	216	216	216
100	216	216	200	200	200	216	216	216

Initial Supporting table - P0402: Excessive EGR flow Max OAT threshold for C1

Description: Maximum desired OAT below which the excessive EGR flow is enabled, for the Normal combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0402: Excessive EGR flow Max OAT threshold for C2

Description: Maximum desired OAT below which the excessive EGR flow is enabled, for the Fully Warm Emissions combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0402: Excessive EGR flow Max OAT threshold for others

Description: Maximum desired OAT below which the excessive EGR flow is enabled, for all others combustion modes. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0402: Excessive EGR flow Max OAT threshold for V2

Description: Maximum desired OAT below which the excessive EGR flow is enabled, for the Soft Warm Up combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	50	50	50	50	50	50	50	50	50	50	50

Initial Supporting table - P0402: Excessive EGR flow Min OAT threshold for C1

Description: Minimum desired OAT above which the excessive EGR flow is enabled, for the Normal combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7

Initial Supporting table - P0402: Excessive EGR flow Min OAT threshold for C2

Description: Minimum desired OAT above which the excessive EGR flow is enabled, for the Fully Warm Emissions combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7

Initial Supporting table - P0402: Excessive EGR flow Min OAT threshold for others

Description: Minimum desired OAT above which the excessive EGR flow is enabled, for all other combustion modes. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7

Initial Supporting table - P0402: Excessive EGR flow Min OAT threshold for V2

Description: Minimum desired OAT above which the excessive EGR flow is enabled, for the Soft Warm Up combustion mode. It is function of barometric pressure.

Value Units: °C
X Unit: kPa

y/x	72	74	77	80	83	86	89	92	95	98	100
1	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7	-7

Initial Supporting table - P140B, P140C: EGR slow response enabling

Description: Calibration map for the enabling of EGR slow response monitoring, function of combustion mode.

Value Units: boolean

P140B, P140C: EGR slow response enabling - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

P140B, P140C: EGR slow response enabling - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	0	0	0

P140B, P140C: EGR slow response enabling - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

P140B, P140C: EGR slow response enabling - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - P140B: Increasing EGR slow response threshold

Description: Threshold for increasing EGR flow slow response monitoring. It is function of ambient air pressure.

Value Units: %
X Unit: kPa

y/x	75	84	97
1	1	2	3

Initial Supporting table - P140C: Decreasing EGR slow response threshold

Description: Threshold for decreasing EGR flow slow response monitoring. It is function of ambient air pressure.

Value Units: %
X Unit: kPa

y/x	75	84	97
1	2	4	10

Initial Supporting table - P0071: OAT Performance Drive Equilibrium Engine Off

Description: OAT Performance Diagnostic counter increment for determining OAT-IAT equilibrium for engine off (for hybrid applications)

Value Units: Counter Increment Value (Unitless)
X Unit: Vehicle Speed (KPH)

y/x	0.0	5.0	10.0	15.0	20.0	25.0	30.0	50.0	80.0
1.0	0.0	1.0	2.0	3.0	4.0	5.0	6.0	7.0	8.0

Initial Supporting table - P0071: OAT Performance Drive Equilibrium Engine Running

Description: OAT Performance Diagnostic counter increment for determining OAT-IAT equilibrium for engine running

Value Units: Counter Increment Value (Unitless)
X Unit: Vehicle Speed (KPH)
Y Units: Engine Air Flow (Grams/Second)

y/x	0.0	5.0	10.0	15.0	20.0	25.0	30.0	50.0	80.0
1.0	1.0	2.0	3.0	4.0	5.0	6.0	7.0	8.0	9.0
5.0	-5.0	-2.0	-1.0	0.0	1.0	2.0	3.0	4.0	5.0
10.0	-4.0	-1.0	0.0	0.0	1.0	2.0	3.0	4.0	5.0
20.0	-2.0	-1.0	0.0	0.0	1.0	2.0	3.0	4.0	5.0
30.0	-1.0	0.0	0.0	1.0	2.0	3.0	4.0	5.0	6.0
40.0	0.0	0.0	0.0	1.0	2.0	3.0	4.0	5.0	6.0
50.0	0.0	0.0	1.0	2.0	3.0	4.0	5.0	6.0	7.0
60.0	0.0	1.0	2.0	3.0	4.0	5.0	6.0	7.0	8.0
70.0	1.0	2.0	3.0	4.0	5.0	6.0	7.0	8.0	9.0

Initial Supporting table - Cool Down Diagnostic Min Heat to Coolant

Description: KtECTR_P_CDD_HeatToCoolantMin

Value Units: Power (kW)
X Unit: Firing fraction (ratio)
Y Units: Ambient Air Temperature (Deg C)

y/x	0.00	0.25	0.50	0.67	1.00
-9.0	15.0	15.0	15.0	15.0	15.0
0.0	15.0	15.0	15.0	15.0	15.0
10.0	30.0	30.0	30.0	30.0	30.0
20.0	30.0	30.0	30.0	30.0	30.0
50.0	30.0	30.0	30.0	30.0	30.0

Initial Supporting table - P0128_Maximum Accumulated Energy for Start-up ECT conditions - Alternate

Description: KtECTR_E_CTR_WrmUpEnrgyLimTest1

Value Units: Cooling system energy failure threshold (kJ)
X Unit: Minimum ECT for the key cycle (°C)

y/x	-40	-7	10	20	55	69	90
1	27,000	17,400	13,100	10,350	2,500	2,500	2,500

Initial Supporting table - P0128_Maximum Accumulated Energy for Start-up ECT conditions - Primary

Description: KtECTR_E_CTR_WrmUpEnrgyLimTest0

Value Units: Cooling system energy failure threshold (kJ)
X Unit: Minimum ECT for the key cycle (°C)

y/x	-40	-7	10	20	55	69	90
1	27,500	20,000	16,000	13,500	5,500	2,500	2,500

Initial Supporting table - P0606_Last Seed Timeout f(Loop Time)

Description: The max time for the Last Seed Timeout as a function of operating loop time sequence.

P0606_Last Seed Timeout f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	200.000	200.000	200.000	200.000	200.000	200.000	200.000

P0606_Last Seed Timeout f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	200.000	200.000	500.000	8,191.875	8,191.875	8,191.875	

Initial Supporting table - P0606_PSW Sequence Fail f(Loop Time)

Description: Fail threshold for PSW per operating loop.

P0606_PSW Sequence Fail f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	5	3	5	3	5	3	5

P0606_PSW Sequence Fail f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	5	5	3	3	3	5	

Initial Supporting table - P0606_PSW Sequence Sample f(Loop Time)

Description: Sample threshold for PSW per operating loop.

P0606_PSW Sequence Sample f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	4	4	4	4	4	4	4

P0606_PSW Sequence Sample f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	4	4	4	4	4	4	

Initial Supporting table - P057B KtBRKI_K_CmpltTestPointWeight

Description:

y/x	0.000	0.042	0.050	0.070	0.350	0.450	0.550	0.750	1.000
1	0	0	1	1	1	1	1	1	1

Initial Supporting table - P057B KtBRKI_K_FastTestPointWeight

Description:

y/x	0.000	0.042	0.043	0.050	0.350	0.450	0.550	0.750	1.000
1	0	0	1	1	1	1	1	1	1

Initial Supporting table - Ambient correction on distance

Description: Ambient pressure correction for threshold on Distance covered since last regeneration

Value Units: [0; 2]
X Unit: kPa

y/x	70	72	80	90	92	100
1	1	1	1	1	1	1

Initial Supporting table - Ambient correction on time

Description: Ambient pressure correction for threshold on time spent since last regeneration

Value Units: [0; 2]
X Unit: kPa

y/x	70	72	80	90	92	100
1	1	1	1	1	1	1

Initial Supporting table - Distance since last regeneration

Description: Base value to trigger regeneration for distance covered since last regeneration, function of regeneration priority

Value Units: km
X Unit: enumerative (mission profiles)

Distance since last regeneration - Part 1						
y/x	CeDPFC_e_RgnPriority_0	CeDPFC_e_RgnPriority_1	CeDPFC_e_RgnPriority_2	CeDPFC_e_RgnPriority_3	CeDPFC_e_RgnPriority_4	CeDPFC_e_RgnPriority_5
1	966	966	966	966	966	966

Distance since last regeneration - Part 2						
y/x	CeDPFC_e_RgnPriority_6	CeDPFC_e_RgnPriority_7	CeDPFC_e_RgnPriority_8	CeDPFC_e_RgnPriority_9	CeDPFC_e_RgnPriority_10	CeDPFC_e_RgnPriority_11
1	966	966	966	966	966	966

Distance since last regeneration - Part 3						
y/x	CeDPFC_e_RgnPriority_12	CeDPFC_e_RgnPriority_13	CeDPFC_e_RgnPriority_14	CeDPFC_e_RgnPriority_15	CeDPFC_e_RgnPriority_16	
1	966	966	966	966	966	

Initial Supporting table - DPF Load correction on distance

Description: Map of DPF Load correction for threshold on distance covered since last regeneration

Value Units: [0; 2]
X Unit: % DPF load

y/x	20	40	50	70	75	80	90	95
1	1	1	1	1	1	1	1	1

Initial Supporting table - DPF Load correction on time

Description: Map of DPF Load correction for threshold on time spent since last regeneration

Value Units: [0; 2]
X Unit: % DPF load

y/x	20	40	50	70	75	80	90	95
1	1	1	1	1	1	1	1	1

Initial Supporting table - DPF_CCB_SootThrsh

Description:

y/x	1,000	1,500	2,000	2,250	2,500	3,000	3,500	4,000	4,500
0	0	0	0	0	0	0	0	0	0
10	0	0	0	0	0	0	0	0	0
15	0	0	0	0	0	0	0	0	0
20	0	0	0	0	0	0	0	0	0
25	0	0	0	0	0	0	0	0	0
35	0	0	0	0	0	0	0	0	0
50	0	0	0	0	0	0	0	0	0
70	0	0	0	0	0	0	0	0	0

Initial Supporting table - DPF_EffRgnHysHi

Description:

y/x	0	7	10	20	40	60	80	100	120	140	160	180	200	220	240
0	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
5	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
10	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
15	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
20	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
25	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
30	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
35	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
40	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
45	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
50	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
55	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
60	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
65	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
70	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
75	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
80	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
90	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535
100	535	535	535	535	535	535	535	535	535	535	535	535	535	535	535

Initial Supporting table - DPF_EffRgnHysLo

Description:

y/x	0	7	10	20	40	60	80	100	120	140	160	180	200	220	240
0	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
5	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
10	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
15	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
20	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
25	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
30	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
35	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
40	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
45	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
50	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
55	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
60	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
65	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
70	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
75	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
80	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
90	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520
100	520	520	520	520	520	520	520	520	520	520	520	520	520	520	520

Initial Supporting table - DPF_ResistFlowDsblHi

Description:

y/x	600	800	1,200	1,600	2,000	2,400	2,800	3,200
1	130	130	130	130	130	130	130	130

Initial Supporting table - DPF_ResistFlowDsblLo

Description:

y/x	600	800	1,200	1,600	2,000	2,400	2,800	3,200
1	0	0	0	0	0	0	0	0

Initial Supporting table - DPF_SootThrshCrtn

Description:

y/x	10	20	30	40	50	60	70	80
1	1	1	1	1	1	1	1	1

Initial Supporting table - EGT_FuelReqHysHiThrsh_DPF

Description:

y/x	1,000	1,200	1,500	2,000	2,500	3,000	3,500	4,000
1	-2	-2	-2	-2	-2	-2	-2	-2

Initial Supporting table - EGT_FuelReqHysLoThrsh_DPF

Description:

y/x	1,000	1,200	1,500	2,000	2,500	3,000	3,500	4,000
1	-2	-2	-2	-2	-2	-2	-2	-2

Initial Supporting table - EGT_FuelReqMaxThreshold

Description:

y/x	800	1,000	1,500	2,000	2,500	3,000	3,500	4,000
1	0	0	0	0	0	0	0	0

Initial Supporting table - EGT_FuelReqMinThrsh

Description:

y/x	800	1,000	1,500	2,000	2,500	3,000	3,500	4,000
1	0	0	0	0	0	0	0	0

Initial Supporting table - EGT1 DynChk EngPtEnbl

Description: Contains the engine speed and fuel rate enablments for EGT1 Dynamic Check.

y/x	15.9	16.0	20.0	40.0	60.0	80.0	80.1
1,249.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
1,250.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
2,000.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
3,000.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
3,999.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
4,000.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

Initial Supporting table - EGT2 DynChk EngPtEnbl

Description: Contains the engine speed and fuel rate enablments for EGT2 Dynamic Check.

y/x	0.0	10.0	20.0	40.0	60.0	80.0	120.0
1,249.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
1,250.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
2,000.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
3,000.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
3,999.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
4,000.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

Initial Supporting table - EGT3 DynChk EngPtEnbl

Description: Contains the engine speed and fuel rate enablments for EGT3 Dynamic Check.

y/x	0.0	16.0	20.0	40.0	60.0	80.0	120.0
1,249.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
1,250.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
2,000.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
3,000.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
3,999.0	0.0	1.0	1.0	1.0	1.0	1.0	0.0
4,000.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

Initial Supporting table - EGT4 DynChk EngPtEnbl

Description: Contains the engine speed and fuel rate enablments for EGT4 Dynamic Check.

y/x	0.0	15.0	20.0	40.0	60.0	80.0	120.0
800.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
1,000.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
1,500.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
2,000.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
2,500.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
3,200.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

Initial Supporting table - EGT5 DynChk EngPtEnbl

Description: Contains the engine speed and fuel rate enablments for EGT5 Dynamic Check.

y/x	0.0	15.0	20.0	40.0	60.0	80.0	120.0
800.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
1,000.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
1,500.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
2,000.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
2,500.0	0.0	0.0	1.0	1.0	1.0	1.0	0.0
3,200.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0

Initial Supporting table - EnginePointEnable_DPF_TempDeviation

Description:

y/x	980	1,000	2,000	2,500	3,000	3,010	4,000	4,200
0	0	0	0	0	0	0	0	0
5	0	1	1	1	1	0	0	0
10	0	1	1	1	1	0	0	0
15	0	1	1	1	1	0	0	0
20	0	1	1	1	1	0	0	0
30	0	1	1	1	1	0	0	0
40	0	1	1	1	1	0	0	0
60	0	1	1	1	1	0	0	0
61	0	0	0	0	0	0	0	0

Initial Supporting table - EnginePointEnable_HC_TempDeviation

Description:

y/x	980	1,000	1,100	1,200	1,800	2,000	2,800	3,500
0	0	0	0	0	0	0	0	0
8	0	1	1	1	1	1	1	1
10	0	1	1	1	1	1	1	1
15	0	1	1	1	1	1	1	1
20	0	1	1	1	1	1	1	1
50	0	1	1	1	1	1	1	1
80	0	1	1	1	1	1	1	1
120	0	1	1	1	1	1	1	1
140	0	1	1	1	1	1	1	1

Initial Supporting table - Exhaust Gas Pressure Too Low Threshold

Description: Diagnostic threshold for the exhaust gas pressure too low monitoring. This threshold is function of the exhaust gas flow and of the soot trapped in the DPF

Value Units: kPa
X Unit: l/s
Y Units: % DPF load

y/x	10	20	60	100	140	200	200	200
40	0	0	0	0	0	0	0	0
60	0	0	0	0	0	0	0	0
120	1	1	1	1	1	1	1	1
160	3	3	3	3	3	3	3	3
200	3	3	3	3	3	3	3	3
240	4	4	4	4	4	4	4	4
280	5	5	5	5	5	5	5	5
320	6	6	6	6	6	6	6	6

Initial Supporting table - KaFADC_b_CB_EnblCMBR

Description: Specifies, for the specific combustion mode, if enable or not CB

KaFADC_b_CB_EnblCMBR - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	1	0	0	0

KaFADC_b_CB_EnblCMBR - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

KaFADC_b_CB_EnblCMBR - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	1	1	0	0	0

KaFADC_b_CB_EnblCMBR - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	1	1	0	0	

Initial Supporting table - KaFADC_b_SQC_CWA_EnblLink

Description: Engine speed ranges to be learned with CWA before give a positive report to Zero Torque Coordinator.

y/x	0	1	2	3	4	5
1	0	0	0	0	0	0

Initial Supporting table - KaFADC_n_CB_EngSpdRngThrsh2

Description: Threshold 2 for engine speed range detection in the Cylinder Balancing (driveline-group dependent) [rpm]

Value Units: rpm

KaFADC_n_CB_EngSpdRngThrsh2 - Part 1

y/x	0	1	2	3	4	5	6	7	8	9	10
1	1,250	1,250	1,250	1,250	1,250	1,250	1,250	1,250	1,250	1,250	1,250

KaFADC_n_CB_EngSpdRngThrsh2 - Part 2

y/x	11	12	13	14	15	16	17	18	19	20	
1	1,250	1,250	1,250	1,250	1,250	1,250	1,250	1,250	1,250	1,250	

Initial Supporting table - KaFADC_n_CB_EngSpdRngThrsh3

Description: Threshold 3 for engine speed range detection in the Cylinder Balancing (driveline-group dependent) [rpm].

Value Units: rpm

KaFADC_n_CB_EngSpdRngThrsh3 - Part 1

y/x	0	1	2	3	4	5	6	7	8	9	10
1	1,200	1,200	1,200	1,200	1,200	1,200	1,200	1,200	1,200	1,200	1,200

KaFADC_n_CB_EngSpdRngThrsh3 - Part 2

y/x	11	12	13	14	15	16	17	18	19	20	
1	1,200	1,200	1,200	1,200	1,200	1,200	1,200	1,200	1,200	1,200	

Initial Supporting table - KaFADC_n_DFSA_EngSpdThrsh

Description: Threshold to evaluate the engine speed steady state, as function of the engaged gear

Value Units: rpm

y/x	0	1	2	3	4	5	6	7	8	9	10	11	12
1	5	5	5	5	5	5	5	5	5	5	5	5	5

Initial Supporting table - KaFADC_n_FSA_EngSpdThrsh

Description: Threshold to evaluate the engine speed steady state, as function of the engaged gear

Value Units: rpm

y/x	0	1	2	3	4	5	6	7	8	9	10	11	12
1	1	1	1	1	0	0	0	4	4	4	4	4	4

Initial Supporting table - KaFADC_n_SQC_HiThrshDelt

Description: Engine speed high threshold [rpm] delta for SQC actuators enable function of driveline group

Value Units: rpm

KaFADC_n_SQC_HiThrshDelt - Part 1				
y/x	CeFADR_e_CWA_DrvlnGrpNotAlwd	CeFADR_e_CWA_DrivelineGrp1	CeFADR_e_CWA_DrivelineGrp2	CeFADR_e_CWA_DrivelineGrp3
1	200	200	200	200

KaFADC_n_SQC_HiThrshDelt - Part 2				
y/x	CeFADR_e_CWA_DrivelineGrp4	CeFADR_e_CWA_DrivelineGrp5	CeFADR_e_CWA_DrivelineGrp6	CeFADR_e_CWA_DrivelineGrp7
1	200	200	200	200

KaFADC_n_SQC_HiThrshDelt - Part 3				
y/x	CeFADR_e_CWA_DrivelineGrp8	CeFADR_e_CWA_DrivelineGrp9	CeFADR_e_CWA_DrivelineGrp10	
1	200	200	200	

Initial Supporting table - KaFADC_p_SQA_LrnDelt

Description: Delta Rail Pressure allowed to enable SQA learning [MPa] function of nominal rail pressure setpoint defined for SQA.

Value Units: MPa

y/x	0	1	2	3	4
1	5	5	5	5	5

Initial Supporting table - KaFADC_t_SQA_MaxAdptDeltET[us]

Description: Upper Energizing time limit for SQA [us] max authority function of rail pressure levels defined for SQA.

Value Units: us

y/x	0	1	2	3	4
1	199	138	90	82	0

Initial Supporting table - KaFADC_t_SQA_MinAdptDeltET[us]

Description: Lower Energizing time limit for SQA max authority [us] function of rail pressure levels defined for SQA.

Value Units: us

y/x	0	1	2	3	4
1	-174	-115	-138	-94	0

Initial Supporting table - KtFADC_p_SQA_MAP_HiThrsh

Description: Manifold Air Pressure High Threshold [kPa] to disable SQA Strategy function on Rail Pressure levels defined for SQA

Value Units: MPa

y/x	1,000	1,200	1,700	1,701	2,100
1	160	160	160	160	160

Initial Supporting table - KtFADC_V_CB_HiThrshFuelQnty

Description: Injected quantity high threshold to enable Cylinder Balancing control [mm^3]

Value Units: mm^3

y/x	655	750	1,000	1,250	1,500	1,750	2,000	2,250	2,500	3,000	3,500	4,000
1	0	40	50	60	70	80	90	90	90	80	45	0

Initial Supporting table - KtFADC_V_FSA_FuelMax

Description: Map used to define FSA maximum authority

Value Units: mm^3

y/x	10	20	30	40	50	60	70	80	90	100
800	11	12	14	17	20	23	24	26	27	29
1,000	12	13	15	17	20	23	24	26	27	29
1,250	13	14	16	18	21	24	24	26	27	29
1,500	13	15	17	19	22	24	25	27	28	30
1,750	13	15	17	20	23	25	26	28	29	31
2,000	13	15	17	20	23	26	27	29	30	31
2,250	13	15	17	20	23	26	28	30	31	32
2,500	13	15	17	20	23	26	28	30	31	33
2,750	13	15	17	20	23	26	28	30	31	33
3,000	13	15	17	20	23	26	28	30	31	33

Initial Supporting table - KtFADC_V_FSA_FuelMin

Description: Map used to define FSA minimum authority

Value Units: mm^3

y/x	10	20	30	40	50	60	70	80	90	100
800	-11	-12	-14	-17	-20	-23	-24	-26	-27	-29
1,000	-12	-13	-15	-17	-20	-23	-24	-26	-27	-29
1,250	-13	-14	-16	-18	-21	-24	-24	-26	-27	-29
1,500	-13	-15	-17	-19	-22	-24	-25	-27	-28	-30
1,750	-13	-15	-17	-20	-23	-25	-26	-28	-29	-31
2,000	-13	-15	-17	-20	-23	-26	-27	-29	-30	-31
2,250	-13	-15	-17	-20	-23	-26	-28	-30	-31	-32
2,500	-13	-15	-17	-20	-23	-26	-28	-30	-31	-33
2,750	-13	-15	-17	-20	-23	-26	-28	-30	-31	-33
3,000	-13	-15	-17	-20	-23	-26	-28	-30	-31	-33

Initial Supporting table - KtFADC_V_FSA_MaxFuelFall

Description: Upper bound of fuel quantity range to enable the FSA learning phase depending on the engine speed

Value Units: mm^3

y/x	510	511	1,000	1,600	1,800	2,000	2,400	3,200	3,600	4,000
1	0	65	65	100	100	100	100	100	100	100

Initial Supporting table - KtFADD_p_XSQA_MAP_HiThrsh

Description: Manifold Air Pressure High Threshold [kPa] to disable SQA Emission Correlated Monitoring function on Rail Pressure levels defined for SQA

Value Units: kPa

y/x	1,000	1,200	1,400	1,600	1,800
1	160	160	160	160	160

Initial Supporting table - KtFADD_Pct_SSQA_InjSuspConfLvl

Description: Calibration table to define the suspicious confidence level [%] function of current last raw Delta Energizing Time [us] and previous one [us]

Value Units: %

y/x	-100	-70	-51	-50	-20	0	20	50	51	70	100
-100	0	0	0	0	0	0	0	0	0	0	0
-70	0	0	0	0	0	0	0	0	0	0	0
-51	0	0	0	100	100	100	100	100	0	0	0
-50	0	0	0	100	100	100	100	100	0	0	0
0	0	0	0	100	100	100	100	100	0	0	0
50	0	0	0	100	100	100	100	100	0	0	0
51	0	0	0	0	0	0	0	0	0	0	0
70	0	0	0	0	0	0	0	0	0	0	0
100	0	0	0	0	0	0	0	0	0	0	0

Initial Supporting table - Maximum allowed time to complete regeneration

Description:

Value Units: enumerative (mission profiles)
X Unit: seconds
Y Units: N/A

Maximum allowed time to complete regeneration - Part 1

y/x	CeDPFR_e_MisProf0	CeDPFR_e_MisProf1	CeDPFR_e_MisProf2	CeDPFR_e_MisProf3	CeDPFR_e_MisProf4	CeDPFR_e_MisProf5	CeDPFR_e_MisProf6
1	7,200	7,200	7,200	7,200	7,200	7,200	7,200

Maximum allowed time to complete regeneration - Part 2

y/x	CeDPFR_e_MisProf7	CeDPFR_e_MisProf8	CeDPFR_e_MisProf9	CeDPFR_e_MisProf10	CeDPFR_e_MisProf11	CeDPFR_e_MisProf12	CeDPFR_e_MisProf13
1	7,200	7,200	7,200	7,200	7,200	7,200	7,200

Maximum allowed time to complete regeneration - Part 3

y/x	CeDPFR_e_MisProf14	CeDPFR_e_MisProf15	CeDPFR_e_MisProf16	CeDPFR_e_MisProf17 Srv	CeDPFR_e_MisProf18 Rec		
1	7,200	7,200	7,200	7,200	7,200		

Initial Supporting table - Maximum allowed time to reach steady state for regeneration

Description:

Value Units: seconds
X Unit: enumerative (mission profiles)
Y Units: N/A

Maximum allowed time to reach steady state for regeneration - Part 1

y/x	CeDPFR_e_MisProf0	CeDPFR_e_MisProf1	CeDPFR_e_MisProf2	CeDPFR_e_MisProf3	CeDPFR_e_MisProf4	CeDPFR_e_MisProf5	CeDPFR_e_MisProf6
1	2,700	2,700	2,700	2,700	2,700	2,700	2,700

Maximum allowed time to reach steady state for regeneration - Part 2

y/x	CeDPFR_e_MisProf7	CeDPFR_e_MisProf8	CeDPFR_e_MisProf9	CeDPFR_e_MisProf10	CeDPFR_e_MisProf11	CeDPFR_e_MisProf12	CeDPFR_e_MisProf13
1	2,700	2,700	2,700	2,700	2,700	2,700	2,700

Maximum allowed time to reach steady state for regeneration - Part 3

y/x	CeDPFR_e_MisProf14	CeDPFR_e_MisProf15	CeDPFR_e_MisProf16	CeDPFR_e_MisProf17 Srv	CeDPFR_e_MisProf18 Rec		
1	2,700	2,700	2,700	2,700	2,700		

Initial Supporting table - Maximum allowed time to release post injections for regeneration

Description:

Value Units: enumerative (mission profiles)
X Unit: seconds
Y Units: N/A

Maximum allowed time to release post injections for regeneration - Part 1

y/x	CeDPFR_e_MisProf0	CeDPFR_e_MisProf1	CeDPFR_e_MisProf2	CeDPFR_e_MisProf3	CeDPFR_e_MisProf4	CeDPFR_e_MisProf5	CeDPFR_e_MisProf6
1	5,000	5,000	5,000	5,000	5,000	5,000	5,000

Maximum allowed time to release post injections for regeneration - Part 2

y/x	CeDPFR_e_MisProf7	CeDPFR_e_MisProf8	CeDPFR_e_MisProf9	CeDPFR_e_MisProf10	CeDPFR_e_MisProf11	CeDPFR_e_MisProf12	CeDPFR_e_MisProf13
1	5,000	5,000	5,000	5,000	5,000	5,000	5,000

Maximum allowed time to release post injections for regeneration - Part 3

y/x	CeDPFR_e_MisProf14	CeDPFR_e_MisProf15	CeDPFR_e_MisProf16	CeDPFR_e_MisProf17 Srv	CeDPFR_e_MisProf18 Rec		
1	5,000	5,000	5,000	5,000	5,000		

Initial Supporting table - Mission profile correction on distance

Description: Curve of Mission profile dependent correction for threshold on distance covered since last regeneration

Value Units: [0; 2]
X Unit: enumerative (mission profiles)

Mission profile correction on distance - Part 1

y/x	CeDPFR_e_MisProf0	CeDPFR_e_MisProf1	CeDPFR_e_MisProf2	CeDPFR_e_MisProf3	CeDPFR_e_MisProf4	CeDPFR_e_MisProf5	CeDPFR_e_MisProf6
1	1	1	1	1	1	1	1

Mission profile correction on distance - Part 2

y/x	CeDPFR_e_MisProf7	CeDPFR_e_MisProf8	CeDPFR_e_MisProf9	CeDPFR_e_MisProf10	CeDPFR_e_MisProf11	CeDPFR_e_MisProf12	CeDPFR_e_MisProf13
1	1	1	1	1	1	1	1

Mission profile correction on distance - Part 3

y/x	CeDPFR_e_MisProf14	CeDPFR_e_MisProf15	CeDPFR_e_MisProf16	CeDPFR_e_MisProf17 Srv	CeDPFR_e_MisProf18 Rec		
1	1	1	1	1	1		

Initial Supporting table - Mission profile correction on time

Description: Curve of Mission profile dependent correction for threshold on time spent since last regeneration

Value Units: [0; 2]
X Unit: enumerative (mission profiles)

Mission profile correction on time - Part 1							
y/x	CeDPFR_e_MisProf0	CeDPFR_e_MisProf1	CeDPFR_e_MisProf2	CeDPFR_e_MisProf3	CeDPFR_e_MisProf4	CeDPFR_e_MisProf5	CeDPFR_e_MisProf6
1	1	1	1	1	1	1	1

Mission profile correction on time - Part 2							
y/x	CeDPFR_e_MisProf7	CeDPFR_e_MisProf8	CeDPFR_e_MisProf9	CeDPFR_e_MisProf10	CeDPFR_e_MisProf11	CeDPFR_e_MisProf12	CeDPFR_e_MisProf13
1	1	1	1	1	1	1	1

Mission profile correction on time - Part 3							
y/x	CeDPFR_e_MisProf14	CeDPFR_e_MisProf15	CeDPFR_e_MisProf16	CeDPFR_e_MisProf17 Srv	CeDPFR_e_MisProf18 Rec		
1	1	1	1	1	1		

Initial Supporting table - P0087 Minimum rail pressure

Description: Minimum rail pressure threshold (MPa) as function of engine speed (rpm).

Value Units: MPa
X Unit: rpm

y/x	450	500	511	800	1,000	1,200	1,400	1,600	2,000	2,400	2,800	3,200	3,600	4,200	4,800	5,400
1	0	0	13	13	13	13	13	13	13	13	13	13	13	13	13	13

Initial Supporting table - P0089 Maximum rail pressure with MU

Description: Maximum rail pressure threshold (MPa) when pressure is governed by Metering Unit as function of engine speed (rpm).

Value Units: MPa
X Unit: rpm

y/x	0	1,500	4,250	5,250
1	67	217	217	117

Initial Supporting table - P0181 Fuel Temperature Sensor Reference

Description: Define which sensor is used as reference for check plausibility of fuel temperature sensor.
(CeFTSR_e_ECT_Snsr = Engine coolant temperature, CeFTSR_e_IAT_Snsr = Intake air temperature, CeFTSR_e_IAT_2_Snsr = Manifold air temperature, CeFTSR_e_MainCatTempSnsr = Upstream DPF temperature)

Value Units: -

y/x	1
1	CeFTSR_e_MainCatTempSnsr

Initial Supporting table - P0191 Rail Pressure Sensor Configuration

Description:

Value Units: -

y/x	1
1	CeFHPG_e_RPS_DoubleTrack

Initial Supporting table - P0606_Last Seed Timeout f(Loop Time)

Description: The max time for the Last Seed Timeout as a function of operating loop time sequence.

Value Units: Max Time for Last Seed Timeout (ms)
X Unit: Operating Loop Sequence (enum)

P0606_Last Seed Timeout f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	200.000	200.000	200.000	200.000	200.000	200.000	200.000

P0606_Last Seed Timeout f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	200.000	200.000	500.000	8,191.875	8,191.875	8,191.875	

Initial Supporting table - P0606_PSW Sequence Fail f(Loop Time)

Description: Fail threshold for PSW per operating loop.

Value Units: Fail threshold for PSW (count)
X Unit: Operating Loop (enum)

P0606_PSW Sequence Fail f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	5	3	5	3	5	3	5

P0606_PSW Sequence Fail f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	5	5	3	3	3	5	

Initial Supporting table - P0606_PSW Sequence Sample f(Loop Time)

Description: Sample threshold for PSW per operating loop.

Value Units: Sample threshold for PSW (count)
X Unit: Operating Loop (enum)

P0606_PSW Sequence Sample f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	4	4	4	4	4	4	4

P0606_PSW Sequence Sample f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	4	4	4	4	4	4	

Initial Supporting table - P1682_PT Relay Pull-in Run/Crank Voltage f(IAT)

Description: The Run/Crank voltages required to pull in the PT relay as a function of induction air temperature.

Value Units: Run/Crank Voltages required to pull in PT Relay (V)
X Unit: Induction Air Temperature (deg C)

y/x	23.0	85.0	95.0	105.0	125.0
1	7.000	8.699	9.000	9.199	10.000

Initial Supporting table - P16F3_CB safety deadband threshold f(Fuel Rail Pressure)

Description: Maximum allowable safety deadband on CB Energizing Time compensation (for each torque forming pulse) as a function of Fuel Rail Pressure.

y/x	12	24	36	47	59	71	83	94	106	118	130	141	153	165	177	188	200
1	1,613	1,152	793	607	499	448	398	363	332	309	287	271	255	241	231	220	210

Initial Supporting table - P16F3_EIA safety deadband threshold f(Fuel Rail Pressure)

Description: Maximum allowable safety deadband on EIA Energizing Time compensation (for each torque forming pulse) as function of Fuel Rail Pressure.

y/x	12	24	36	47	59	71	83	94	106	118	130	141	153	165	177	188	200
1	1,621	1,158	797	610	502	450	400	365	333	311	289	272	256	243	232	221	211

Initial Supporting table - P16F3_FTD safety deadband threshold f(Fuel Rail Pressure)

Description: Maximum allowable safety deadband on FTD Energizing Time compensation as function of Fuel Rail Pressure.

y/x	12	24	36	47	59	71	83	94	106	118	130	141	153	165	177	188	200
1	1,621	1,158	797	610	502	450	400	365	333	311	289	272	256	243	232	221	211

Initial Supporting table - P16F3_Rail Pressure Wave Compensation f(Fuel Rail Pressure, Fuel Quantity)

Description: Safety treshold for the Rail Pressure Wave Compensation on each torque forming pulse as a function of Fuel Rail Pressure and Fuel Quantity

y/x	1	2	3	4	5	7	10	20	30	45	60	85	117
16	5	5	5	5	5	5	5	5	5	5	5	5	5
22	11	11	11	11	11	11	11	10	6	5	4	3	2
40	29	29	29	26	24	22	20	14	12	9	7	5	4
60	49	49	42	40	37	34	30	22	18	14	12	9	7
90	79	73	65	62	57	53	48	31	26	21	17	13	11
120	105	98	89	82	75	68	58	34	35	27	21	17	11
150	132	123	112	103	94	86	75	50	43	33	27	21	16
185	165	153	136	124	114	104	89	62	46	40	33	25	19
200	178	165	145	132	122	111	94	65	49	41	36	26	11
210	187	174	152	138	128	116	97	68	54	46	40	30	19

Initial Supporting table - P16F3_Speed Control External Load f(Oil Temp, RPM)

Description: Specifies the external load table for SPDR torque security as a function of engine oil temperature and engine RPM.

y/x	-40	-20	-10	0	50	90
430	239	212	196	158	120	120
530	233	206	190	110	67	67
630	212	185	169	89	46	46
730	205	178	161	82	41	41
750	197	170	154	74	36	36
800	182	156	141	83	45	45
900	164	139	124	88	53	53
1,000	145	121	107	93	60	60
1,100	147	125	113	101	72	72
1,200	149	129	119	109	84	84
1,400	93	73	63	53	28	28
1,600	11	-9	-19	-29	-54	-54
2,000	-220	-220	-220	-220	-220	-220
2,500	-242	-242	-242	-242	-242	-242
3,000	-264	-264	-264	-264	-264	-264
3,500	-286	-286	-286	-286	-286	-286
5,000	-286	-286	-286	-286	-286	-286

Initial Supporting table - P16F3_SQA safety deadband threshold f(Fuel Rail Pressure)

Description: Maximum allowable safety deadband on SQA Energizing Time compensation (for each torque forming pulse) as function of Fuel Rail Pressure.

y/x	12	29	46	63	80	97	115	132	149	166	183	200
1	1,669	1,023	730	593	521	458	397	370	344	319	293	275

Initial Supporting table - P16F3_VCA safety max deadband threshold f(Fuel Rail Pressure)

Description: Maximum allowable safety deadband on VCA energizing time correction as function of Fuel Rail Pressure.

y/x	12	24	36	47	59	71	83	94	106	118	130	141	153	165	177	188	200
1	811	579	398	305	251	225	200	183	167	155	144	136	128	121	116	111	106

Initial Supporting table - P16F3_VCA safety min deadband threshold f(Fuel Rail Pressure)

Description: Minimum allowable safety deadband on VCA energizing time correction as function of Fuel Rail Pressure.

y/x	12	24	36	47	59	71	83	94	106	118	130	141	153	165	177	188	200
1	-811	-579	-398	-305	-251	-225	-200	-183	-167	-155	-144	-136	-128	-121	-116	-111	-106

Initial Supporting table - P228A Fuel High Pressure Pump efficiency

Description: Efficiency percentage of high pressure pump as function of rail pressure (MPa) and engine speed (rpm).

Value Units: %
X Unit: MPa
Y Units: rpm

y/x	30	80	100	120	200
0	0	100	100	100	100
1,000	42	89	86	84	100
1,800	96	90	88	85	100
2,300	96	90	88	86	100
2,800	96	90	88	86	100
3,250	96	90	88	86	100
3,750	93	87	85	83	100
4,400	85	82	78	77	100

Initial Supporting table - P228A Fuel High Pressure Pump efficiency correction

Description: Correction of high pressure pump eficiency as function of fuel temperature (°C).

Value Units: -
X Unit: °C

y/x	-40	-20	20	40	80
1	1	1	1	1	1

Initial Supporting table - P228B Pressure Regulator completely closed command

Description: Command, in terms of pressure (MPa), to consider pressure regulator valve completely closed as function of rail pressure (MPa).

Value Units: MPa
X Unit: MPa

y/x	0	100	190	250
1	30	120	210	210

Initial Supporting table - P228C Positive rail pressure deviation (MU)

Description: Positive rail pressure deviation threshold (MPa) when metering unit is controlled in closed loop as function of engine speed (rpm).

Value Units: MPa
X Unit: rpm

y/x	199	510	511	800	1,000	1,200	1,400	1,600	2,000	2,400	2,800	3,200	3,600	4,200	4,800	5,400
1	80	80	12	12	12	12	12	12	12	12	12	12	12	12	12	12

Initial Supporting table - P228D Negative rail pressure deviation (MU)

Description: Negative rail pressure deviation threshold (MPa) when metering unit is controlled in closed loop as function of engine speed (rpm).

Value Units: MPa
X Unit: rpm

y/x	199	510	511	800	1,000	1,200	1,400	1,600	2,000	2,400	2,800	3,200	3,600	4,200	4,800	5,400
1	-80	-80	-15	-15	-15	-15	-15	-15	-15	-15	-15	-15	-15	-15	-15	-15

Initial Supporting table - P2293 Maximum rail pressure with PR

Description: Maximum rail pressure threshold (MPa) when pressure is governed by Pressure Regulator as function of engine speed (rpm).

Value Units: MPa
X Unit: rpm

y/x	0	1,500	4,250	5,250
1	67	217	217	117

Initial Supporting table - P229A Positive rail pressure deviation (PR)

Description: Positive rail pressure deviation threshold (MPa) when pressure regulator is controlled in closed loop as function of engine speed (rpm).

Value Units: MPa
X Unit: rpm

y/x	199	510	511	800	1,000	1,200	1,400	1,600	2,000	2,400	2,800	3,200	3,600	4,200	4,800	5,400
1	80	80	12	12	12	12	12	12	12	12	12	12	12	12	12	12

Initial Supporting table - Rail Pressure Control Configuration

Description: CeFHPG_e_MU_And_PR_ModeSel = pressure control can be governed by both metering unit and pressure regulator
CeFHPG_e_MU = pressure control can be governed by metering unit only
CeFHPG_e_PR = pressure control can be governed by pressure regulator only

Value Units: -

y/x	1
1	CeFHPG_e_MU_And_PR_ModeSel

Initial Supporting table - Time since last regeneration

Description: Base value to trigger regeneration for time spent since last regeneration, function of regeneration priority

Value Units: s
X Unit: enumerative (mission profiles)

Time since last regeneration - Part 1						
y/x	CeDPFC_e_RgnPriority_0	CeDPFC_e_RgnPriority_1	CeDPFC_e_RgnPriority_2	CeDPFC_e_RgnPriority_3	CeDPFC_e_RgnPriority_4	CeDPFC_e_RgnPriority_5
1	54,000	54,000	54,000	54,000	54,000	54,000

Time since last regeneration - Part 2						
y/x	CeDPFC_e_RgnPriority_6	CeDPFC_e_RgnPriority_7	CeDPFC_e_RgnPriority_8	CeDPFC_e_RgnPriority_9	CeDPFC_e_RgnPriority_10	CeDPFC_e_RgnPriority_11
1	54,000	54,000	54,000	54,000	54,000	54,000

Time since last regeneration - Part 3						
y/x	CeDPFC_e_RgnPriority_12	CeDPFC_e_RgnPriority_13	CeDPFC_e_RgnPriority_14	CeDPFC_e_RgnPriority_15	CeDPFC_e_RgnPriority_16	
1	54,000	54,000	54,000	54,000	54,000	

Initial Supporting table - P0216_ET_CumulEnbl

Description: This calibration provides the capability to select which pulses of the injection pattern have to be monitored
1 -> pulse monitored
0 -> pulse NOT monitored

Value Units: Boolean
X Unit: Pulse ID

P0216_ET_CumulEnbl - Part 1

y/x	CeFULR_e_PulsPI	CeFULR_e_PulsR2	CeFULR_e_PulsR1	CeFULR_e_PulsM	CeFULR_e_PulsA1	CeFULR_e_PulsA2	CeFULR_e_PulsA3
1.00	0.00	1.00	1.00	1.00	1.00	1.00	1.00

P0216_ET_CumulEnbl - Part 2

y/x	CeFULR_e_PulsA4	CeFULR_e_PulsP1	CeFULR_e_PulsP2	CeFULR_e_PulsP3	CeFULR_e_PulsP4	CeFULR_e_PulsP5	
1.00	1.00	0.00	0.00	0.00	0.00	0.00	

Initial Supporting table - P0216_PulsWidthErrHi

Description: This error threshold map defines the maximum acceptable positive error [us] between cumulative ET HW and ET SW, depending on the number of pulses driven and monitored.

Value Units: us
X Unit: -
Y Units: Number of pulses

y/x	0.00	1.00	2.00	3.00	4.00	5.00
1.00	32,767.00	32,767.00	32,767.00	32,767.00	32,767.00	32,767.00

Initial Supporting table - P054E_IFM_CombModesEnbl

Description: This calibration provides the capability to select in which combustion mode the Idle Fuel Monitoring shall be enabled.
1 -> monitor enabled
0 -> monitor disabled

Value Units: Boolean
X Unit: Combustion Mode

P054E_IFM_CombModesEnbl - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

P054E_IFM_CombModesEnbl - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	1	0

P054E_IFM_CombModesEnbl - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

P054E_IFM_CombModesEnbl - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	1	1	0	0	

Initial Supporting table - P054E_IFM_MinFuelIdleC1_G

Description: During Normal combustion mode, this error threshold map indicates the minimum fuel requested [mm3] in nominal condition and with transmission in gear. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	30	30	30	30	30
-10	25	25	25	25	25
0	22	22	22	24	22
20	20	20	20	20	20
40	16	16	18	16	16
70	13	13	13	13	13

Initial Supporting table - P054E_IFM_MinFuelIdleC1_PN

Description: During Normal combustion mode, this error threshold map indicates the minimum fuel requested [mm3] in nominal condition and with transmission in park and neutral. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	16	16	16	16	16
-10	15	15	15	15	15
0	11	11	11	11	11
20	12	12	12	12	12
40	8	8	8	8	8
70	7	7	7	7	7

Initial Supporting table - P054E_IFM_MinFuelIdleHC_G

Description: During HC Unloading combustion mode, this error threshold map indicates the minimum fuel requested [mm3] in nominal condition and with transmission in gear. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	30	30	30	30	30
-10	25	25	25	25	25
0	22	22	22	24	22
20	20	20	20	20	20
40	16	16	18	16	16
70	13	13	13	13	13

Initial Supporting table - P054E_IFM_MinFuelIdleHC_PN

Description: During HC Unloading combustion mode, this error threshold map indicates the minimum fuel requested [mm3] in nominal condition and with transmission in park and neutral. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	16	16	16	16	16
-10	15	15	15	15	15
0	11	11	11	11	11
20	12	12	12	12	12
40	8	8	8	8	8
70	7	7	7	7	7

Initial Supporting table - P054E_IFM_MinFuelIdleV2_G

Description: During Soft Warm Up combustion mode, this error threshold map indicates the minimum fuel requested [mm3] in nominal condition and with transmission in gear. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	30	30	30	30	30
-10	25	25	25	25	25
0	22	22	22	24	22
20	20	20	20	20	20
40	16	16	18	16	16
70	13	13	13	13	13

Initial Supporting table - P054E_IFM_MinFuelIdleV2_PN

Description: During Soft Warm Up combustion mode, this error threshold map indicates the minimum fuel requested [mm3] in nominal condition and with transmission in park and neutral. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	16	16	16	16	16
-10	15	15	15	15	15
0	11	11	11	11	11
20	12	12	12	12	12
40	8	8	8	8	8
70	7	7	7	7	7

Initial Supporting table - P054E_IFM_MinFuelIdleV3_G

Description: During Strong Warm Up combustion mode, this error threshold map indicates the minimum fuel requested [mm3] in nominal condition and with transmission in gear. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	30	30	30	30	30
-10	25	25	25	25	25
0	22	22	22	24	22
20	20	20	20	20	20
40	16	16	19	16	16
70	13	13	13	13	13

Initial Supporting table - P054E_IFM_MinFuelIdleV3_PN

Description: During Strong Warm Up combustion mode, this error threshold map indicates the minimum fuel requested [mm3] in nominal condition and with transmission in park and neutral. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	16	16	16	16	16
-10	15	15	15	15	15
0	11	11	11	11	11
20	12	12	12	12	12
40	8	8	8	8	8
70	7	7	7	7	7

Initial Supporting table - P054F_IFM_CombModesEnbl

Description: This calibration provides the capability to select in which combustion mode the Idle Fuel Monitoring shall be enabled.
1 -> monitor enabled
0 -> monitor disabled

Value Units: Boolean
X Unit: Combustion Mode

P054F_IFM_CombModesEnbl - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

P054F_IFM_CombModesEnbl - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	1	0

P054F_IFM_CombModesEnbl - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

P054F_IFM_CombModesEnbl - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	1	1	0	0	

Initial Supporting table - P054F_IFM_MaxFuelIdleC1_G

Description: During Normal combustion mode, this error threshold map indicates the maximum fuel requested [mm3] in nominal condition and with transmission in gear. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	40	40	40	40	40
-10	35	35	35	35	35
0	32	32	32	34	32
20	29	29	29	29	29
40	26	26	28	26	26
70	23	23	23	23	23

Initial Supporting table - P054F_IFM_MaxFuelIdleC1_PN

Description: During Normal combustion mode, this error threshold map indicates the maximum fuel requested [mm3] in nominal condition and with transmission in park and neutral. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	28	28	28	28	28
-10	27	27	27	27	27
0	22	22	22	22	22
20	23	23	23	23	23
40	19	19	19	19	19
70	18	18	18	18	18

Initial Supporting table - P054F_IFM_MaxFuelIdleHC_G

Description: During HC Unloading combustion mode, this error threshold map indicates the maximum fuel requested [mm3] in nominal condition and with transmission in gear. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	40	40	40	40	40
-10	35	35	35	35	35
0	32	32	32	34	32
20	29	29	29	29	29
40	26	26	28	26	26
70	23	23	23	23	23

Initial Supporting table - P054F_IFM_MaxFuelIdleHC_PN

Description: During HC Unloading combustion mode, this error threshold map indicates the maximum fuel requested [mm3] in nominal condition and with transmission in park and neutral. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	28	28	28	28	28
-10	27	27	27	27	27
0	22	22	22	22	22
20	23	23	23	23	23
40	19	19	19	19	19
70	18	18	18	18	18

Initial Supporting table - P054F_IFM_MaxFuelIdleV2_G

Description: During Soft Warm Up combustion mode, this error threshold map indicates the maximum fuel requested [mm3] in nominal condition and with transmission in gear. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	44	44	44	44	44
-10	39	39	39	39	39
0	35	35	35	37	35
20	32	32	32	32	32
40	29	29	31	29	29
70	25	25	25	25	25

Initial Supporting table - P054F_IFM_MaxFuelIdleV2_PN

Description: During Soft Warm Up combustion mode, this error threshold map indicates the maximum fuel requested [mm3] in nominal condition and with transmission in park and neutral. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	31	31	31	31	31
-10	29	29	29	29	29
0	25	25	25	25	25
20	26	26	26	26	26
40	21	21	21	21	21
70	20	20	20	20	20

Initial Supporting table - P054F_IFM_MaxFuelIdleV3_G

Description: During Strong Warm Up combustion mode, this error threshold map indicates the maximum fuel requested [mm3] in nominal condition and with transmission in gear. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	44	44	44	44	44
-10	39	39	39	39	39
0	35	35	35	37	35
20	32	32	32	32	32
40	29	29	31	29	29
70	25	25	25	25	25

Initial Supporting table - P054F_IFM_MaxFuelIdleV3_PN

Description: During Strong Warm Up combustion mode, this error threshold map indicates the maximum fuel requested [mm3] in nominal condition and with transmission in park and neutral. It's function of engine coolant temperature [°C] and engine speed [rpm]

Value Units: mm3
X Unit: rpm
Y Units: °C

y/x	511	730	800	1,200	1,600
-20	31	31	31	31	31
-10	29	29	29	29	29
0	25	25	25	25	25
20	26	26	26	26	26
40	21	21	21	21	21
70	20	20	20	20	20

Initial Supporting table - P2160 range change delay time

Description: If the transmission range state changes, the transmission range state must be stable for this amount of time as part of the P2160 enable conditions.

X Unit: transmission fluid temperature DegC
Y Units: delay time seconds

y/x	-40.00	0.00	40.00
1	5.000	5.000	5.000

Initial Supporting table - P2161 range change delay time

Description: If the transmission range state changes, the transmission range state must be stable for this amount of time as part of the P2161 enable conditions.

X Unit: transmission fluid temperature DegC
Y Units: delay time seconds

y/x	-40.00	-20.00	40.00
1	5.000	5.000	5.000

Initial Supporting table - P0606_Last Seed Timeout f(Loop Time)

Description: The max time for the Last Seed Timeout as a function of operating loop time sequence.

Value Units: Max Time for Last Seed Timeout (ms)
X Unit: Operating Loop Sequence (enum)

P0606_Last Seed Timeout f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	200.000	200.000	200.000	200.000	200.000	200.000	200.000

P0606_Last Seed Timeout f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	200.000	200.000	500.000	8,191.875	8,191.875	8,191.875	

Initial Supporting table - P0606_PSW Sequence Fail f(Loop Time)

Description: Fail threshold for PSW per operating loop.

Value Units: Fail threshold for PSW (count)
X Unit: Operating Loop (enum)

P0606_PSW Sequence Fail f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	5	3	5	3	5	3	5

P0606_PSW Sequence Fail f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	5	5	3	3	3	5	

Initial Supporting table - P0606_PSW Sequence Sample f(Loop Time)

Description: Sample threshold for PSW per operating loop.

Value Units: Sample threshold for PSW (count)
X Unit: Operating Loop (enum)

P0606_PSW Sequence Sample f(Loop Time) - Part 1

y/x	CePISR_e_5msSeq	CePISR_e_6p25msSeq	CePISR_e_10msSeq	CePISR_e_12p5msSeq	CePISR_e_20msSeq	CePISR_e_25msSeq	CePISR_e_40msSeq
1	4	4	4	4	4	4	4

P0606_PSW Sequence Sample f(Loop Time) - Part 2

y/x	CePISR_e_50msSeq	CePISR_e_80msSeq	CePISR_e_100msSeq	CePISR_e_EventA_Seq	CePISR_e_EventB_Seq	CePISR_e_EventC_Seq	
1	4	4	4	4	4	4	

Initial Supporting table - KaFADC_b_SQA_EnblCMBR

Description: SQA combustion mode enable

KaFADC_b_SQA_EnblCMBR - Part 1

y/x	CeCMBR_e_Normal	CeCMBR_e_DPF_HiO2	CeCMBR_e_DPF_LoO2	CeCMBR_e_FullyWarmEmissions	CeCMBR_e_LNT_DeNOx
1	1	0	0	0	0

KaFADC_b_SQA_EnblCMBR - Part 2

y/x	CeCMBR_e_LNT_DeSOx_Lean	CeCMBR_e_LNT_DeSOx_Rich	CeCMBR_e_StrongExhGasWarmUp	CeCMBR_e_SoftExhGasWarmUp	CeCMBR_e_DPF_PN
1	0	0	1	0	0

KaFADC_b_SQA_EnblCMBR - Part 3

y/x	CeCMBR_e_DPF_RichIdle	CeCMBR_e_DPF_EngPrtct_HiO2	CeCMBR_e_DPF_EngPrtct_LoO2	CeCMBR_e_LNT_EngPrtct	CeCMBR_e_FAD_IdleInjLrn
1	0	0	0	0	0

KaFADC_b_SQA_EnblCMBR - Part 4

y/x	CeCMBR_e_HCS_DeHC_Drive	CeCMBR_e_HCS_DeHC_Park	CeCMBR_e_SCR_ServWarmUp	CeCMBR_e_SCR_ServCheck	
1	0	0	0	0	

Initial Supporting table - KaFADC_n_SQC_HiThrsh

Description: Engine speed high threshold for SQC enable function of driveline group and SQA rail pressure level index.

Value Units: Rpm

KaFADC_n_SQC_HiThrsh - Part 1

y/x	CeFADR_e_CWA_DrvlnGrpNotAlwd	CeFADR_e_CWA_DrivelineGrp1	CeFADR_e_CWA_DrivelineGrp2	CeFADR_e_CWA_DrivelineGrp3
0	2,100	2,100	2,100	2,100
1	2,100	2,100	2,100	2,100
2	2,100	2,100	2,100	2,100
3	2,100	2,100	2,100	2,100
4	2,100	2,100	2,100	2,100

KaFADC_n_SQC_HiThrsh - Part 2

y/x	CeFADR_e_CWA_DrivelineGrp4	CeFADR_e_CWA_DrivelineGrp5	CeFADR_e_CWA_DrivelineGrp6	CeFADR_e_CWA_DrivelineGrp7
0	2,100	2,100	2,100	2,100
1	2,100	2,100	2,100	2,100
2	2,100	2,100	2,100	2,100
3	2,100	2,100	2,100	2,100
4	2,100	2,100	2,100	2,100

KaFADC_n_SQC_HiThrsh - Part 3

y/x	CeFADR_e_CWA_DrivelineGrp8	CeFADR_e_CWA_DrivelineGrp9	CeFADR_e_CWA_DrivelineGrp10	
0	2,100	2,100	2,100	
1	2,100	2,100	2,100	
2	2,100	2,100	2,100	
3	2,100	2,100	2,100	
4	2,100	2,100	2,100	

Initial Supporting table - KaFADC_n_SQC_LoThrsh

Description: Engine speed low threshold for SQC enable function of driveline group and SQA rail pressure level index.

Value Units: Rpm

KaFADC_n_SQC_LoThrsh - Part 1

y/x	CeFADR_e_CWA_DrvlnGrpNotAlwd	CeFADR_e_CWA_DrivelineGrp1	CeFADR_e_CWA_DrivelineGrp2	CeFADR_e_CWA_DrivelineGrp3
0	1,350	1,350	1,350	1,350
1	1,350	1,350	1,350	1,350
2	1,350	1,350	1,350	1,350
3	1,350	1,350	1,350	1,350
4	1,350	1,350	1,350	1,350

KaFADC_n_SQC_LoThrsh - Part 2

y/x	CeFADR_e_CWA_DrivelineGrp4	CeFADR_e_CWA_DrivelineGrp5	CeFADR_e_CWA_DrivelineGrp6	CeFADR_e_CWA_DrivelineGrp7
0	1,200	1,200	1,350	1,350
1	1,200	1,200	1,350	1,350
2	1,200	1,200	1,350	1,350
3	1,200	1,200	1,350	1,350
4	1,200	1,200	1,350	1,350

KaFADC_n_SQC_LoThrsh - Part 3

y/x	CeFADR_e_CWA_DrivelineGrp8	CeFADR_e_CWA_DrivelineGrp9	CeFADR_e_CWA_DrivelineGrp10	
0	1,350	1,350	1,350	
1	1,350	1,350	1,350	
2	1,350	1,350	1,350	
3	1,350	1,350	1,350	
4	1,350	1,350	1,350	

Initial Supporting table - RufCyl_Decel

Description: Used for P0300-P0308. Crankshaft decel threshold during Idle or GPF regen. Thresholds are a function of rpm and % engine Load.

Value Units: Delta time per cylinder (usec)
X Unit: rpm
Y Units: percent load of max indicated torque (%)

RufCyl_Decel - Part 1

y/x	580	655	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,200
2	4,239	2,939	2,042	1,546	1,139	760	632	471	310	211	146	133	116
4	3,746	2,603	1,811	1,362	1,025	670	564	420	271	190	138	123	102
6	3,481	2,406	1,707	1,218	924	640	549	365	231	158	123	104	78
8	2,974	2,062	1,450	1,218	823	611	500	365	231	126	109	85	69
10	4,049	2,748	1,963	1,362	910	611	525	406	227	126	94	79	60
12	5,124	3,413	2,475	1,651	1,084	687	574	489	223	140	83	73	50
14	6,199	4,079	2,988	1,940	1,259	840	673	572	218	154	94	67	53
16	7,267	4,743	3,501	2,229	1,433	993	772	655	214	168	106	76	59
18	8,347	5,414	4,013	2,518	1,607	1,146	871	738	249	182	117	85	65
20	9,417	6,087	4,527	2,807	1,781	1,299	970	821	285	196	128	95	71
22	10,488	6,753	5,036	3,095	1,956	1,452	1,069	904	320	210	140	104	77
24	11,570	7,425	5,551	3,383	2,130	1,605	1,168	987	355	224	151	113	83
26	12,640	8,091	6,066	3,672	2,304	1,758	1,267	1,071	390	238	162	123	89
30	14,782	9,430	7,090	4,251	2,653	2,064	1,465	1,237	461	266	185	141	101
40	20,156	12,779	9,652	5,695	3,523	2,829	1,960	1,652	637	336	242	188	131
60	28,000	19,472	14,776	8,584	5,268	4,359	2,951	2,483	989	476	356	281	191
97	28,000	28,000	24,391	13,997	8,535	7,228	4,806	4,040	1,649	739	569	456	304

RufCyl_Decel - Part 2

y/x	2,400	2,600	2,800	3,000	3,200	3,400	3,600	3,800	4,000	4,200	4,400	4,600	4,800
2	100	111	76	81	78	59	62	58	58	60	54	54	54
4	87	96	73	71	69	52	56	52	53	56	50	50	50
6	84	82	71	61	61	44	50	47	49	52	46	46	46
8	75	68	71	52	52	41	43	42	44	48	42	42	42
10	66	54	59	52	43	39	40	36	39	44	39	39	39
12	57	54	48	47	40	38	34	32	34	40	35	35	35
14	53	56	48	42	40	36	29	32	32	35	32	32	32
16	50	56	48	41	38	36	30	31	30	32	30	30	30
18	53	56	48	40	36	37	32	31	29	30	28	28	28
20	58	58	48	39	34	38	34	30	28	27	26	26	26
22	64	62	50	43	36	39	37	30	26	24	21	21	21

Initial Supporting table - RufCyl_Decel

24	69	66	54	47	39	40	39	32	28	25	23	23	23
26	75	70	59	50	43	42	41	35	31	27	24	24	24
30	86	79	67	58	50	47	45	39	35	31	28	28	28
40	114	100	89	78	68	59	56	51	46	40	35	35	35
60	169	142	132	117	104	82	77	75	69	59	51	51	51
97	274	221	213	190	172	127	117	120	110	94	80	80	80

Initial Supporting table - RufCyl_Jerk

Description: Crankshaft jerk threshold during Idle or GPF regen. Thresholds are a function of rpm and % engine Load.

Value Units: Delta time per cylinder (usec)
X Unit: rpm
Y Units: percent load of max indicated torque (%)

RufCyl_Jerk - Part 1

y/x	580	655	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,200
2	3,970	2,761	1,912	1,446	1,133	697	581	460	311	215	174	133	124
4	3,476	2,424	1,672	1,272	1,016	650	512	409	302	183	143	124	104
6	4,464	3,098	2,152	1,552	1,251	790	580	487	320	183	143	116	89
8	5,452	3,773	2,507	1,970	1,486	976	706	591	338	215	143	107	73
10	6,854	4,693	3,126	2,426	1,904	1,287	831	695	356	246	174	133	92
12	7,903	5,509	3,746	2,862	2,316	1,632	1,081	903	374	277	206	158	112
14	8,952	6,307	4,365	3,299	2,727	1,977	1,332	1,110	392	311	243	183	131
16	9,983	7,112	4,984	3,736	3,139	2,322	1,582	1,318	483	371	274	206	150
18	11,036	7,910	5,603	4,173	3,551	2,667	1,833	1,525	575	415	305	228	169
20	12,079	8,721	6,222	4,610	3,962	3,012	2,083	1,733	667	458	336	250	188
22	13,123	9,522	6,841	5,046	4,374	3,357	2,334	1,940	759	502	367	272	207
24	14,172	10,324	7,461	5,483	4,785	3,702	2,584	2,147	850	545	397	295	226
26	15,218	11,126	8,080	5,920	5,197	4,047	2,835	2,355	942	589	428	317	245
30	17,305	12,729	9,318	6,794	6,020	4,737	3,335	2,770	1,125	676	490	362	284
40	22,540	16,746	12,414	8,978	8,076	6,461	4,586	3,807	1,584	893	643	473	379
60	28,000	24,771	18,606	13,346	12,195	9,911	7,094	5,882	2,501	1,328	951	697	571
97	28,000	28,000	28,000	21,536	19,910	16,379	11,789	9,770	4,221	2,144	1,527	1,115	929

RufCyl_Jerk - Part 2

y/x	2,400	2,600	2,800	3,000	3,200	3,400	3,600	3,800	4,000	4,200	4,400	4,600	4,800
2	112	113	92	78	75	57	61	57	59	60	53	53	53
4	91	97	81	68	67	49	54	51	54	55	49	49	49
6	87	82	69	58	58	42	48	45	49	51	45	45	45
8	83	75	66	48	50	38	42	40	44	47	41	41	41
10	78	73	64	48	41	38	39	34	39	42	37	37	37
12	94	81	62	58	44	42	36	32	34	38	33	33	33
14	109	97	71	66	47	42	32	34	31	34	30	30	30
16	123	107	80	73	54	43	35	36	33	32	28	28	28
18	138	117	89	80	61	49	40	38	37	34	30	30	30
20	152	128	98	87	67	55	45	41	40	38	33	33	33
22	167	138	107	94	74	61	51	44	43	41	37	37	37

Initial Supporting table - RufCyl_Jerk

24	181	148	116	101	81	67	56	47	46	44	41	41	41
26	195	158	125	108	87	73	61	50	49	47	44	44	44
30	224	178	142	122	101	86	72	56	56	53	49	49	49
40	297	229	187	158	134	117	99	70	72	68	61	61	61
60	441	330	276	228	201	179	152	98	104	98	85	85	85
97	712	520	442	360	325	294	252	152	165	154	130	130	130

Initial Supporting table - RufSCD_Decel

Description: Used for P0300-P0308. Crankshaft decel threshold while in SCD mode during Idle or GPF regen. SCD mode uses smaller windows near TDC. Thresholds are a function of rpm and % engine Load. Note: Misfire's Load term is %, but not PID$04. PID $04 is not robust to temperature and alititude shifts. (especially decel and jerk thresholds since they track actual air trapped in cylinder)

Value Units: Delta time per cylinder (usec)
X Unit: rpm
Y Units: percent load of max indicated torque (%)

RufSCD_Decel - Part 1

y/x	580	655	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,200
2	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
4	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
6	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
8	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
10	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
12	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
14	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
16	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
18	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
20	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
22	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
24	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
26	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
30	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
40	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
60	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
97	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

RufSCD_Decel - Part 2

y/x	2,400	2,600	2,800	3,000	3,200	3,400	3,600	3,800	4,000	4,200	4,400	4,600	4,800
2	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
4	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
6	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
8	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
10	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
12	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
14	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
16	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
18	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

Initial Supporting table - RufSCD_Decel

20	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
22	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
24	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
26	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
30	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
40	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
60	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
97	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

Initial Supporting table - RufSCD_Jerk

Description: Used for P0300-P0308. Crankshaft jerk threshold while in SCD mode during Idle or GPF regen. SCD mode uses smaller windows near TDC. Thresholds are a function of rpm and % engine Load.

Value Units: Delta time per cylinder (usec)
X Unit: rpm
Y Units: percent load of max indicated torque (%)

RufSCD_Jerk - Part 1

y/x	580	655	730	800	900	1,000	1,100	1,200	1,400	1,600	1,800	2,000	2,200
2	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
4	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
6	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
8	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
10	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
12	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
14	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
16	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
18	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
20	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
22	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
24	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
26	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
30	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
40	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
60	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
97	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

RufSCD_Jerk - Part 2

y/x	2,400	2,600	2,800	3,000	3,200	3,400	3,600	3,800	4,000	4,200	4,400	4,600	4,800
2	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
4	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
6	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
8	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
10	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
12	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
14	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
16	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
18	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
20	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

Initial Supporting table - RufSCD_Jerk

22	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
24	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
26	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
30	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
40	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
60	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767
97	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767	32,767

Initial Supporting table - P2BAA RDP Min Press Drop

Description: This calibration is used to define the minimum expected pressure drop based on pump efficiency after that the injection is commanded. The input of this table is the motorpump average commanded duty cycle before the injection is commanded

Value Units: kPa
X Unit: %

y/x	45	46	48	50	51	52	54	55	57
1	44	42	40	39	38	36	34	32	30

Initial Supporting table - P2ADD_Measure_Error

Description: Maximum temperature measurement error as function of last good measured temperature

Value Units: °C
X Unit: °C

y/x	-40.0	-20.0	80.0	120.0
1.0	3.0	2.0	3.0	3.0

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
Transmission Control Module (TCM)	P0601	Transmission Electro-Hydraulic Control Module Read Only Memory	Incorrect program/calibrations checksum	= TRUE Boolean			>= 5 Fail Counts	One Trip
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0601 ECM: None		
Transmission Control Module (TCM)	P0603	Transmission Electro-Hydraulic Control Module Long-Term Memory Reset	Non-volatile memory (static or dynamic) checksum failure at Powerup	= TRUE Boolean			Runs Continously	One Trip
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0603 ECM: None		
Transmission Control Module (TCM)	P0604	Transmission Electro-Hydraulic Control Module Random Access Memory	RAM Read/Write Failure (Single Word)	= TRUE Boolean			>= 5 Fail Counts = 16 Sample Counts	One Trip
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0604 ECM: None		
Transmission Control Module (TCM)	P062F	Transmission Electro-Hydraulic Control Module Long Term Memory Performance	TCM Non-Volatile Memory bit Incorrect flag at Powerdown	= TRUE Boolean			Runs Continously	One Trip
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P062F ECM: None		
Transmission Control Module (TCM)	P0634	Transmission Electro-Hydraulic Control Module Internal Temperature Too High	Fail Case 1 Substrate Temperature	>= 142.1015625 °C			>= 5 Fail Time (Sec)	One Trip
			Fail Case 2 Substrate Temperature	>= 50 °C			>= 2 Fail Time (Sec)	
			Ignition Voltage	>= 18 Volts				
			Note: either fail case can set the DTC					
					Ignition Voltage Lo Ignition Voltage Hi Substrate Temp Lo Substrate Temp Hi	>= 8.5996094 Volts <= 31.999023 Volts >= 0 °C <= 170 °C		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Substrate Temp Between Temp Range for Time	>= 0.25 Sec		
					P0634 Status is	≠ Test Failed This Key On or Fault Active		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
High Side Driver 1	P0658	Actuator Supply Voltage Circuit Low	The HWIO reports a low voltage (open or ground short) error flag	= TRUE Boolean			>= 4 Fail Counts out of 6 Sample Counts	One Trip
					P0658 Status is not	= Test Failed This Key On or Fault Active		
					High Side Driver 1 On	= True Boolean		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Transmission Control Module (TCM)	P0667	TCM Internal Temp (substrate) Sensor Circuit Range/Performance	If transmission oil temp to substrate temp Δ	> Refer to Table 19 in supporting documents ℃				Two Trips
			If TCM substrate temp to power up temp Δ	> Refer to Table 20 in supporting documents ℃				
			Both conditions above required to increment fail counter Note: table reference temp = to the median temp of trans oil temp, substrate temp and power up temp.				>= 3000 Fail Counts (100ms loop) Out of 3750 Sample Counts (100ms loop)	
			Non-continuous (intermittent) fail conditions will delay resetting fail counter until				>= 700 Pass Counts (100ms loop) Out of 875 Sample Counts (100ms loop)	
					Engine Torque Signal Valid	= TRUE Boolean		
					Accelerator Position Signal Valid	= TRUE Boolean		
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions			Time Required	Mil Illum.
					Engine Speed is within the allowable limits for	>=	5	Sec		
					Brake torque active	=	FALSE			
					Below describes the brake torque entry criteria					
					Engine Torque	>=	90	N*m		
					Throttle	>=	30.000305	Pct		
					Transmission Input Speed	<=	200	RPM		
					Vehicle Speed	<=	8	Kph		
					Transmission Range	≠	Park			
					Transmission Range	≠	Neutral			
					PTO	=	Not Active			
					Set Brake Torque Active TRUE if above conditions are met for:	>=	7	sec		
					Below describes the brake torque exit criteria					
					Brake torque entry criteria	=	Not Met			
					Clutch hydraulic pressure	≠	Clutch Hydraulic Air Purge Event			
					Clutch used to exit brake torque active	=	CeTFTD_e_C3_RatlEnbl			
					The above clutch pressure is greater than this value for one loop	>=	600	kpa		
					Set Brake Torque Active FALSE if above conditions are met for:	>=	20	Sec		
					P0667 Status is	≠	Test Failed This Key On or Fault Active			
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0658, P0668, P0669, P06AD, P06AE, P0716, P0712, P0713, P0717, P0722, P0723, P0962, P0963, P0966, P0967, P0970, P0971, P215C, P2720, P2721, P2729, P2730 ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E			
Transmission Control Module (TCM)	P0668	TCM internal temperature (substrate) thermistor failed at a low voltge	Type of Sensor Used	= CeTFTI_e_VoltageDirectPrp						Two Trips
			If TCM Substrate Temperature Sensor = Direct Proportional and Temp	<= -249 °C						

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			If TCM Substrate Temperature Sensor = Indirect Proportional and Temp	>= -249 ºC				
			Either condition above will satisfy the fail conditions				>= 60 Fail Timer (Sec)	
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					P0668 Status is	≠ Test Failed This Key On or Fault Active		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Transmission Control Module (TCM)	P0669	TCM internal temperature (substrate) thermistor failed at a high voltage	Type of Sensor Used	= CeTFTI_e_VoltageDirectPro p				Two Trips
			If TCM Substrate Temperature Sensor = Direct Proportional and Temp	>= 249 ºC				
			If TCM Substrate Temperature Sensor = Indirect Proportional and Temp	<= 249 ºC				
			Either condition above will satisfy the fail conditions				>= 60 Fail Timer (Sec)	
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					P0669 Status is	≠ Test Failed This Key On or Fault Active		
					For Hybrids, below conditions must also be met			
					Estimated Motor Power Loss	>= 0 kW		
					Estimated Motor Power Loss greater than limit for time	>= 0 Sec		
					Lost Communication with Hybrid Processor Control Module	= FALSE		
					Estimated Motor Power Loss Fault	= FALSE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723 ECM: None		
Transmission Control Module (TCM)	P06AC	TCM Power-up Temp Sensor Circuit Range/Performance	If TCM power-up temp to substrate temp Δ	> Refer to Table 20 in supporting documents ℃				Two Trips
			If transmission oil temp to power up temp Δ	> Refer to Table 18 in supporting documents ℃				
			Both conditions above required to increment fail counter Note: table reference temp = to the median temp of trans oil temp, substrate temp and power up temp.				>= 3000 Fail Counts (100ms loop) Out of 3750 Sample Counts (100ms loop)	
			Non-continuous (intermittent) fail conditions will delay resetting fail counter until				>= 700 Pass Counts (100ms loop) Out of 875 Sample Counts (100ms loop)	
					Engine Torque Signal Valid	= TRUE Boolean		
					Accelerator Position Signal Valid	= TRUE Boolean		
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					Brake torque active	= FALSE		
					Below describes the brake torque entry criteria			
					Engine Torque	>= 90 N*m		
					Throttle	>= 30.000305 Pct		
					Transmission Input Speed	<= 200 RPM		
					Vehicle Speed	<= 8 Kph		
					Transmission Range	≠ Park		
					Transmission Range	≠ Neutral		
					PTO	= Not Active		
					Set Brake Torque Active TRUE if above conditions are met for:	>= 7 sec		
					Below describes the brake torque exit criteria			
					Brake torque entry criteria	= Not Met		
					Clutch hydraulic pressure	≠ Clutch Hydraulic Air Purge Event		
					Clutch used to exit brake torque active	= CeTFTD_e_C3_RatlEnbl		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					The above clutch pressure is greater than this value for one loop	>= 600 kpa		
					Set Brake Torque Active FALSE if above conditions are met for:	>= 20 Sec		
					P06AC Status is	≠ Test Failed This Key On or Fault Active		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0658, P0668, P0669, P06AD, P06AE, P0716, P0712, P0713, P0717, P0722, P0723, P0962, P0963, P0966, P0967, P0970, P0971, P215C, P2720, P2721, P2729, P2730 ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Transmission Control Module (TCM)	P06AD	TCM power-up thermistor circuit voltage low	Power Up Temp	<= -59 °C			>= 60 Fail Time (Sec)	Two Trips
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					P06AD Status is	≠ Test Failed This Key On or Fault Active		
					For Hybrids, below conditions must also be met			
					Estimated Motor Power Loss	>= 0 kW		
					Estimated Motor Power Loss greater than limit for time	>= 0 Sec		
					Lost Communication with Hybrid Processor Control Module	= FALSE		
					Estimated Motor Power Loss Fault	= FALSE		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723 ECM: None		
Transmission Control Module (TCM)	P06AE	TCM power-up thermistor circuit voltage high	Power Up Temp	>= 164 °C			>= 60 Fail Time (Sec)	Two Trips
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions			Time Required			Mil Illum.
					Engine Speed Lo	>=	400	RPM				
					Engine Speed Hi	<=	7500	RPM				
					Engine Speed is within the allowable limits for	>=	5	Sec				
					P06AE Status is	≠	Test Failed This Key On or Fault Active					
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None						
Transmission Fluid Temperature Sensor (TFT)	P0711	Trans Fluid Temp Sensor Circuit Range/Performance	If transmission oil temp to substrate temp Δ	> Refer to Table 19 in supporting documents ℃								Two Trips
			If transmission oil temp to power up temp Δ	> Refer to Table 18 in supporting documents ℃								
			Both conditions above required to increment fail counter Note: table reference temp = to the median temp of trans oil temp, substrate temp and power up temp.						>=	3000	Fail Counts (100ms loop)	
									Out of	3750	Sample Counts (100ms loop)	
			Non-continuous (intermittent) fail conditions will delay resetting fail counter until						>=	700	Pass Counts (100ms loop)	
									Out of	875	Sample Counts (100ms loop)	
					Engine Torque Signal Valid	=	TRUE	Boolean				
					Accelerator Position Signal Valid	=	TRUE	Boolean				
					Ignition Voltage Lo	>=	8.5996094	Volts				
					Ignition Voltage Hi	<=	31.999023	Volts				
					Engine Speed Lo	>=	400	RPM				
					Engine Speed Hi	<=	7500	RPM				
					Engine Speed is within the allowable limits for	>=	5	Sec				
					Brake torque active	=	FALSE					
					Below describes the brake torque entry criteria							
					Engine Torque	>=	90	N*m				
					Throttle	>=	30.000305	Pct				
					Transmission Input Speed	<=	200	RPM				
					Vehicle Speed	<=	8	Kph				
					Transmission Range	≠	Park					
					Transmission Range	≠	Neutral					
					PTO	=	Not Active					

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Set Brake Torque Active TRUE if above conditions are met for:	>= 7 sec		
					Below describes the brake torque exit criteria			
					Brake torque entry criteria	= Not Met		
					Clutch hydraulic pressure	≠ Clutch Hydraulic Air Purge Event		
					Clutch used to exit brake torque active	= CeTFTD_e_C3_RatlEnbl		
					The above clutch pressure is greater than this value for one loop	>= 600 kpa		
					Set Brake Torque Active FALSE if above conditions are met for:	>= 20 Sec		
					P0711 Status is	≠ Test Failed This Key On or Fault Active		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0658, P0668, P0669, P06AD, P06AE, P0716, P0712, P0713, P0717, P0722, P0723, P0962, P0963, P0966, P0967, P0970, P0971, P215C, P2720, P2721, P2729, P2730 ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Transmission Fluid Temperature Sensor (TFT)	P0712	Transmission fluid temperature thermistor failed at a low voltage	Type of Sensor Used	= CeTFTI_e_VoltageDirectProp				Two Trips
			If Transmission Fluid Temperature Sensor = Direct Proportional and Temp	<= -74 °C				
			If Transmission Fluid Temperature Sensor = Indirect Proportional and Temp	>= -74 °C				
			Either condition above will satisfy the fail conditions				>= 60 Fail Time (Sec)	
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					P0712 Status is ≠ Test Failed This Key On or Fault Active			
					For Hybrids, below conditions must also be met			
					Estimated Motor Power Loss >= 0 kW			
					Estimated Motor Power Loss greater than limit for time >= 0 Sec			
					Lost Communication with Hybrid Processor Control Module = FALSE			
					Estimated Motor Power Loss Fault = FALSE			
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723 ECM: None		
Transmission Fluid Temperature Sensor (TFT)	P0713	Transmission fluid temperature thermistor failed at a high voltage	Type of Sensor Used	= CeTFTI_e_VoltageDirectProp				Two Trips
			If Transmission Fluid Temperature Sensor = Direct Proportional and Temp	>= 174 °C				
			If Transmission Fluid Temperature Sensor = Indirect Proportional and Temp	<= 174 °C				
			Either condition above will satisfy the fail conditions				>= 60 Fail Time (Sec)	
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					P0713 Status is	≠ Test Failed This Key On or Fault Active		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0713, P0716, P0717, P0722, P0723 ECM: None		
Transmission Input Speed Sensor (TISS)	P0716	Input Speed Sensor Performance	Transmission Input Speed Sensor Drops	>= 900 RPM			>= 0.8 Fail Time (Sec)	One Trip
					Engine Torque is	>= 0 N*m		
					Engine Torque is	<= 8191.875 N*m		
					Engine Speed	>= 400 RPM		
					Engine Speed	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Vehicle Speed is >= 10 Kph Throttle Position is >= 0 Pct --- Transmission Input Speed is >= 0 RPM The previous requirement has been satisfied for >= 0 Sec --- The change (loop to loop) in transmission input speed is < 8191.875 RPM/Loop The previous requirement has been satisfied for >= 0 Sec Throttle Position Signal Valid = TRUE Boolean Engine Torque Signal Valid = TRUE Boolean Ignition Voltage >= 8.5996094 Volts Ignition Voltage <= 31.999023 Volts P0716 Status is not = Test Failed This Key On or Fault Active		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0717, P0752, P0973, P0974 ECM: P0101, P0102, P0103, P0121, P0122, P0123		
Transmission Input Speed Sensor (TISS)	P0717	Input Speed Sensor Circuit Low Voltage	Fail Case 1 Transmission Input Speed is	< 33 RPM			>= 4.5 Fail Time (Sec)	One Trip
			Fail Case 2 When P0722 DTC Status equal to Test Failed and Transmission Input Speed is	< 653.125 RPM	Controller uses a single power supply for the speed sensors = 1 Boolean			
					Engine Torque is >= 80 N*m Engine Torque is <= 8191.875 N*m Vehicle Speed >= 10 Kph Engine Torque Signal Valid = TRUE Boolean Ignition Voltage >= 8.5996094 Volts Ignition Voltage <= 31.999023 Volts Engine Speed >= 400 RPM Engine Speed <= 7500 RPM Engine Speed is within the allowable limits for >= 5 Sec P0717 Status is not = Test Failed This Key On or Fault Active		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0722, P0723 ECM: P0101, P0102, P0103		
Transmission Output Speed Sensor (TOSS)	P0722	Output Speed Sensor Circuit Low Voltage	Transmission Output Speed Sensor Raw Speed	<= 35 RPM			>= 4.5 Fail Time (Sec)	One Trip

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions			Time Required	Mil Illum.
					P0722 Status is not	=	Test Failed This Key On or Fault Active			
					Transmission Input Speed Check	=	TRUE	Boolean		
					Engine Torque Check	=	TRUE	Boolean		
					Throttle Position	>=	8.0001831	Pct		
					Transmission Fluid Temperature	>=	-40	°C		
					Disable this DTC if the PTO is active	=	1	Boolean		
					Engine Torque Signal Valid	=	TRUE	Boolean		
					Throttle Position Signal Valid	=	TRUE	Boolean		
					Ignition Voltage is	>=	8.5996094	Volts		
					Ignition Voltage is	<=	31.999023	Volts		
					Engine Speed is	>=	400	RPM		
					Engine Speed is	<=	7500	RPM		
					Engine Speed is within the allowable limits for	>=	5	Sec		
					Enable_Flags Defined Below					
					The Engine Torque Check is TRUE, if either of the two following conditions are TRUE					
					Engine Torque Condition 1					
					Range Shift Status	≠	Range shift completed	ENUM		
					OR					
					Transmission Range is	=	Park or Neutral			
					Engine Torque is	>=	8191.75	N*m		
					Engine Torque is	<=	8191.75	N*m		
					Engine Torque Condition 2					
					Engine Torque is	>=	50	N*m		
					Engine Torque is	<=	8191.75	N*m		

					The Transmission Input Speed (TIS) Check is TRUE, if either of the two following conditions are TRUE					
					TIS Check Condition 1					
					Transmission Input Speed is	>=	653.125	RPM		
					Transmission Input Speed is	<=	5350	RPM		
					TIS Check Condition 2					
					Engine Speed without the brake applied is	>=	3200	RPM		
					Engine Speed with the brake applied is	>=	3200	RPM		
					Engine Speed is	<=	8191.875	RPM		
					Controller uses a single power supply for the speed sensors	=	1	Boolean		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Powertrain Brake Pedal is Valid	= TRUE Boolean		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0723 ECM: P0101, P0102, P0103, P0121, P0122, P0123		
Transmission Output Speed Sensor (TOSS)	P0723	Output Speed Sensor Circuit Intermittent	Transmission Output Speed Sensor Raw Speed	>= 105 RPM			>= 0 Enable Time (Sec)	One Trip
			Output Speed Delta	<= 8192 RPM			>= 0 Enable Time (Sec)	
			Output Speed Drop	> 650 RPM			>= 1.5 Output Speed Drop Recovery Fail Time (Sec)	
			AND					
			Transmission Range is	= Driven range (R,D)				

					Range_Disable	= FALSE See Below		
					OR			

					Neutral_Range_Enable	= TRUE See Below		
					And			
					Neutral_Speed_Enable	= TRUE See Below		
					are TRUE concurrently			

					Transmission_Range_Enable	= TRUE See Below		
					Transmission_Input_Speed_Enable	= TRUE See Below		
					No Change in Transfer Case Range (High <-> Low) for	>= 5 Seconds		
					P0723 Status is not	= Test Failed This Key On or Fault Active		
					Disable this DTC if the PTO is active	= 1 Boolean		
					Ignition Voltage is	>= 8.5996094 Volts		
					Ignition Voltage is	<= 31.999023 Volts		
					Engine Speed is	>= 400 RPM		
					Engine Speed is	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					Enable_Flags Defined Below			
					Transmission_Input_Speed_Enable is TRUE when either TIS Condition 1 or TIS Condition 2 is TRUE:			
					TIS Condition 1 is TRUE when both of the following conditions are satsified for	>= 0 Enable Time (Sec)		
					Input Speed Delta	<= 4095.875 RPM		
					Raw Input Speed	>= 500 RPM		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions			Time Required	Mil Illum.
					TIS Condition 2 is TRUE when ALL of the next two conditions are satisfied					
					Input Speed	=	0	RPM		
					A Single Power Supply is used for all speed sensors	=	TRUE	Boolean		

					Neutral_Range_Enable is TRUE when any of the next 3 conditions are TRUE					
					Transmission Range is	=	Neutral	ENUM		
					Transmission Range is	=	Reverse/Neutral Transitonal	ENUM		
					Transmission Range is	=	Neutral/Drive Transitional	ENUM		
					And when a drop occurs					
					Loop to Loop Drop of Transmission Output Speed is	>	650	RPM		

					Range_Disable is TRUE when any of the next three conditions are TRUE					
					Transmission Range is	=	Park	ENUM		
					Transmission Range is	=	Park/Reverse Transitonal	ENUM		
					Input Clutch is not	=	ON (Fully Applied)	ENUM		

					Neutral_Speed_Enable is TRUE when All of the next three conditions are satsified for	>	1.5	Seconds		
					Transmission Output Speed	>	130	RPM		
					The loop to loop change of the Transmission Output Speed is	<	20	RPM		
					The loop to loop change of the Transmission Output Speed is	>	-10	RPM		

					Transmission_Range_Enable is TRUE when one of the next six conditions is TRUE					
					Transmission Range is	=	Neutral	ENUM		
					Transmission Range is	=	Reverse/Neutral Transitional	ENUM		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Transmission Range is	= Neutral/Drive Transitional ENUM		
					Time since a driven range (R,D) has been selected	>= Table Based Time Please Refer to Table 21 in supporting documents Sec		
					Transmission Output Speed Sensor Raw Speed	>= 500 RPM		
					Output Speed when a fault was detected	>= 500 RPM		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0973, P0974, P0976, P0977 ECM: P0101, P0102, P0103, P0121, P0122, P0123		
Torque Converter Clutch (TCC)	P0741	TCC System Stuck OFF	TCC Pressure	>= 750 Kpa			>= 2 Enable Time (Sec)	Two Trips
			Either Condition (A) or (B) Must be Met					
			(A) TCC Slip Error @ TCC On Mode	>= Refer to Table 1 in Supporting Documents RPM			>= 5 Fail Time (Sec)	
			(B) TCC Slip @ Lock On Mode	>= 130 RPM			>= 5 Fail Time (Sec)	
			If Above Conditions Have been Met, and Fail Timer Expired, Increment Fail Counter				>= 2 TCC Stuck Off Fail Counter	
					TCC Mode	= On or Lock		
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed	>= 400 RPM		
					Engine Speed	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					Engine Torque Lo	>= 50 N*m		
					Engine Torque Hi	<= 8191.875 N*m		
					Throttle Position Lo	>= 8.0001831 Pct		
					Throttle Position Hi	<= 99.998474 Pct		
					2nd Gear Ratio Lo	>= 2.1948242 Ratio		
					2nd Gear Ratio High	<= 2.5251465 Ratio		
					3rd Gear Ratio Lo	>= 1.4228516 Ratio		
					3rd Gear Ratio High	<= 1.637085 Ratio		
					4th Gear Ratio Lo	>= 1.069458 Ratio		
					4th Gear Ratio High	<= 1.2304688 Ratio		
					5th Gear Ratio Lo	>= 0.7905273 Ratio		
					5th Gear Ratio Hi	<= 0.9095459 Ratio		
					6th Gear Ratio Lo	>= 0.6230469 Ratio		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					6th Gear Ratio High	<= 0.7169189 Ratio		
					Transmission Fluid Temperature Lo	>= -6.65625 °C		
					Transmission Fluid Temperature Hi	<= 130 °C		
					PTO Not Active	= TRUE Boolean		
					Engine Torque Signal Valid	= TRUE Boolean		
					Throttle Position Signal Valid	= TRUE Boolean		
					Dynamic Mode	= FALSE Boolean		
					P0741 Status is	≠ Test Failed This Key On or Fault Active		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P0742, P2763, P2764 ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Torque Converter Clutch (TCC)	P0742	TCC System Stuck ON	TCC Slip Speed	>= -50 RPM				One Trip
			TCC Slip Speed	<= 13 RPM				
			If Above Conditions Have been Met, and Fail Timer Expired, Increment Fail Counter				>= 1.5 Fail Time (Sec) >= 6 Fail Counter	
					TCC Mode	= Off		
					Enable test if Cmnd Gear = 1stFW and value true	= 1 Boolean		
					Enable test if Cmnd Gear = 2nd and value true	= 0 Boolean		
					Engine Speed Hi	<= 6000 RPM		
					Engine Speed Lo	>= 500 RPM		
					Vehicle Speed HI	<= 511 KPH		
					Vehicle Speed Lo	>= 1 KPH		
					Engine Torque Hi	<= 8191.875 Nm		
					Engine Torque Lo	>= 80 Nm		
					Current Range	≠ Neutral Range		
					Current Range	≠ Reverse Range		
					Transmission Sump Temperature	<= 130 °C		
					Transmission Sump Temperature	>= 18 °C		
					Throttle Position Hyst High AND	>= 5.0003052 Pct		
					Max Vehicle Speed to Meet Throttle Enable	<= 8 KPH		
					Once Hyst High has been met, the enable will remain while Throttle Position	>= 2.0004272 Pct		
					Disable for Throttle Position	>= 75 Pct		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions			Time Required			Mil Illum.
					Disable if PTO active and value true	=	1	Boolean				
					Disable if in D1 and value true	=	1	Boolean				
					Disable if in D2 and value true	=	1	Boolean				
					Disable if in D3 and value true	=	1	Boolean				
					Disable if in D4 and value true	=	1	Boolean				
					Disable if in D5 and value true	=	1	Boolean				
					Disable if in MUMD and value true	=	1	Boolean				
					Disable if in TUTD and value true	=	1	Boolean				
					4 Wheel Drive Low Active	=	FALSE	Boolean				
					Disable if Air Purge active and value false	=	0	Boolean				
					RVT Diagnostic Active	=	FALSE	Boolean				
					Ignition Voltage	>=	8.5996094	V				
					Ignition Voltage	<=	31.999023	V				
					Vehicle Speed	<=	511	KPH				
					Engine Speed	>=	400	RPM				
					Engine Speed	<=	7500	RPM				
					Engine Speed is within the allowable limits for	>=	5	Sec				
					Engine Torque Signal Valid	=	TRUE	Boolean				
					Throttle Position Signal Valid	=	TRUE	Boolean				
					P0742 Status is	≠	Test Failed This Key On or Fault Active					
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P0741, P2763, P2764 ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E						
Mode 2 Multiplex Valve	P0751	Shift Solenoid Valve A Stuck Off	Commaned Gear Slip	>= 400 RPM								Two Trips
			Commanded Gear	= 1st Lock rpm								
			Gear Ratio	<= 1.209594727					>=	0.2	Fail Tmr	
			Gear Ratio	>= 1.094360352					=	5	Fail Counts	
			If the above parameters are true						≠	0	Neutral Timer (Sec)	
									>=	0.3	Fail Timer (Sec)	
									>=	8	Counts	
					Ignition Voltage Lo	>=	8.5996094	Volts				
					Ignition Voltage Hi	<=	31.999023	Volts				
					Engine Speed Lo	>=	400	RPM				
					Engine Speed Hi	<=	7500	RPM				
					Engine Speed is within the allowable limits for	>=	5	Sec				
					Transmission Fluid Temperature	>=	-6.65625	°C				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Range Shift State = Range Shift Completed ENUM			
					TPS >= 0.5004883 % OR Output Speed >= 67 RPM			
					Throttle Position Signal Valid from ECM = TRUE Boolean			
					Engine Torque Signal Valid from ECM, High side driver is enabled = TRUE Boolean			
					High-Side Driver is Enabled = TRUE Boolean			
					Input Speed Sensor fault = FALSE Boolean			
					Output Speed Sensor fault = FALSE Boolean			
					Default Gear Option is not present = TRUE			
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Mode 2 Multiplex Valve	P0752	Shift Solenoid Valve A Stuck On	Gear Box Slip >= 400 RPM Commanded Gear = 3rd Gear Commanded Gear has Achieved 1st Locked OR 1st Free-Wheel OR 2nd with Mode 2 Sol. Commanded On = TRUE Boolean If the above parameters are true Command 4th Gear once Output Shaft Speed <= 400 RPM If Gear Ratio >= 3.825683594 And Gear Ratio <= 4.228393555				>= Please Refer to Table 16 in Supporting Documents Neutral Timer (Sec) >= 1.5 Fail Timer (Sec) >= 5 Counts	One Trip
					Ignition Voltage Lo >= 8.5996094 Volts Ignition Voltage Hi <= 31.999023 Volts Engine Speed Lo >= 400 RPM Engine Speed Hi <= 7500 RPM Engine Speed is within the allowable limits for >= 5 Sec High-Side Driver is Enabled = TRUE Boolean Throttle Position Signal Valid from ECM = TRUE Boolean Output Speed >= 67 RPM			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					OR TPS >= 0.5004883 %			
					Range Shift State = Range Shift Completed ENUM			
					Transmission Fluid Temperature >= -6.65625 °C			
					Input Speed Sensor fault = FALSE Boolean			
					Output Speed Sensor fault = FALSE Boolean			
					Default Gear Option is not present = TRUE			
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Mode 2 Multiplex Valve	P0756	Shift Solenoid Valve B Stuck Off	Fail Case 1 Commanded Gear = 1st Locked Gear Box Slip >= 400 RPM Intrusive Shift to 2nd Commanded Gear Previous = 1st Locked Gear Gear Ratio <= 2.482177734 Gear Ratio >= 2.245849609 If the above parameters are true				>= Please Refer to Table 5 in Supporting Documents Neutral Timer (Sec) >= 1 sec >= 3 counts	One Trip
					Ignition Voltage Lo >= 8.5996094 Volts Ignition Voltage Hi <= 31.999023 Volts Engine Speed Lo >= 400 RPM Engine Speed Hi <= 7500 RPM Engine Speed is within the allowable limits for >= 5 Sec Output Speed >= 67 RPM OR TPS >= 0.5004883 % Range Shift State = Range Shift Completed ENUM Transmission Fluid Temperature >= -6.65625 °C High-Side Driver is Enabled = TRUE Boolean Throttle Position Signal Valid from ECM = TRUE Boolean Input Speed Sensor fault = FALSE Boolean Output Speed Sensor fault = FALSE Boolean Default Gear Option is not present = TRUE			

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Variable Bleed Solenoid (VBS)	P0776	Pressure Control (PC) Solenoid B Stuck Off [C35R]	Fail Case 1 Case: Steady State 3rd Gear Commanded Gear Gearbox Slip Command 4th Gear once Output Shaft Speed If Gear Ratio And Gear Ratio It the above condiations are true, Increment 3rd gear fail counter and C35R Fail counter	= 3rd Gear >= 400 RPM <= 400 RPM >= 1.094360352 <= 1.209594727			>= Please Refer to Table 16 in Supporting Documents Neutral Timer (Sec) >= 3 Fail Timer (Sec) >= 3 3rd Gear Fail Counts or >= 14 3-5R Clutch Fail Counts	One Trip
			Fail Case 2 Case: Steady State 5th Gear Commanded Gear Gearbox Slip Intrusive Test: Command 6th Gear If attained Gear=6th gear Time It the above condiations are true, Increment 5th gear fail counter and C35R Fail counter	= 5th Gear >= 400 Rpm >= Please refer to Table 3 in supporting documents Shift Time (Sec)			>= Please Refer to Table 5 in Supporting Documents Neutral Timer (Sec) >= 3 5th Gear Fail Counts or >= 14 3-5R Clutch Fail Counts	
					PRNDL State defaulted = FALSE Boolean inhibit RVT = FALSE Boolean IMS fault pending indication = FALSE Boolean TPS validity flag = TRUE Boolean Hydraulic System Pressurized = TRUE Boolean Minimum output speed for RVT >= 67 RPM A OR B (A) Output speed enable >= 67 RPM (B) Accelerator Pedal enable >= 0.5004883 Pct		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Common Enable Criteria			
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					Throttle Position Signal valid	= TRUE Boolean		
					HSD Enabled	= TRUE Boolean		
					Transmission Fluid Temperature	>= -6.65625 ºC		
					Input Speed Sensor fault	= FALSE Boolean		
					Output Speed Sensor fault	= FALSE Boolean		
					Default Gear Option is not present	= TRUE		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Variable Bleed Solenoid (VBS)	P0777	Pressure Control (PC) Solinoid B Stuck On [C35R] (Steady State)	Fail Case 1 Case: Steady State 1st					One Trip
			Attained Gear slip	>= 400 RPM				
			If the Above is True for Time	>= Table Based Time Please Refer to Table 4 in supporting documents Enable Time (Sec)				
			Intrusive test: (CBR1 clutch exhausted)					
			Gear Ratio	<= 1.608642578				
			Gear Ratio	>= 1.455444336				
			If the above parameters are true				>= 1.1 Fail Timer (Sec) >= 2 Fail Count in 1st Gear or >= 3 Total Fail Counts	
			Fail Case 2 Case: Steady State 2nd gear					
			Max Delta Output Speed Hysteresis	>= Table Based value Please Refer to Table 22 in supporting documents rpm/sec				
			Min Delta Output Speed Hysteresis	>= Table Based value Please Refer to Table 23 in supporting documents rpm/sec				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Table Based Time Please Refer to Table 17 in supporting documents Sec				
			If the Above is True for Time	>=				
			Intrusive test: (CB26 clutch exhausted)					
			Gear Ratio	<= 1.608642578				
			Gear Ratio	>= 1.455444336				
			If the above parameters are true				>= 1.1 Fail Timer (Sec) >= 3 Fail Count in 2nd Gear or >= 3 Total Fail Counts	
			Fail Case 3 Case: Steady State 4th gear					
			Max Delta Output Speed Hysteresis	>= Table Based value Please Refer to Table 22 in supporting documents rpm/sec				
			Min Delta Output Speed Hysteresis	>= Table Based value Please Refer to Table 23 in supporting documents rpm/sec				
			If the Above is True for Time	>= Table Based Time Please Refer to Table 17 in supporting documents Sec				
			Intrusive test: (C1234 clutch exhausted)					
			Gear Ratio	<= 0.89465332				
			Gear Ratio	>= 0.809448242				
			If the above parameters are true				>= 1.1 Fail Timer (Sec) >= 3 Fail Count in 4th Gear or >= 3 Total Fail Counts	
			Fail Case 4 Case: Steady State 6th gear					
			Max Delta Output Speed Hysteresis	>= Table Based value Please Refer to Table 22 in supporting documents rpm/sec				
			Min Delta Output Speed Hysteresis	>= Table Based value Please Refer to Table 23 in supporting documents rpm/sec				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			If the Above is True for Time	>= Table Based Time Please Refer to Table 17 in supporting documents Sec				
			Intrusive test: (CB26 clutch exhausted)					
			Gear Ratio	<= 0.89465332			>= 1.1 Fail Timer (Sec)	
			Gear Ratio	>= 0.809448242			>= 3 counts	
			If the above parameters are true				>= 1.1 Fail Timer (Sec)	
							>= 3 Fail Count in 6th Gear or	
							>= 3 Total Fail Counts	
					PRNDL State defaulted	= FALSE Boolean		
					inhibit RVT	= FALSE Boolean		
					IMS fault pending indication	= FALSE Boolean		
					output speed	>= 0 RPM		
					TPS validity flag	= TRUE Boolean		
					HSD Enabled	= TRUE Boolean		
					Hydraulic_System_Pressurized	= TRUE Boolean		
					A OR B			
					(A) Output speed enable	>= 67 Nm		
					(B) Accelerator Pedal enable	>= 0.5004883 Nm		
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					if Attained Gear=1st FW Accelerator Pedal enable	>= 5.0003052 Pct		
					if Attained Gear=1st FW Engine Torque Enable	>= 5 Nm		
					if Attained Gear=1st FW Engine Torque Enable	<= 8191.875 Nm		
					Transmission Fluid Temperature	>= -6.65625 °C		
					Input Speed Sensor fault	= FALSE Boolean		
					Output Speed Sensor fault	= FALSE Boolean		
			Disable Conditions:		**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value			Secondary Malfunction	Enable Conditions	Time Required		Mil Illum.
											One Trip
Variable Bleed Solenoid (VBS)	P0777	Pressure Control (PC) Solenoid B StuckOn [C35R] (Dymanic)	Primary Offgoing Clutch is exhausted (See Table 12 in Supporting Documents for Exhaust Delay Timers)	=	TRUE	Boolean					
			Primary Oncoming Clutch Pressure Command Status	=	Maximum pressurized Clutch						
			Primary Offgoing Clutch Pressure Command Status	=	exhaust command						
			Range Shift Status	≠	Initial Clutch Control						
			Attained Gear Slip	<=	40	RPM					
			If the above conditions are true run appropriate Fail 1 Timers Below:								
			fail timer 1 (3-1 shifting with Closed Throttle)	>=	0.5	Fail Time (Sec)					
			fail timer 1 (3-2 shifting with Throttle)	>=	0.299804688	Fail Time (Sec)					
			fail timer 1 (3-2 shifting with Closed Throttle)	>=	0.5	Fail Time (Sec)					
			fail timer 1 (3-4 shifting with Throttle)	>=	0.299804688	Fail Time (Sec)					
			fail timer 1 (3-4shifting with Closed Throttle)	>=	0.5	Fail Time (Sec)					
			fail timer 1 (3-5 shifting with Throttle)	>=	0.299804688	Fail Time (Sec)					
			fail timer 1 (3-5 shifting with Closed Throttle)	>=	0.5	Fail Time (Sec)					
			fail timer 1 (5-3 shifting with Throttle)	>=	0.299804688	Fail Time (Sec)					
			fail timer 1 (5-3 shifting with Closed Throttle)	>=	0.5	Fail Time (Sec)					
			fail timer 1 (5-4 shifting with Throttle)	>=	0.299804688	Fail Time (Sec)					
			fail timer 1 (5-4 shifting with Closed Throttle)	>=	0.5	Fail Time (Sec)					
			fail timer 1 (5-6 shifting with Throttle)	>=	0.299804688	Fail Time (Sec)					
			fail timer 1 (5-6 shifting with Closed Throttle)	>=	0.5	Fail Time (Sec)					
			If Attained Gear Slip is Less than Above Cal Increment Fail Timers						>=	Total Fail Time = (Fail 1 + Fail 2) See Enable Timers for Fail Timer 1, and Reference Supporting Table 15 for Fail Timer 2	sec	
			If fail timer is greater than threshold increment corresponding gear fail counter and total fail counter								
			3rd gear fail counter						>=	3	3rd gear fail counts	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			5th gear fail counter				>= 3 OR 5th gear fail counts	
			Total fail counter				>= 5 OR total fail counts	
					TUT Enable temperature	>= -6.65625 °C		
					Input Speed Sensor fault	= FALSE Boolean		
					Output Speed Sensor fault	= FALSE Boolean		
					Command / Attained Gear	≠ 1st Boolean		
					High Side Driver ON	= TRUE Boolean		
					output speed limit for TUT	>= 100 RPM		
					input speed limit for TUT	>= 150 RPM		
					PRNDL state defaulted	= FALSE Boolean		
					IMS Fault Pending	= FALSE Boolean		
					Service Fast Learn Mode	= FALSE Boolean		
					HSD Enabled	= TRUE Boolean		
					Default Gear Option is not present	= TRUE		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Variable Bleed Solenoid (VBS)	P0796	Pressure Control (PC) Solenoid C Stuck Off [C456] (Steady State)	Fail Case 1 Case: Steady State 4th Gear					One Trip
			Gear slip	>= 400 RPM			>= Please See Table 5 For Neutral Time Cal Neutral Timer (Sec)	
			Intrusive test: commanded 5th gear					
			If attained Gear ≠5th for time	>= Please refer to Table 3 in Supporting Documents Shift Time (Sec)				
			if the above conditions have been met					
			Increment 4th Gear Fail Counter				>= 3 4th Gear Fail Count OR	
			and C456 Fail Counters				>= 14 C456 Fail Counts	
			Fail Case 2 Case: Steady State 5th Gear					
			Gear slip	>= 400 RPM			>= Please See Table 5 For Neutral Time Cal Neutral Timer (Sec)	
			Intrusive test: commanded 6th gear					

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			If attained Gear ≠ 6th for time	>= Please Refer to Table 3 in Supporting Documents Shift Time (Sec)				
			if the above conditions have been met					
			Increment 5th Gear Fail Counter				>= 3 5th Gear Fail Count	
			and C456 Fail Counters				OR >= 14 C456 Fail Counts	
			Fail Case 3 Case: Steady State 6th Gear					
			Gear slip	>= 400 RPM			>= Please See Table 5 For Neutral Time Cal Neutral Timer (Sec)	
			Intrusive test: commanded 5th gear					
			If attained Gear ≠ 5th for time	>= Please refer to Table 3 in Supporting Documents Shift Time (Sec)				
			if the above conditions have been met					
			Increment 6th Gear Fail Counter and C456 Fail Counter				>= 3 6th Gear Fail Count	
			and C456 Fail Counter				OR >= 14 C456 Fail Counts	
					PRNDL State defaulted	= FALSE Boolean		
					inhibit RVT	= FALSE Boolean		
					IMS fault pending indication	= FALSE Boolean		
					TPS validity flag	= TRUE Boolean		
					Hydraulic System Pressurized	= TRUE Boolean		
					Minimum output speed for RVT	>= 67 RPM		
					A OR B			
					(A) Output speed enable	>= 67 RPM		
					(B) Accelerator Pedal enable	>= 0.5004883 Pct		
					Common Enable Criteria			
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					Throttle Position Signal valid	= TRUE Boolean		
					HSD Enabled	= TRUE Boolean		
					Transmission Fluid Temperature	>= -6.65625 °C		
					Input Speed Sensor fault	= FALSE Boolean		
					OutputSpeed Sensor fault	= FALSE Boolean		
					Default Gear Option is not present	= TRUE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Variable Bleed Solenoid (VBS)	P0797	Pressure Control (PC) Solenoid C Stuck On [C456] (Steady State)	Fail Case 1 Case: Steady State 1st Attained Gear slip If the Above is True for Time Intrusive test: (CBR1 clutch exhausted) Gear Ratio Gear Ratio If the above parameters are true	 >= 400 RPM >= Table Based Time Please Refer to Table 4 in supporting documents Enable Time (Sec) <= 1.209594727 >= 1.094360352			>= 1.1 Fail Timer (Sec) >= 2 Fail Count in 1st Gear or >= 3 Total Fail Counts	One Trip
			Fail Case 2 Case Steady State 2nd Max Delta Output Speed Hysteresis Min Delta Output Speed Hysteresis If the Above is True for Time Intrusive test: (CB26 clutch exhausted) Gear Ratio Gear Ratio If the above parameters are true	 >= Table Based value Please Refer to Table 22 in supporting documents rpm/sec >= Table Based value Please Refer to Table 23 in supporting documents rpm/sec >= Table Based Time Please Refer to Table 17 in supporting documents Sec <= 1.209594727 >= 1.094360352			>= 1.1 Fail Timer (Sec) >= 3 Fail Count in 2nd Gear or >= 3 Total fail counts	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			Fail Case 3 Case Steady State 3rd					
			Max Delta Output Speed Hysteresis	>= Table Based value Please Refer to Table 22 in supporting documents rpm/sec				
			Min Delta Output Speed Hysteresis	>= Table Based value Please Refer to Table 23 in supporting documents rpm/sec				
			If the Above is True for Time	>= Table Based Time Please Refer to Table 17 in supporting documents Sec				
			Intrusive test: (C35R clutch exhausted)					
			Gear Ratio	<= 1.209594727				
			Gear Ratio	>= 1.094360352				
			If the above parameters are true				>= 1.1 Fail Timer (Sec) >= 3 Fail Count in 3rd Gear OR >= 3 Total Fail Counts	
					PRNDL State defaulted	= FALSE Boolean		
					inhibit RVT	= FALSE Boolean		
					IMS fault pending indication	= FALSE Boolean		
					output speed	>= 0 RPM		
					TPS validity flag	= TRUE Boolean		
					HSD Enabled	= TRUE Boolean		
					Hydraulic_System_Pressurized	= TRUE Boolean		
					A OR B			
					(A) Output speed enable	>= 67 Nm		
					(B) Accelerator Pedal enable	>= 0.5004883 Nm		
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					if Attained Gear=1st FW Accelerator Pedal enable	>= 5.0003052 Pct		
					if Attained Gear=1st FW Engine Torque Enable	>= 5 Nm		
					if Attained Gear=1st FW Engine Torque Enable	<= 8191.875 Nm		
					Transmission Fluid Temperature	>= -6.65625 °C		
					Input Speed Sensor fault	= FALSE Boolean		
					Output Speed Sensor fault	= FALSE Boolean		
					Default Gear Option is not present	= TRUE		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Variable Bleed Solenoid (VBS)	P0797	Pressure Control (PC) Solenoid C Stuck On [C456] (Dynamic)	Primary Offgoing Clutch is exhausted (See Table 11 in Supporting Documents for Exhaust Delay Timers)	= TRUE Boolean				One Trip
			Primary Oncoming Clutch Pressure Command Status	= Maximum pressurized Clutch				
			Primary Offgoing Clutch Pressure Command Status	= exhaust command				
			Range Shift Status	≠ Initial Clutch Control				
			Attained Gear Slip	<= 40 RPM				
			If the above conditions are true increment appropriate Fail 1 Timers Below:					
			fail timer 1 (4-1 shifting with throttle)	>= 0.299804688 Fail Time (Sec)				
			fail timer 1 (4-1 shifting without throttle)	>= 0.5 Fail Time (Sec)				
			fail timer 1 (4-2 shifting with throttle)	>= 0.299804688 Fail Time (Sec)				
			fail timer 1 (4-2 shifting without throttle)	>= 0.5 Fail Time (Sec)				
			fail timer 1 (4-3 shifting with throttle)	>= 0.299804688 Fail Time (Sec)				
			fail timer 1 (4-3 shifting without throttle)	>= 0.5 Fail Time (Sec)				
			fail timer 1 (5-3 shifting with throttle)	>= 0.299804688 Fail Time (Sec)				
			fail timer 1 (5-3 shifting without throttle)	>= 0.5 Fail Time (Sec)				
			fail timer 1 (6-2 shifting with throttle)	>= 0.299804688 Fail Time (Sec)				
			fail timer 1 (6-2 shifting without throttle)	>= 0.5 Fail Time (Sec)				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			If Attained Gear Slip is Less than Above Cal Increment Fail Timers				>= Total Fail Time = (Fail 1 + Fail 2) See Enable Timers for Fail Timer 1, and Reference Supporting Table 15 for Fail Timer 2 sec	
			If fail timer is greater than threshold increment corresponding gear fail counter and total fail counter					
			4th gear fail counter				>= 3 Fail Counter From 4th Gear OR	
			5th gear fail counter				>= 3 Fail Counter From 5th Gear OR	
			6th gear fail counter				>= 3 Fail Counter From 6th Gear OR	
			Total fail counter				>= 5 Total Fail Counter	
					TUT Enable temperature	>= -6.65625 °C		
					Input Speed Sensor fault	= FALSE Boolean		
					Output Speed Sensor fault	= FALSE Boolean		
					Command / Attained Gear	≠ 1st Boolean		
					High Side Driver ON	= TRUE Boolean		
					output speed limit for TUT	>= 100 RPM		
					input speed limit for TUT	>= 150 RPM		
					PRNDL state defaulted	= FALSE Boolean		
					IMS Fault Pending	= FALSE Boolean		
					Service Fast Learn Mode	= FALSE Boolean		
					HSD Enabled	= TRUE Boolean		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Tap Up Tap Down Switch (TUTD)	P0815	Upshift Switch Circuit	Fail Case 1 Tap Up Switch Stuck in the Up Position in Range 1 Enabled	= 0 Boolean				Special No MIL
			Tap Up Switch Stuck in the Up Position in Range 2 Enabled	= 0 Boolean				
			Tap Up Switch Stuck in the Up Position in Range 3 Enabled	= 0 Boolean				
			Tap Up Switch Stuck in the Up Position in Range 4 Enabled	= 0 Boolean				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria		Threshold Value		Secondary Malfunction	Enable Conditions			Time Required			Mil Illum.
			Tap Up Switch Stuck in the Up Position in Range 5 Enabled	=	0	Boolean								
			Tap Up Switch Stuck in the Up Position in Range 6 Enabled	=	0	Boolean								
			Tap Up Switch Stuck in the Up Position in Neutral Enabled	=	1	Boolean								
			Tap Up Switch Stuck in the Up Position in Park Enabled	=	1	Boolean								
			Tap Up Switch Stuck in the Up Position in Reverse Enabled	=	0	Boolean								
			Tap Up Switch ON	=	TRUE	Boolean					>=	1	Fail Time (Sec)	
			Fail Case 2 Tap Up Switch Stuck in the Up Position in Range 1 Enabled	=	1	Boolean								
			Tap Up Switch Stuck in the Up Position in Range 2 Enabled	=	1	Boolean								
			Tap Up Switch Stuck in the Up Position in Range 3 Enabled	=	1	Boolean								
			Tap Up Switch Stuck in the Up Position in Range 4 Enabled	=	1	Boolean								
			Tap Up Switch Stuck in the Up Position in Range 5 Enabled	=	1	Boolean								
			Tap Up Switch Stuck in the Up Position in Range 6 Enabled	=	1	Boolean								
			Tap Up Switch Stuck in the Up Position in Neutral Enabled	=	0	Boolean								
			Tap Up Switch Stuck in the Up Position in Park Enabled	=	0	Boolean								
			Tap Up Switch Stuck in the Up Position in Reverse Enabled	=	0	Boolean								
			Tap Up Switch ON	=	TRUE	Boolean								
			NOTE: Both Failcase1 and Failcase 2 Must Be Met								>=	600	Fail Time (Sec)	
							Time Since Last Range Change	>=	1	Enable Time (Sec)				
							Ignition Voltage Lo	>=	8.5996094	Volts				
							Ignition Voltage Hi	<=	31.999023	Volts				
							Engine Speed Lo	>=	400	RPM				
							Engine Speed Hi	<=	7500	RPM				
							Engine Speed is within the allowable limits for	>=	5	Sec				
							P0815 Status is	≠	Test Failed This Key On or Fault Active					

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0816, P0826, P182E, P1876, P1877, P1915, P1761 ECM: None		
Tap Up Tap Down Switch (TUTD)	P0816	Downshift Switch Circuit	Fail Case 1					Special No MIL
			Tap Down Switch Stuck in the Down Position in Range 1 Enabled	= 0 Boolean				
			Tap Down Switch Stuck in the Down Position in Range 2 Enabled	= 0 Boolean				
			Tap Down Switch Stuck in the Down Position in Range 3 Enabled	= 0 Boolean				
			Tap Down Switch Stuck in the Down Position in Range 4 Enabled	= 0 Boolean				
			Tap Down Switch Stuck in the Down Position in Range 5 Enabled	= 0 Boolean				
			Tap Down Switch Stuck in the Down Position in Range 6 Enabled	= 0 Boolean				
			Tap Down Switch Stuck in the Down Position in Range Neutral Enabled	= 1 Boolean				
			Tap Down Switch Stuck in the Down Position in Range Park Enabled	= 1 Boolean				
			Tap Down Switch Stuck in the Down Position in Range Reverse Enabled	= 0 Boolean				
			Tap Down Switch ON	= TRUE Boolean			>= 1 sec	
			Fail Case 2					
			Tap Down Switch Stuck in the Down Position in Range 1 Enabled	= 1 Boolean				
			Tap Down Switch Stuck in the Down Position in Range 2 Enabled	= 1 Boolean				
			Tap Down Switch Stuck in the Down Position in Range 3 Enabled	= 1 Boolean				
			Tap Down Switch Stuck in the Down Position in Range 4 Enabled	= 1 Boolean				
			Tap Down Switch Stuck in the Down Position in Range 5 Enabled	= 1 Boolean				
			Tap Down Switch Stuck in the Down Position in Range 6 Enabled	= 1 Boolean				
			Tap Down Switch Stuck in the Down Position in Neutral Enabled	= 0 Boolean				
			Tap Down Switch Stuck in the Down Position in Park Enabled	= 0 Boolean				
			Tap Down Switch Stuck in the Down Position in Reverse Enabled	= 0 Boolean				
			Tap Down Switch ON	= TRUE Boolean				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			NOTE: Both Failcase1 and Failcase 2 Must Be Met				>= 600 sec	
					Time Since Last Range Change	>= 1 Enable Time (Sec)		
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					P0816 Status is	≠ Test Failed This Key On or Fault Active		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0815, P0826, P182E, P1876, P1877, P1915, P1761 ECM: None		
Tap Up Tap Down Switch (TUTD)	P0826	Up and Down Shift Switch Circuit	TUTD Circuit Reads Invalid Voltage	= TRUE Boolean			>= 60 Fail Time (Sec)	Special No MIL
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					P0826 Status is	≠ Test Failed This Key On or Fault Active		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P1761 ECM: None		
Variable Bleed Solenoid (VBS)	P0961	Pressure Control (PC) Solenoid A Control Circuit Rationality Test (Line Pressure VBS)	The HWIO reports an invalid voltage (out of range) error flag	= TRUE Boolean			>= 4.4 Fail Time (Sec) out of 5 Sample Time (Sec)	Two Trips
					Ignition Voltage	>= 8.5996094 Volts		
					Ignition Voltage	<= 31.999023 Volts		
					Engine Speed	>= 400 RPM		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Engine Speed	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Variable Bleed Solenoid (VBS)	P0962	Pressure Control (PC) Solenoid A Control Circuit Low Voltage (Line Pressure VBS)	The HWIO reports a low voltage (ground short) error flag	= TRUE Boolean			>= 1.5 Fail Time (Sec) out of 1.875 Sample Time (Sec)	One Trip
					Ignition Voltage	>= 8.5996094 Volts		
					Ignition Voltage	<= 31.999023 Volts		
					Engine Speed	>= 400 RPM		
					Engine Speed	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Variable Bleed Solenoid (VBS)	P0963	Pressure Control (PC) Solenoid A Control Circuit High Voltage (Line Pressure VBS)	The HWIO reports a high voltage (open or power short) error flag	= TRUE Boolean			>= 4.4 Fail Time (Sec) out of 5 Sample Time (Sec)	Two Trips
					Ignition Voltage	>= 8.5996094 Volts		
					Ignition Voltage	<= 31.999023 Volts		
					Engine Speed	>= 400 RPM		
					Engine Speed	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Variable Bleed Solenoid (VBS)	P0966	Pressure Control (PC) Solenoid B Control Circuit Low Voltage (C35R VBS)	The HWIO reports a low voltage (ground short) error flag	= TRUE Boolean			>= 0.3 Fail Time (Sec) out of 0.375 Sample Time (Sec)	One Trip
					Ignition Voltage	>= 8.5996094 Volts		
					Ignition Voltage	<= 31.999023 Volts		
					Engine Speed	>= 400 RPM		
					Engine Speed	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					P0966 Status is not = Test Failed This Key On or Fault Active			
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Variable Bleed Solenoid (VBS)	P0967	Pressure Control (PC) Solenoid B Control Circuit High Voltage (C35R VBS)	The HWIO reports a high voltage (open or power short) error flag	= TRUE Boolean			>= 0.3 Fail Time (Sec) out of 0.375 Sample Time (Sec)	One Trip
					Ignition Voltage >= 8.5996094 Volts Ignition Voltage <= 31.999023 Volts Engine Speed >= 400 RPM Engine Speed <= 7500 RPM Engine Speed is within the allowable limits for >= 5 Sec P0967 Status is not = Test Failed This Key On or Fault Active			
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Variable Bleed Solenoid (VBS)	P0970	Pressure Control (PC) Solenoid C Control Circuit Low Voltage (C456/CBR1 VBS)	The HWIO reports a low voltage (ground short) error flag	= TRUE Boolean			>= 0.3 Fail Time (Sec) out of 0.375 Sample Time (Sec)	One Trip
					P0970 Status is not = Test Failed This Key On or Fault Active Ignition Voltage >= 8.5996094 Volts Ignition Voltage <= 31.999023 Volts Engine Speed >= 400 RPM Engine Speed <= 7500 RPM Engine Speed is within the allowable limits for >= 5 Sec			
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Variable Bleed Solenoid (VBS)	P0971	Pressure Control (PC) Solenoid C Control Circuit High Voltage (C456/CBR1 VBS)	The HWIO reports a high voltage (open or power short) error flag	= TRUE Boolean			>= 0.3 Fail Time (Sec)	One Trip

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
							out of 0.375 Sample Time (Sec)	
					P0971 Status is not	= Test Failed This Key On or Fault Active		
					Ignition Voltage	>= 8.5996094 Volts		
					Ignition Voltage	<= 31.999023 Volts		
					Engine Speed	>= 400 RPM		
					Engine Speed	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Shift Solinoid	P0973	Shift Solenoid A Control Circuit Low (Mode 2 Solenoid)	The HWIO reports a low voltage (ground short) error flag	= TRUE Boolean			>= 1.2 Fail Time (Sec) out of 1.5 Sample Time (Sec)	One Trip
					P0973 Status is not	= Test Failed This Key On or Fault Active		
					Ignition Voltage	>= 8.5996094 Volts		
					Ignition Voltage	<= 31.999023 Volts		
					Engine Speed	>= 400 RPM		
					Engine Speed	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Shift Solinoid	P0974	Shift Solenoid A Control Circuit High (Mode 2 Solenoid)	The HWIO reports a high voltage (open or power short) error flag	= TRUE Boolean			>= 1.2 Fail Time (Sec) out of 1.5 Sample Time (Sec)	Two Trips
					P0974 Status is not	= Test Failed This Key On or Fault Active		
					Ignition Voltage	>= 8.5996094 Volts		
					Ignition Voltage	<= 31.999023 Volts		
					Engine Speed	>= 400 RPM		
					Engine Speed	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Mode 3 Multiplex Valve	P0977	Shift Solenoid B Control Circuit High (Mode 3 Solenoid)	The HWIO reports a high voltage (open or power short) error flag	= TRUE Boolean			>= 1.2 Sec out of 1.5 Sec	One Trip
					P0977 Status is not	= Test Failed This Key On or Fault Active		
					Ignition Voltage	>= 8.5996094 Volts		
					Ignition Voltage	<= 31.999023 Volts		
					Engine Speed	>= 400 RPM		
					Engine Speed	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Tap Up Tap Down Switch (TUTD)	P1761	Tap Up and Down switch signal circuit (rolling count)	Rolling count value received from BCM does not match expected value	= TRUE Boolean			>= 3 Fail Counter > 10 Sample Timer (Sec)	Special No MIL
					Tap Up Tap Down Message Health	= TRUE Boolean		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Internal Mode Switch (IMS)	P182E	Internal Mode Switch - Invalid Range	Fail Case 1 Current range	= Transition 1 (bit state 1110) Range				One Trip
			Previous range	≠ CeTRGR_e_PRNDL_Drive6 Range				
			Previous range	≠ CeTRGR_e_PRNDL_Drive5 Range				
			Range Shift State	= Range Shift Completed ENUM				
			Absolute Attained Gear Slip	<= 50 rpm				
			Attained Gear	<= Sixth				
			Attained Gear	>= First				
			Throttle Position Available	= TRUE				
			Throttle Position	>= 8.000183105 pct				
			Output Speed	>= 200 rpm				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria		Threshold Value		Secondary Malfunction	Enable Conditions			Time Required		Mil Illum.
			Engine Torque	>=	50	Nm							
			Engine Torque	<=	8191.75	Nm							
			If the above conditions are met then Increment Fail Timer								>= 1	Fail Seconds	
			If Fail Timer has Expired then Increment Fail Counter								>= 5	Fail Counts	
			Fail Case 2 Output Speed	<=	70	rpm							
			The following PRNDL sequence events occur in this exact order:										
			PRNDL state	=	Drive 6 (bit state 0110)	Range							
			PRNDL state = Drive 6 for	>=	1	Sec							
			PRNDL state	=	Transition 8 (bit state 0111)	Range							
			PRNDL state	=	Drive 6 (bit state 0110)	Range							
			PRNDL state	=	Transition 1 (bit state 1110)	Range							
			Above sequencing occurs in	<=	1	Sec							
			Neutral Idle Mode	=	Inactive								
			If all conditions above are met Increment delay Timer										
			If the below two conditions are met Increment Fail Timer								>= 3	Fail Seconds	
			delay timer	>=	1	Sec							
			Input Speed	>=	400	Sec							
			If Fail Timer has Expired then Increment Fail Counter								>= 2	Fail Counts	
			Fail Case 3 Current range	=	Transition 13 (bit state 0010)	Range	Previous range	≠	CeTRGR_e_PRNDL_Drive5				
			Engine Torque	>=	-8192	Nm	Previous range	≠	CeTRGR_e_PRNDL_Drive5				
			Engine Torque	<=	8191.75	Nm	IMS is 7 position configuration If the "IMS 7 Position Config" = 1 then the "previous range" criteria above must also be satsified when the "current range" = "Transition 13"	=	0	Boolean			
			If the above conditions are met then, Increment Fail Timer								>= 0.225	Seconds	
			If Fail Timer has Expired then Increment Fail Counter								>= 15	Fail Counts	
			Fail Case 4 Current range	=	Transition 8 (bit state 0111)	Range	Disable Fail Case 4 if last positive range was Drive 6 and current range is transition 8						
			Inhibit bit (see definition)	=	FALSE		Set inhibit bit true if PRNDL = 1100 (rev) or 0100 (Rev-Neu transition 11) Set inhibit bit false if PRNDL = 1001 (park)						
			Steady State Engine Torque	>=	100	Nm							

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria		Threshold Value		Secondary Malfunction	Enable Conditions		Time Required		Mil Illum.
			Steady State Engine Torque	<=	8191.75	Nm						
			If the above conditions are met then Increment Fail Timer							>= 0.225	Seconds	
			If the above Condtions have been met, Increment Fail Counter							>= 15	Fail Counts	
			Fail Case 5 Throttle Position Available	=	TRUE	Boolean						
			The following PRNDL sequence events occur in this exact order:									
			PRNDL State	=	Reverse (bit state 1100)	Range						
			PRNDL State	=	Transition 11 (bit state 0100)	Range						
			PRNDL State	=	Neutral (bit state 0101)	Range						
			PRNDL State	=	Transition 11 (bit state 0100)	Range						
			Above sequencing occurs in	<=	1	Sec						
			Then delay timer increments									
			Delay timer	>=	5	sec						
			Range Shift State	=	Range Shift Complete							
			Absolute Attained Gear Slip	<=	50	rpm						
			Attained Gear	<=	Sixth							
			Attained Gear	>=	First							
			Throttle Position	>=	8.000183105	pct						
			Output Speed	>=	200	rpm						
			If the above conditions are met Increment Fail Timer							>= 20	Seconds	
			Fail Case 6 Current range	=	Illegal (bit state 0000 or 1000 or 0001)		A Open Circuit Definition (flag set false if the following conditions are met):					
			and				Current Range	≠	Transition 11 (bit state 0100)			
			A Open Circuit (See Definition)	=	FALSE	Boolean	or					
							Last positive state	≠	Neutral (bit state 0101)			
							or					
							Previous transition state	≠	Transition 8 (bit state 0111)			
							Fail case 5 delay timer	=	0 sec			
			If the above Condtions are met then, Increment Fail timer							>= 6.25	Seconds	
			Fail Case 7 Current PRNDL State	=	PRNDL circuit ABCP = 1101	Range						
			and									
			Previous PRNDL state	=	PRNDL circuit ABCP =1111	Range						
			Input Speed	>=	150	RPM						
			Reverse Trans Ratio	<=	2.975952148	ratio						
			Reverse Trans Ratio	>=	3.423950195	ratio						
			If the above Condtions are met then, Increment Fail timer							>= 6.25	Seconds	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			P182E will report test fail when any of the above 7 fail cases are met		Ignition Voltage Lo >= 8.5996094 Volts Ignition Voltage Hi <= 31.999023 Volts Engine Speed Lo >= 400 RPM Engine Speed Hi <= 7500 RPM Engine Speed is within the allowable limits for >= 5 Sec Engine Torque Signal Valid = TRUE Boolean		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P07C0, P07BF, P077C, P077D ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Internal Mode Switch (IMS)	P1915	Internal Mode Switch Does Not Indicate Park/Neutral (P/N) During Start	PRNDL State is ≠ Park or Neutral Enumeration The following events must occur Sequentially Initial Engine speed <= 50 RPM				>= 0.25 Enable Time (Sec)	One Trip
			Then Engine Speed Between Following Cals Engine Speed Lo Hist >= 50 RPM Engine Speed Hi Hist <= 480 RPM				>= 0.06875 Enable Time (Sec)	
			Then Final Engine Speed >= 525 RPM Final Transmission Input Speed >= 100 RPM				>= 1.25 Fail Time (Sec)	
					DTC has Ran this Key Cycle? = FALSE Boolean Ignition Voltage Lo >= 6 V Ignition Voltage Hi <= 31.999023 V Ignition Voltage Hyst High (enables above this value) >= 5 V Ignition Voltage Hyst Low (disabled below this value) <= 2 V Transmission Output Speed <= 90 rpm P1915 Status is ≠ Test Failed This Key On or Fault Active		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0722, P0723 ECM: None		
Transmission Control Module (TCM)	P2534	Ignition Switch Run/Start Position Circuit Low	TCM Run crank active (based on voltage thresholds below)	= FALSE Boolean				One Trip
			Ignition Voltage High Hyst (run crank goes true when above this value)	5 Volts			>= 280 Fail Counts (25ms loop)	
			Ignition Voltage Low Hyst (run crank goes false when below this value)	2 Volts			Out of 280 Sample Counts (25ms loop)	
					ECM run/crank active status available	= TRUE Boolean		
					ECM run/crank active status	= TRUE Boolean		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Transmission Control Module (TCM)	P2535	Ignition Switch Run/Start Position Circuit High	TCM Run crank active (based on voltage thresholds below)	= TRUE Boolean				One Trip
			Ignition Voltage High Hyst (run crank goes true when above this value)	5 Volts			>= 280 Fail Counts (25ms loop)	
			Ignition Voltage Low Hyst (run crank goes false when below this value)	2 Volts			Out of 280 Sample Counts (25ms loop)	
					ECM run/crank active status available	= TRUE Boolean		
					ECM run/crank active status	= FALSE Boolean		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Variable Bleed Solenoid (VBS)	P2714	Pressure Control (PC) Solenoid D Stuck Off [CB26]	Fail Case 1 Case: Steady State 2nd Gear					One Trip
			Gear slip	>= 400 RPM			>= Please See Table 5 For Neutral Time Cal Neutral Timer (Sec)	
			Intrusive test: commanded 3rd gear					
			If attained Gear = 3rd for Time	>= Table Based Time Please see Table 2 in Supporting Documents Enable Time (Sec)				
			If Above Conditions have been met					
			Increment 2nd gear fail count				>= 3 2nd Gear Fail Count	
			and CB26 Fail Count				>= 14 or CB26 Fail Count	

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			Fail Case 2 Case: Steady State 6th Gear					
			Gear slip	>= 400 RPM			>= Please See Table 5 For Neutral Time Cal Neutral Timer (Sec)	
			Intrusive test: commanded 5th gear					
			If attained Gear = 5th For Time	>= Table Based Time Please see Table 2 in Supporting Documents Enable Time (Sec)				
			If Above Conditions have been met, Increment 5th gear fail counter				>= 3 5th Gear Fail Count	
			and CB26 Fail Count				>= 14 or CB26 Fail Count	
					PRNDL State defaulted	= FALSE Boolean		
					inhibit RVT	= FALSE Boolean		
					IMS fault pending indication	= FALSE Boolean		
					TPS validity flag	= TRUE Boolean		
					Hydraulic System Pressurized	= TRUE Boolean		
					Minimum output speed for RVT	>= 0 RPM		
					A OR B			
					(A) Output speed enable	>= 67 RPM		
					(B) Accelerator Pedal enable	>= 0.5004883 Pct		
					Common Enable Criteria			
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					Throttle Position Signal valid	= TRUE Boolean		
					HSD Enabled	= TRUE Boolean		
					Transmission Fluid Temperature	>= -6.65625 °C		
					Input Speed Sensor fault	= FALSE Boolean		
					Output Speed Sensor fault	= FALSE Boolean		
					Default Gear Option is not present	= TRUE		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Variable Bleed Solenoid (VBS)	P2715	Pressure Control (PC) Solenoid D Stuck On [CB26] (Dynamic)	Primary Offgoing Clutch is exhausted (See Table 13 in Supporting Documents for Exhaust Delay Timers)	= TRUE Boolean				One Trip

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			Primary Oncoming Clutch Pressure Command Status	= Maximum pressurized				
			Primary Offgoing Clutch Pressure Command Status	= Clutch exhaust command				
			Range Shift Status	≠ Initial Clutch Control				
			Attained Gear Slip	<= 40 RPM				
			If above coditons are true, increment appropriate Fail 1 Timers Below:					
			fail timer 1 (2-1 shifting with throttle)	>= 0.299804688 Fail Time (Sec)				
			fail timer 1 (2-1 shifting without throttle)	>= 0.5 Fail Time (Sec)				
			fail timer 1 (2-3 shifting with throttle)	>= 0.299804688 Fail Time (Sec)				
			fail timer 1 (2-3 shifting without throttle)	>= 0.5 Fail Time (Sec)				
			fail timer 1 (2-4 shifting with throttle)	>= 0.299804688 Fail Time (Sec)				
			fail timer 1 (2-4 shifting without throttle)	>= 0.5 Fail Time (Sec)				
			fail timer 1 (6-4 shifting with throttle)	>= 0.299804688 Fail Time (Sec)				
			fail timer 1 (6-4 shifting without throttle)	>= 0.5 Fail Time (Sec)				
			fail timer 1 (6-5 shifting with throttle)	>= 0.299804688 Fail Time (Sec)				
			fail timer 1 (6-5 shifting without throttle)	>= 0.5 Fail Time (Sec)				
			If Attained Gear Slip is Less than Above Cal Increment Fail Timers				>= Total Fail Time = (Fail 1 + Fail 2) See Enable Timers for Fail Timer 1, and Reference Supporting Table 15 for Fail Timer 2 sec	
			If fail timer is greater than threshold increment corresponding gear fail counter and total fail counter					
			2nd gear fail counter				>= 3 Fail Counter From 2nd Gear OR	
			6th gear fail counter				>= 3 Fail Counter From 6th Gear OR	
			total fail counter				>= 5 Total Fail Counter	
					TUT Enable temperature	>= -6.65625 °C		
					Input Speed Sensor fault	= FALSE Boolean		
					Output Speed Sensor fault	= FALSE Boolean		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Command / Attained Gear	≠ 1st Boolean		
					High Side Driver ON	= TRUE Boolean		
					output speed limit for TUT	>= 100 RPM		
					input speed limit for TUT	>= 150 RPM		
					PRNDL state defaulted	= FALSE Boolean		
					IMS Fault Pending	= FALSE Boolean		
					Service Fast Learn Mode	= FALSE Boolean		
					HSD Enabled	= TRUE Boolean		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Variable Bleed Solenoid (VBS)	P2715	Pressure Control (PC) Solenoid D Stuck On [CB26] (Steady State)	Fail Case 1 Case: Steady State 1st Attained Gear slip If the Above is True for Time Intrusive test: (CBR1 clutch exhausted) Gear Ratio Gear Ratio If the above parameters are true	 >= 400 RPM >= Table Based Time Please Refer to Table 4 in supporting documents Enable Time (Sec) <= 2.482177734 >= 2.245849609			>= 1.1 Fail Timer (Sec) >= 5 Fail Count in 1st Gear or >= 5 Total Fail Counts	One Trip
			Fail Case 2 Case: Steady State 3rd Gear Max Delta Output Speed Hysteresis Min Delta Output Speed Hysteresis If the Above is True for Time	 >= Table Based value Please Refer to Table 22 in supporting documents rpm/sec >= Table Based value Please Refer to Table 23 in supporting documents rpm/sec >= Table Based Time Please Refer to Table 17 in supporting documents Sec				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			Intrusive test: (C35R clutch exhausted)					
			Gear Ratio	<= 2.482177734				
			Gear Ratio	>= 2.245849609				
			If the above parameters are true				>= 1.1 Fail Timer (Sec) >= 3 Fail Count in 3rd Gear or >= 5 Total Fail Counts	
			Fail Case 3 Case: Steady State 4rd Gear					
			Max Delta Output Speed Hysteresis	>= Table Based value Please Refer to Table 22 in supporting documents rpm/sec				
			Min Delta Output Speed Hysteresis	>= Table Based value Please Refer to Table 23 in supporting documents rpm/sec				
			If the Above is True for Time	>= Table Based Time Please Refer to Table 17 in supporting documents Sec				
			Intrusive test: (C1234 clutch exhausted)					
			Gear Ratio	<= 0.700317383				
			Gear Ratio	>= 0.633666992				
			If the above parameters are true				>= 1.1 Fail Timer (Sec) >= 3 Fail Count in 4th Gear or >= 5 Total Fail Counts	
			Fail Case 4 Case: Steady State 5th Gear					
			Max Delta Output Speed Hysteresis	>= Table Based value Please Refer to Table 22 in supporting documents rpm/sec				
			Min Delta Output Speed Hysteresis	>= Table Based value Please Refer to Table 23 in supporting documents rpm/sec				
			If the Above is True for Time	>= Table Based Time Please Refer to Table 17 in supporting documents Sec				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			Intrusive test: (C35R clutch exhausted) Gear Ratio Gear Ratio If the above parameters are true	 <= 0.700317383 >= 0.633666992 			>= 1.1 Fail Timer (Sec) >= 3 Fail Count in 5th Gear or >= 5 Total Fail Counts	
					PRNDL State defaulted inhibit RVT IMS fault pending indication output speed TPS validity flag HSD Enabled Hydraulic_System_Pressurized A OR B (A) Output speed enable (B) Accelerator Pedal enable Ignition Voltage Lo Ignition Voltage Hi Engine Speed Lo Engine Speed Hi Engine Speed is within the allowable limits for if Attained Gear=1st FW Accelerator Pedal enable if Attained Gear=1st FW Engine Torque Enable if Attained Gear=1st FW Engine Torque Enable Transmission Fluid Temperature Input Speed Sensor fault Output Speed Sensor fault Default Gear Option is not present	= FALSE Boolean = FALSE Boolean = FALSE Boolean >= 0 RPM = TRUE Boolean = TRUE Boolean = TRUE Boolean >= 67 Nm >= 0.5004883 Nm >= 8.5996094 Volts <= 31.999023 Volts >= 400 RPM <= 7500 RPM >= 5 Sec >= 5.0003052 Pct >= 5 Nm <= 8191.875 Nm >= -6.65625 °C = FALSE Boolean = FALSE Boolean = TRUE	
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Variable Bleed Solenoid (VBS)	P2720	Pressure Control (PC) Solenoid D Control Circuit Low (CB26 VBS)	The HWIO reports a low voltage (ground short) error flag	= TRUE Boolean			>= 0.3 Fail Time (Sec) out of 0.375 Sample Time (Sec)	One Trip

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					P2770 Status is not = Test Failed This Key On or Fault Active			
					Ignition Voltage >= 8.5996094 Volts Ignition Voltage <= 31.999023 Volts Engine Speed >= 400 RPM Engine Speed <= 7500 RPM Engine Speed is within the allowable limits for >= 5 Sec			
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Variable Bleed Solenoid (VBS)	P2721	Pressure Control (PC) Solenoid D Control Circuit High (CB26 VBS)	The HWIO reports a high voltage (open or power short) error flag	= TRUE Boolean			>= 0.3 Fail Time (Sec) out of 0.375 Sample Time (Sec)	One Trip
					P2721 Status is not = Test Failed This Key On or Fault Active			
					Ignition Voltage >= 8.5996094 Volts Ignition Voltage <= 31.999023 Volts Engine Speed >= 400 RPM Engine Speed <= 7500 RPM Engine Speed is within the allowable limits for >= 5 Sec			
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Variable Bleed Solenoid (VBS)	P2723	Pressure Control (PC) Solenoid E Stuck Off	Fail Case 1 Case: Steady State 1st Gear					One Trip
			Gear slip	>= 400 RPM			>= Please See Table 5 For Neutral Time Cal Neutral Timer (Sec)	
			Intrusive test: commanded 2nd gear					
			If attained Gear ≠ 2nd for Time	>= Please refer to Table 3 in Supporting Documents Shift Time (Sec)				
			If Above Conditions have been met, Increment 1st gear fail counter				>= 3 1st Gear Fail Count	
			and C1234 fail counter				>= 14 or C1234 Clutch Fail Count	
			Fail Case 2 Case: Steady State 2nd Gear					

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			Gear slip	>= 400 RPM			>= Please See Table 5 For Neutral Time Cal Neutral Timer (Sec)	
			Intrusive test: commanded 3rd gear If attained Gear ≠ 3rd for Time	>= Please refer to Table 3 in Supporting Documents Shift Time (Sec)				
			If Above Conditions have been met, Increment 2nd gear fail counter				>= 3 2nd Gear Fail Count	
			and C1234 fail counter				>= 14 or C1234 Clutch Fail Count	
			Fail Case 3 Case: Steady State 3rd Gear Gear slip	>= 400 RPM			>= Please See Table 5 For Neutral Time Cal Neutral Timer (Sec)	
			Intrusive test: commanded 4th gear If attained Gear ≠ 4th for time	>= Please refer to Table 3 in Supporting Documents Shift Time (Sec)				
			If Above Conditions have been met, Increment 3rd gear fail counter				>= 3 3rd Gear Fail Count	
			and C1234 fail counter				>= 14 or C1234 Clutch Fail Count	
			Fail Case 4 Case: Steady State 4th Gear Gear slip	>= 400 RPM			>= Please See Table 5 For Neutral Time Cal Neutral Timer (Sec)	
			Intrusive test: commanded 5th gear If attained Gear = 5th For Time	>= Please refer to Table 3 in Supporting Documents Shift Time (Sec)				
			If Above Conditions have been met, Increment 4th gear fail counter				>= 3 4th Gear Fail Count	
			and C1234 fail counter				>= 14 or C1234 Clutch Fail Count	
					PRNDL State defaulted	= FALSE Boolean		
					inhibit RVT	= FALSE Boolean		
					IMS fault pending indication	= FALSE Boolean		
					TPS validity flag	= TRUE Boolean		
					Hydraulic System Pressurized	= TRUE Boolean		
					Minimum output speed for RVT	>= 0 RPM		
					A OR B (A) Output speed enable	>= 67 RPM		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					(B) Accelerator Pedal enable	>= 0.5004883 Pct		
					Common Enable Criteria			
					Ignition Voltage Lo	>= 8.5996094 Volts		
					Ignition Voltage Hi	<= 31.999023 Volts		
					Engine Speed Lo	>= 400 RPM		
					Engine Speed Hi	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					Throttle Position Signal valid	= TRUE Boolean		
					HSD Enabled	= TRUE Boolean		
					Transmission Fluid Temperature	>= -6.65625 °C		
					Input Speed Sensor fault	= FALSE Boolean		
					Output Speed Sensor fault	= FALSE Boolean		
					Default Gear Option is not present	= TRUE		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Variable Bleed Solenoid (VBS)	P2724	Pressure Control (PC) Solenoid E Stuck On (Dynamic)	Primary Offgoing Clutch is exhausted (See Table 10 in Supporting Documents for Exhaust Delay Timers)	= TRUE Boolean				One Trip
			Primary Oncoming Clutch Pressure Command Status	= Maximum pressurized				
			Primary Offgoing Clutch Pressure Command Status	= Clutch exhaust command				
			Range Shift Status	≠ Initial Clutch Control				
			Attained Gear Slip	<= 40 RPM				
			If the above conditions are true increment appropriate Fail 1 Timers Below:					
			fail timer 1 (2-6 shifting with throttle)	>= 0.299804688 sec				
			fail timer 1 (2-6 shifting without throttle)	>= 0.5 sec				
			fail timer 1 (3-5 shifting with throttle)	>= 0.299804688 sec				
			fail timer 1 (3-5 shifting without throttle)	>= 0.5 sec				
			fail timer 1 (4-5 shifting with throttle)	>= 0.299804688 sec				
			fail timer 1 (4-5 shifting without throttle)	>= 0.5 sec				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
			fail timer 1 (4-6 shifting with throttle)	>= 0.299804688 sec				
			fail timer 1 (4-6 shifting without throttle)	>= 0.5 sec				
			If Attained Gear Slip is Less than Above Cal Increment Fail Timers				>= Total Fail Time = (Fail 1 + Fail 2) See Enable Timers for Fail Timer 1, and Reference Supporting Table 15 for Fail Timer 2 sec	
			If fail timer is greater than threshold increment corresponding gear fail counter and total fail counter					
			2nd gear fail counter				>= 3 Fail Counter From 2nd Gear	
			3rd gear fail counter				>= 3 Fail Counter From 3rd Gear	
			4th gear fail counter				>= 3 Fail Counter From 4th Gear	
			total fail counter				>= 5 Total Fail Counter	
					TUT Enable temperature	>= -6.65625 °C		
					Input Speed Sensor fault	= FALSE Boolean		
					Output Speed Sensor fault	= FALSE Boolean		
					Command / Attained Gear	≠ 1st Boolean		
					High Side Driver ON	= TRUE Boolean		
					output speed limit for TUT	>= 100 RPM		
					input speed limit for TUT	>= 150 RPM		
					PRNDL state defaulted	= FALSE Boolean		
					IMS Fault Pending	= FALSE Boolean		
					Service Fast Learn Mode	= FALSE Boolean		
					HSD Enabled	= TRUE Boolean		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E		
Variable Bleed Solenoid (VBS)	P2724	Pressure Control (PC) Solenoid E Stuck On (Steady State)	Fail Case 1 Case: 5th Gear					One Trip

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria		Threshold Value		Secondary Malfunction	Enable Conditions			Time Required			Mil Illum.
				Max Delta Output Speed Hysteresis	>=	Table Based value Please Refer to Table 22 in supporting documents rpm/sec								
				Min Delta Output Speed Hysteresis	>=	Table Based value Please Refer to Table 23 in supporting documents rpm/sec								
				If the Above is True for Time	>=	Table Based Time Please Refer to Table 17 in supporting documents Sec								
				Intrusive test: (C35R clutch exhausted)										
				Gear Ratio	<=	1.209594727								
				Gear Ratio	>=	1.094360352								
				If the above parameters are true										
											>=	1.1	Fail Timer (Sec)	
											>=	3	Fail Count in 5th Gear OR	
											>=	3	Total Fail Counts	
			Fail Case 2	Case: 6th Gear										
				Max Delta Output Speed Hysteresis	>=	Table Based value Please Refer to Table 22 in supporting documents rpm/sec								
				Min Delta Output Speed Hysteresis	>=	Table Based value Please Refer to Table 23 in supporting documents rpm/sec								
				If the Above is True for Time	>=	Table Based Time Please Refer to Table 17 in supporting documents Sec								
				Intrusive test: (CB26 clutch exhausted)										
				Gear Ratio	<=	1.209594727								
				Gear Ratio	>=	1.094360352								
				If the above parameters are true										
											>=	1.1	Fail Timer (Sec)	
											>=	3	Fail Count in 6th Gear OR	
											>=	3	Total Fail Counts	
							PRNDL State defaulted	=	FALSE	Boolean				
							inhibit RVT	=	FALSE	Boolean				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions			Time Required			Mil Illum.
					IMS fault pending indication	=	FALSE	Boolean				
					output speed	>=	0	RPM				
					TPS validity flag	=	TRUE	Boolean				
					HSD Enabled	=	TRUE	Boolean				
					Hydraulic_System_Pressurized	=	TRUE	Boolean				
					A OR B							
					(A) Output speed enable	>=	67	Nm				
					(B) Accelerator Pedal enable	>=	0.5004883	Nm				
					Ignition Voltage Lo	>=	8.5996094	Volts				
					Ignition Voltage Hi	<=	31.999023	Volts				
					Engine Speed Lo	>=	400	RPM				
					Engine Speed Hi	<=	7500	RPM				
					Engine Speed is within the allowable limits for	>=	5	Sec				
					if Attained Gear=1st FW Accelerator Pedal enable	>=	5.0003052	Pct				
					if Attained Gear=1st FW Engine Torque Enable	>=	5	Nm				
					if Attained Gear=1st FW Engine Torque Enable	<=	8191.875	Nm				
					Transmission Fluid Temperature	>=	-6.65625	°C				
					Input Speed Sensor fault	=	FALSE	Boolean				
					Output Speed Sensor fault	=	FALSE	Boolean				
					Default Gear Option is not present	=	TRUE					
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0716, P0717, P0722, P0723, P182E ECM: P0101, P0102, P0103, P0106, P0107, P0108, P0171, P0172, P0174, P0175, P0201, P0202, P0203, P0204, P0205, P0206, P0207, P0208, P0300, P0301, P0302, P0303, P0304, P0305, P0306, P0307, P0308, P0401, P042E							
Variable Bleed Solenoid (VBS)	P2729	Pressure Control (PC) Solenoid E Control Circuit Low (C1234 VBS)	The HWIO reports a low voltage (ground short) error flag	= TRUE Boolean					>=	0.3	Fail Time (Sec)	One Trip
									out of	0.375	Sample Time (Sec)	
					P2729 Status is not	=	Test Failed This Key On or Fault Active					
					Ignition Voltage	>=	8.5996094	Volt				
					Ignition Voltage	<=	31.999023	Volt				
					Engine Speed	>=	400	RPM				
					Engine Speed	<=	7500	RPM				
					Engine Speed is within the allowable limits for	>=	5	Sec				

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Variable Bleed Solenoid (VBS)	P2730	Pressure Control (PC) Solenoid E Control Circuit High (C1234 VBS)	The HWIO reports a high voltage (open or power short) error flag	= TRUE Boolean			>= 0.3 Fail Time (Sec) out of 0.375 Sample Time (Sec)	One Trip
					P2730 Status is not	= Test Failed This Key On or Fault Active		
					Ignition Voltage	>= 8.5996094 Volt		
					Ignition Voltage	<= 31.999023 Volt		
					Engine Speed	>= 400 RPM		
					Engine Speed	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: None ECM: None		
Variable Bleed Solenoid (VBS)	P2763	Torque Converter Clutch Pressure High	The HWIO reports a low pressure/high voltage (open or power short) error flag	= TRUE Boolean			>= 4.4 Fail Time (Sec) out of 5 Sample Time (Sec)	Two Trips
					P2763 Status is not	= Test Failed This Key On or Fault Active		
					Ignition Voltage	>= 8.5996094 Volt		
					Ignition Voltage	<= 31.999023 Volt		
					Engine Speed	>= 400 RPM		
					Engine Speed	<= 7500 RPM		
					Engine Speed is within the allowable limits for	>= 5 Sec		
					High Side Driver Enabled	= TRUE Boolean		
				Disable Conditions:	**MIL not Illuminated for DTC's:**	TCM: P0658, P0659 ECM: None		
Variable Bleed Solenoid (VBS)	P2764	Torque Converter Clutch Pressure Control Solenoid Control Circuit Low	The HWIO reports a high pressure/low voltage (ground short) error flag	= TRUE Boolean			>= 4.4 Fail Time (Sec) out of 5 Sample Time (Sec)	One Trip
					P2764 Status is not	= Test Failed This Key On or Fault Active		

Component/ System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Malfunction	Enable Conditions	Time Required	Mil Illum.
					Ignition Voltage >= 8.5996094 Volt Ignition Voltage <= 31.999023 Volt Engine Speed >= 400 RPM Engine Speed <= 7500 RPM Engine Speed is within the allowable limits for >= 5 Sec High Side Driver Enabled = TRUE Boolean			
					Disable Conditions:	**MIL not Illuminated for DTC's:** TCM: P0658, P0659 ECM: None		
Communication	U0073	Controller Area Network Bus Communication Error	CAN Hardware Circuitry Detects a Low Voltage Error	= TRUE Boolean			>= 62 Fail counts (≈ 10 seconds)	One Trip
			Delay timer	>= 0.1125 sec			Out of 70 Sample Counts (≈ 11 seconds)	
					Stabilization delay >= 3 sec Ignition Voltage >= 8.5996094 Volt Ignition Voltage <= 31.999023 Volt Power Mode = Run			
					Disable Conditions:	**MIL not Illuminated for DTC's:** TCM: None ECM: None		
Communication	U0100	Lost Communications with ECM (Engine Control Module)	CAN messages from ECM are not received by the TCM	= TRUE Boolean			>= 12 sec	One Trip
					Stabilization delay >= 3 sec Ignition Voltage >= 8.5996094 Volt Ignition Voltage <= 31.999023 Volt Power Mode = Run			
					Disable Conditions:	**MIL not Illuminated for DTC's:** TCM: U0073 ECM: None		

TCM Supporting Tables

Table 1

Axis	0.00	64.00	128.00	192.00	256.00	320.00	384.00	448.00	512.00	N*m
Curve	50.00	50.00	50.00	50.00	50.00	50.00	50.00	50.00	50.00	RPM

Table 2

Axis	-6.67	-6.66	40.00	ºC
Curve	409.59	2.00	2.00	Sec

Table 3

Axis	-6.67	-6.66	40.00	ºC
Curve	409.59	4.00	4.00	Sec

Table 4

Axis	-6.67	-6.66	40.00	ºC
Curve	409.59	2.00	2.00	Sec

Table 5

Axis	-6.67	-6.66	40.00	ºC
Curve	409.59	3.00	3.00	Sec

Table 6

Axis	-6.67	-6.66	40.00	80.00	120.00	ºC
Curve	409.00	3.60	1.60	1.40	1.40	Sec

Table 7

Axis	-6.67	-6.66	40.00	80.00	120.00	°C
Curve	409.00	3.40	1.40	1.30	1.20	Sec

Table 8

Axis	-6.67	-6.66	40.00	80.00	120.00	°C
Curve	409.00	3.60	1.60	1.50	1.40	Sec

Table 9

Axis	-6.67	-6.66	40.00	80.00	120.00	°C
Curve	409.00	3.30	1.30	1.20	1.10	Sec

Table 10

Axis	-6.67	-6.66	40.00	80.00	120.00	°C
Curve	3.03	1.86	1.00	0.75	0.58	Sec

Table 11

Axis	-6.67	-6.66	40.00	80.00	120.00	°C
Curve	1.72	1.11	0.60	0.36	0.22	Sec

Table 12

Axis	-6.67	-6.66	40.00	80.00	120.00	°C
Curve	2.12	1.39	0.84	0.64	0.33	Sec

Table 13

Axis	-6.67	-6.66	40.00	80.00	120.00	°C
Curve	2.51	0.95	0.50	0.29	0.13	Sec

Table 14

Axis	-6.67	-6.66	40.00	80.00	120.00	ºC
Curve	2.97	0.82	0.47	0.20	0.13	Sec

Table 15

Axis	-40.00	-30.00	-20.00	-10.00	0.00	10.00	20.00	30.00	40.00	ºC
Curve	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	Sec

Table 16

Axis	-6.67	-6.66	40.00	ºC
Curve	409.59	2.50	2.50	Sec

Table 17

Axis	-6.67	-6.66	40.00	ºC
Curve	0.40	0.35	0.30	Sec

Table 18

Axis	-40.10	-40.00	-20.00	0.00	30.00	60.00	100.00	149.00	149.10	ºC
Curve	256.00	50.00	45.00	40.00	34.00	25.00	20.00	20.00	256.00	ºC

Table 19

Axis	-40.10	-40.00	-20.00	0.00	30.00	60.00	100.00	149.00	149.10	ºC
Curve	256.00	50.00	45.00	40.00	34.00	25.00	20.00	20.00	256.00	ºC

Table 20

Axis	-40.10	-40.00	-20.00	0.00	30.00	60.00	100.00	149.00	149.10	ºC
Curve	256.00	10.00	8.00	8.00	8.00	8.00	8.00	8.00	256.00	ºC

Table 21

Axis	-40.00	-20.00	40.00	ºC
Curve	5.00	3.00	1.00	Sec

Table 22

Axis	-6.67	-6.66	40.00	ºC
Curve	8191.75	8191.75	8191.75	RPM/Sec

Table 23

Axis	-6.67	-6.66	40.00	ºC
Curve	8191.75	8191.75	8191.75	RPM/Sec

Component/System	Fault Code	Monitor Strategy Description	Malfunction Criteria	Threshold Value	Secondary Parameters	Enable Conditions	Time Required	MIL Illum.
Ignition Switch Run/Start Position Circuit Stuck Low Detected	B2B0D	This monitoring checks if the hardwired Run/Crank analog signal matches the value of the Run/Crank Terminal Status message received from the ECM. This fault is set if the two signals do not match where the hardwired signal is set to INACTIVE while the serial data signal is set to ACTIVE.	Run/Crank Analog Signal State **AND** Run/Crank Terminal Status **AND** X **OUT OF** Y	<= 1.5V = ACTIVE = 80 = 100	ECM Timed Out	= FALSE	0.8 [Sec]	Type B 2 Trips
Ignition Switch Run/Start Position Circuit Stuck High Detected	B2B0E	This monitoring checks if the hardwired Run/Crank analog signal matches the value of the Run/Crank Terminal Status message received from the ECM. This fault is set if the two signals do not match where the hardwired signal is set to ACTIVE while the serial data signal is set to INACTIVE.	Run/Crank Analog Signal State **AND** Run/Crank Terminal Status **AND** X **OUT OF** Y	>=5.5V = INACTIVE = 80 = 100	ECM Timed Out	= FALSE	0.8 [Sec]	Type B 2 Trips
Bus-Off detected on the HS Primary bus (Bus A)	U2413	This fault is set if the HS Primary bus enters the Bus-Off state	Bus Off Event Occurred on HS Primary	= TRUE	Run/Crank Analog Signal State **OR** Comm Enable Hardwire Line **AND** System Voltage	>= 5.5V >= 4.5V > 5.5V	25[usec] for pass 10[usec] for fail	Type B 2 Trips

Internal memory failure on the CGM Detected	B2B12	This monitoring checks whether a double bit ECC error has occurred in code flash or RAM. This fault is set if an ECC error has occurred.	ECC Error Detected	= TRUE	Guarded Read Flag	= FALSE	50ms	Type B 2 Trips
		This monitoring checks and sets a fault if a defect in the data flash (NVM) is detected.	NVM Fault Detected	= TRUE	N/A	N/A	1.5 us	
Microcontroller Performance Failure Detected	B2B13	This monitoring shall check whether the ALU in the microcontroller is functioning correctly by running an algorithm and checking the results against an expected value. If the result is incorrect the fault shall be set.	Test Result 1 **AND** Test Result 2	!= Expected Result 1 != Expected Result 2	N/A	N/A	1.5 us	Type B 2 Trips
		This monitoring shall check whether any clock monitoring interrupts have occurred. If any clock monitoring interrupts have occurred this fault shall be set.	Clock Monitoring Interrupt Occurred	= TRUE	N/A	N/A		

Loss of Communication with the ECM Detected	U18D5	This monitoring shall check a supervised message from the ECM to check the communication status. If the CGM has not received the supervised message from the ECM for 2.5x of its periodic rate, a secondary counter shall be enabled and decremented. When the secondary timer reaches zero, this fault shall be set if the message still has not been received.	Supervised Message has not been received in 62.5[ms] **THEN** Secondary Timer (4 sec)	= TRUE = 0 sec	Run/Crank Analog Signal State **AND** System Voltage	>= 5.5V >= 7V	4.0625 [sec]	Type B 2 Trips
Loss of Communication with the TCM Detected	U18D7	This monitoring shall check a supervised message from the TCM to check the communication status. If the CGM has not received the supervised message from the TCM for 2.5x of its periodic rate, a secondary counter shall be enabled and decremented. When the secondary timer reaches zero, this fault shall be set if the message still has not been received.	Supervised Message has not been received in 2.5[sec] **THEN** Secondary Timer (4 sec)	= TRUE = 0 sec	Run/Crank Analog Signal State **AND** System Voltage	= ACTIVE >= 7V	6.5 [sec]	Type B 2 Trips